

Shaping Fine-Tuning of Geospatial Foundation Models: Effects of Label Availability and Temporal Resolution

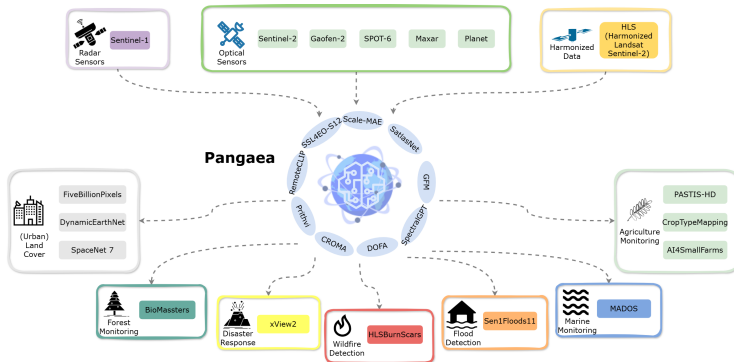
Giovanni Castiglioni, Nicolás Isla, Cristian B. Calderon, Javiera Castillo-Navarro, Sébastien Lefèvre, Valentin Barriere

ICML TerraBytes Workshop

Universidad de Chile, CENIA, Conservatoire National des Arts et Métiers, Université Bretagne Sud

Motivation

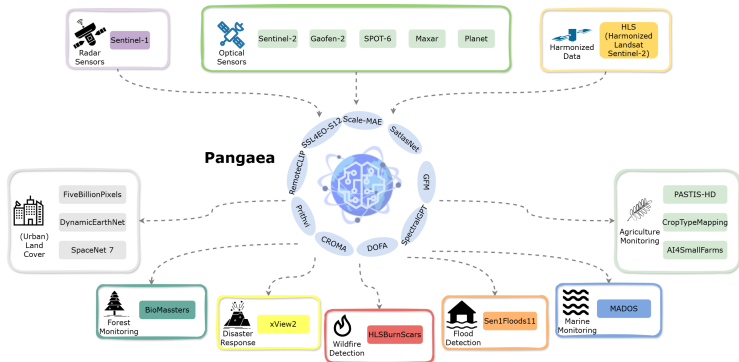
- Remote sensing is shifting from task-specific models to GFM.



Evaluation on Diverse Downstream Datasets and Applications

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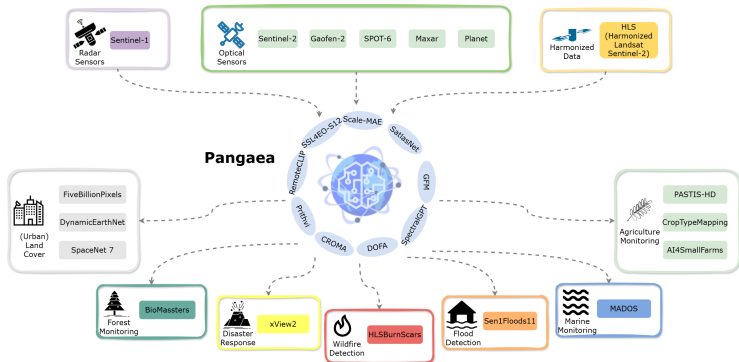
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Evaluation on Diverse Downstream Datasets and Applications

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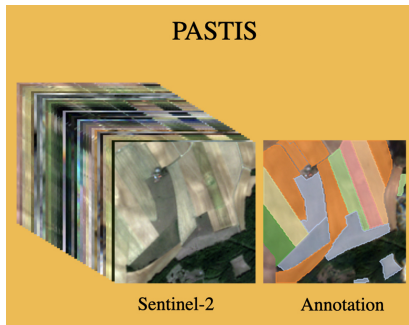
- Remote sensing is shifting from task-specific models to GFM.
- Scarcity of labeled data and temporal sequences is a challenge.
- **How should we fine-tune GFMs for a specific task?**



Evaluation on Diverse Downstream Datasets and Applications

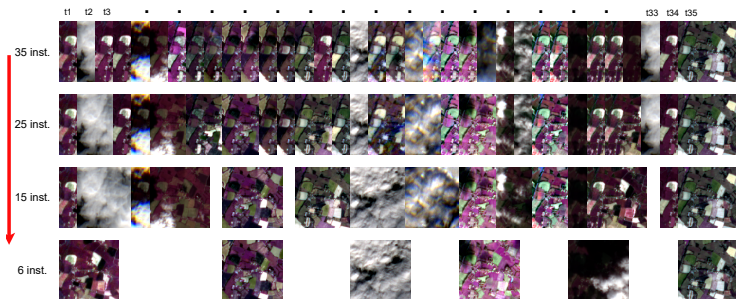
Dataset: PASTIS-HD

- **Crop-type mapping** of $\sim 2.4\text{k}$ SITS of 128×128 and $t \in [38, 63]$.
- We used **Sentinel-2 images**, excluding S1 and SPOT-6 sensors.



Dataset: PASTIS-HD

- **Crop-type mapping** of $\sim 2.4k$ SITS of 128×128 and $t \in [38, 63]$.
- We used **Sentinel-2 images**, excluding S1 and SPOT-6 sensors.
- We explored two expressions of data scarcity:
 - **Label availability:** 1, 10, 50, 100%.
 - **Temporal resolution:** 1, 6, 15, 25, 35 instances



Methodology: Encoder and Decoder Models

- Two GFMs were tested as **encoders**:

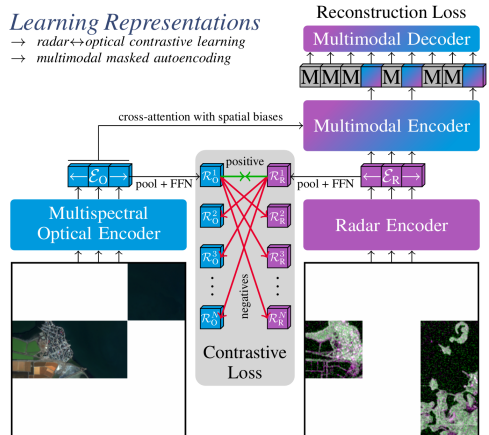
Methodology: Encoder and Decoder Models

- Two GFM's were tested as **encoders**:

- CROMA.

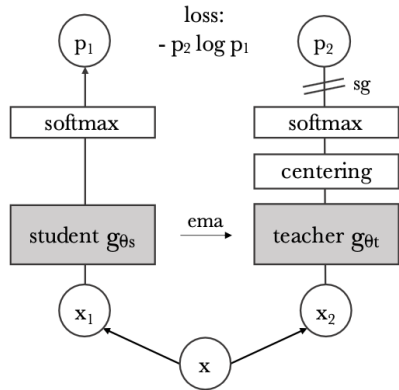
Learning Representations

- radar ↔ optical contrastive learning
- multimodal masked autoencoding



Methodology: Encoder and Decoder Models

- Two GFM's were tested as **encoders**:
 - CROMA.
 - SSL4EO-DINO.



Caron, M. et al. "Emerging Properties in Self-Supervised Vision Transformers." IEEE/CVF International Conference on Computer Vision (ICCV), 2018.

Wang, Y., et al. "SSL4EO-S12: A Large-Scale Multi-Modal, Multi-Temporal Dataset for Self-Supervised Learning in Earth Observation." IEEE Geoscience and Remote Sensing Magazine, Vol. 11, Issue 3, pp. 98 - 106, 2023.

Methodology: Encoder and Decoder Models

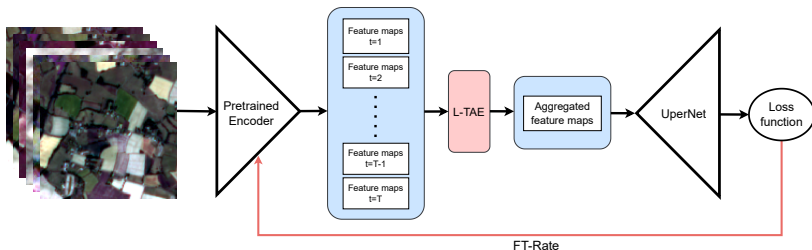
- Two GFM's were tested as **encoders**:

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Fine-Tuning Policy

$$\text{FT-Rate} = \frac{l_{r_{\text{encoder}}}}{l_{r_{\text{decoder}}}}$$

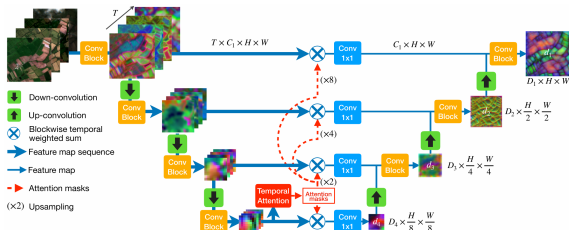
- An UperNet* was adopted for the **decoder**.



*Xiao, T., et al. "Unified Perceptual Parsing for Scene Understanding." European Conference on Computer Vision (ECCV), 2018.

Methodology: Encoder and Decoder Models

- Two GFM's were tested as **encoders**:
 - CROMA.
 - SSL4EO-DINO.
- An UperNet* was adopted for the **decoder**.
- We compare GFM's to a **baseline**: fully-supervised U-TAE.



Garnot, V.S.F., et al. "Panoptic Segmentation of Satellite Image Time Series with Convolutional Temporal Attention Networks." Proceedings of the IEEE International Conference on Computer Vision, pp. 4852–4861, 2021.

Results: Abundant labels

- U-TAE is always better than frozen encoders when $t > 1$.

Model	FT-Rate	100% of data					50% of data				
		1	6	15	25	35	1	6	15	25	35
CROMA	0.0	16.10	43.40	53.37	55.66	56.71	14.83	39.83	47.43	51.02	52.15
	0.1	19.52	49.65	58.11	60.41	61.12	17.44	45.54	53.08	56.95	57.50
	1.0	17.71	49.15	56.55	60.12	61.06	15.71	45.03	52.71	56.20	57.10
DINO	0.0	15.55	38.08	47.41	49.59	50.68	13.52	34.55	42.52	44.30	44.92
	0.1	16.43	42.50	51.17	54.03	55.19	14.36	37.34	46.98	48.65	50.24
	1.0	16.91	44.61	53.65	56.14	57.23	15.34	40.28	49.16	51.85	53.02
U-TAE	-	13.75	45.45	54.33	57.36	58.98	11.52	40.99	51.50	53.85	55.18

Results: Abundant labels

- U-TAE is always better than frozen encoders when $t > 1$.
- CROMA with partial fine-tuning reported the best results.

Model	FT-Rate	100% of data					50% of data				
		1	6	15	25	35	1	6	15	25	35
CROMA	0.0	16.10	43.40	53.37	55.66	56.71	14.83	39.83	47.43	51.02	52.15
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U-TAE	-	13.75	45.45	54.33	57.36	58.98	11.52	40.99	51.50	53.85	55.18

Results: Scarce labels

- CROMA with frozen encoder outperforms U-TAE.

Model	FT-Rate	10% of data					1% of data				
		1	6	15	25	35	1	6	15	25	35
CROMA	0.0	10.89	26.17	34.05	36.28	37.37	7.21	16.62	20.64	22.77	25.53
	0.1	13.09	30.07	37.89	39.43	40.67	7.30	18.63	22.81	23.26	24.06
	1.0	12.47	32.73	40.58	42.29	45.30	6.44	20.81	24.46	25.64	26.42
DINO	0.0	10.23	23.18	28.64	31.11	31.72	6.13	13.69	16.53	17.30	15.99
	0.1	11.00	25.06	32.83	35.79	36.09	6.52	14.56	17.69	19.12	18.71
	1.0	11.03	27.75	35.60	37.94	39.56	6.98	17.38	20.29	21.77	22.38
U-TAE	-	9.24	28.66	37.33	38.68	39.44	5.43	18.96	19.45	19.62	21.40

Results: Scarce labels

- CROMA with frozen encoder outperforms U-TAE.
- CROMA with full fine-tuning reported the best results.

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Results: Scarce labels

- CROMA with frozen encoder outperforms U-TAE.
- CROMA with full fine-tuning reported the best results.
- Full fine-tuned DINO outperforms U-TAE.

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Conclusions

- In high-label regimes: task-specific models can compete with, but are not better than, fine-tuned GFMs (**and are cheaper**).

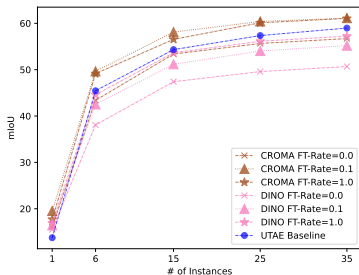
Model	# of Trainable Parameters (M)	
	Only Decoder	Whole network
CROMA	46.95	350.0
DINO	30.89	53.5
U-TAE	-	1.1

Conclusions

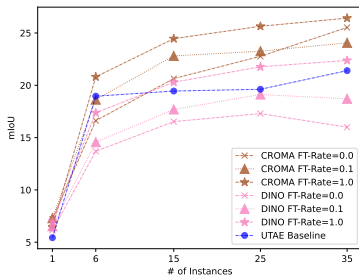
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- Careful fine-tuning is key to leverage GFMs:

Conclusions

- In high-label regimes: task-specific models can compete with, but are not better than, fine-tuned GFM (and are cheaper).
- Careful fine-tuning is key to leverage GFM:
 - Treat FT-Rate as a relevant hyperparameter.



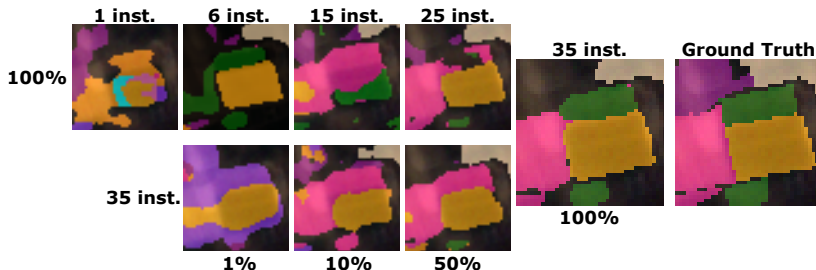
(a) 100% of data.



(b) 1% of data.

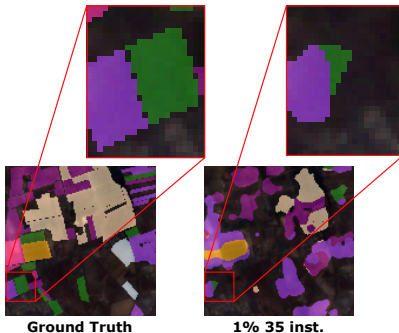
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- Careful fine-tuning is key to leverage GFMs:
 - Treat FT-Rate as a relevant hyperparameter.
 - Temporal resolution and label availability affect performance.



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- In high-label regimes: task-specific models can compete with, but are not better than, fine-tuned GFM (and are cheaper).
- Careful fine-tuning is key to leverage GFMs:
 - Treat FT-Rate as a relevant hyperparameter.
 - Temporal resolution and label availability affect performance.
- Performance improves with longer time-sequences in low-label settings, even for frozen GFMs.



Thank you for your attention!

Contact:

`giovanni.castiglioni@cenia.cl`