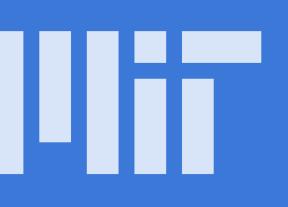
# On the Duality between Gradient Transformations and Adapters

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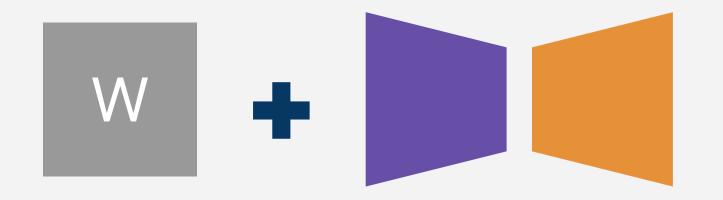
### Background

Training LLMs requires a lot of memory. Two memory-efficient training methods stand out.

### Adapter methods

**Key idea:** Freeze base weights and train only an additive perturbation. Fewer parameters means less optimizer and gradient memory.

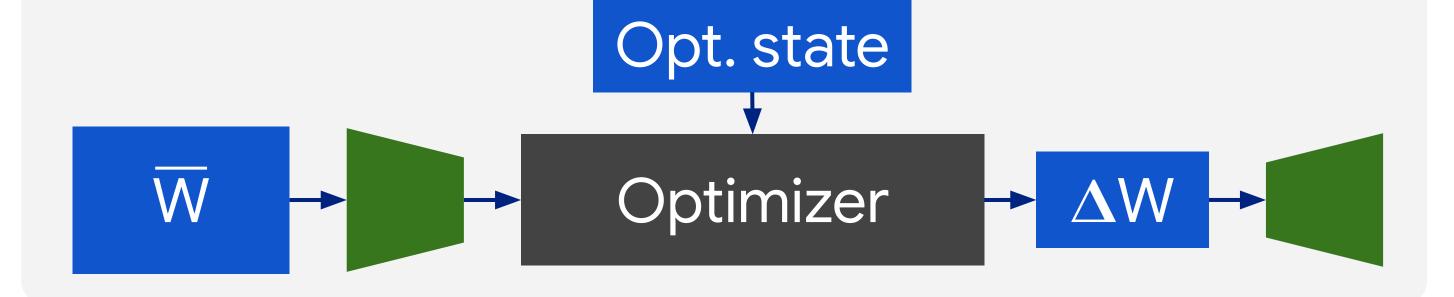
Example: Low-rank (LoRA; Hu et al., 2021)



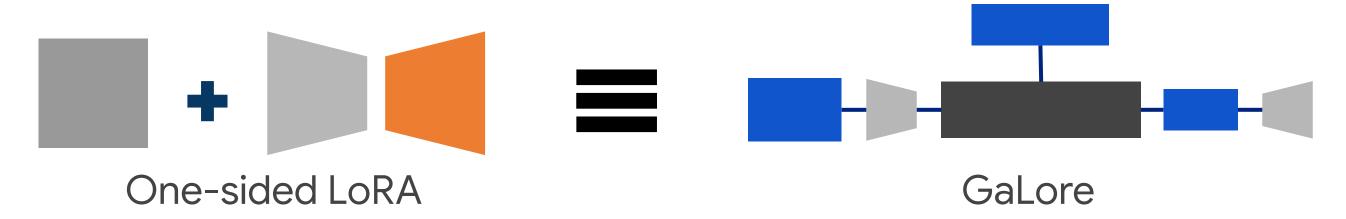
#### Gradient transformation methods

**Key idea:** Perform optimizer update in lower-dimensional space. Reduces optimizer states, and hence memory.

Example: GaLore (Zhao et al., 2024)



Previous work: The two methods above are equivalent under certain conditions



#### **Key contributions:**

- Generalize the equivalence between adapters and gradient transformations
- 2 Exploit this equivalence to improve memory-efficient pretraining
- Explore this equivalence in the context of memory-constrained distributed pretraining

# 1 Equivalence theorem

Main result: Training with linear gradient transformations is equivalent to training with a linear adapter.

We explore a general setting:

- Model is a *d*-dim vector, e.g.,  $\Theta = \text{vec}(\mathbf{W})$
- Gradient transformation is a linear map to a smaller space, i.e.,  $\mathbf{S} \in \mathbb{R}^{r \times d}$
- Optimizer takes gradient  $\overline{\Theta}^{(t)}$  and states  $\xi_{\Theta}^{(t)}$  at step t as inputs (e.g., SGD, Adam)

Theorem 1 (Duality theorem) shows that training a model with gradient transformations, i.e.,

$$(\Delta_{\mathbf{S}\Theta}^{(t)}, \xi_{\mathbf{S}\Theta}^{(t+1)}) = \text{Optimizer}(\mathbf{S}\overline{\Theta}^{(t)}, \xi_{\mathbf{S}\Theta}^{(t)})$$
$$\Theta^{(t+1)} = \Theta^{(t)} + \mathbf{S}^{\top} \Delta_{\mathbf{S}\Theta}^{(t)},$$

is equivalent to training it with a linear adapter, i.e., substitute original parameter with  $\Theta^{(0)} + \mathbf{S}^{\top} \Lambda$  where  $\Lambda \in \mathbb{R}^r$  is our new parameter. From this:

$$\mathbf{W}^{(0)} + \mathbf{L}^{\mathsf{T}} \mathbf{A} \mathbf{R}^{\mathsf{T}}$$
 =  $\mathbf{L} \overline{\mathbf{W}} \mathbf{R}$  (Gradient view)

New result: If S is Kronecker-factored, i.e.,  $\mathbf{S} = \mathbf{R}^{\top} \otimes \mathbf{L}$ , then this establishes an equivalence between MoRA (Jiang et al., 2024) and a two-sided version of GaLore.

**Remark:** In GaLore, the gradient transformation is periodically swapped out; this is equivalent to ReLoRA (Lialin et al., 2023).

Experiments: We conduct two studies.

In 2 we investigate two key knobs: choice of transformation and base weight quantization.

In 3 we explore whether worker-specific transformations help in distributed training.

Setup: 200M/1B pretraining; Llama architecture

# 2 Memory-efficient pretraining

Goal: Retain perplexity but reduce memory use

Finding 1: Rematerializable transformations often reduce memory without big impact to perplexity

Model	Adapter form	PPL	Mem.
Full pretraining ReLoRA	$\mathbf{W} + \mathbf{B}\mathbf{A}$	$12.44 \\ 13.94$	$8.04 \\ 5.77$
SVD (GaLore) Gauss. (Flora) Rademacher Semi-orthogonal Two-side Gauss. Two-side SVD	$\mathbf{W} + \mathbf{P}^{\top} \mathbf{A},  \mathbf{P}^{\top} = \text{SVD}(\overline{\mathbf{W}})$ $\mathbf{W} + \mathbf{P}^{\top} \mathbf{A},  \mathbf{P} \sim k \mathcal{N}(0, \mathbf{I})$ $\mathbf{W} + \mathbf{P}^{\top} \mathbf{A},  \mathbf{P} \sim k \operatorname{Unif}(\{-1, 1\})$ $\mathbf{W} + \mathbf{P}^{\top} \mathbf{A},  \mathbf{P}^{\top} \mathbf{P} = k \mathbf{I}$ $\mathbf{W} + \mathbf{L}^{\top} \mathbf{A} \mathbf{R}^{\top},  \mathbf{L}, \mathbf{R} \sim k \mathcal{N}(0, \mathbf{I})$ $\mathbf{W} + \mathbf{L}^{\top} \mathbf{A} \mathbf{R}^{\top},  \mathbf{L}^{\top},  \mathbf{R}^{\top} = \operatorname{SVD}(\overline{\mathbf{W}})$	13.62 $13.88$ $13.86$ $13.71$ $15.28$ $14.27$	5.27 $5.02$ $5.27$ $5.02$ $5.02$ $6.55$

Finding 2: INT8 quantization can be done without major degradation; NF4 incurs ~2-4 PPL penalty

Finding 3: No obvious relationship between gradient reconstruction and PPL

### 3 Distributed pretraining

Goal: Memory-constrained distributed training

Setting: Train for 500 steps and construct pseudo-gradient (~DiLoCo; Douillard et al., 2023).

**Finding**: Identical < Random < Semi-orthogonal (i.e., distributes dimensions across workers)

Method	Projection Init.	200M	1 <b>B</b>
Dist. Training (DiLoCo) Dist. ReLoRA (LTE)	<del>-</del>	$18.00 \\ 20.97$	12.77 $13.72$
Identical Random Independent Random Distributed Random	$egin{aligned} \mathbf{P}_i &= \mathbf{P}_j \ \mathbb{E}[\mathbf{P}_i \mathbf{P}_j^ op] &= 0 \ \mathbf{P}_i \mathbf{P}_j^ op &= 0 \end{aligned}$	21.51 20.11 19.81	14.28 13.66 13.51

Approaches shine with many low-rank workers

Method	(Rank, Workers)			
	(128, 8)	(256, 4)	(512, 2)	
Dist. Training (DiLoCo) Dist. ReLoRA (LTE) Identical Random Independent Random Distributed Random	17.81 $23.76$ $23.96$ $20.64$ $20.32$	18.00 $20.97$ $21.51$ $20.11$ $19.81$	18.56 $19.54$ $20.32$ $19.97$ $19.66$	