

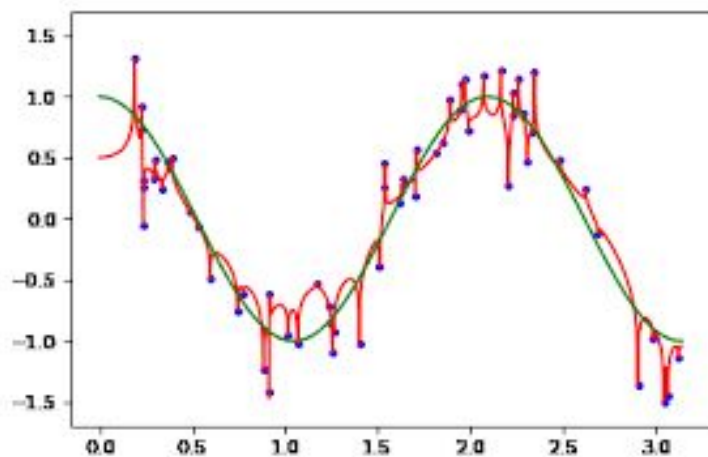
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# **TPV: Parameter Perturbations Through the Lens of Test Prediction Variance**

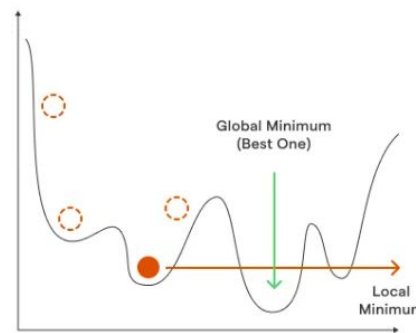
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**Devansh Arpit<sup>1</sup>**

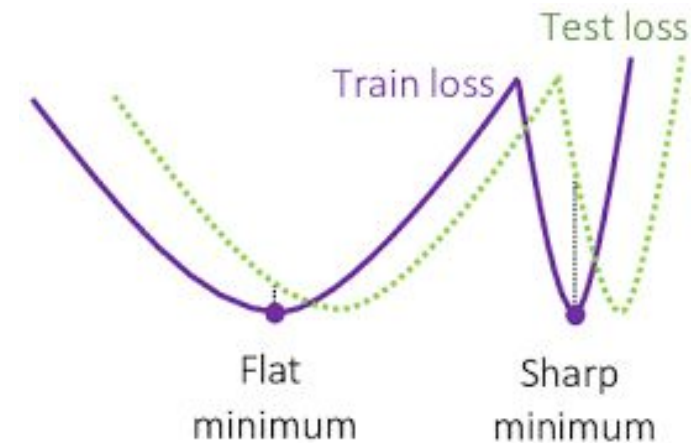
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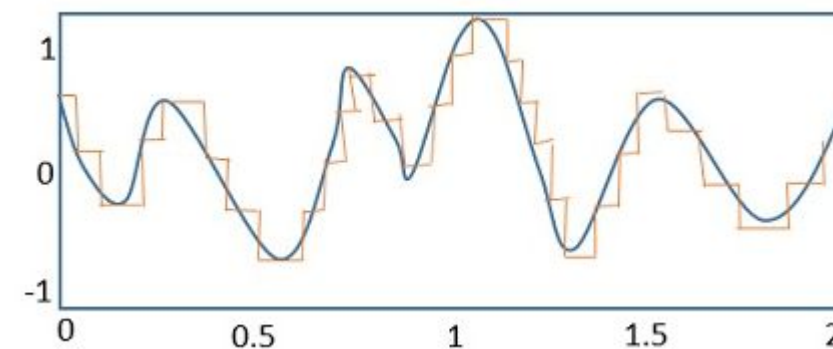
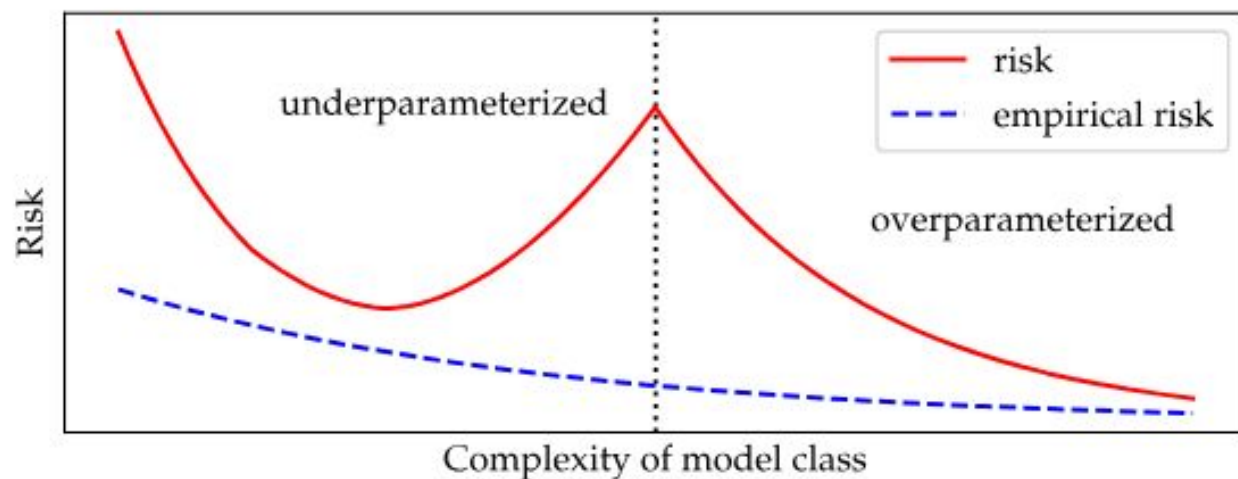
Benign Overfitting  
under Label Noise



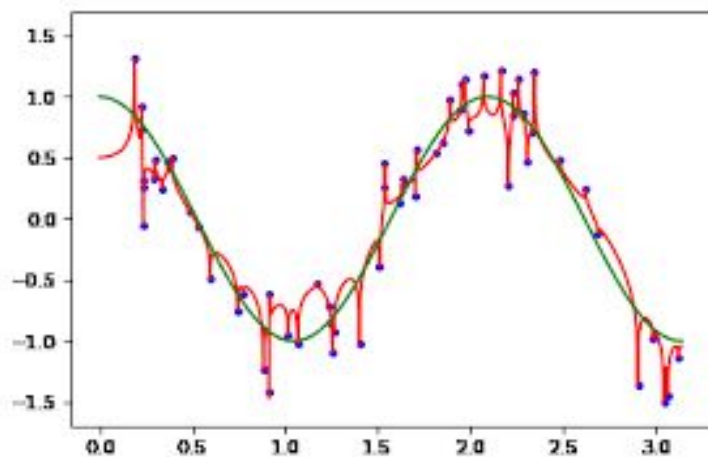
SGD Noise



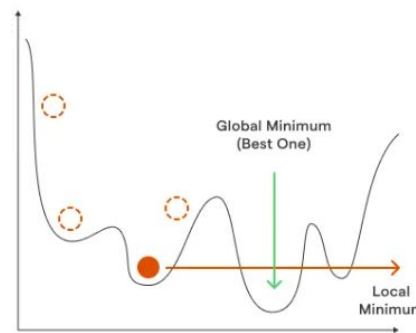
## Scattered Views of Generalization & Robustness in Deep Learning



Quantization Noise



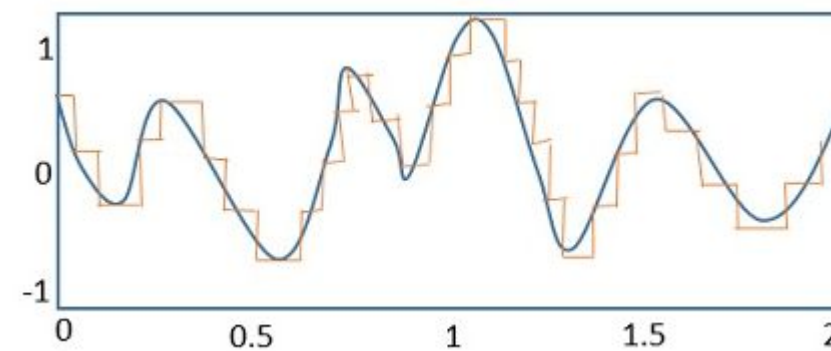
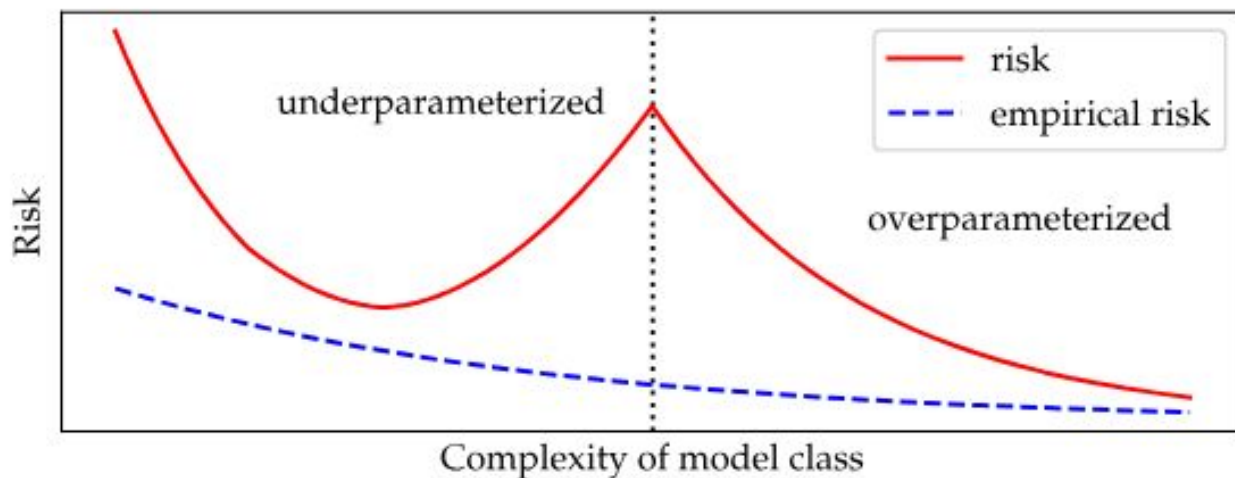
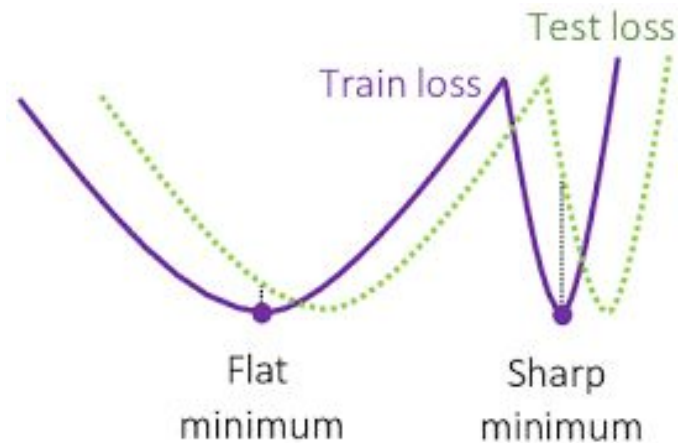
Benign Overfitting  
under Label Noise



SGD Noise

## Motivation

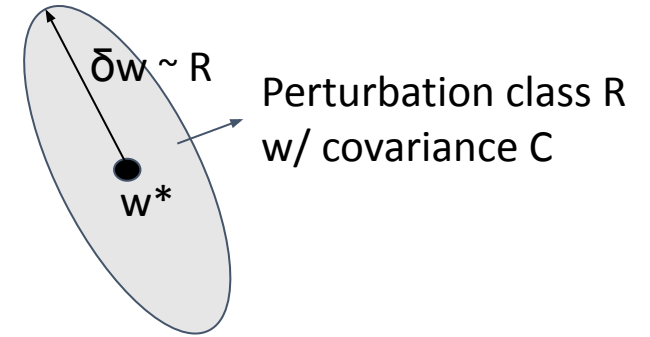
- Unified framework for studying robustness of a trained model
- Model selection using training-set



Quantization Noise

# Test Prediction Variance (TPV)

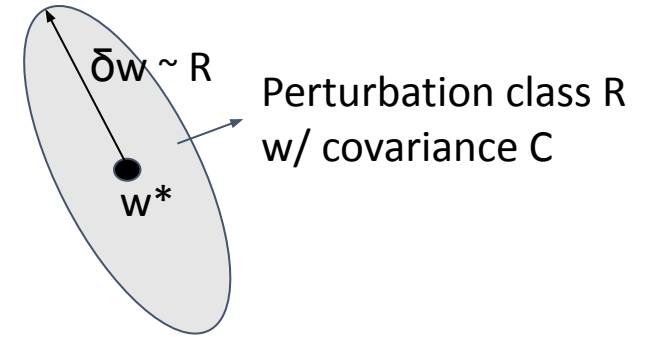
$$\text{TPV} := \mathbb{E}_{x, \delta w} \left[ \|f_{w^* + \delta w}(x) - f_{w^*}(x)\|^2 \right]$$



TPV measures variance of predictions under perturbation class  $R$

# Test Prediction Variance (TPV)

$$\text{TPV} := \mathbb{E}_{x, \delta w} \left[ \|f_{w^* + \delta w}(x) - f_{w^*}(x)\|^2 \right]$$



TPV measures variance of predictions under perturbation class R

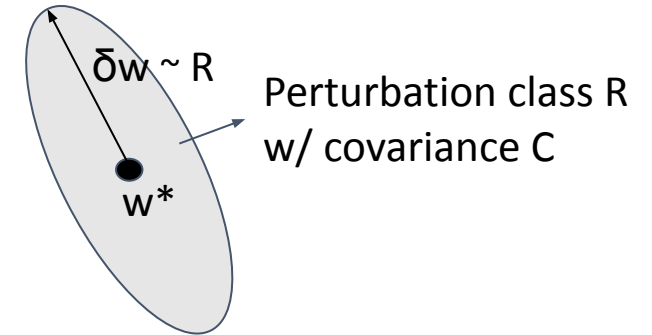
Many natural sources of randomness R in real-world:

- Fine-tuning on noisy label data
- Fine-tuning on data with covariate shift
- Quantization noise
- SGD noise at convergence
- Pruning noise

Each source induces parameter perturbations around  $w^*$  directly or indirectly

# Test Prediction Variance (TPV)

$$\text{TPV} := \mathbb{E}_{x, \delta w} \left[ \|f_{w^* + \delta w}(x) - f_{w^*}(x)\|^2 \right]$$



## Bias-Variance Decomposition

$$\mathcal{E}_{\text{test}} = \mathbb{E}_{x, y, R} \left[ (f_{w^* + \delta w}(x) - y)^2 \right]$$

$$\mathcal{E}_{\text{test}} = \text{TPV} + \underbrace{\mathbb{E}_x \left[ (f_{w^*}(x) - f^*(x))^2 \right]}_{\text{bias}^2}.$$

# Local vs Global Bias-Variance Decomposition

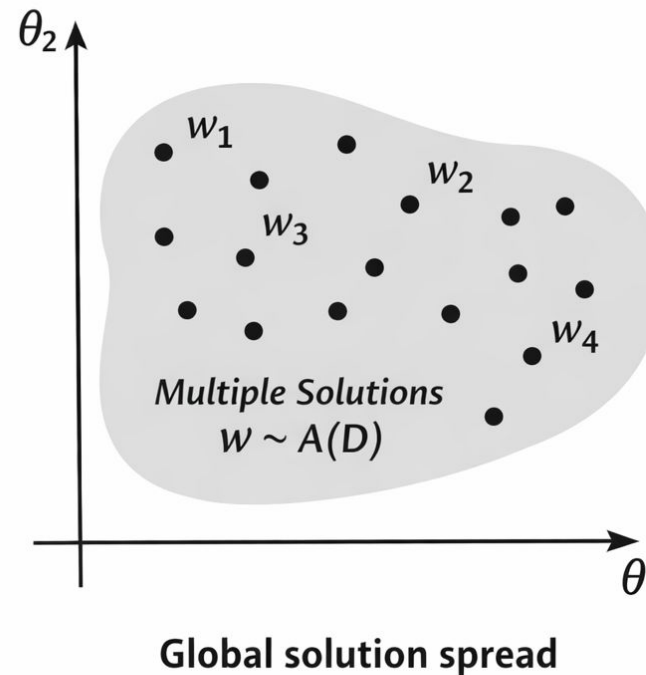
## Global Decomposition

- provides insight into properties of the learning algorithm

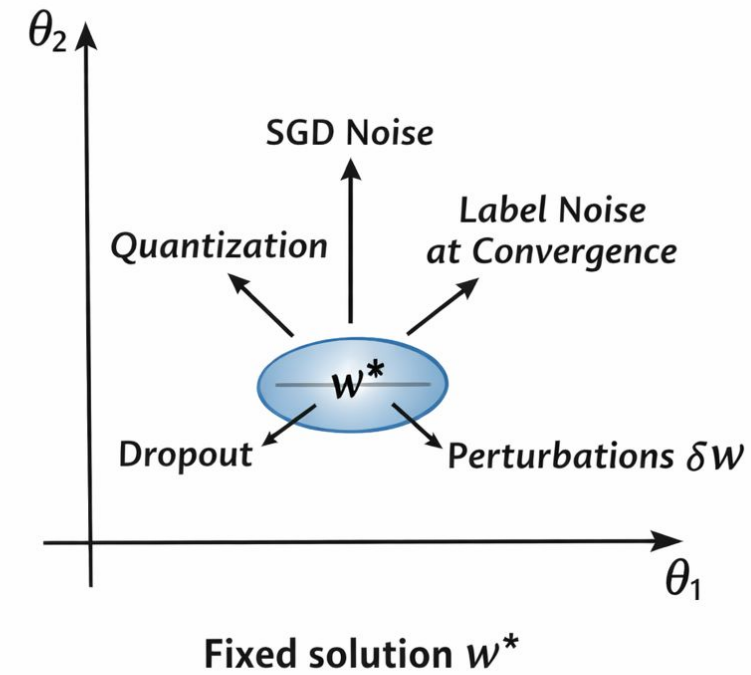
## Local Decomposition

- provides insight into robustness of the trained model

### Global Variance



### Local Variance (TPV)



TPV is Local Variance

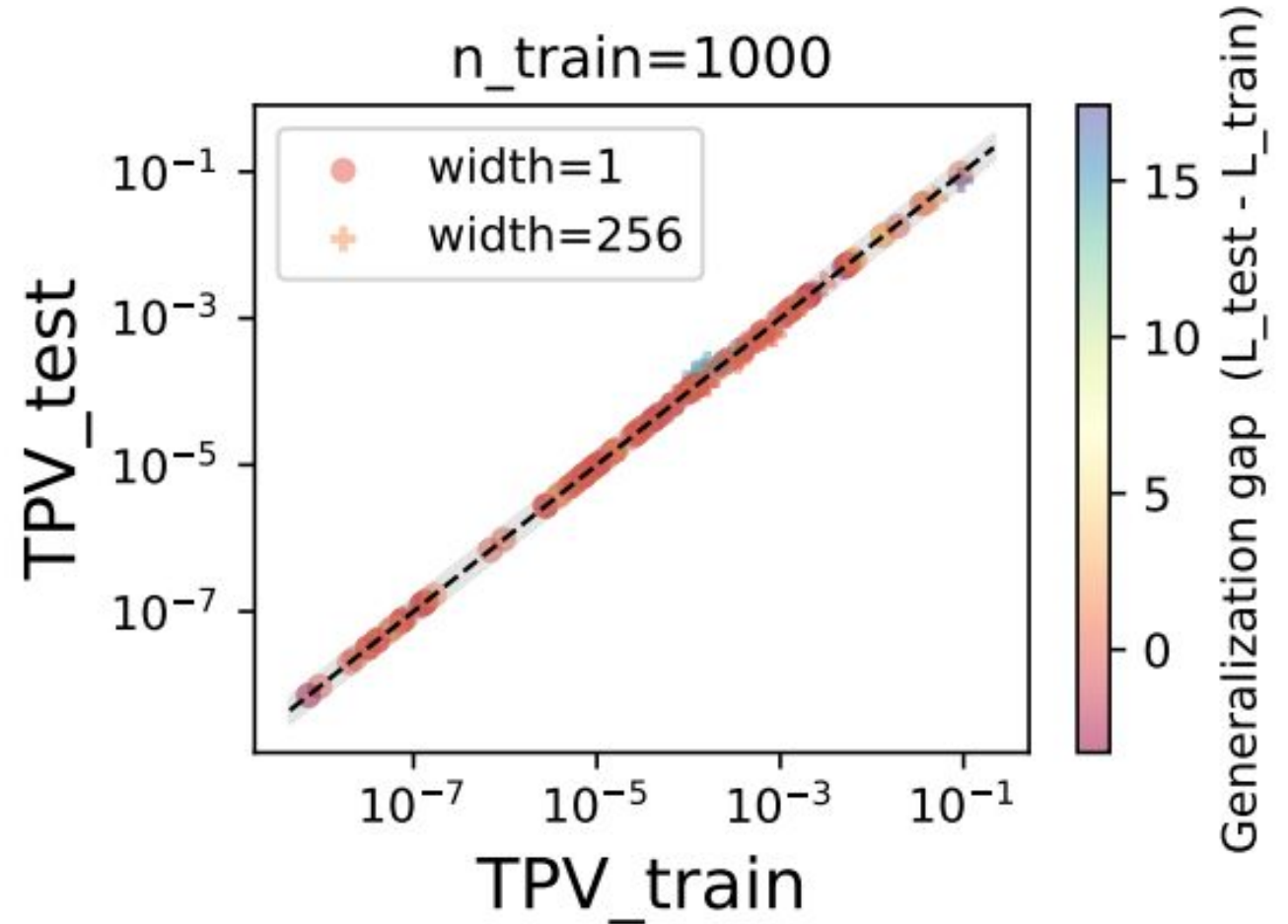
# Why is TPV Useful?

- Unifying view:
  - Overparameterization -> low TPV under label noise (benign overfitting)
  - Wide minima -> low TPV under SGD/quantization noise
  - Other noise sources can also be studied under TPV framework
- Two properties of TPV:
  - TPV stability
    - $\text{TPV}(w^*; X_{\text{tr}}) \approx \text{TPV}(w^*; X_{\text{te}})$
  - TPV and Generalization
    - TPV correlated with test loss in low training loss regime
- Applications (due to above 2 properties):
  - Model/Training-recipe selection using training set
  - Label-free pruning algorithm

# TPV Stability => $\text{TPV}(w^*; X_{\text{tr}}) \approx \text{TPV}(w^*; X_{\text{te}})$

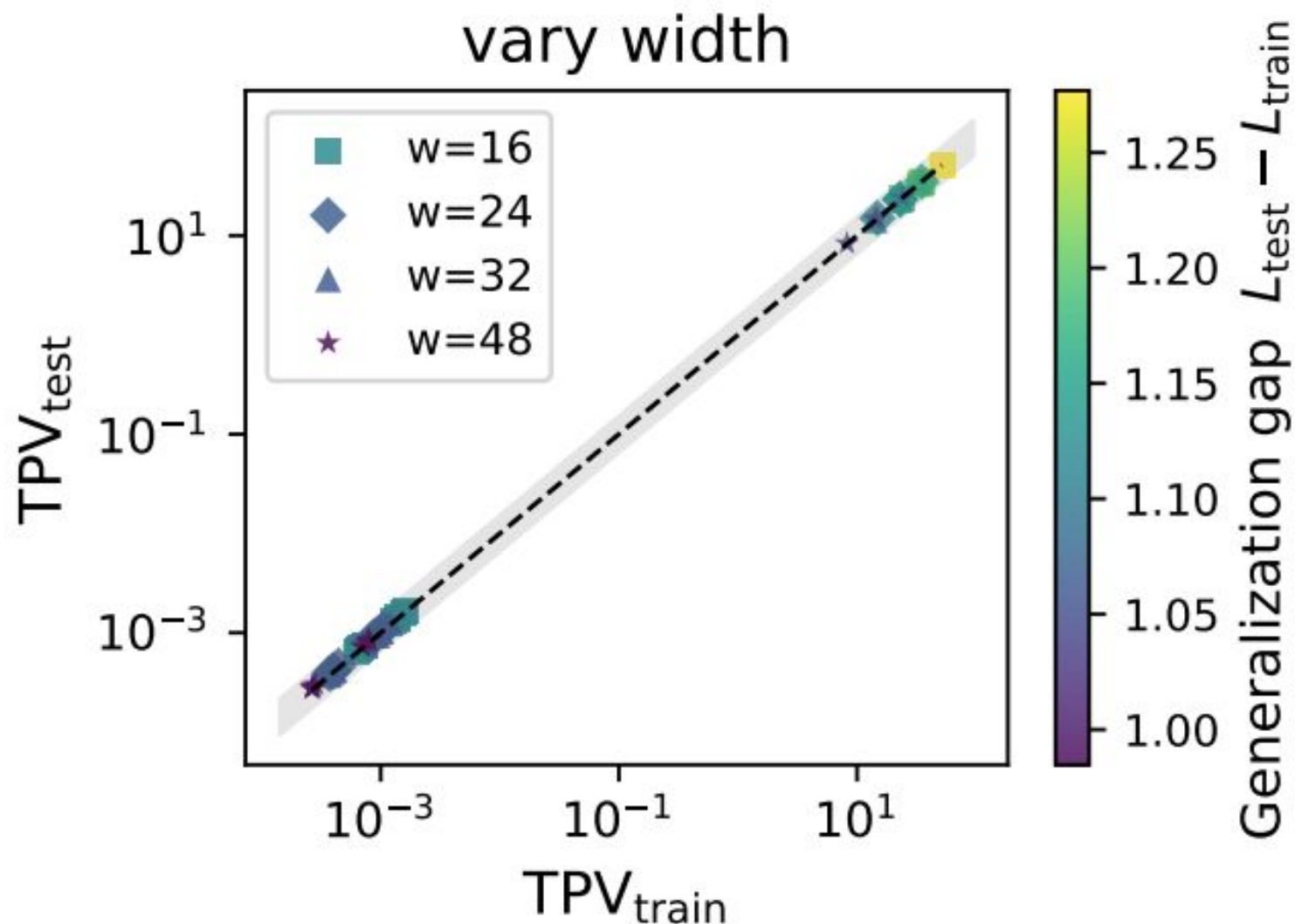
TPV stability (synthetic data)

- broad grid of:
  - architectures (depth/width),
  - data distributions/dimensions
  - perturbation sources
  - 324 configurations each w/ 50 runs



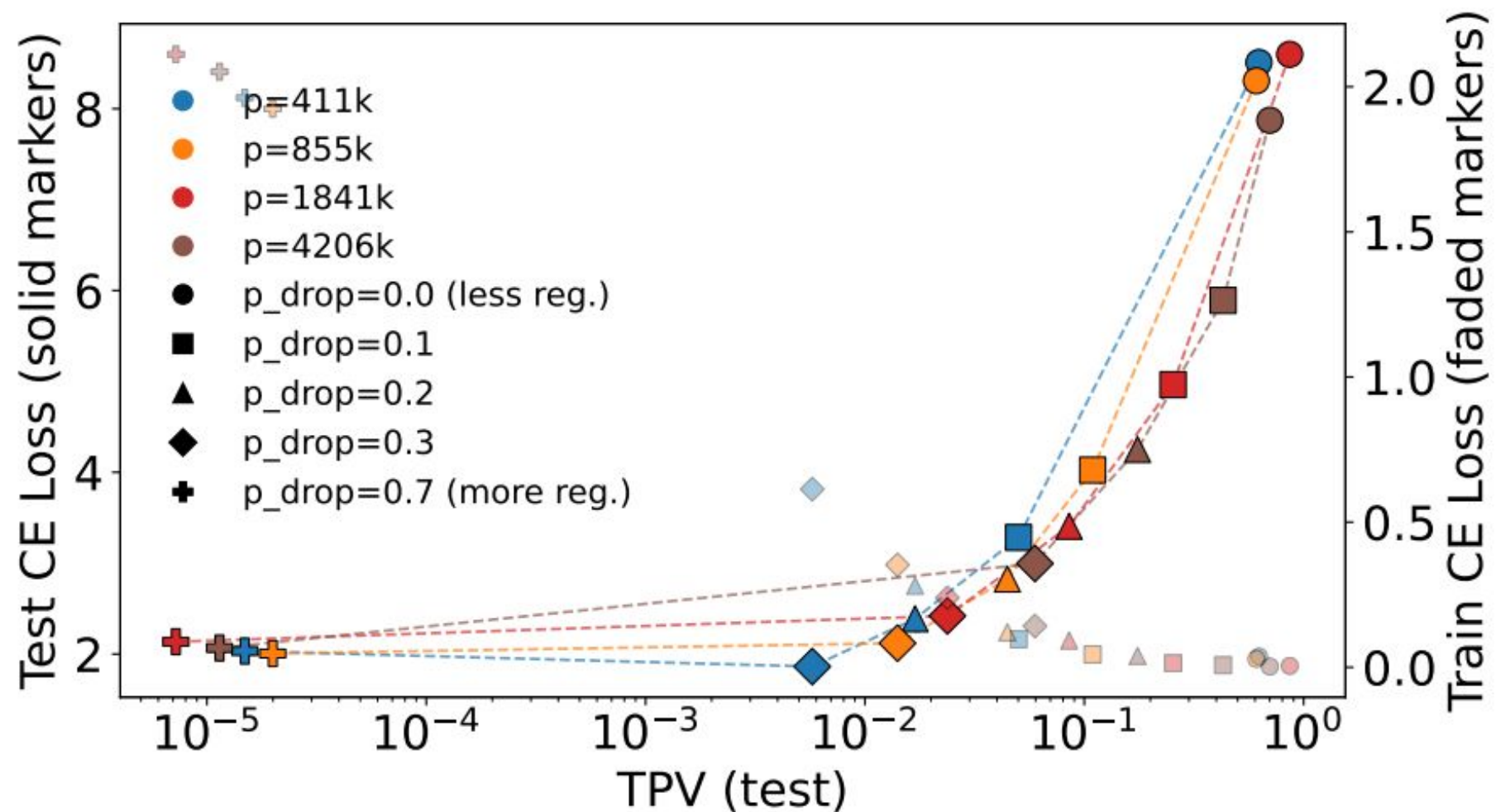
TPV Stability =>  $\text{TPV}(w^*; X_{\text{tr}}) \approx \text{TPV}(w^*; X_{\text{te}})$

TPV stability (real data)



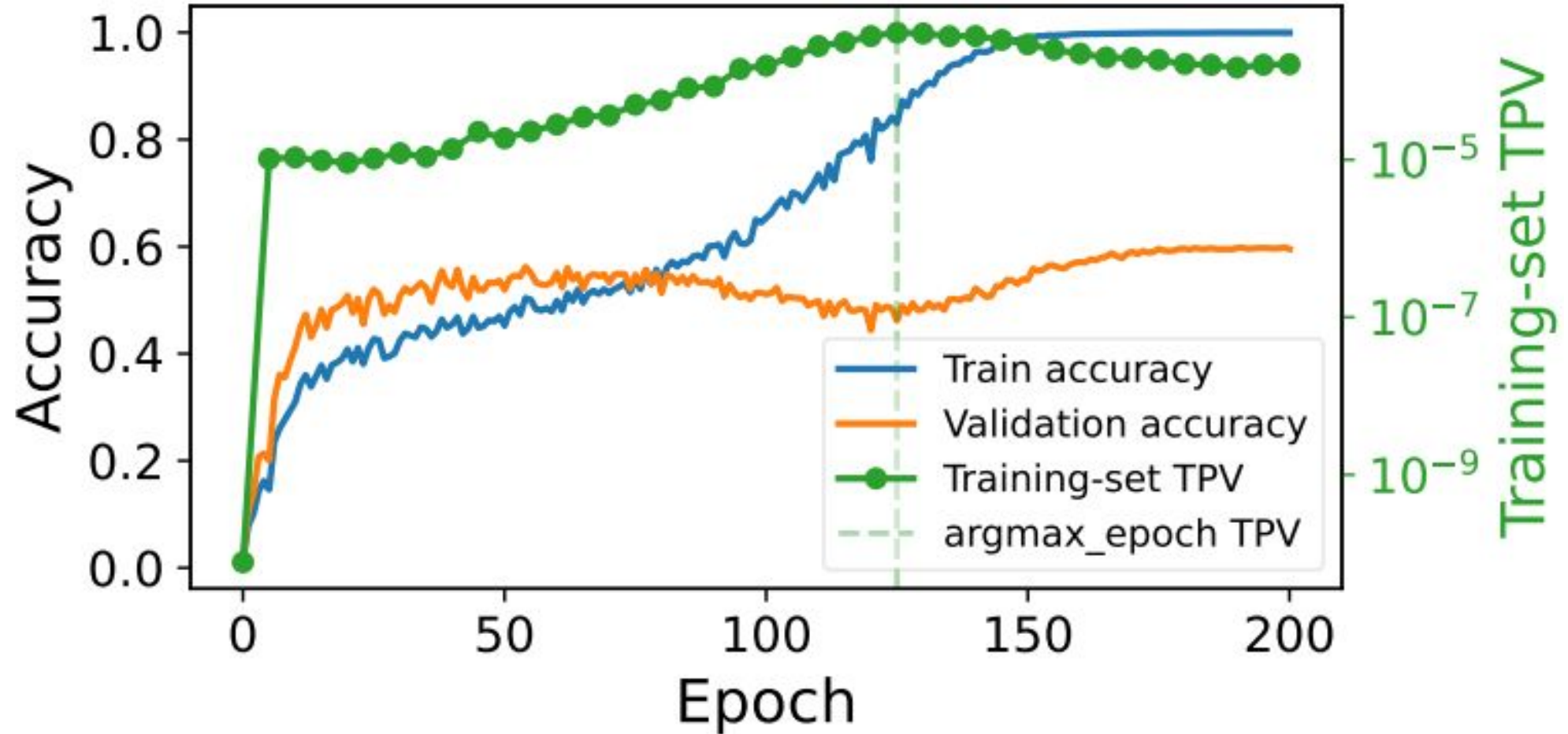
# TPV & Generalization

Across Models



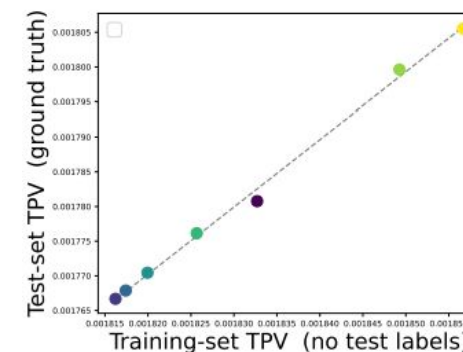
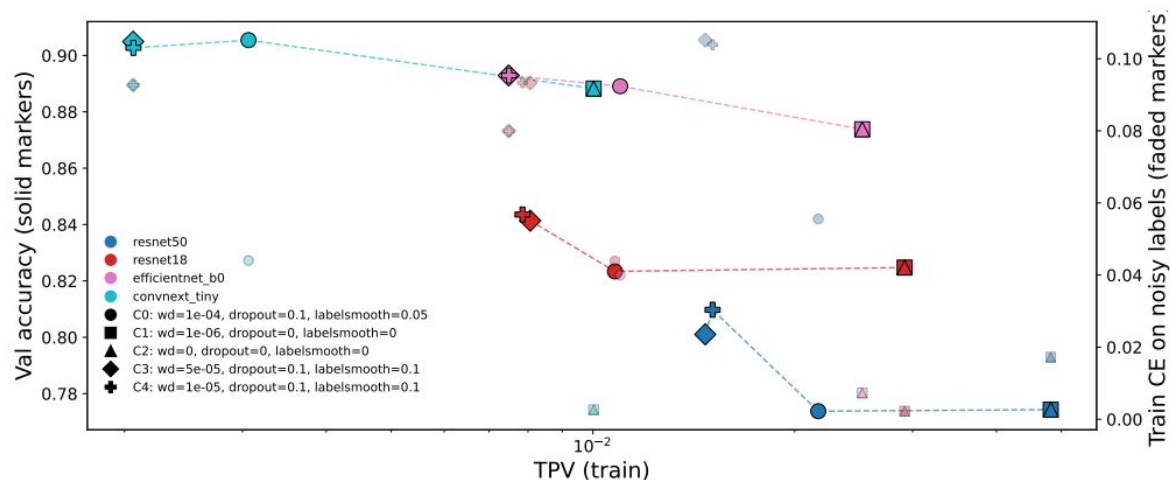
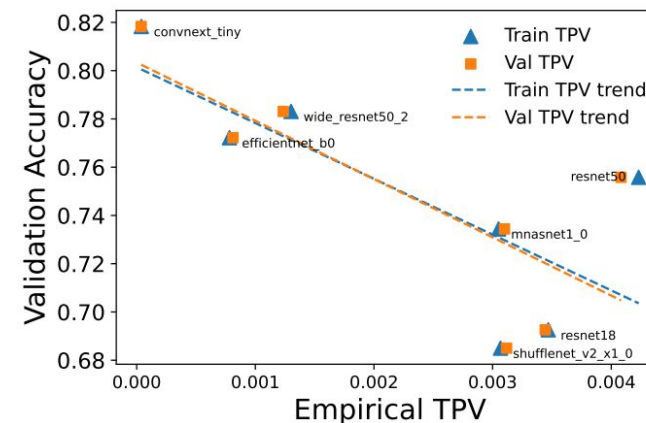
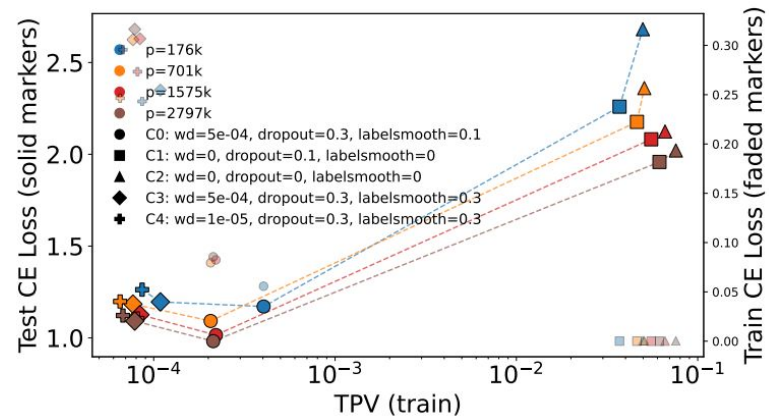
# TPV & Generalization

Across Epochs



# Applications of TPV

Model selection in in-distribution and transfer learning settings



# Summary

- TPV provides a unifying theoretical framework for studying the robustness of trained models
- TPV stability and correlation with test loss enable training-set based model selection