

# MEC: Machine-Learning-Assisted Generalized Entropy Calibration for Semi-Supervised Mean Estimation

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# Motivation: labels are costly, covariates are abundant

## Data structure

$$\{X_i\}_{i=1}^N \sim P_X, \quad \{(X_j, Y_j) : j \in S\} \sim P,$$
$$|S| = n, \quad f = \frac{n}{N}.$$

## Target

$$\theta_0 = \mathbb{E}(Y).$$

- Labels  $Y$  are expensive.
- Unlabeled covariates  $X$  are cheap.
- Goal: valid confidence intervals using both samples.

Inference, not just prediction.

# Prediction-powered inference: elegant but not always efficient

## PPI / CF-PPI form

$$\hat{\theta}_{\text{PPI}} = \frac{1}{N} \sum_{i=1}^N \hat{m}(X_i) + \frac{1}{n} \sum_{j \in S} \{Y_j - \hat{m}(X_j)\}.$$

### Problem 1: label reuse

If the same labels train  $\hat{m}$  and evaluate residuals, flexible ML can overfit.

### Problem 2: efficiency shortfall

Even with cross-fitting, misspecified predictions can inflate variance.

MEC keeps cross-fitting and adds calibration to resolve two problems.

Angelopoulos, A. N., Bates, S., Fannjiang, C., Jordan, M. I., & Zrnic, T. (2023). Prediction-powered inference. *Science*, 382(6671), 669–674.  
Zrnic, T., & Candès, E. J. (2024). Cross-prediction-powered inference. *Proceedings of the National Academy of Sciences*, 121(15).

## MEC idea: use ML predictions as calibration information

### Cross-fitted (out-of-fold) predictor basis

$$h(X) = \{1, \hat{m}^{(-)}(X)\}.$$

### Calibration constraints

$$\sum_{j \in S} \hat{\omega}_j = N, \quad \sum_{j \in S} \hat{\omega}_j \hat{m}^{(-)}(X_j) = \sum_{i=1}^N \hat{m}^{(-)}(X_i).$$

### MEC estimator

$$\hat{\theta}_{\text{MEC}} = \frac{1}{N} \sum_{j \in S} \hat{\omega}_j Y_j.$$

MEC balances the out-of-fold prediction between the labeled sample and the full covariate sample.

# Why MEC helps?

## Key idea

MEC replaces a condition on the *raw prediction error* with a condition on the *projection error* onto the calibration subspace.

## CF-PPI

Raw prediction error:

$$\|\widehat{m}^{(-)} - m_0\|_{L_2(P_X)} = o_p(1).$$

## MEC

Projection error:

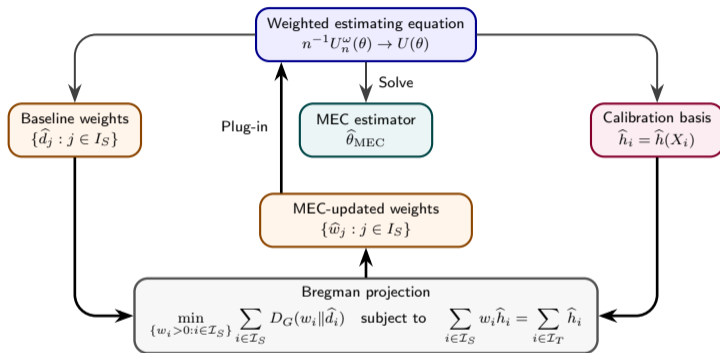
$$\mathcal{W} = \text{span}\{1, \widehat{m}^{(-)}\}, \quad m_{0,\perp} = m_0 - \Pi_{\mathcal{W}}m_0.$$

$$\|m_{0,\perp}\|_{L_2(P_X)} = o_p(1).$$

## Why this is good?

$$\|m_0 - \Pi_{\mathcal{W}}m_0\|_{L_2(P_X)} \leq \|\widehat{m}^{(-)} - m_0\|_{L_2(P_X)}.$$

Thus, MEC can remain efficient when  $m_0 \approx a + b\widehat{m}^{(-)}$ , even if  $\widehat{m}^{(-)}$  is not perfectly precise.



## Semi-supervised mean

$$U_{n,N}^\omega(\theta; m) = \sum_{i \in \mathcal{I}_T} m(X_i) - \theta + \sum_{j \in \mathcal{I}_S} \omega_j (Y_j - m(X_j)) = 0$$

## Average treatment effect

$$U_n^{\omega_1, \omega_0}(\theta) = \sum_{i \in \mathcal{I}_{S,1}} \omega_{1i} Y_i - \sum_{i \in \mathcal{I}_{S,0}} \omega_{0i} Y_i - |\mathcal{I}_T| \theta = 0$$

## ATT-marginal hazard

$$U_n^\omega(\theta) = \sum_{i \in \mathcal{I}_T \cup \mathcal{I}_S} \int \omega_i (A_i - \bar{A}_\omega(t; \theta)) dN_i(t) = 0$$

## Choice of calibration basis

The calibration basis  $h$  determines both the estimator and its robustness properties.

Default choice (this paper):

$$h(x) = \{1, \hat{m}^{(-)}(x)\}.$$

Richer choices are also possible:

$$h(x) = \{1, \hat{m}^{(-)}(x), \hat{m}^{(-)}(x)^2\},$$

or multiple ML predictors:

$$h(x) = \{1, \hat{m}_1^{(-)}(x), \hat{m}_2^{(-)}(x)\}.$$

This can improve robustness, but may increase weight instability.

## When efficiency gains are limited

Efficiency gains from MEC are not automatic for every target parameter.

MEC is most useful when the calibration basis captures outcome- or score-relevant variation in the estimating equation.

For semi-supervised mean estimation, this is natural because  $X$  helps predict  $Y$ .

If the estimating equation has little component predictable from  $X$ , then calibration has limited room to reduce variance.

## One-sentence summary

MEC is a cross-fitted calibration framework that uses machine-learning predictions to construct a calibration basis for updating weights, thereby enabling valid and efficient inference.

### Easy to implement

MEC does not require a problem-specific derivation of the efficient influence function for implementation.

### Efficient

Efficiency gains can arise when the ML-based calibration basis captures outcome- or score-relevant variation.

### Generalizable

Extends naturally to a broad class of weighted estimating equations, including missing-data problems, causal inference problems, and weighted Cox regression.

Thank you!