

# Structure-Induced Information for Rerooting Levin Tree Search

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# Motivation

## Hard planning problems need structure.

- Learned policies and heuristics help, but can struggle to reach distant goals.

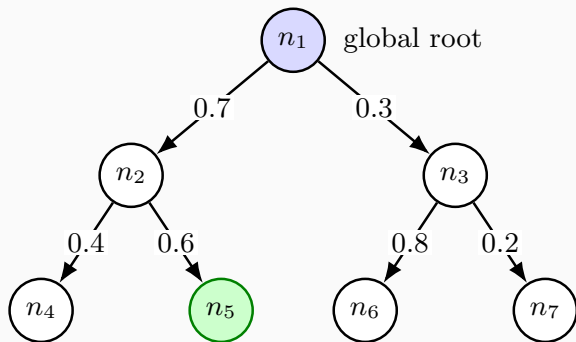
## Explicit subgoals are powerful but costly.

- They require generating or reconstructing intermediate target states.

## Our idea:

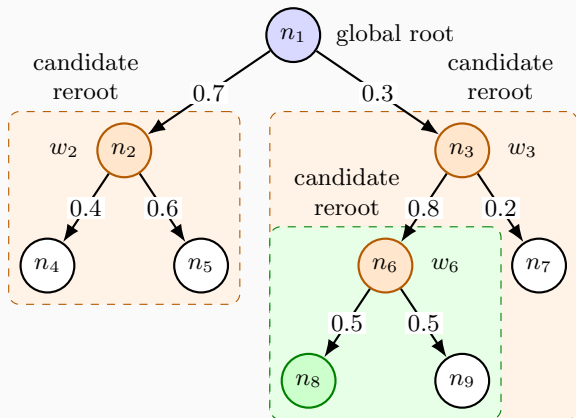
Use **rerooting weights** to allocate search effort to useful internal roots, creating **soft subtasks** during search.

# Levin Tree Search (LTS)



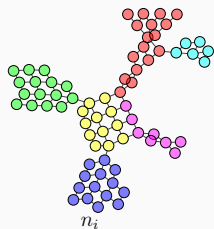
$$\varphi_{\text{LTS}}(n) = \frac{d}{\pi}(n) = \frac{d(n)}{\pi(n)}$$

Search is guided only from the global root  $n_1$ .



$$\varphi_{\sqrt{\text{LTS}}}(n) = \min_{n_t \prec n} \frac{1}{w_t} \frac{d}{\pi}(n_t \prec n)$$

Search effort is redistributed across multiple local roots.



Set color counts:

1. Select graph  $G_k = (V_k, E_k)$  for a given cluster level  $k \in [1, N]$ .
2. Color nodes  $v \in V_0$  using cluster association from  $V_k$ :

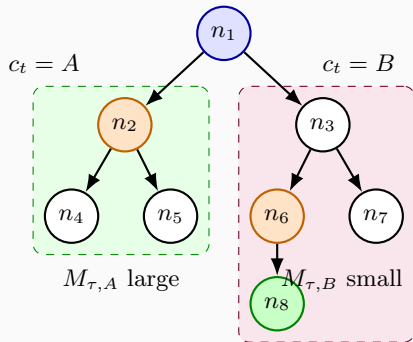
$$M_{\tau, c_i} = \{$$

■ = 6,	■ = 17,	■ = 12,
■ = 8,	■ = 14,	■ = 15

$$\}$$

$$w_t = \frac{1}{M_{\tau, c_t} + \delta_{\tau, c_t}}$$

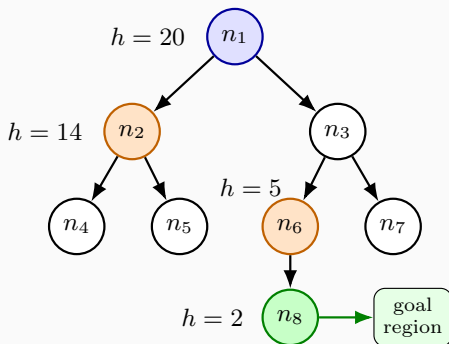
## Global Structure Rerooter



$$w_t^L = \frac{1}{M_{\tau, c_t} + \delta_{\tau, c_t}}$$

Prefer less-explored structural regions.

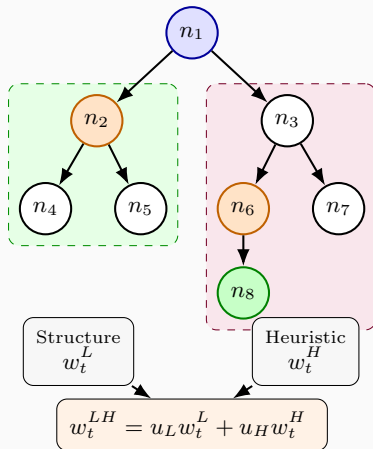
## Local Heuristic Rerooter



$$w_t^H = \exp\left(-\alpha \frac{h(n_t)}{h(n_1)}\right)$$

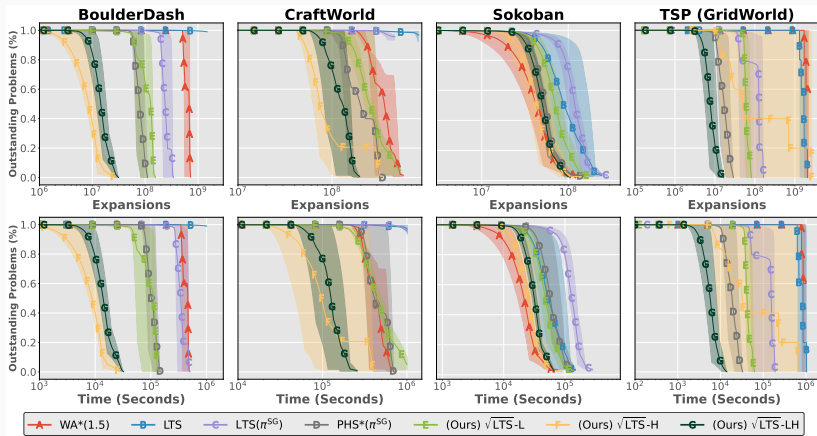
Prefer roots that appear closer to the goal.

## Hybrid Additive Rerooter



Use global structure for broad allocation and heuristic progress for local refinement.

# Results - Training Efficiency



# Results - Domain Complexity Scaling

Algorithm	Expansions	Time	Solved	Nodes/s
BoulderDash (10%)				
PHS*( $\pi^{SG}$ )	30,686,786	10.63	10,000	802.1
$\sqrt{LTS}$ -LH	18,654,789	5.36	10,000	967.4
BoulderDash (20%)				
PHS*( $\pi^{SG}$ )	299,672,516	137.12	10,000	607.1
$\sqrt{LTS}$ -LH	25,971,412	7.70	9,992	936.6
BoulderDash (30%)				
PHS*( $\pi^{SG}$ )	429,407,720	278.23	11	428.7
$\sqrt{LTS}$ -LH	57,780,467	16.50	10,000	972.5
BoulderDash (40%)				
PHS*( $\pi^{SG}$ )	—	—	—	—
$\sqrt{LTS}$ -LH	75,672,897	22.49	9,995	934.79
BoulderDash (50%)				
PHS*( $\pi^{SG}$ )	—	—	—	—
$\sqrt{LTS}$ -LH	97,117,682	30.13	9,990	895.2

# Takeaway

Rerooting provides a scalable way to exploit structure in policy-guided tree search without explicitly generating subgoals.

## **Structure from search itself.**

- Use clusters, heuristics, or both to define rerooting weights.

## **Subgoal-like behavior without subgoal models.**

- Allocate effort to useful internal roots instead of reconstructing target states.

## **Practical and scalable**

- Improves online training efficiency across challenging planning domains.