

Beyond Self-Repellent Kernels: History-Driven Target Towards Efficient Nonlinear MCMC on General Graphs

Jie Hu, Yi-Ting Ma, Do Young Eun

Department of Electrical and Computer Engineering
NC State University

ICML 2025
Vancouver, Canada

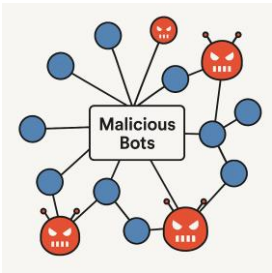
MCMC on General Graphs






Markov Chain Monte Carlo (MCMC) on General Graphs

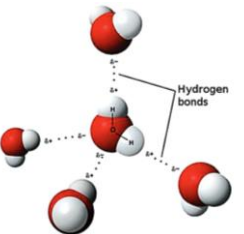
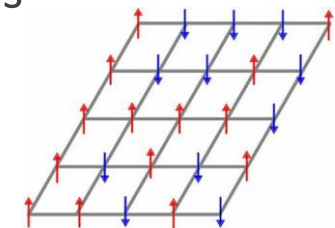
- A fundamental tool for understanding graphs, including discrete spaces:
 - E.g., social networks, IoTs, smart grids, biochemical molecules, Ising/Potts models, etc.
- Draw samples from a **Known** Distribution (up to a multiplicative constant) $\mu(x) \propto \exp(-H(x)/T)$
- Estimates $E_{\mu}\{f(X)\} = \sum_{x \in \mathcal{X}} f(x)\mu(x)$ when analyzing entire finite state space is **infeasible**

Applications:

- ✓ Detect malicious bots & malware spread
- ✓ Identify key influencers or customer groups
- ✓ Infer user's preference



- ✓ Recommendation Systems  YouTube  NETFLIX
- ✓ Web Crawling / Search Index   
- ✓ Monte Carlo Molecular Modeling
- ✓ Ising and Potts Models
- ✓ Energy-based Models



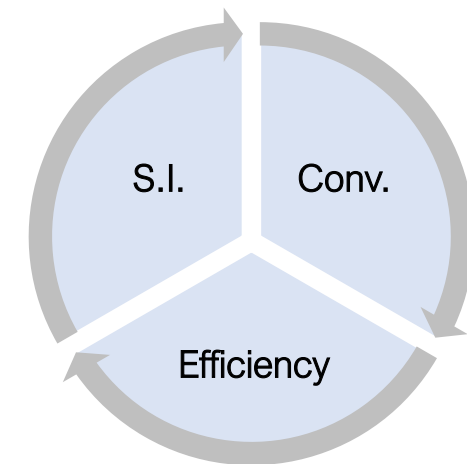
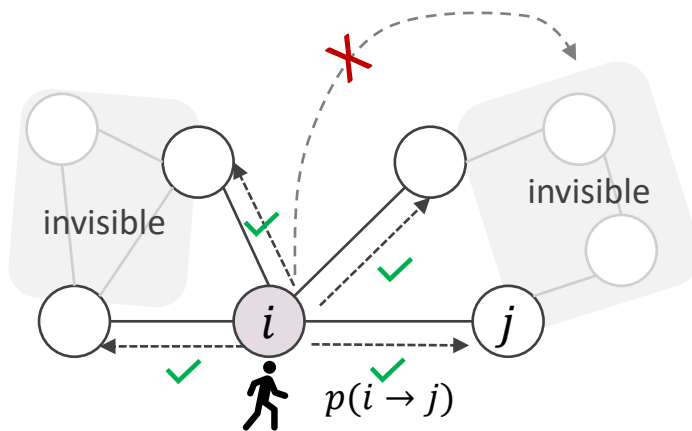
Algorithmic Design of MCMC

Key Design Criteria for Efficient Graph Samplers:

$$\mu(x) = \exp(-H(x)/T)/Z, \text{ where } Z = \int_x \exp(-H(x)/T)$$

1. Scale Invariant (S.I.): Operate w/o global information Z of the graph
2. Robust Theoretical Convergence (conv.): Guarantee convergence to the target distribution
3. Efficiency: Requires *fewer samples* to achieve a similar level of approximation accuracy

Determine transition probability $p(i \rightarrow j)$ from node i to node j




Improving MCMC – Self Interactions

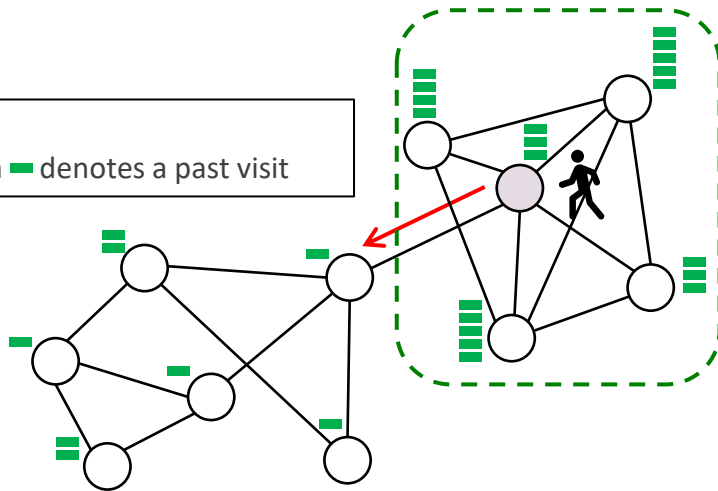
Our recent breakthrough: **Self-Repellent Random Walk (SRRW)**

- **Concept:** Use the random walker's *history* to influence future transitions
 - Given a time-reversible Markov chain P with target probability distribution μ
 - Based on visit frequency vector \mathbf{x} , modify probability from node $i \rightarrow j$: $\boxed{K[\mathbf{x}]_{ij}} \propto P_{ij} \left(\frac{x_j}{\mu_j} \right)^{-\alpha}$
 - ‘Non-Markov’ or ‘history-aware’ walker

nonlinear kernel



Key:
Each  denotes a past visit



- Tackle a challenging open problem, MCMC with *self-repellent scheme for the first time*
- Beyond traditional *non-backtracking* approaches which avoid the immediate previous sample

Vishwaraj Doshi, Jie Hu, and Do Young Eun, “Self Repelling Random Walks on General Graphs – Achieving Minimal Sampling Variance via Non-linear Markov Chains”, ICML, 2023

Improving MCMC – Self Interactions

Benefits:

- ✓ Generated samples still converges to the correct target μ
- ✓ Exhibits S.I. property: $K[\mathbf{x}]_{ij} \propto P_{ij} \left(\frac{x_j}{\mu_j} \right)^{-\alpha}$ proved to be the only form to adjust the kernel P w/o knowing Z
- ✓ Achieves *much better performance*

$$\sqrt{n}(\mathbf{x}_n - \mu) \xrightarrow[n \rightarrow \infty]{\text{dist.}} N(\mathbf{0}, V_{\mathbf{x}}(\alpha))$$

and the *near-zero* sampling variance $V_{\mathbf{x}}(\alpha) = O(1/\alpha)$

More efficient than i.i.d sampler under topological constraints!

Vishwaraj Doshi, Jie Hu, and Do Young Eun, “Self Repelling Random Walks on General Graphs – Achieving Minimal Sampling Variance via Non-linear Markov Chains”, ICML, 2023

The Catch: Issues Overlooked in SRRW

1. Computational issues: SRRW requires pre-computation of P_{ij} for all j

Standard Metropolis-Hastings

Lightweight & On-Demand

Step 1: Propose one neighbor j w.p. Q_{ij}

Step 2: Calculate acceptance rate

$$A(i, j) = \min \left\{ 1, \frac{\mu_j Q_{ji}}{\mu_i Q_{ij}} \right\}$$

Step 3: Flip a coin to decide the movement

Cost of acquiring
a neighbor's
information: $O(1)$

Key Idea: The probability of staying at i ($P_{ii} = 1 - \sum_j P_{ij}$) is an *implicit outcome* of rejection. It is never pre-computed.

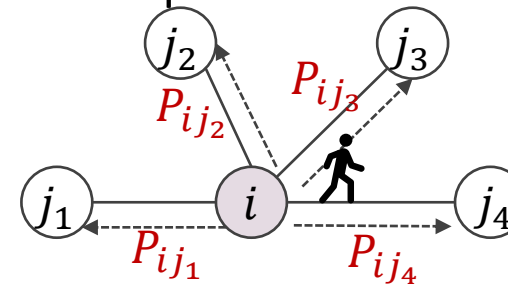
Self-Repellent Random Walk

Heavy & Pre-Computed Transition Probability

Step 1: Compute prob. to each neighbor P_{ij}

(including self-transition P_{ii})

Step 2: Sample from the full distribution and move



$$P_{ii} = 1 - \sum_{k=1}^4 P_{ij_k}$$

Cost: $O(\deg_i)$

Problem: Need P_{ij} for all j **pre-computed**, destroying the lightweight nature of MH.

The cost for one sample scales with the node's degree, making it extremely slow in dense graphs.

The Catch: Issues Overlooked in SRRW

2. **Reversibility**: Requires P to be reversible w.r.t. the given target μ (i.e., $\mu_i P_{ij} = \mu_j P_{ji}$)

- A requirement to ensure a well-defined stationary distribution $\pi[\mathbf{x}]$ for the SRRW kernel $K[\mathbf{x}]$
- E.g., $\pi_i[\mathbf{x}] K_{ij}[\mathbf{x}] = \pi_j[\mathbf{x}] K_{ji}[\mathbf{x}]$, $\forall i, j \in \mathcal{V}, \mathbf{x} \in \text{Int}(\Sigma)$
- Exclude a whole class of efficient, advanced **non-reversible** MCMC samplers

3. **Memory Constraints**: Dimension of \mathbf{x}_n = the size (#) of state space

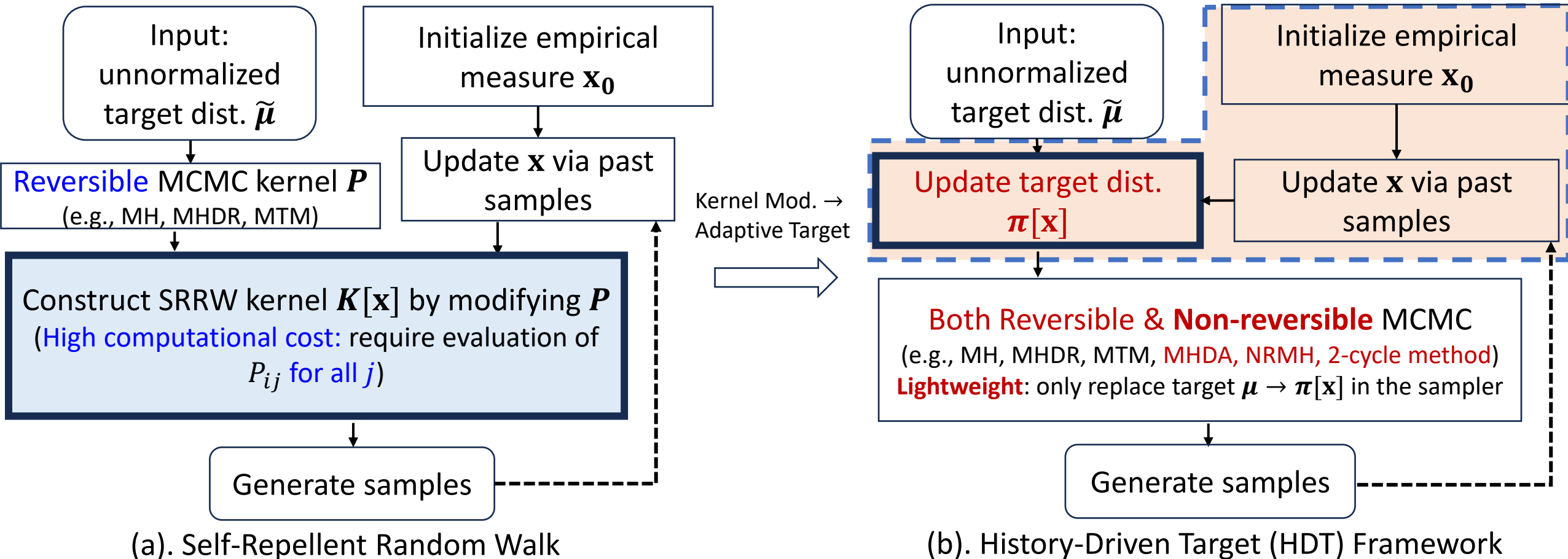
History-Driven Target (HDT) MCMC:

Tackle first two issues of SRRW --- computational costs & time-reversibility

- Only takes **$O(1)$** computational cost per sample
- Compatible with **non-reversible MCMC samplers**
- A heuristic remedy for memory issue --- **Least Recently Used (LRU)** cache scheme

Improvement over SRRW: A Simple Paradigm Shift

Instead of altering the walker's kernel, we *modify the target distribution* (based on history)



The History-Driven Target (HDT) Framework

- Our History-Driven Target (HDT) is simple but powerful

- The HDT Formula:

$$\pi_i[\mathbf{x}] \propto \underbrace{\mu_i}_{\text{original target}} \left(\frac{x_i}{\mu_i} \right)^{-\alpha}$$

↘
repellence penalty

- Why HDT is a Game-Changer:

- **Universal (Bring your own MCMC):** Works as a "wrapper" for any MCMC method, including the **fast non-reversible** ones that SRRW cannot use.
- **Lightweight:** Integrates into any sampler by simply replacing the target μ with $\pi[\mathbf{x}]$, preserving the original $O(1)$ cost.

For example, in MHRW, the acceptance rate

$$A_{ij}[\mathbf{x}] = \min \left\{ 1, \frac{\pi_j[\mathbf{x}] Q_{ji}}{\pi_i[\mathbf{x}] Q_{ij}} \right\}$$

only unnormalized value is needed for calculation

Key Theoretical Guarantees

Three key theoretical findings (c.f. Theorem 3.3, Corollary 3.4, Lemma 3.6)

1. Unbiased Sampling: Proven to converge to the correct target distribution

- $\mathbf{x}_n \xrightarrow[n \rightarrow \infty]{a.s.} \boldsymbol{\mu}$, i.e., empirical measure converges to the target distribution almost surely

2. Near-Zero Variance: Same $O(1/\alpha)$ variance reduction as SRRW in the CLT

- $\sqrt{n}(\mathbf{x}_n - \boldsymbol{\mu}) \xrightarrow[n \rightarrow \infty]{dist.} N(\mathbf{0}, \mathbf{V}_{\mathbf{x}}(\alpha))$, where sampling variance $\mathbf{V}_{\mathbf{x}}(\alpha) = \frac{1}{2\alpha+1} \mathbf{V}^{base}$

3. Superior Cost-Efficiency: Provably more efficient than SRRW under same budget

- $\sqrt{B}(\mathbf{x}_B - \boldsymbol{\mu}) \xrightarrow[B \rightarrow \infty]{a.s.} N(\mathbf{0}, \mathbf{V}_{cost}(\alpha))$, and cost-based sampling variance $\mathbf{V}_{cost}^{HDT}(\alpha) \leq_L \frac{2}{\text{avg deg}+1} \cdot \mathbf{V}_{cost}^{SRRW}(\alpha)$

Budget of computation B

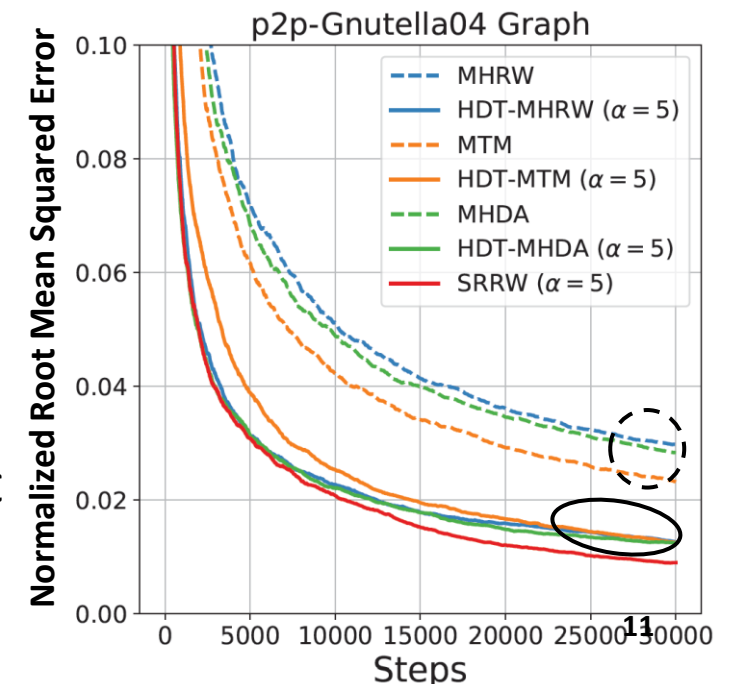
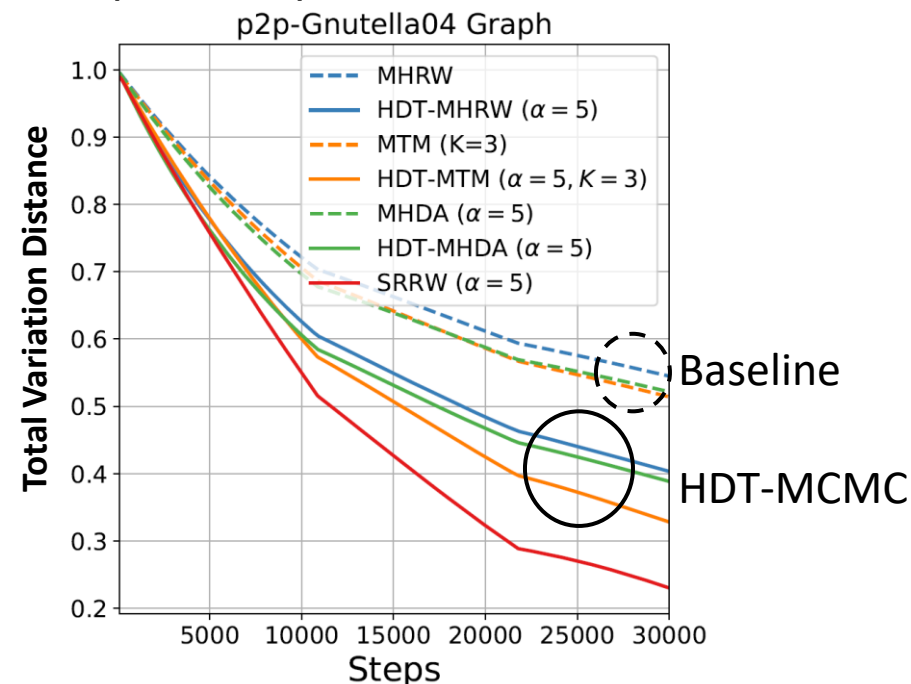
Loewner ordering

Result 1: HDT Universally Boosts Sampler Performance

HDT-MCMC delivers the best of both worlds for MCMC tasks:

- Draw samples from uniform target on multiple real-world graphs
- Test over multiple baseline MCMC samplers, including
 - Metropolis-Hastings Random Walk (MHRW), Multiple-Try Metropolis (MTM), MH with delayed acceptance (MHDA) *non-reversible*

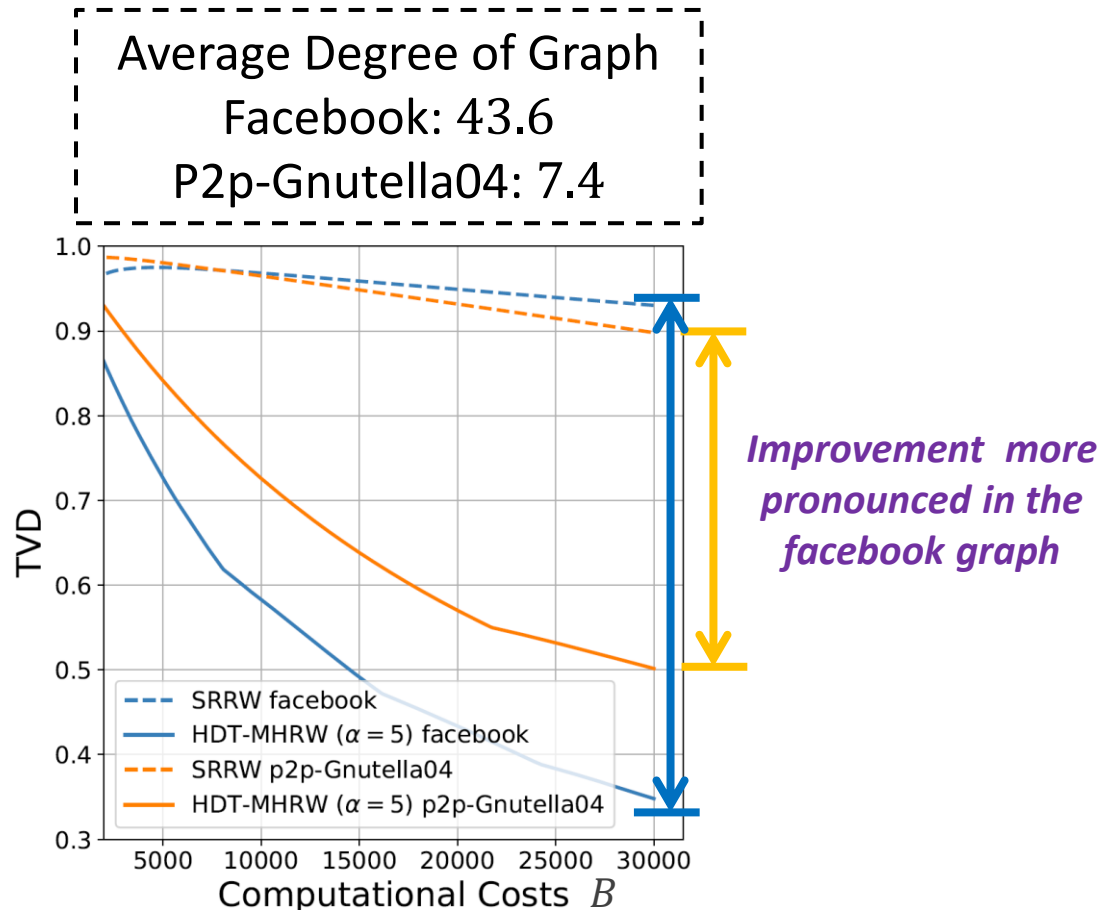
Improvement over *any*
MCMC sampler
Solid lines (HDT version)
v.s. dash lines (baseline)



Result 2: HDT is More Cost-Efficient than SRRW

Compare HDT-MHRW and SRRW under a fixed computational budget B

➤ Lightweight design, HDT-MCMC more cost efficient than SRRW



Computational cost per sample at node i :

- HDT-MCMC: 1
- SRRW: \deg_i (degree of node i) due to the pre-computation of all P_{ij} of neighbor j

Denser the graph

⇒ **larger** the average neighborhood size

⇒ **smaller** covariance

Heuristic Memory Reduction Scheme

Least Recently Used (LRU) cache scheme

- **Essential idea:** track only recently visited states, discarding the least-recently used when capacity in cache \mathcal{C} is reached, whose size $|\mathcal{C}| = r|\mathcal{V}|$ (r acts as *the compression ratio*)
- Leverages temporal locality: non-neighboring states do not affect self-repellency
- For a neighbor $j \notin \mathcal{C}$ of current state i , extrapolate its frequency \hat{x}_j via

$$\frac{\hat{x}_j}{\mu_j} = \underbrace{\sum_{k \in (\mathcal{N}(i) \cup \{i\}) \cap \mathcal{C}} \frac{1}{|(\mathcal{N}(i) \cup \{i\}) \cap \mathcal{C}|}}_{\text{Average level of 'deviation' from neighbors that are in the cache } \mathcal{C}} \cdot \frac{x_k}{\mu_k}$$

Assume the level of 'deviation' of node j is similar to its neighbors in the cache \mathcal{C}

'Deviation' of past visit of node k in the cache \mathcal{C} compared to its target value

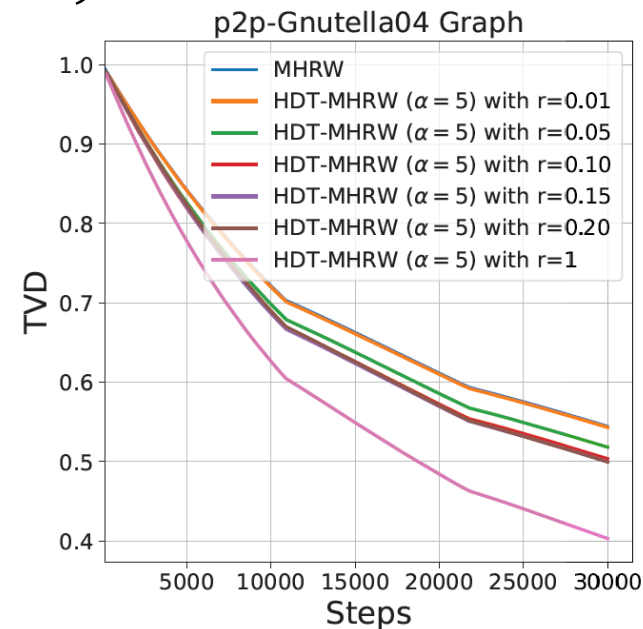
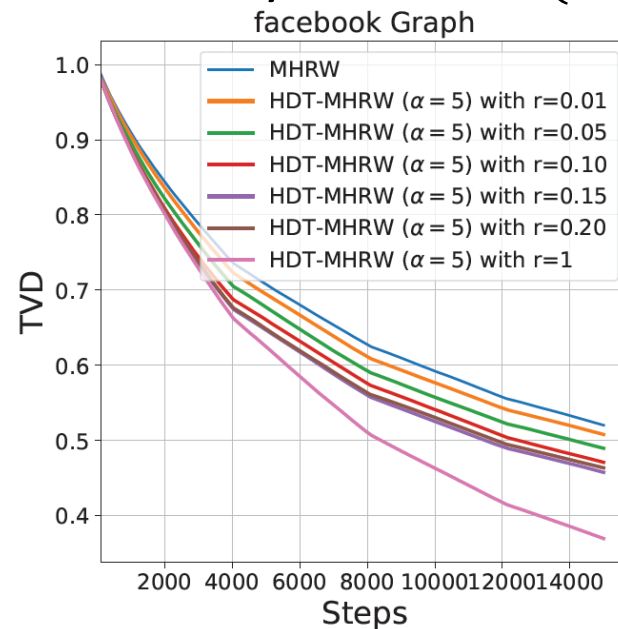
Result 3: HDT is Scalable and Memory-Efficient

Least Recently Used (LRU) cache scheme

- For a neighbor $j \notin \mathcal{C}$ of current state i , extrapolate its frequency via

$$\hat{x}_j = \mu_j \sum_{k \in (\mathcal{N}(i) \cup \{i\}) \cap \mathcal{C}} \frac{1}{|\mathcal{N}(i) \cup \{i\} \cap \mathcal{C}|} \cdot \frac{x_k}{\mu_k}$$

- HDT-MHRW w/ LRU robust to the choice of r (compression ratio) leads to **10%** smaller TVD than MHRW with over **90%** memory reduction ($r = 0.1$)



Conclusion

Our previous work SRRW – first to utilize history with theoretical analysis to show near-zero sampling variance

HDT makes history-aware MCMC a practical, powerful, and universal tool:

- ✓ **Paradigm shift** from kernel mod to target mod: Retain *near-zero* variance benefits
- ✓ **Universal and lightweight "wrapper"**: accelerate any MCMC sampler on discrete spaces
- ✓ Provably more **cost-efficient** than the previous state-of-the-art
- ✓ **Scalable to large graphs** via a memory-saving LRU cache scheme

Thank you!

Q&A

Feel free to chat with us at [East Exhibition Hall A-B #E-1304 \(11 am – 1:30 pm\)](#)

Paper link [arXiv preprint] 



Backup Slides

SRRW vs. HDT-MCMC: A Comparison

ICML 2023 Outstanding Paper Award

This work

Feature	SRRW (Self-Repellent Random Walk)	HDT-MCMC (History-Driven Target MCMC)
Core Idea	Tweaks the <u>kernel</u> $K[\mathbf{x}]_{ij} \propto P_{ij} \left(\frac{x_j}{\mu_j} \right)^{-\alpha}$	Tweaks the <u>target</u> $\pi_i[\mathbf{x}] \propto \mu_i \left(\frac{x_i}{\mu_i} \right)^{-\alpha}$
Baseline Chain	Must be time-reversible	Works with advanced non-reversible (faster) chains AND reversible ones Cor. 3.4
Computational Cost	Higher (needs to evaluate P_{ij} for all neighbors)	Lower (simpler to implement with existing samplers)
Ergodicity	✓	✓
Asymptotic Covariance	$V^{SRRW}(\alpha) \sim O(1/\alpha)$	$V^{HDT}(\alpha) \sim O(1/\alpha)$ Thm. 3.3
Key Advantage	Groundbreaking performance	Often better practical speed due to lower cost & adoption of non-reversible chains [†]

† Covariance of HDT-MCMC $\approx \frac{1}{\text{avg degree}}$ of SRRW under same budget of computation (cf. Lemma 3.6)

HDT-MCMC: Deterministic analysis

- The closed form of $\boldsymbol{\pi}(\mathbf{x}) = [\pi_i(\mathbf{x})]$, $\forall i \in \mathcal{V}$, is given by

$$\pi_i(\mathbf{x}) = \frac{\mu_i \left(\frac{x_i}{\mu_i} \right)^{-\alpha}}{\sum_k \mu_k \left(\frac{x_k}{\mu_k} \right)^{-\alpha}} = \omega(\mathbf{x})$$

Theorem (Global stability of ODE) For all $\alpha \geq 0$, $\mathbf{x}(0) \in \text{Int}(\Sigma)$, we have

$$\mathbf{x}(t) \rightarrow \boldsymbol{\mu} \text{ as } t \rightarrow \infty,$$

where $\boldsymbol{\mu} = [\mu_i] \in \text{Int}(\Sigma)$ is the target stationary distribution, and $\mathbf{x}(t)$ is the solution (trajectory) of the mean-field ODE $\dot{\mathbf{x}}(t) = \boldsymbol{\pi}(\mathbf{x}(t)) - \mathbf{x}(t)$.

- The proof steps are similar to the ODE analysis of SRRW.

HDT-MCMC: Stochastic Analysis

Theorem 1 (Strong Law of Large Number (SLLN) and Central Limit Theorem (CLT)) For all $\alpha \geq 0$, any $\mathbf{x}_0 \in \text{Int}(\Sigma)$, and any $X_0 \in [N]$, we have

$$\begin{aligned} \mathbf{x}_n &\rightarrow \boldsymbol{\mu} \text{ as } n \rightarrow \infty, & \text{almost surely} \\ \sqrt{n}(\mathbf{x}_n - \boldsymbol{\mu}) &\rightarrow N(\mathbf{0}, \mathbf{V}_x(\alpha)) \text{ as } n \rightarrow \infty, & \text{in dist.} \end{aligned}$$

where $N(\mathbf{0}, \mathbf{V}(\alpha))$ is a normal distribution with mean $\mathbf{0}$ and covariance $\mathbf{V}_x(\alpha)$, given by

$$\mathbf{V}_x(\alpha) = \frac{1}{2\alpha + 1} \mathbf{V}^{base} = O(1/\alpha)$$

Corollary 2 (Preserved Efficiency Ordering)

Suppose two MCMC samplers S_1 and S_2 converge to $\boldsymbol{\mu}$ with limiting covariances \mathbf{V}^{S_1} and \mathbf{V}^{S_2} satisfying

$$\mathbf{V}^{S_1} <_L \mathbf{V}^{S_2},$$

Meaning that sampler S_1 is more efficient than sampler S_2 . Applying HDT framework to both, yielding $\mathbf{V}^{S_1-HDT}(\alpha)$ and $\mathbf{V}^{S_2-HDT}(\alpha)$, preserves the ordering:

$$\mathbf{V}^{S_1-HDT}(\alpha) <_L \mathbf{V}^{S_2-HDT}(\alpha), \forall \alpha \geq 0.$$

Any known covariance orderings between reversible and non-reversible samplers carry over to HDT-MCMC, whereas SRRW cannot accommodate non-reversible Markov chains.

HDT-MCMC: Cost-Related Analysis

Let a_i (resp. b_i) $\in (0, \infty)$ be the *computational cost* of the i -th sample in HDT-MCMC (resp. SRRW). Define:

$$T^{HDT}(B) := \max\{k \mid a_1 + a_2 + \cdots + a_k \leq B\}$$
$$T^{SRRW}(B) := \max\{k' \mid b_1 + b_2 + \cdots + b_{k'} \leq B\}$$

the number of samples that HDT-MCMC (resp. SRRW) can generate *before hitting the total budget B* .

Average computational cost of HDT, SRRW

Theorem 7 (Cost-Based CLT)

Suppose that as $B \rightarrow \infty$,

$$B/T^{HDT}(B) \rightarrow C^{HDT}, \quad B/T^{SRRW}(B) \rightarrow C^{SRRW} \text{ a.s.}$$

Then, we have

$$\sqrt{B} \left(\mathbf{x}_{T^{HDT}(B)} - \boldsymbol{\mu} \right) \rightarrow N\left(\mathbf{0}, C^{HDT} \mathbf{V}_x^{HDT}(\alpha)\right) \quad \text{as } n \rightarrow \infty, \quad \text{in dist.}$$

$$\sqrt{B} \left(\mathbf{x}_{T^{SRRW}(B)} - \boldsymbol{\mu} \right) \rightarrow N\left(\mathbf{0}, C^{SRRW} \mathbf{V}_x^{SRRW}(\alpha)\right) \quad \text{as } n \rightarrow \infty, \quad \text{in dist.}$$

HDT-MCMC: Cost-Related Analysis

Theorem 3 (Cost-based CLT)

Suppose that as $B \rightarrow \infty$,

$$B/T^{HDT}(B) \rightarrow C^{HDT}, \quad B/T^{SRRW}(B) \rightarrow C^{SRRW} \quad a.s.$$

Then, we have

$$\sqrt{B} \left(\mathbf{x}_{T^{HDT}(B)} - \boldsymbol{\mu} \right) \rightarrow N(\mathbf{0}, C^{HDT} \mathbf{V}_{\mathbf{x}}^{HDT}(\alpha)) \quad \text{as } n \rightarrow \infty, \quad \text{in dist.}$$

$$\sqrt{B} \left(\mathbf{x}_{T^{SRRW}(B)} - \boldsymbol{\mu} \right) \rightarrow N(\mathbf{0}, C^{SRRW} \mathbf{V}_{\mathbf{x}}^{SRRW}(\alpha)) \quad \text{as } n \rightarrow \infty, \quad \text{in dist.}$$

Lemma 8 (Ordering of cost-based covariances between HDT-MCMC and SRRW)

$$C^{HDT} \mathbf{V}_{\mathbf{x}}^{HDT}(\alpha) <_L \frac{2}{E_{i \sim \mu}[\mathcal{N}(i)] + 1} C^{SRRW} \mathbf{V}_{\mathbf{x}}^{SRRW}(\alpha)$$

- Cost-based covariance of HDT-MCMC **at least a factor of $\frac{2}{E_{i \sim \mu}[\mathcal{N}(i)] + 1}$ times smaller** than that of SRRW for every given α , suggesting a universal advantage.
- **Denser** the graph, **larger** the average neighborhood size $E_{i \sim \mu}[\mathcal{N}(i)]$, **smaller** covariance