



Federated Oriented Learning (FOL): A Practical One-Shot Personalized Federated Learning Framework

Guan Huang and Tao Shu

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Presenter: Guan Huang





Introduction and Motivation

1. What is Personalized Federated Learning (PFL)?

- Each client trains a local model on its own private data.
- Shared knowledge is used to adapt a global model into a personalized one for each client.
- Results in higher accuracy on non-IID local distributions than a single global model.

2. Why is one-shot PFL Essential?

- Intermittent Connectivity (e.g., LEO satellites, remote IoT): clients often get only one brief window to exchange models.
- **Communication Cost:** multiple rounds increase total data transfer and latency—especially costly on low-bandwidth or energy-limited links.
- **Need for Local Personalization:** with a single exchange—using alignment, pruning, and distillation—clients can still achieve high local accuracy without multiple back-and-forths.

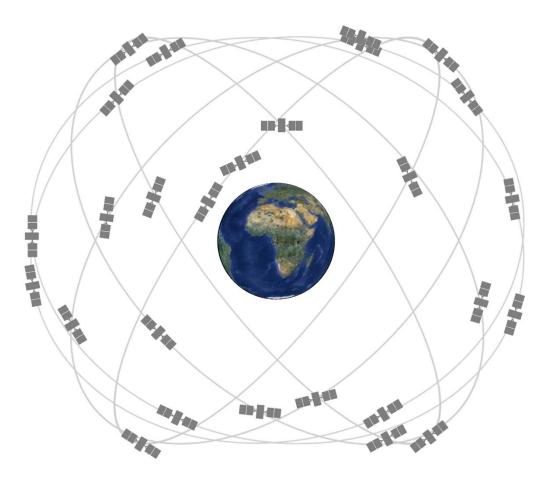


Fig 1. Image Source: Screenshot from https://www.gps.gov/multimedia/images/constellation.jpg. Retrieved [6/4, 2025].

Related Work & Limitations

1. One-Shot Federated Learning

- Synthetic Data Methods
 - Server synthesizes proxy data to train a single global model in one communication round.
- Ensemble/Distillation Methods
 - Clients send snapshots once; server ensembles or distills into a single global model.
- Limitation
 - All clients receive the same model no per-client personalization.

2. Personalized Federated Learning (PFL)

- Optimization-Based
 - Clients refine a shared model over multiple rounds using regularization, dynamic aggregation, or second-order updates.
- Parameter-Decoupling
 - Divides the model into a shared backbone and a local head, requiring multiple rounds of updates to obtain a tailored model.
- Limitation.
 - Require repeated communication impractical for LEO satellites or IoTs with limited contact

FOL Overview

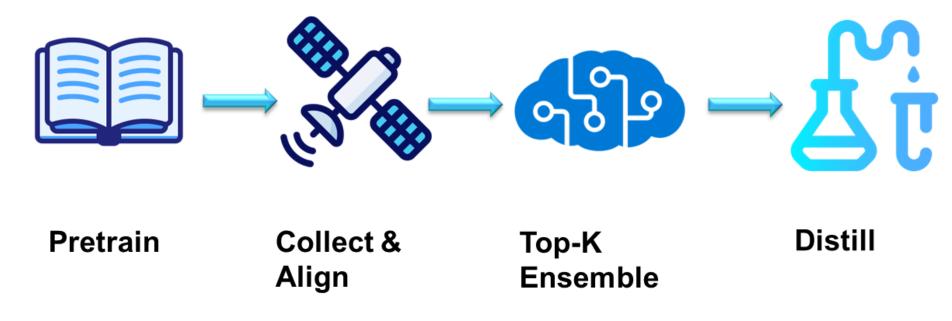


Fig. 2 Architecture Overview

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Model Alignment Process (1)

• **Fine-Tuning:** Each received neighbor model $\{\phi_j^{(e)}\}_{j=1}^Q$ is fine-tuned on the local training data:

$$\phi_{j \to k}^{'(e)} = \arg \min_{\phi} \frac{1}{|\mathcal{D}_{\text{train}}^{k}|} \sum_{(x_{i}, y_{i}) \in \mathcal{D}_{\text{train}}^{k}} \ell(f_{j}(x_{i}; \phi), y_{i}),$$

where ϕ is initialized by $\phi \leftarrow \phi_j^{(e)}$.

• Structured Pruning: Prune the model using an alignment-aware regularizer:

Group-Lasso for Unshared Layers

$$\min_{\substack{\tilde{\phi}_{j\to k}^{(e)}, \\ \{\alpha_{l}\}_{(l,l')\in\mathbb{L}_{\mathrm{shared}}(k,j), \\ \{\alpha_{u}\}_{u\in\mathbb{L}_{\mathrm{unshared}}(k,j)}}}} \frac{1}{|\mathcal{D}_{\mathrm{train}}^{k}|} \sum_{(x_{i},y_{i})\in\mathcal{D}_{\mathrm{train}}^{k}} \ell(f_{j}(x_{i};\tilde{\phi}_{j\to k}^{(e)},\{\alpha_{l}\},\{\alpha_{u}\}),y_{i})} \\ 1. \text{ Task Loss on Local Data}$$

$$+ \lambda_{p} \sum_{\underbrace{(l,l')\in\mathbb{L}_{\mathrm{shared}}(k,j)}} \sum_{i=1}^{m_{l}} \left\|\alpha_{l,i}\mathbf{W}_{l,i}^{(j\to k)} - \mathbf{W}_{l',i}^{k}\right\|_{2}^{2} \\ 2. \text{ Alignment Regularization (Shared Layers Only)}$$

$$+ \gamma_{\mathrm{shared}} \sum_{\underbrace{l\in\mathbb{L}_{\mathrm{shared}}(k,j)}} \left\|\alpha_{l}\odot\mathbf{W}_{l}^{(j\to k)}\right\|_{2,1} \\ 3. \text{ Group-Lasso for Shared Layers}$$

$$+ \gamma_{\mathrm{unshared}} \sum_{u\in\mathbb{L}_{\mathrm{unshared}}(k,j)} \left\|\alpha_{u}\odot\mathbf{W}_{u}^{(j\to k)}\right\|_{2,1},$$

where α is a gating vector, λ_p and γ are hyperparameters controlling the strength of the alignment regularization and the structured pruning, respectively. $\|\cdot\|_{2,1}$ represents the group-lasso norm. \odot denotes element-wise multiplication.

Model Alignment Process (2)

Post-Finetuning: Refine the pruned model to recover any lost accuracy.

$$\phi_{j \to k}^{(e)} \leftarrow \arg \min_{\phi} \frac{1}{|\mathcal{D}_{\text{train}}^{k}|} \sum_{(x_i, y_i) \in \mathcal{D}_{\text{train}}^{k}} \ell(f_j(x_i; \phi), y_i),$$

where ϕ is initialized by $\tilde{\phi}_{j\to k}^{(e)}$.

• Validation Scoring: Evaluate each post-tuned neighbor model $\phi_{j\to k}^{(e)}$ and the client's own model $\theta_k^{(e)-}$ on a local validation set $\mathcal{D}_{\mathrm{val}}^{k}$.

$$\operatorname{score}_{k}^{(e)}(\theta) = \frac{1}{|\mathcal{D}_{\operatorname{val}}^{k}|} \sum_{(x_{i}, y_{i}) \in \mathcal{D}_{\operatorname{val}}^{k}} \mathbb{1}(\operatorname{arg\,max} f(x_{i}; \theta) = y_{i}),$$

where $\mathbb{1}(\cdot)$ is the indicator function.

• **Top-K Selection Prep:** Rank all candidates by validation score (break ties using cosine similarity) for the next ensemble stage.

$$\begin{split} \{s_i^{(e)}\}_{i=1}^K &= \text{TopK}(CB, \{\phi_{j \to k}^{(e)}\}_{j=1}^Q \cup \{\theta_k^{(e)-}\}, \\ \{\text{score}_k^{(e)}(\phi_{j \to k}^{(e)})\}_{j=1}^Q \cup \{\text{score}_k^{(e)}(\theta_k^{(e)-})\}, K), \end{split}$$

Where CB specifies that in the event of tied scores, models are further ranked using their cosine similarity to the local model.

Top-K Ensemble → **Knowledge Distillation**

Top-K Ensemble (Teacher Construction)

Build a weighted ensemble of the top-K aligned models:

$$A_{\mathbf{w}_{k}^{(e)}}(x; \{s_{i}^{(e)}\}_{i=1}^{K}) = \sum_{i=1}^{K} w_{i}^{(e)} \cdot f_{i}(x; s_{i}^{(e)}),$$

where the optimal weights $\mathbf{w}_k^{(e)}$ is computed by minimizing the following KL-based distillation loss:

$$\mathbf{w}_{k}^{(e)} = \arg\min_{\mathbf{w}_{k}^{0}} \frac{1}{|\mathcal{D}_{\text{train}}^{k}|} \sum_{(x_{i}, y_{i}) \in \mathcal{D}_{\text{train}}^{k}} \ell(A_{\mathbf{w}_{k}^{0}}(x_{i}; \{s_{i}^{(e)}\}_{i=1}^{K}), y_{i}).$$

Regularization-based Knowledge Distillation

• Distill the weighted ensemble $A_w^{(e)}$ into the client's student model $\theta_k^{(e)+}$ by minimizing following KL-based distillation loss:

$$\mathcal{L}_{\mathrm{KD}}(\boldsymbol{\theta}_{k}^{(e)+}) = \frac{1}{|\mathcal{D}_{\mathrm{train}}^{k}|} \sum_{\boldsymbol{x}_{i} \in \mathcal{D}_{\mathrm{train}}^{k}} \mathrm{KL}\Big(\mathrm{softmax}\Big(\frac{A_{\mathbf{w}_{k}^{(e)}}(\boldsymbol{x}_{i})}{T}\Big) \parallel$$

softmax
$$\left(\frac{f_k(x_i; \theta_k^{(e)+})}{T}\right) + \lambda \|\theta_k^{(e)+} - \theta_k^{(e)-}\|^2$$
,

where T > 0 controls the smoothness of the softmax distributions applied to the logits.

Theoretical Analysis

Theorem 1. Risk Discrepancy Bound.

• Let $\theta_k^{(e)}$ be the student model obtained by minimizing the distillation loss $\mathcal{L}_{\text{KD}}(\theta_k^{(e)})$ on D_{train}^k . Then, for a C-class problem with L-Lipschitz cross-entropy loss, T>0, and softmax outputs in $(\alpha, 1-\alpha)$, the empirical risk discrepancy between the student and teacher models is bounded as follows:

$$|R_{\mathrm{S}}(\theta_k^{(e)}) - R(A_{\mathbf{w}_k^{(e)}})| \le \frac{L \cdot CT}{\alpha(1-\alpha)} \cdot \left(\frac{\mathcal{L}_{\mathrm{KD}}(\theta_k^{(e)})}{2} + \frac{1}{8}\right).$$

Theorem 2. Convergence of Knowledge Distillation.

• Suppose $\{\theta_k^r\}_{r=0}^R$ are generated by $\theta_k^{r+1} = \theta_k^r - \eta \nabla \mathcal{L}_{\mathrm{KD},k}(\theta_k^r, \xi_k^r)$, under standard assumptions that the distillation loss $L_{KD,k}$ is Ls-smooth and μ -strongly convex, and that the variance of the stochastic gradient is bounded by σ^2 , then for $r \geq 0$, and any step size $O < \eta < 1/Ls$, the following bound holds:

$$\mathbb{E}[\|\theta_k^r - \theta_k^*\|^2] \le \gamma^r \|\theta_k^0 - \theta_k^*\|^2 + \sum_{\tau=0}^{r-1} \gamma^\tau \beta,$$

Where $\gamma = \left(1 - 2\eta\mu + \frac{L_s^3}{\mu}\eta^2\right)$, $\beta = \eta^2\sigma^2$, and θ_k^* is the minimizer of $L_{KD,k}$.

Experimental Setup

Datasets

- Satellite imagery: Wildfire, Hurricane
- Vision benchmarks: SVHN, CIFAR-10, CIFAR-100

Setup

- Federated setting: 70 clients, non-IID partitioning ($\psi = 0.1, 0.3, 0.5, 0.7$)
- One-shot: Each client communicates with neighbors only once

Baselines

• Local-only, FedAvg (global, multi-round), DENSE, Co-Boosting (one-shot global), FOL-A (FOL without distillation), FOL (with distillation)

Metrics

Client-level accuracy

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Quantitative Results

Table 1. Test accuracies (%) on Wildfire and Hurricane ($\psi = 0.7$), reported as mean \pm std.

Dataset		Wildfire		Hurricane			
Satellite #	13	28	48	35	32	44	
Methods	$\psi=0.7$						
Local	94.23 ± 1.84	94.12 ± 1.80	90.53 ± 1.57	86.93 ± 1.56	87.34 ± 1.60	89.82 ± 1.82	
FOL-A (E=1)	97.19 ± 1.53	97.16 ± 1.24	95.97 ± 1.55	95.34 ± 1.42	96.18 ± 1.02	97.61 ± 1.68	
FOL-A (E=2)	97.50 ± 1.12	97.52 ± 1.17	97.33 ± 1.23	96.59 ± 1.76	96.97 ± 1.41	97.87 ± 1.22	
FOL-A (E=3)	97.53 ± 0.76	97.70 ± 0.98	97.99 ± 0.93	96.90 ± 1.09	97.47 ± 1.11	98.20 ± 1.03	
FOL (E=1)	94.94 ± 1.38	95.21 ± 1.32	91.26 ± 1.62	90.09 ± 1.55	89.87 ± 0.69	91.62 ± 0.58	
FOL (E=2)	95.23 ± 1.35	95.57 ± 0.72	91.60 ± 1.29	91.23 ± 1.57	91.77 ± 0.83	95.21 ± 1.49	
FOL (E=3)	96.32 ± 0.96	95.75 ± 1.39	91.95 ± 1.31	92.26 ± 1.05	92.41 ± 1.68	95.81 ± 1.88	
FOL-AN (E=1)	94.38 ± 1.86	94.86 ± 1.67	91.28 ± 1.82	88.24 ± 1.82	91.14 ± 1.13	92.81 ± 1.10	
FOL-AN (E=2)	95.63 ± 1.40	95.04 ± 1.43	93.29 ± 1.51	90.09 ± 0.64	92.47 ± 1.86	94.01 ± 1.70	
FOL-AN (E=3)	95.94 ± 0.71	96.45 ± 0.65	95.97 ± 1.43	93.19 ± 1.23	93.04 ± 1.19	96.41 ± 1.26	
FOL-N (E=1)	93.44 ± 1.68	94.68 ± 1.79	88.59 ± 2.31	85.76 ± 1.85	89.22 ± 0.93	91.62 ± 1.19	
FOL-N (E=2)	94.69 ± 0.53	94.86 ± 0.88	90.60 ± 1.01	89.16 ± 1.31	90.21 ± 1.28	92.22 ± 1.65	
FOL-N (E=3)	95.31 ± 1.49	95.21 ± 0.98	91.95 ± 0.97	90.71 ± 0.59	90.51 ± 1.21	94.61 ± 0.73	
DENSE	88.75 ± 1.91	87.41 ± 1.63	83.22 ± 1.57	67.49 ± 1.81	69.95 ± 1.70	73.05 ± 1.62	
Co-Boosting	90.31 ± 1.26	89.19 ± 1.13	88.02 ± 1.25	72.14 ± 1.52	74.45 ± 1.72	74.04 ± 1.54	
FedAvg (E=1)	73.19 ± 1.73	73.94 ± 1.96	68.18 ± 2.02	60.21 ± 1.73	62.03 ± 1.95	66.26 ± 1.62	
FedAvg (E=2)	73.13 ± 1.91	72.29 ± 1.74	66.92 ± 1.55	59.44 ± 1.64	64.33 ± 1.33	69.88 ± 1.57	
FedAvg (E=3)	74.61 ± 1.54	71.58 ± 1.16	68.48 ± 1.23	63.70 ± 0.71	65.16 ± 1.14	67.82 ± 0.92	

Table 3. Test accuracies (%) on CIFAR-10, CIFAR-100, and SVHN, reported as mean \pm std.

Dataset	CIFAR-10	CIFAR-100	CATINI	
Dataset	CIFAR-10	CIFAR-100	SVHN	
Satellite #	9	14	21	
Methods	$\psi = 0.7$	$\psi = 0.7$	$\psi = 0.5$	
Local	60.06 ± 1.97	30.41 ± 2.28	78.97 ± 1.75	
FOL-A (E=1)	70.73 ± 2.09	46.32 ± 2.12	85.73 ± 1.63	
FOL-A (E=2)	70.93 ± 1.16	47.72 ± 1.53	86.26 ± 1.28	
FOL-A (E=3)	71.02 ± 0.73	49.24 ± 1.12	88.37 ± 0.92	
FOL (E=1)	65.68 ± 2.14	37.31 ± 2.43	81.09 ± 1.54	
FOL (E=2)	66.06 ± 1.05	37.43 ± 1.58	81.62 ± 1.36	
FOL (E=3)	66.83 ± 0.82	39.42 ± 1.03	82.85 ± 1.18	
FOL-AN (E=1)	61.77 ± 2.36	31.23 ± 2.31	79.62 ± 1.64	
FOL-AN (E=2)	62.35 ± 1.31	31.58 ± 1.75	80.92 ± 1.41	
FOL-AN (E=3)	63.01 ± 0.71	32.05 ± 1.68	83.15 ± 1.33	
FOL-N (E=1)	59.68 ± 2.43	30.64 ± 2.57	80.04 ± 1.74	
FOL-N (E=2)	60.44 ± 1.37	30.99 ± 1.74	80.39 ± 1.39	
FOL-N (E=3)	61.49 ± 1.43	31.11 ± 2.12	81.15 ± 1.22	
DENSE	61.68 ± 2.03	29.59 ± 2.53	69.53 ± 1.57	
Co-Boosting	63.11 ± 1.98	33.45 ± 2.12	73.58 ± 1.48	
FedAvg (E=1)	47.76 ± 2.63	12.16 ± 3.93	53.08 ± 2.32	
FedAvg (E=2)	44.90 ± 2.45	12.75 ± 3.23	58.72 ± 1.79	
FedAvg (E=3)	45.57 ± 1.79	12.40 ± 2.89	55.49 ± 1.93	

Table 2. Test accuracies (%) on Wildfire and Hurricane ($\psi \in \{0.5, 0.3, 0.1\}$), reported as mean \pm std.

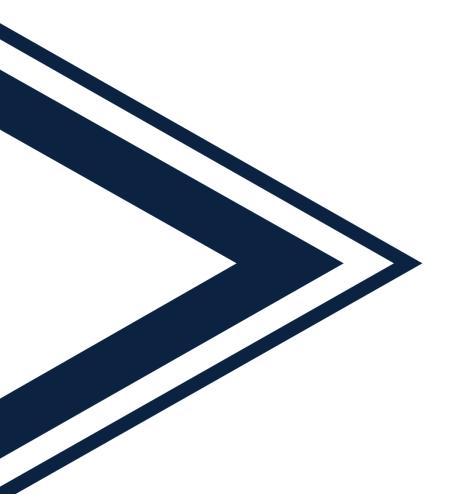
Dataset	Wildfire			Hurricane			
Satellite #	32	43	48	8	26	44	
Methods	$\psi = 0.5$	$\psi = 0.3$	$\psi = 0.1$	$\psi = 0.5$	$\psi = 0.3$	$\psi = 0.1$	
Local	79.07 ± 1.71	90.37 ± 1.76	85.50 ± 2.16	86.77 ± 1.90	57.14 ± 2.87	77.78 ± 1.35	
FOL-A (E=1)	95.35 ± 1.42	94.07 ± 1.89	90.63 ± 1.92	95.04 ± 1.70	90.48 ± 1.57	88.89 ± 1.92	
FOL-A (E=2)	96.52 ± 1.02	94.92 ± 1.25	96.14 ± 1.16	95.34 ± 1.16	91.72 ± 1.26	91.67 ± 1.26	
FOL-A (E=3)	97.67 ± 0.71	95.76 ± 0.85	96.88 ± 1.01	95.87 ± 1.03	93.65 ± 1.14	94.44 ± 0.87	
FOL (E=1)	90.70 ± 1.75	90.68 ± 1.01	88.46 ± 1.99	89.26 ± 1.25	84.13 ± 1.57	83.33 ± 1.69	
FOL (E=2)	91.96 ± 1.09	91.53 ± 1.78	90.63 ± 1.77	90.08 ± 1.74	85.71 ± 1.38	84.43 ± 1.92	
FOL (E=3)	93.02 ± 1.22	92.37 ± 1.27	93.75 ± 1.40	90.91 ± 1.38	87.30 ± 1.07	86.11 ± 1.18	
FOL-AN (E=1)	90.77 ± 1.38	91.53 ± 1.26	87.51 ± 2.32	91.34 ± 1.70	87.47 ± 2.55	86.73 ± 1.94	
FOL-AN (E=2)	93.22 ± 1.85	93.22 ± 1.17	90.63 ± 1.69	92.56 ± 1.18	88.89 ± 1.91	88.67 ± 1.75	
FOL-AN (E=3)	95.35 ± 1.25	94.07 ± 1.21	90.94 ± 1.14	93.39 ± 1.37	90.48 ± 1.55	91.39 ± 1.26	
FOL-N (E=1)	86.05 ± 1.96	88.14 ± 1.67	85.13 ± 1.92	85.95 ± 1.95	76.19 ± 1.73	80.56 ± 2.11	
FOL-N (E=2)	87.35 ± 1.41	89.83 ± 1.76	86.38 ± 2.07	86.74 ± 1.83	80.95 ± 1.94	81.94 ± 1.38	
FOL-N (E=3)	90.54 ± 1.51	90.06 ± 1.59	88.47 ± 1.37	87.60 ± 1.49	82.54 ± 1.76	83.37 ± 1.56	
DENSE	79.91 ± 1.73	78.63 ± 1.98	52.08 ± 2.03	61.10 ± 1.51	58.73 ± 1.43	46.14 ± 1.81	
Co-Boosting	86.05 ± 1.68	85.59 ± 1.65	54.51 ± 1.85	72.29 ± 1.68	52.38 ± 1.85	48.78 ± 1.50	
FedAvg (E=1)	53.11 ± 1.82	63.25 ± 1.87	35.33 ± 2.76	66.12 ± 1.50	41.27 ± 1.99	46.14 ± 1.72	
FedAvg (E=2)	56.03 ± 2.53	67.52 ± 1.92	45.16 ± 1.97	58.79 ± 1.86	45.16 ± 1.26	42.61 ± 1.86	
FedAvg (E=3)	51.07 ± 1.93	66.10 ± 2.05	42.86 ± 1.53	60.33 ± 1.24	44.44 ± 1.76	43.33 ± 1.46	

Table 4. Test accuracies (%) for six additional clients on the *Hurricane* dataset with $\psi = 0.7$.

Dataset	Hurricane					
Satellite # Methods	41	3	$\psi =$	22 = 0.7	56	51
Local	90.45	82.35	88.63	90.67	86.01	91.18
FOL-A (E=1)	94.27	91.18	92.73	93.10	93.87	96.57
FOL-A (E=2)	95.54	94.12	93.64	93.68	95.16	97.06
FOL-A (E=3)	96.18	96.06	94.09	95.40	95.74	97.55
FOL (E=1)	93.11	85.29	90.02	91.95	89.81	93.63
FOL (E=2)	93.63	91.33	91.82	92.53	90.07	94.12
FOL (E=3)	94.27	93.04	92.27	94.25	91.92	95.59
DENSE	70.02	67.35	68.13	71.31	69.57	70.16
Co-Boosting	74.61	69.16	72.51	73.63	75.21	74.47

Summary

- We propose **FOL**, a one-shot personalized federated learning framework tailored for constrained communication environments.
- FOL integrates **model alignment**, **top-K ensemble**, and **regularization-based distillation** to deliver strong personalization in just one exchange.
- We provide theoretical guarantees on risk bounds and convergence.
- Experiments across **five diverse datasets and 70 clients** show that FOL outperforms baselines, especially under high data heterogeneity.
- **Future work**: developing more advanced one-shot PFL techniques and integrate stronger privacy guarantees.



Thank you.



Guan Huang
PhD Student, Auburn University
gzh0040@auburn.edu



Tao Shu
Associate Professor, Auburn University
tshu@auburn.edu