

# Algorithmic Recourse for Long-Term Improvement

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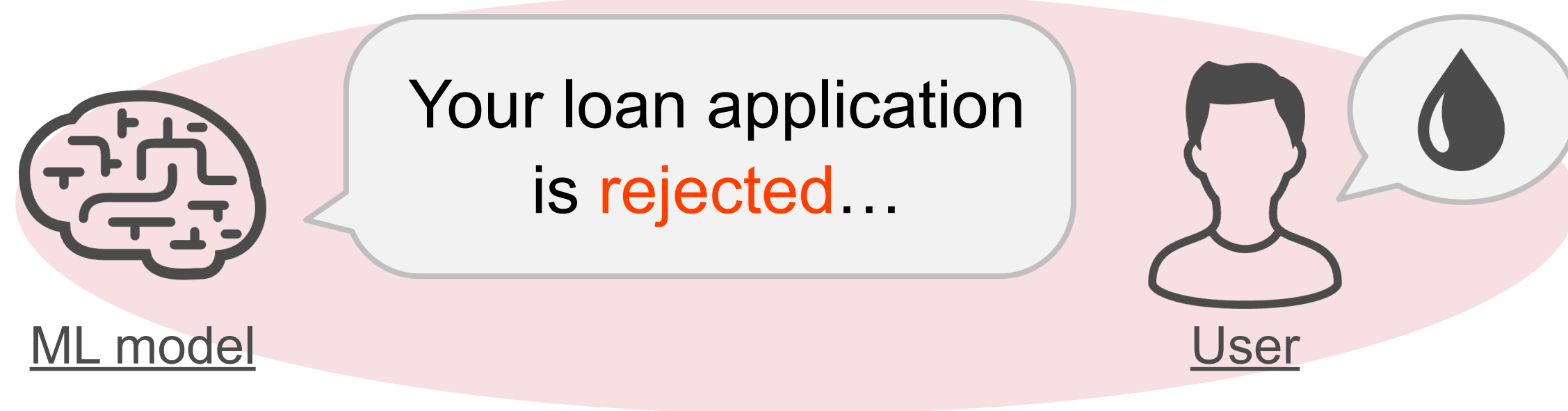
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# Background

Algorithmic recourse aims to provide an “action” for altering unfavorable predictions

## Algorithmic Recourse [Ustun+ 19]

Explaining a “*recourse action*” for obtaining a favorable prediction result from an ML model

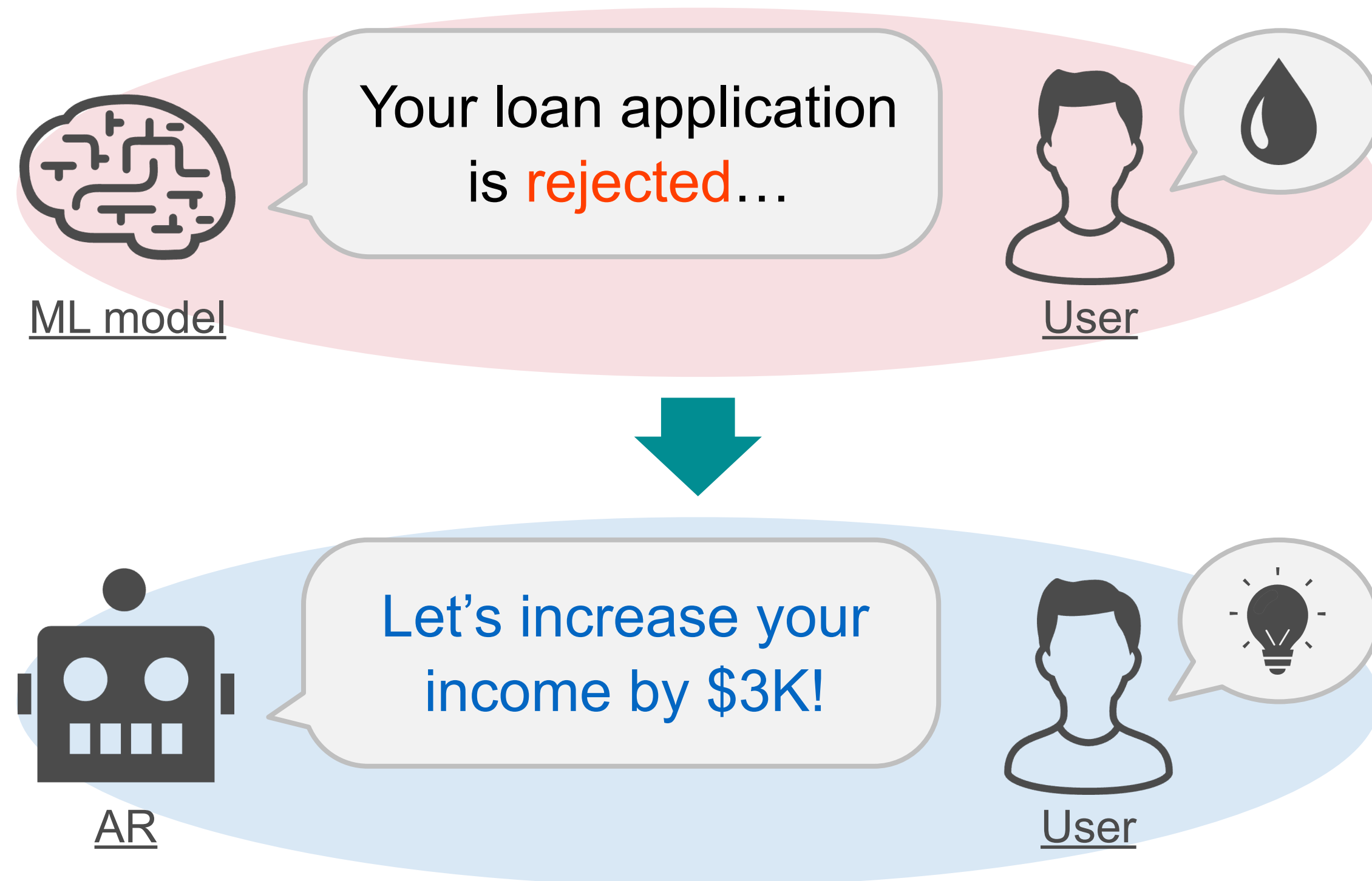


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### Problem 1. (Algorithmic Recourse; AR)

Given a model  $h: \mathcal{X} \rightarrow \mathcal{Y}$ , an input instance  $x \in \mathcal{X}$ , and a favorable class  $y^* \in \mathcal{Y}$ , find an action  $a^*$  such that

$$a^* = \arg \min_{a \in \mathcal{A}} c(a | x) \text{ s.t. } h(x + a) = y^*$$

where  $\mathcal{A}$  is a set of feasible actions and  $c$  is a cost function.

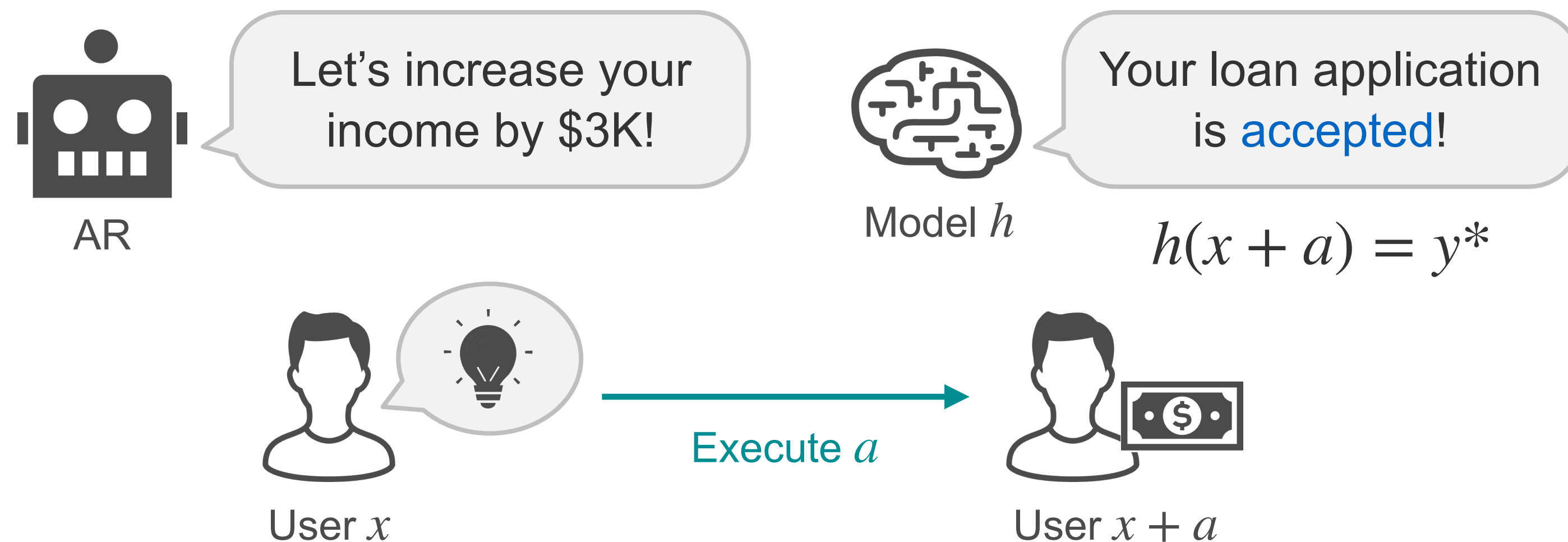
- Provide a minimum-cost action  $a$  that alters the prediction by the ML model  $h$

# Motivation

Provide improvement-oriented actions for making the real-world outcome better

“Improvement” [König+ 23]

To maintain the quality and reliability of high-stakes decision-making tasks, we need to provide actions that improve the user's real-world outcome as well as prediction

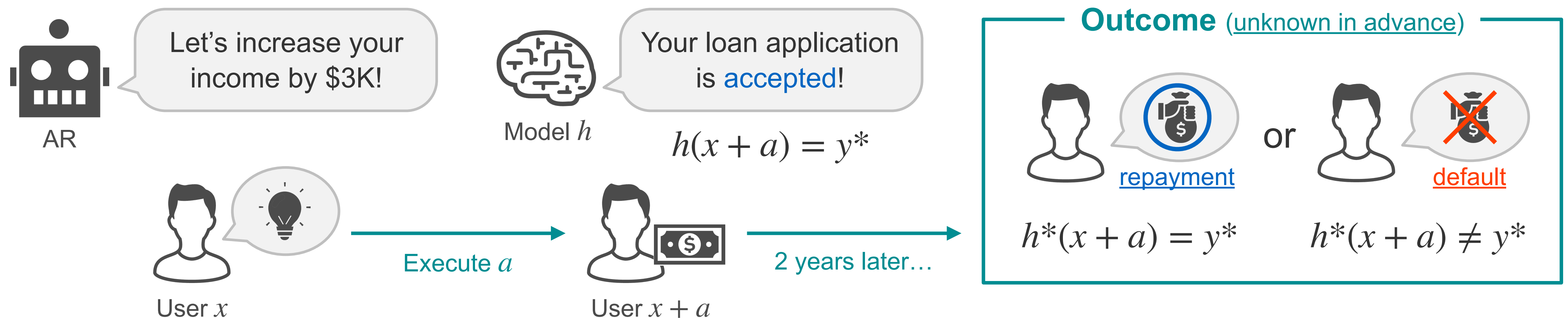


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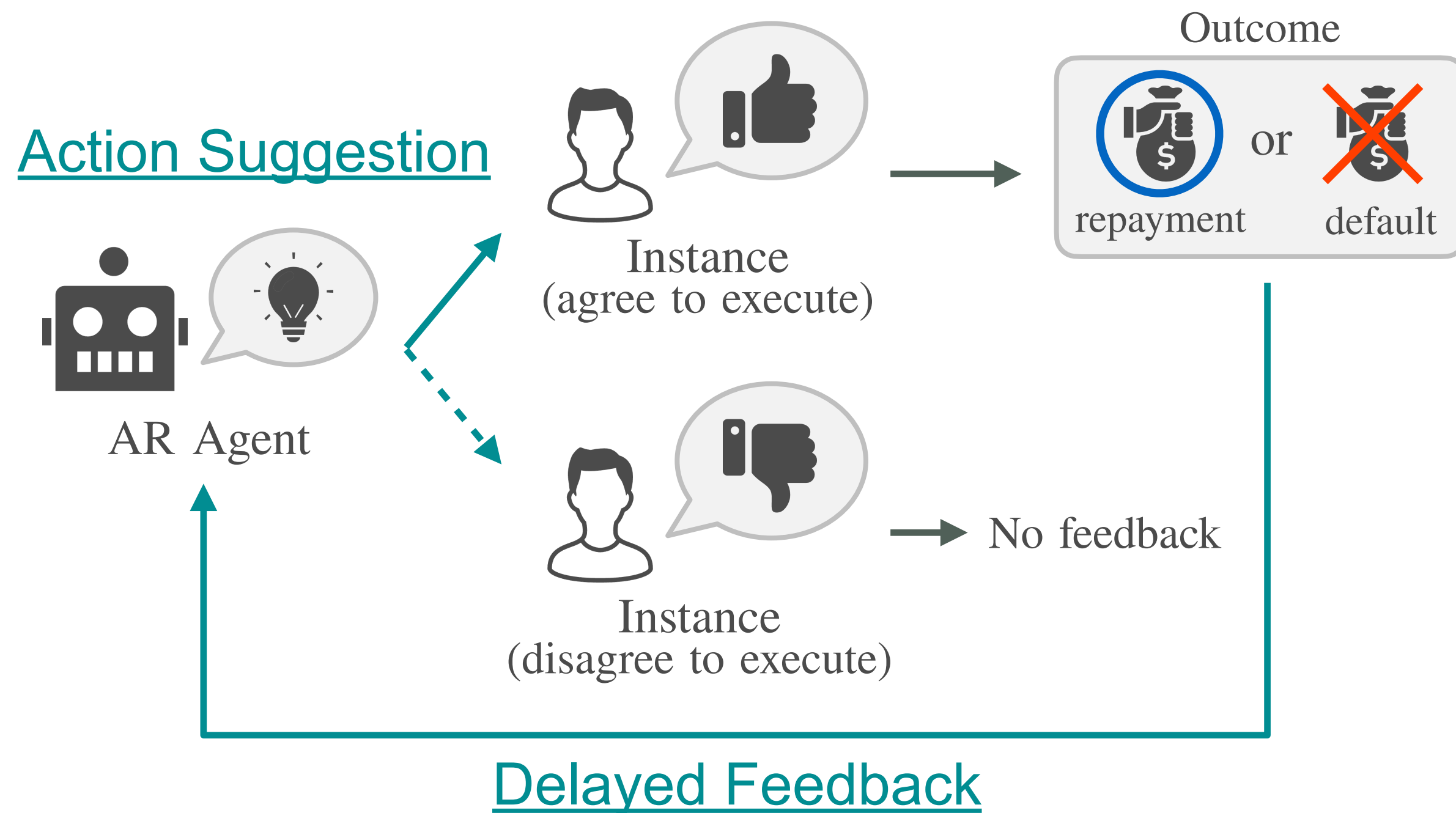


► Achieving improvement is fundamentally difficult because we do not know the oracle  $h^*$

# Problem Formulation

Suggest actions for given instances and observe delayed feedback on outcomes

**Assumption** We can observe the outcome if an instance  $x$  executes a suggested action  $a$

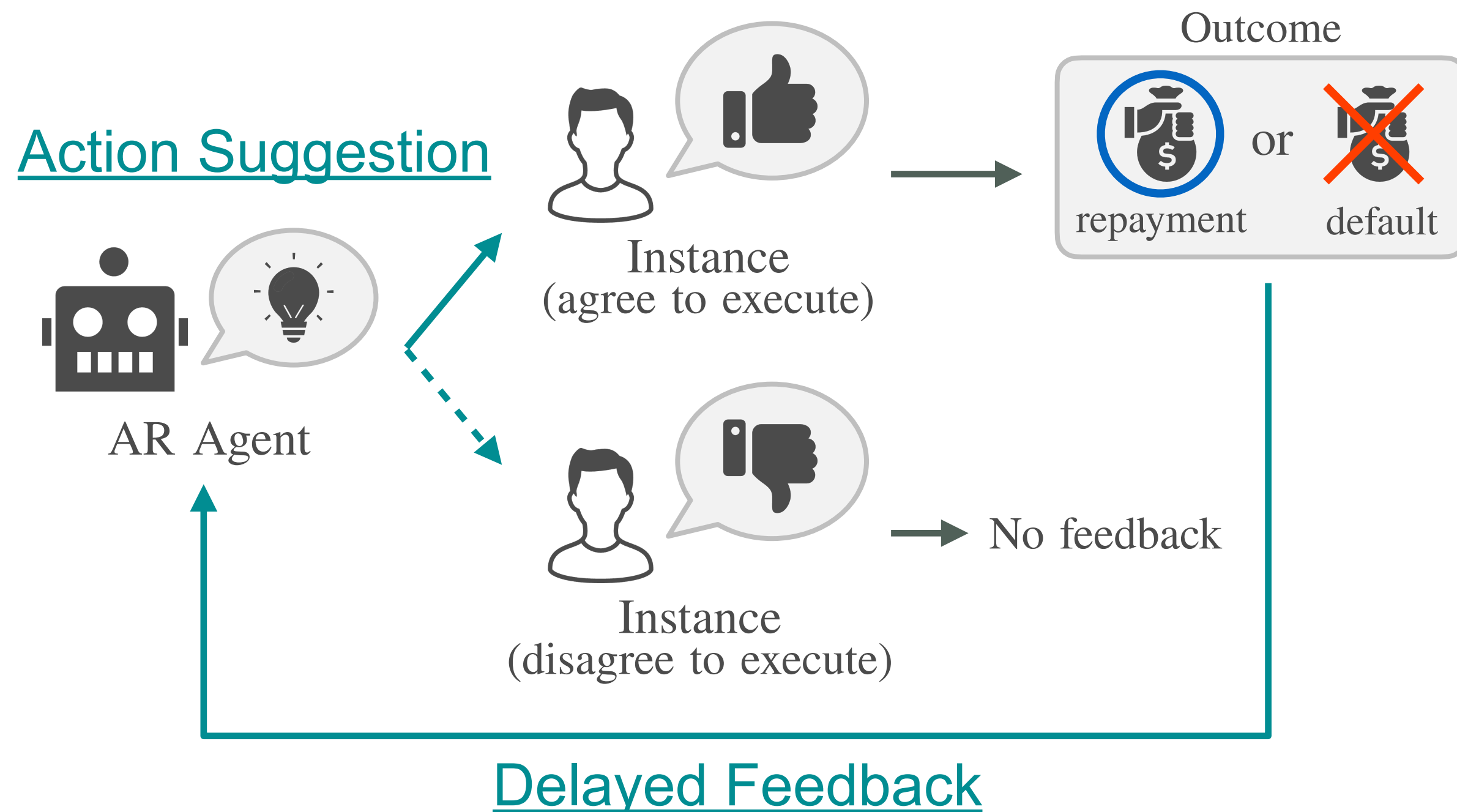




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## Problem 2. (AR for Long-Term Improvement; ARLIM)

For each round  $t = 1, 2, \dots, T$ ,

1. Receive an instance  $x_t$  and candidate valid actions  $\mathcal{A}_t$
2. Suggest an action  $a_t \in \mathcal{A}_t$  based on the past observations
3. Sample a reward  $R_t \sim \mathcal{B}(p_t)$  and delay  $D_t \sim \mathcal{D}$ , where  $p_t$  is the probability that  $x_t$  executes  $a_t$  and  $h^*(x_t + a_t) = y^*$
4. Observe feedback on the past rewards  $\{R_s \mid s + D_s = t\}_{s=1}^{t-1}$

**Goal** Maximize the mean expected reward  $R_T = \frac{1}{T} \sum_{t=1}^T \mathbb{E}[R_t]$

► We aim to provide improvement-oriented actions  $a_t$  for as many instances  $x_t$  as possible

# Algorithms

Apply contextual linear bandit and contextual Bayesian optimization algorithms

## Contextual Linear Bandit (CLB)

**Assumption** We can model the probability  $p_t$  as:

$$p_t = \underbrace{\exp(-c(a_t \mid x_t))}_{\text{prob. of execution (known)}} \cdot \underbrace{\mathbb{P}(h^*(x_t + a_t) = y^*)}_{\text{prob. of improvement (unknown)}}$$

- Our problem can be reduced to the *CLB problem under stochastic delayed feedback* [Vernade+ 20]

### Proposition 4.2

There exists an algorithm ([\*LinUCB\*](#)) that satisfies:

$$R_T \geq \underbrace{\frac{1}{T} \sum_{t=1}^T R_t^*}_{\text{optimal rewards}} - \underbrace{\mathcal{O}(\log T / \sqrt{T})}_{\text{converges to 0}}$$



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## Contextual Bayesian Optimization (CBO)

**Idea** Train a model  $f: \mathcal{X} \times \mathcal{A} \rightarrow \mathbb{R}$  such that

$$f(x_t, a_t) \approx R_t$$

using the past observations  $Z_t = \{(x_s, a_s, R_s)\}_{s=1}^{t-1}$

- Our problem can be regarded as the *CBO problem under stochastic delayed feedback* [Verma+ 22]

😊 No need for the cost function  $c$  to be known

😞 Scalability issue with the GP-based algorithms

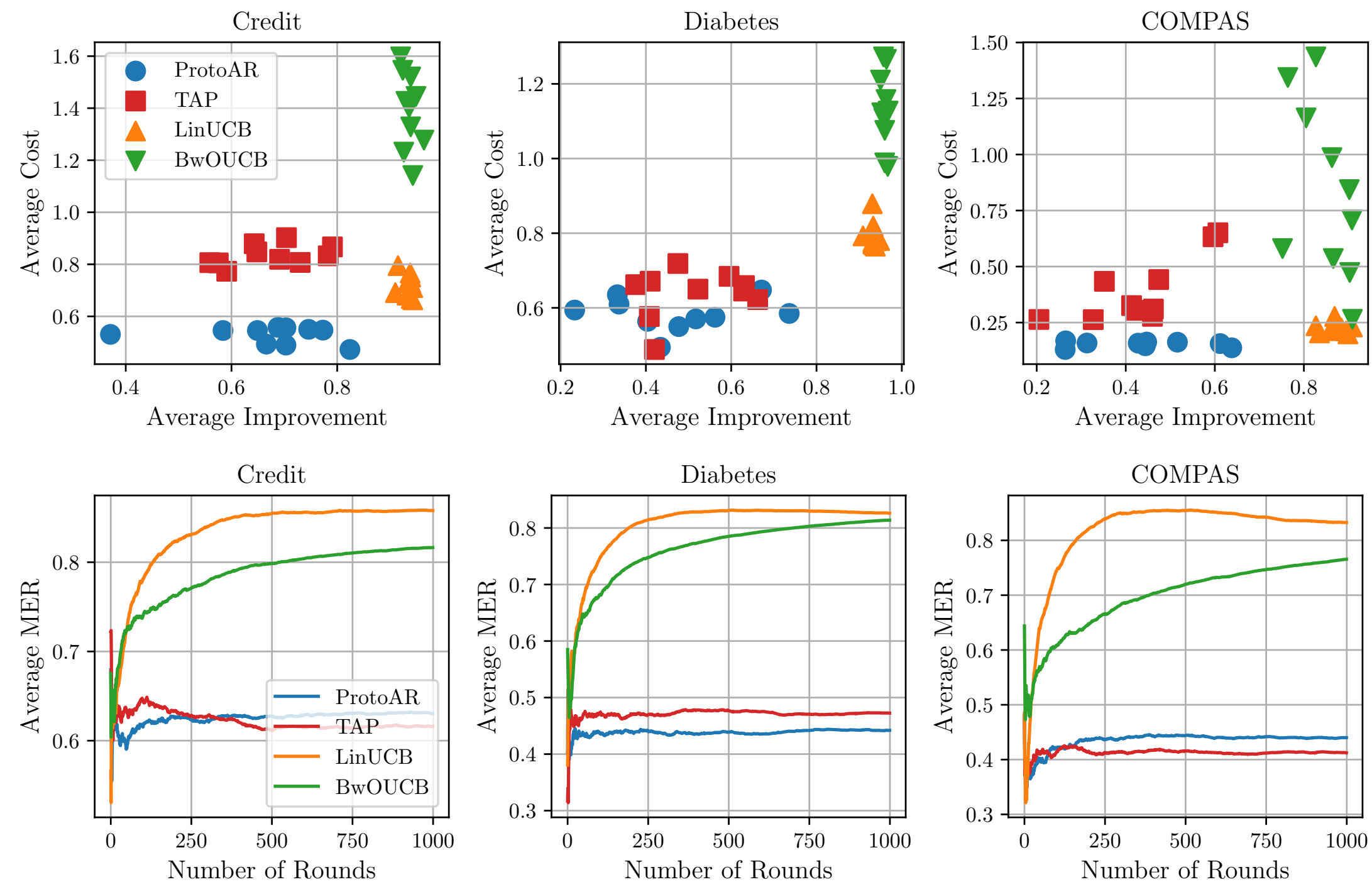
- By employing *BwO forest* [Kim+ 22] instead of GP, we propose a scalable algorithm (BwOUCB)

# Experiments

Achieve higher improvement than baselines without significantly degrading cost

## Case 1. “Noiseless” Cost Scenario

- Our LinUCB attained higher improvements while maintaining comparable costs

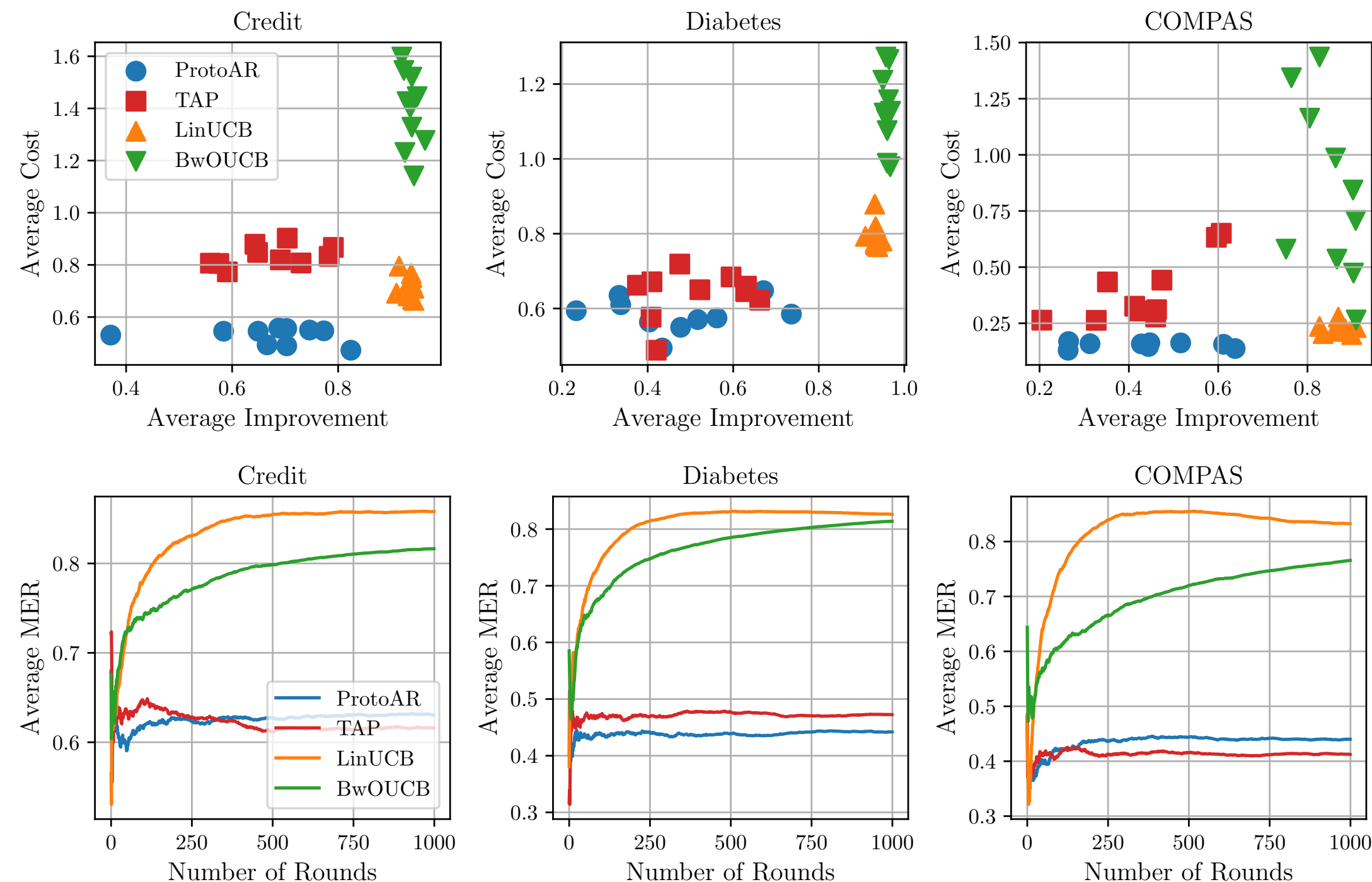


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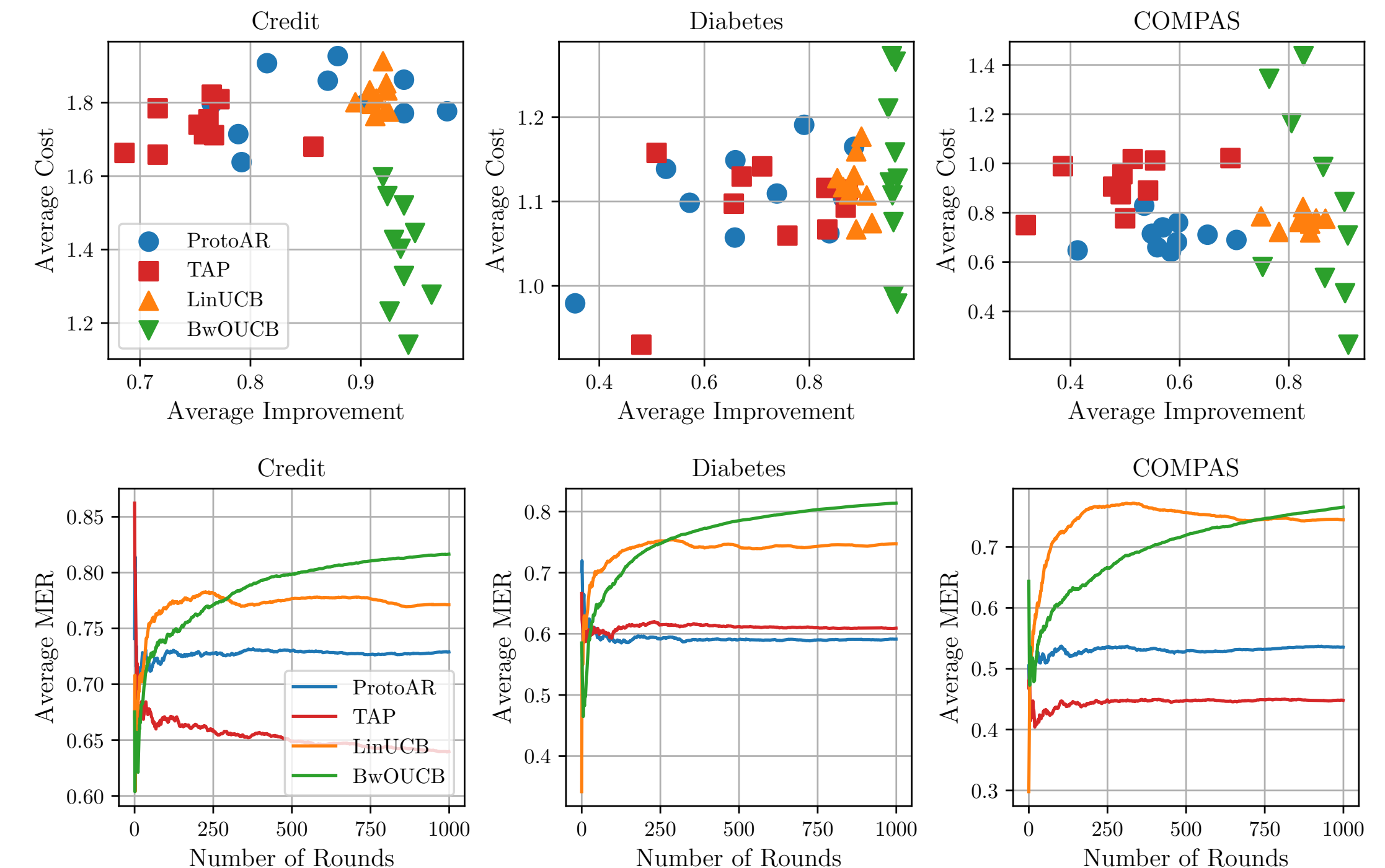
## Case 1. “Noiseless” Cost Scenario

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## Case 2. “Noisy” Cost Scenario

- The performance of our BwOUCB was better than or close to others in many cases



# Summary

Provide improvement-oriented recourse actions from the long-term perspective

- Introduce a new online learning task: *algorithmic recourse for long-term improvement*
- Propose two algorithms based on the *contextual linear bandit* and *Bayesian optimization*
- Demonstrate that our methods could provide actions for improving the real-world outcome

