M3-JEPA:

Multimodal Alignment via Multi-gate MoE based on the Joint-Embedding Predictive Architecture

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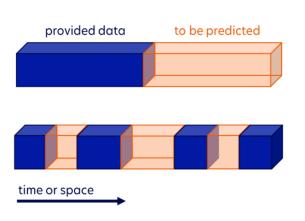
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Motivations



- Human perception has a multimodal nature
- Ubiquitous unannotated data => self-supervised learning (SSL): mask some, predict the other
- Information bias when aligning on the token space => energy-based model (EBM)
- Alignment on the latent space
- use an embedding predictor to avoid representation collapse => JEPA

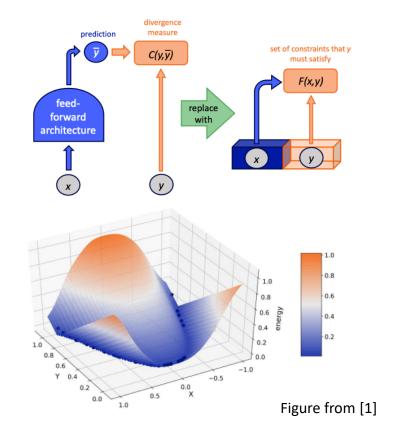
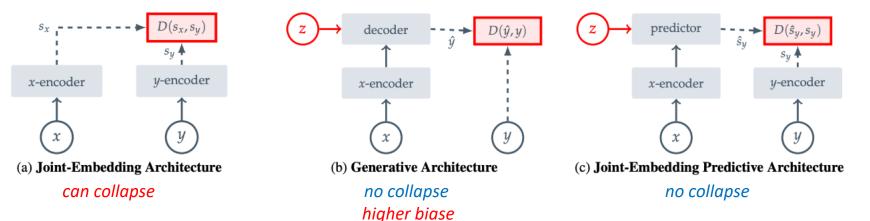


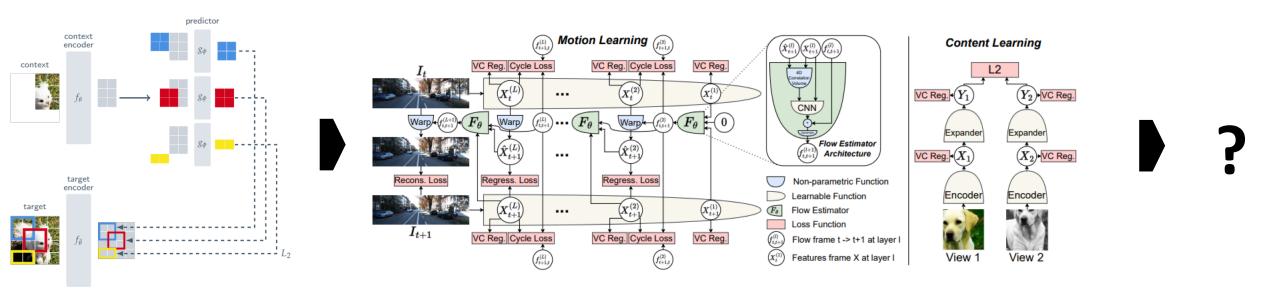
Figure from [2]



^[1] Dawid, LeCun. Introduction to latent variable energy-based models: a path toward autonomous machine intelligence. JSTAT 2024

^[2] Assran, et al. Self-Supervised Learning from Images with a Joint-Embedding Predictive Architecture. ICCV 2023

Transfer JEPA from single to multiple modalities



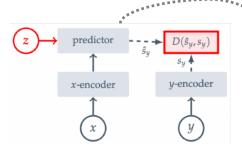
i-JEPA [1] MC-JEPA [2] MM + JEPA ?

- i-JEPA studies the image classification task
- MC-JEPA expands to motion-content learning
- Here we leverage JEPA on broader multimodal (MM) scenarios
 - Vision, Text, Audio, Others
 - Various masking strategies (different combinations of modalities w.r.t input or output)

^[1] Assran, et al. Self-Supervised Learning from Images with a Joint-Embedding Predictive Architecture. ICCV 2023

^[2] Bardes, Ponce, LeCun. MC-JEPA: A Joint-Embedding Predictive Architecture for Self-Supervised Learning of Motion and Content Features. Arxiv 2024

M3-JEPA



Multi-modal

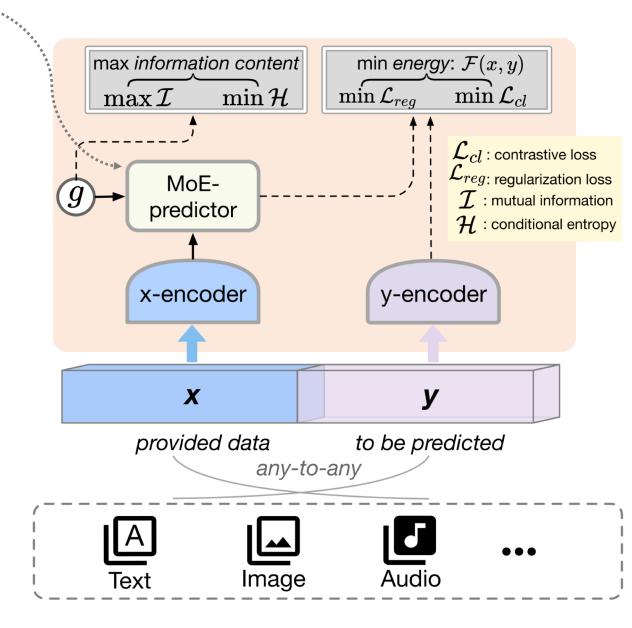
 Input (x) and output (y) can be any modality or combination of modalities

Multi-gate

- Gate output for contrastive loss
- Gate output for regularization loss

Mixture-of-expert

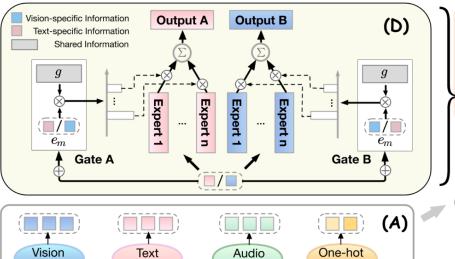
Implement the latent predictor by the MoE structure



M3-JEPA: detailed architecture

MMoE-like Predictor

- Totally n experts
- Top-k selection
- 2 gates



Encoder

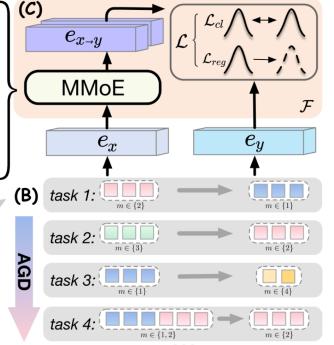
m = 3

Encoder

m = 4

Losses

- Contrastive loss (cl)
- Regularization loss (reg)
- Total Loss: L = $(1 \alpha) * L_{cl} + \alpha * L_{reg}$



Modality Encoder

- Vision: DinoV2-Large [1]
- Text: Llama3-8b
- Audio: LanguageBind [2]

Task optimization

- Alternative Gradient Descent (AGD)
- Interleaved optimization: task1, task2, ...

[1] Oquab et al. Dinov2: Learning robust visual features without supervision. TMLR 2024

Encoder

[2] Zhan, et al. Languagebind: Extending video-language pretraining to n-modality by language-based semantic alignment. ICLR 2024

Encoder

Information-Theoretic Analysis

 \mathcal{L}_{cl} : contrastive loss

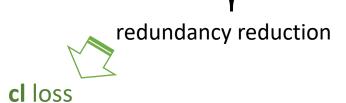
 \mathcal{L}_{reg} : regularization loss

 ${\mathcal I}$: mutual information

 ${\mathcal H}$: conditional entropy

$$(1 - \alpha)\mathcal{L}_{\text{cl}} + \alpha\mathcal{L}_{\text{reg}} \Longleftrightarrow -\mathcal{I}(x; y) + \alpha\left(\mathcal{H}(y|x) + \mathcal{H}(x|y)\right)$$

Formulation of Losses



uncertainty reduction





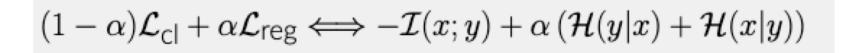
Information-Theoretic Analysis

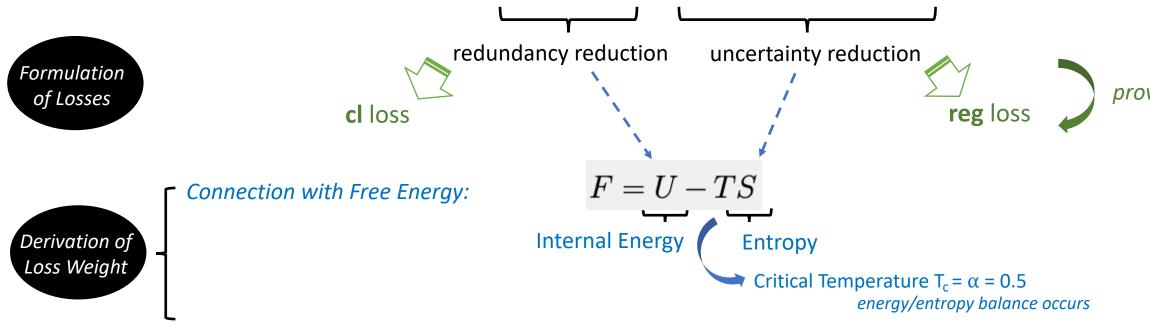
 \mathcal{L}_{cl} : contrastive loss

 \mathcal{L}_{reg} : regularization loss

 \mathcal{I} : mutual information

 ${\cal H}$: conditional entropy





^[1] Lin, Gou, et al. COMPLETER: Incomplete Multi-View Clustering via Contrastive Prediction. CVPR 2021

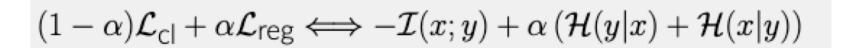
Information-Theoretic Analysis

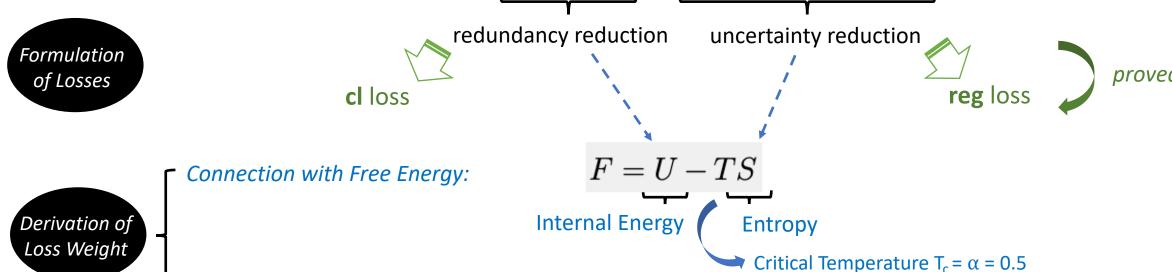
 \mathcal{L}_{cl} : contrastive loss

 $\mathcal{L}_{reg:}$ regularization loss

 ${\mathcal I}$: mutual information

 ${\mathcal H}$: conditional entropy





From convergence assumption:

 $\mathcal{L} \to \frac{1}{2}(\mathcal{L}(x \to y) + \mathcal{L}(y \to x)) \to \frac{1}{2}\Big(-\mathcal{I}(x;y) + \mathcal{H}(y|x) - \mathcal{I}(y;x) + \mathcal{H}(x|y)\Big) = -\mathcal{I}(x;y) + \frac{1}{2}\Big(\mathcal{H}(y|x) + \mathcal{H}(x|y)\Big)$ consecutive steps $\alpha = 0.5$

convergence theorem of alternating optimization

proved by [2]

energy/entropy balance occurs

^[1] Lin, Gou, et al. COMPLETER: Incomplete Multi-View Clustering via Contrastive Prediction. CVPR 2021

^[2] Jain & Kar. Non-convex optimization for machine learning. Found. Trends Mach. Learn. 2017

M3-JEPA performs well on cross-modality alignment

Table 1. Finetuned results on Vision-Language Retrieval tasks.

Vision-Language
Retrieval

				Flick	r30K			COC		CO	20		
Method	# Trainable Params	$Image \rightarrow Text \qquad Text \rightarrow Image$				$Image \rightarrow Text$			$Text \rightarrow Image$				
		R@1	R@5	R@10	R@1	R@5	R@10	R@1	R@5	R@10	R@1	R@5	R@10
Lightweight models													
TinyCLIP (Wu et al., 2023)	63M + 31M	84.9	-	-	66.0	-	-	56.9	-	-	38.5	-	-
MobileCLIP (Vasu et al., 2024)	<30.7M	85.9	-	-	67.7	-	-	58.7	-	-	40.4	-	-
Dual-encoder models													
CLIP (Radford et al., 2021)	428M	88.0	98.7	99.4	68.7	90.6	95.2	-	-	-	-	-	-
ALIGN (Cohen, 1997)	820M	88.6	98.7	99.7	75.7	93.8	96.8	77.0	93.5	96.9	59.9	83.3	89.8
FILIP (Yao et al., 2022)	417M	89.8	99.2	99.8	75.0	93.4	96.3	78.9	94.4	97.4	61.2	84.3	90.6
Florence (Yuan et al., 2021)	893M	90.9	99.1	-	76.7	93.6	-	81.8	95.2	-	63.2	85.7	-
BEIT-3 (Wang et al., 2023b)	1.9B	94.9	99.9	100.0	81.5	95.6	97.8	84.8	96.5	98.3	67.2	87.7	92.8
Fusion-encoder models													
UNITER (Chen et al., 2020)	303M	83.6	95.7	97.7	68.7	89.2	93.9	65.7	88.6	93.8	52.9	79.9	88.0
OSCAR (Li et al., 2020)	345M	-	-	-	-	-	-	70.0	91.1	95.5	54.0	80.8	88.5
VinVL (Zhang et al., 2021)	345M	-	-	-	-	-	-	75.4	92.9	96.2	58.8	83.5	90.3
Dual encoder + Fusion encoder													
ALBEF (Li et al., 2021)	233M	94.1	99.5	99.7	82.8	96.3	98.1	77.6	94.3	97.2	60.7	84.3	90.5
BLIP (Li et al., 2022)	446M	97.1	100.0	100.0	86.7	97.3	98.7	82.4	95.4	97.9	65.1	86.3	91.8
BLIP-2 w/ ViT-L (Li et al., 2023)	474M	96.9	100.0	100.0	88.6	97.6	98.9	83.5	96.0	98.0	66.3	86.5	91.8
BLIP-2 w/ ViT-g (Li et al., 2023)	1.2B	97.6	100.0	100.0	89.7	98.1	98.9	85.4	97.0	98.5	68.3	87.7	92.6
Ours													
M3-JEPA	140 M	97.8	100.0	100.0	97.8	100.0	100.0	87.7	99.6	99.9	89.7	99.7	99.9

- M3-Jepa achieves SOTA performance on Filicker30K and COCO
- M3-Jepa has good computation efficiency (140M trainable parameters)

M3-JEPA adapts to new modalities and generalizes well to different domains

Table 2. Audio-text retrieval results. Results of AVFIC, ImageBind and VALOR are obtained from Zhu et al. (2024) directly. We download the original model of LanguageBind and evaluate it by ourselves to collect the results of all metrics.

Audio-Language Retrieval

		Clotho					Audiocaps					
Method	Aı	udio → ′	Гехt	Te	$xt \rightarrow Au$	ıdio	Aı	ıdio → ˈ	Гехt	Te	$xt \rightarrow Au$	ıdio
	R@1	R@5	R@10	R@1	R@5	R@10	R@1	R@5	R@10	R@1	R@5	R@10
AVFIC (Nagrani et al., 2022)	-	-	-	3.0	-	17.5	-	-	-	8.7	-	37.7
ImageBind (Girdhar et al., 2023)	-	-	-	6.0	-	28.4	-	-	-	9.3	-	42.3
VALOR (Liu et al., 2025)	-	-	-	8.4	-	-	-	-	-	-	-	-
LanguageBind (Zhu et al., 2024) M3-JEPA (ours)	16.1 17.0	39.9 40.8	53.2 53.0	15.5 20.1	38.6 45.2	51.7 58.7	17.8 20.4	47.3 50.8	64.0 66.6	16.5 19.8	48.7 51.4	64.6 66.8

- M3-Jepa has good zero-shot performance on audio-language retrieval
- Generalized on unseen datasets (Clotho and Audiocaps)

Table 3. Image classification results on ImageNet-1K. All results are in percentage.

Method	Accuracy	Precision	Recall	F1 score
CLIP-ViT (Radford et al., 2021)	82.1	82.4	82.0	82.0
DinoV2 (Oquab et al., 2025)	83.2	83.5	83.3	83.1
M3-JEPA (ours)	86.6	86.9	86.6	86.5

lmage Classification

- For image classification, we treat the image label as a new modality
- Encode by one-hot
- M3-Jepa still surpasses the baseline

M3-JEPA can deal with multiple modalities on input or output

NLVR-2

86.8

82.5

87.6

Table 4. VQA scores on VQAv2 and NLVR-2. For each test set, the bold number indicates the best result and the underlined number indicates the second best.

VOAv2

Method	, 4		112	, IC 2
Monod	test-dev	test-std	dev	test-P
ALBEF (Li et al., 2021)	75.8	76.0	82.6	83.14
BLIP (Li et al., 2022)	78.3	78.3	82.2	82.2
X-VLM (Zeng et al., 2022)	78.2	78.4	84.4	84.8
SimVLM (Wang et al., 2022b)	80.0	80.3	84.5	85.2
OFA (Wang et al., 2022a)	82.0	82.0	-	-
Flamingo (Alayrac et al., 2022)	82.0	82.1	-	-
CoCa (Yu et al., 2022)	82.3	82.3	86.1	87.0
BLIP-2 (Li et al., 2023)	82.2	82.3	-	-
BEiT-3 (Wang et al., 2023b)	84.2	84.0	91.5	92.6

82.3

- For VQA, we simply concatenate the embedding of vision and text as the input encoding
- M3-JEPA performs the second best on VQA and NLVR-2
- Better encoding fusion approaches should be explored

A typical case:



M3-JEPA (ours)

Question	Answer	Score
What kind of horse is this?	brown and white	0.6
what kind of horse is this:	clydesdale	1.0
	others	0.0
	1	1.0
How many horses are in the picture?	others	0.0
	5	0.9
	10	0.3
II	4	0.3
How many steps to the building?	6	0.3
	20	0.9
	others	0.0

M3-Jepa correctly answer the questions of horse, but fail to recognize the staircase accurately

VQA

Ablation & sensitivity

Table 5. Ablation of the M3-JEPA approach on COCO.

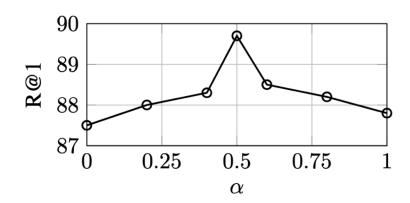
MoE AGD		In	$age \rightarrow 7$	Гехt	$Text \rightarrow Image$			
WICE	TIOD	R@1	R@5	R@10	R@1	R@5	R@10	
×	✓	74.4	86.0	92.2	82.3	89.5	92.6	
\checkmark	×	68.2	68.7	81.1	74.2	88.7	92.4	
✓	✓	87.7	99.6	99.9	89.7	99.7	99.9	

Both MoE and AGD contribute positively to the performance

Table 6. Ablation of modality encoder finetuning on COCO.

Approach	In	nage → T	Text	$Text \rightarrow Image$			
	R@1	R@5	R@10	R@1	R@5	R@10	
freeze	75.4	88.6	94.5	84.3	90.1	97.8	
3-layer LoRA	87.7	99.6	99.9	89.7	99.7	99.9	
full-layer LoRA	92.1	99.4	99.9	91.1	99.8	99.9	

- Training with full-layer LoRA on encoders further improves the result
- Formally use N=3 layers LoRA considering the efficiency



- Empirical results indicate equal weights of CL and Pred losses are optimal
- And this is also consistent with the theoretical result!



We choose n=12 and k=4

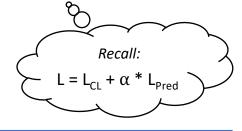


Table 8. Ablation of n on the validation set of VQAvq2. The reported score is the accuracy of VQA answers.

		_	
n	2	8	12
score	55.15	59.84	68.03

Table 9. Ablation of k on COCO. The reported metric is R@1.

$\frac{-}{k}$	Flick	r30K	COCO			
	$\overline{\text{Image} \rightarrow \text{Text}}$	$Text \rightarrow Image$	Image → Text	$\overline{\text{Text} \rightarrow \text{Image}}$		
2	96.0	95.5	85.0	82.0		
4	89.7	87.9	97.8	97.8		
6	88.0	86.5	97.5	97.0		

The efficiency analysis

Training

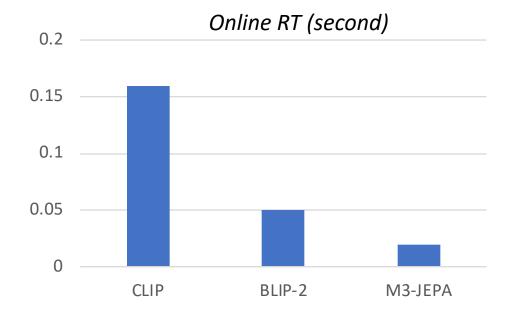
- M3-JEPA has relatively large sizes of modality encoders
- But we only finetune the MoE predictor (maybe also several layers of modality encoders
- M3-JEPA has much fewer # of trainable than baselines

Inference

- M3-JEPA can be fast if modality precomputing and online cache are allowed
- For dynamic inputs (e.g. user-provided input), M3-JEPA's latency is dominated by the modality encoder inference

Table 7. Parameter statistics of vision-language methodologies.

Method	# total parameter	# trainable parameter
CLIP	428M	the same
ALIGN	820M	the same
FLIP	417M	the same
BEiT-3	1.9B	the same
UNITER	303M	the same
OSCAR	345M	the same
BLIP-2	4.1B	474M
M3-JEPA	8.5B	140 M





Takeaways & Future Works

Conclusion

- M3-JEPA applies JEPA on multi-modal learning by implementing a multi-gate MoE aligner
- M3-JEPA achieves SOTA performance with vision, language & audio related tasks
- M3-JEPA can generalize to broader scenarios
- Scalable: various modalities with a unified architecture
- Generalizable: consistent performance across unseen tasks and domains
- Efficient: small amount of trainable parameters

Future work

- Better modality fusion encoding strategy
- Expand to generative tasks
- Embodied tasks; robotics; world model