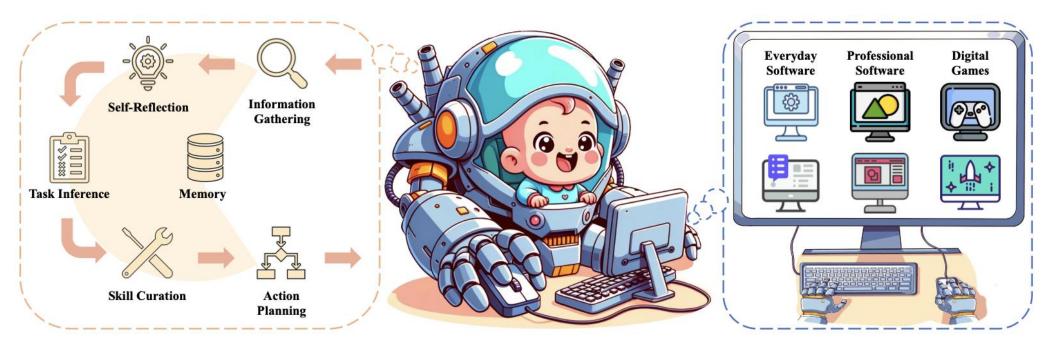
CRADLE: Empowering Foundation Agents Towards General Computer Control



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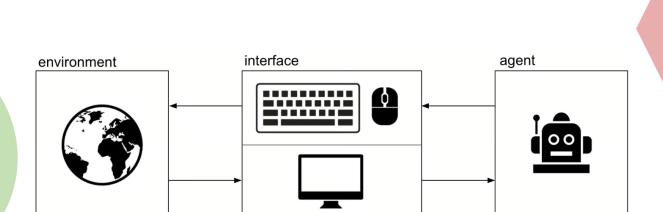
General Computer Control (GCC)



NO built-in APIs needed

Generalization to (unseen) tasks

Data collection with the same granularity for **self-improvement** Building foundation agents that can master **ANY** computer task via the universal human-style interface by receiving input from **screens** and **audio** and outputting **keyboard** and **mouse** actions.





Good Alignment across multimodal inputs

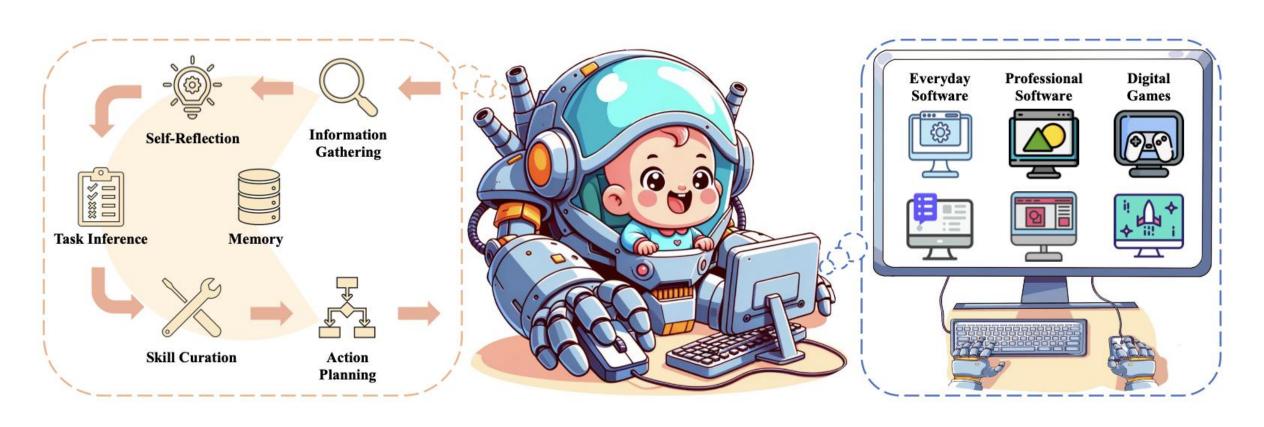
Long-term memorizing & reasoning

Precisecontrol of
keyboard
& mouse

Efficient exploration and self-improving

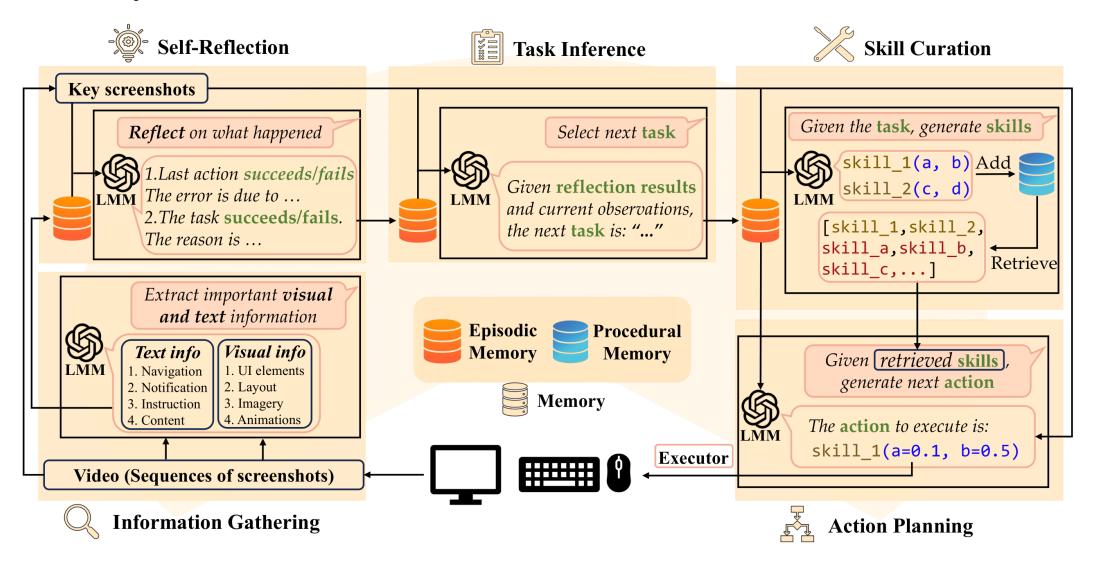
Cradle Framework

➤ Cradle: A Novel Agent Framework under GCC Setting



Cradle Framework

➤Six key modules



Complete Workflow











Information Gathering

Self-Reflection

Task Inference

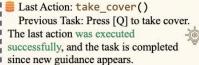




to show the Weapon Whe



Hold [TAB] to show Guidance: the Weapon Wheel.



Hold [TAB] to show the Weapon Wheel.

Generated Skill:

def show weapon wheel(): io_env.key_hold('tab')

Retrieved Skills:

['aim', 'follow', 'turn', 'move_for ward', 'show weapon wheel'...]

show weapon wheel()





1. Axe 2. Hoe (Selected) ... 6. Parsnip Seeds (15) ...

Last Action: use tool() # Till the soil using the hoe.

Previous Task: use the hoe to till the soil. The last action was executed successfully. The hoe is actively being used aiming toward the soil and the soil becomes darker. Therefore, the task is completed.

The new task is to plant the parsnip seeds in the tilled soil.

Retrieved Skills:

['move up', 'move down', 'move left', 'mo ve_right','select_tool','do_action'...

Selects parsnip seeds from the toolbar. T select tool(key='6') # Plants parsnip seeds on the tilled soil. do action()





Error Message: Cannot be built on water

Last Action:

place_water_pumping_station(x=100, y=700) Previous Task: place a water pumping station near the river.

The last action was not executed successfully. As the water pumping station cannot be built on the water as shown in the error message. Therefore, the task is not completed.

The current task is to continue the previous task.

Retrieved Skills:

['place_water_pumping_station','place_ ater drain pipe', 'place water pipe'

place_water_pumping_station (x=400, y=600)







Cradle in Software Applications

Chrome

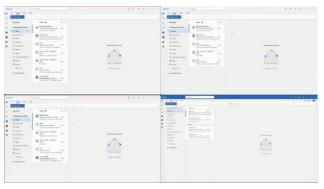


Meitu Xiuxiu



CapCut Chrome Outlook Feishu Meitu 20 Jarget E-mail Create Media Project Oben Closed bage " Change Mode Emply Junk Folder and Add Transition Ctop by Timestamp Create Appointment Send New E-mail Reply to Person Find Target E-mail Ctop by Content Wessage Contact Start Video Conference Go to Profile Add Sticker on Cheste Collage -Cutout

Outlook



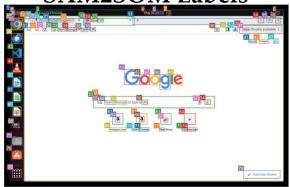
Feishu



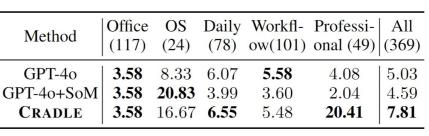
CapCut



SAM2SOM Labels

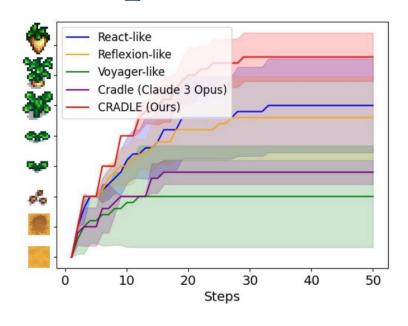


Cradle in OSWorld



Ablation Studies & Baselines Comparison

Method	Follow Dutch	Follow Micah	Hitch Horse	Protect Dutch	Search for Supplies	Cultivation
React [72]-like (GPT-40)	$15 \pm 2 (5/5)$	$74 \pm 0 (1/5)$	N/A	N/A	N/A	N/A
Reflextion [53]-like (GPT-40)	$19 \pm 4 (5/5)$	$58 \pm 14 (2/5)$	N/A	N/A	N/A	N/A
Voyager [57]-like (GPT-40)	$32 \pm 12 (3/5)$	N/A	N/A	N/A	N/A	N/A
CRADLE (Claude 3 Opus)	$30 \pm 7 (5/5)$	$52 \pm 17 (4/5)$	N/A	N/A	N/A	N/A
CRADLE (GPT-40) (Ours)	13 ± 3 (5/5)	33 ± 3 (5/5)	26 ± 5 (4/5)	461 ± 0 (1/5)	134 ± 0 (1/5)	24 ± 4 (4/5)



Subtask	w/o Information Gathering	w/o Self- Reflection	w/o Task Inference	w/o Episodic Memory	CRADLE
Follow Micah	0%	0%	40%	80%	100%
Hitch Horse	0%	$\boldsymbol{100\%}$	$\boldsymbol{100\%}$	$\boldsymbol{100\%}$	$\boldsymbol{100\%}$
Go to Shed	0%	20%	40%	20%	80%
Peek out of Cover	60%	$\boldsymbol{100\%}$	80%	$\boldsymbol{100\%}$	100%
Switch Weapon	0%	80%	60%	80%	100%
Combat	0%	0%	0%	0%	20%

Looking Ahead

➤ Modular growth

- □ As base model's capabilities improves, Cradle improves accordingly!
- □Some or even all of modules can be combined into a single request.

>Self-improvement

- □Greatly extends the reach of AI agents. Every software is potential out-of-box testbed and benchmark.
- □Cradle collects both high-level semantic actions and low-level keyboard and mouse control for self-improvement.

