

**NC STATE
UNIVERSITY**



Keio University



Modulated Diffusion: Accelerating Generative Modeling with Modulated Quantization

Weizhi Gao¹, Zhichao Hou¹, Junqi Yin², Feiyi Wang², Linyu Peng³, Xiaorui Liu¹
¹North Carolina State University, ²Oak Ridge National Lab, ³Keio University



ICML

International Conference
On Machine Learning



Problem and Challenges

Diffusion Models. Diffusion models consist of a forward process and a backward process, operating over T steps -- **Expensive**.

Forward Process: adding noise for training



Reverse Process: predicting noise for generation



Post-Training Quantization. Quantization reduces the inference cost of models by utilizing low-precision integers. Post-Training Quantization (PTQ) post process models -- **Activation Bottleneck**.

Quantize: converting floating numbers to integers

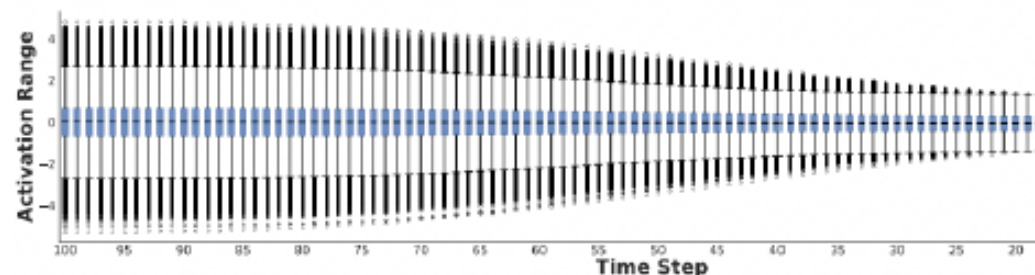
$$x_{int} = \text{clamp}\left(\left\lfloor \frac{x}{s} \right\rfloor + z; 0, 2^b - 1\right)$$

Dequantize: converting integers to floating numbers

$$Q(x) = s(x_{int} - z)$$

- The range of activations is *dynamic* in time step and instance.
- The activations is *long-tailed*.

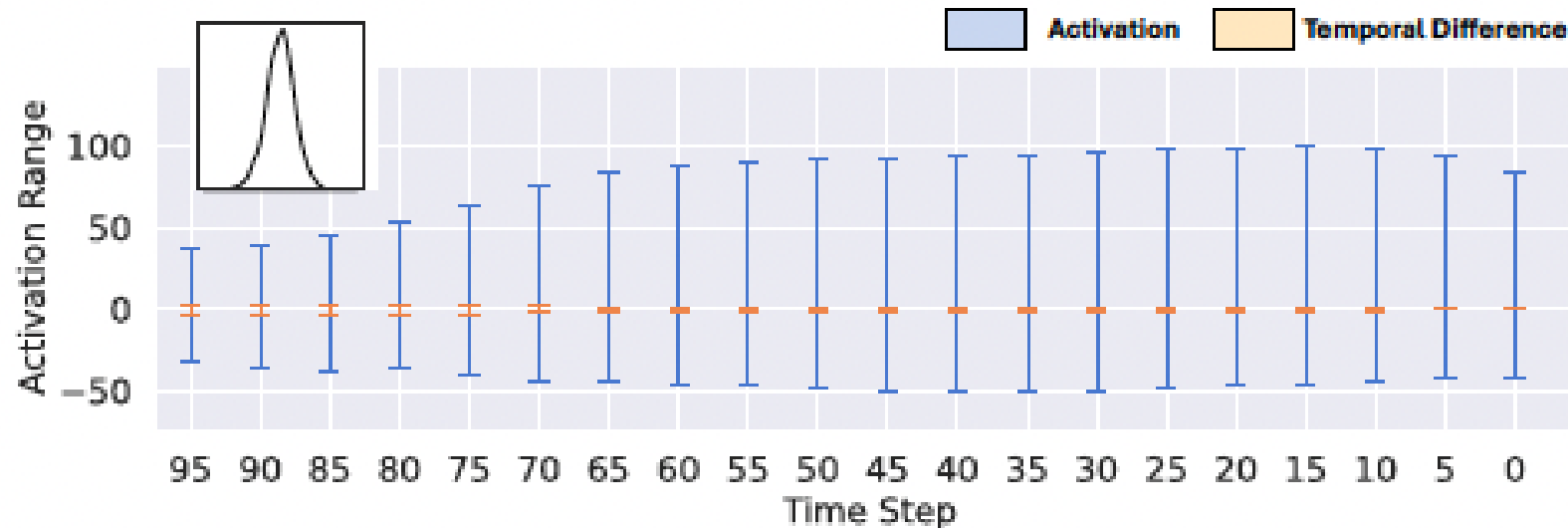
[1]



The mismatch between the weights and activations limits the acceleration of quantization on hardware (for instance, W4A8)

Preliminary Studies and Motivation

Redundancy across Time Steps. The temporal differences ($\mathbf{a}_t^{(l)} - \mathbf{a}_{t-1}^{(l)}$) of activations present concentrated and unified distribution compared to the raw activation ($\mathbf{a}_t^{(l)}$) at layer l in time step t .



Motivation. Make use of the redundancy among time steps for better quantization acceleration – towards aligned and low bits.

Method: Modulated Quantization

Modulated Quantization. We reformulate the linear operators, such as linear layers and convolutional layers, then we propose a unified framework, MoDiff, that inheriting the advantages of quantization and caching methods, compatible to different solvers.

Reformulation:

$$\begin{aligned}
 \mathbf{o}_T^{(l)} &= \mathcal{A}^{(l)}(\mathbf{a}_T^{(l)}) \\
 \mathbf{o}_{T-1}^{(l)} &= \mathcal{A}^{(l)}(\mathbf{a}_{T-1}^{(l)}) = \mathcal{A}^{(l)}(\mathbf{a}_{T-1}^{(l)} - \mathbf{a}_T^{(l)}) + \mathbf{o}_T^{(l)} \\
 &\dots \\
 \mathbf{o}_t^{(l)} &= \mathcal{A}^{(l)}(\mathbf{a}_t^{(l)}) = \mathcal{A}^{(l)}(\mathbf{a}_t^{(l)} - \mathbf{a}_{t+1}^{(l)}) + \mathbf{o}_{t+1}^{(l)} \\
 &\dots \\
 \mathbf{o}_1^{(l)} &= \mathcal{A}^{(l)}(\mathbf{a}_1^{(l)}) = \mathcal{A}^{(l)}(\mathbf{a}_1^{(l)} - \mathbf{a}_2^{(l)}) + \mathbf{o}_2^{(l)}
 \end{aligned}$$

Since we make use of the linearity of \mathcal{A}

$$\begin{aligned}
 \mathcal{A}^{(l)}(\mathbf{a}_t^{(l)}) &= \mathcal{A}^{(l)}(\mathbf{a}_t^{(l)}) - \mathcal{A}^{(l)}(\mathbf{a}_{t+1}^{(l)}) + \mathcal{A}^{(l)}(\mathbf{a}_{t+1}^{(l)}) \\
 &= \mathcal{A}^{(l)}(\mathbf{a}_t^{(l)} - \mathbf{a}_{t+1}^{(l)}) + \mathbf{o}_{t+1}^{(l)}.
 \end{aligned}$$

Quantization:

$$\begin{aligned}
 \hat{\mathbf{o}}_T &= \mathcal{A}\left(Q(\mathbf{a}_T)\right) \approx \mathcal{A}(\mathbf{a}_T) \\
 \hat{\mathbf{o}}_{T-1} &= \mathcal{A}\left(Q(\mathbf{a}_{T-1} - \mathbf{a}_T)\right) + \hat{\mathbf{o}}_T \approx \mathcal{A}(\mathbf{a}_{T-1}) \\
 &\dots \\
 \hat{\mathbf{o}}_t &= \mathcal{A}\left(Q(\mathbf{a}_t - \mathbf{a}_{t+1})\right) + \hat{\mathbf{o}}_{t+1} \approx \mathcal{A}(\mathbf{a}_t) \\
 &\dots \\
 \hat{\mathbf{o}}_1 &= \mathcal{A}\left(Q(\mathbf{a}_1 - \mathbf{a}_2)\right) + \hat{\mathbf{o}}_2 \approx \mathcal{A}(\mathbf{a}_1)
 \end{aligned}$$

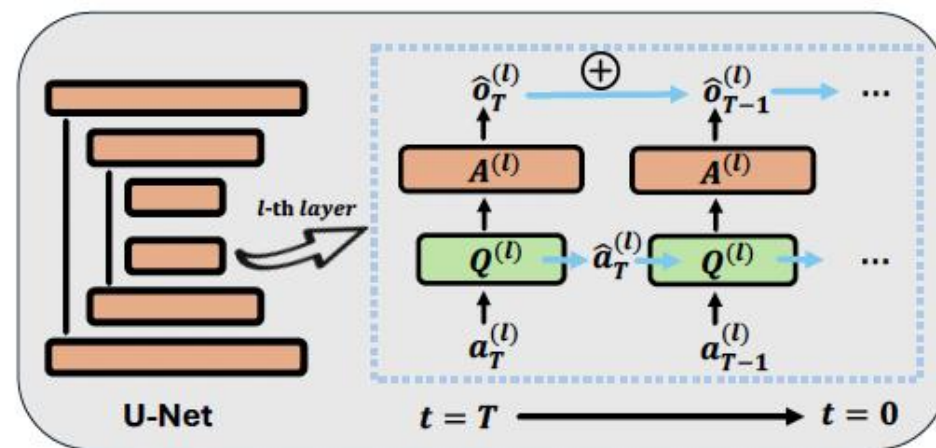
Method: Error-Compensated Modulation

Error-Compensated Modulation. Trace quantization error to reduce the error accumulation in modulated quantization.

$$\begin{aligned}
 \hat{\mathbf{a}}_T &= Q(\mathbf{a}_T) \\
 \hat{\mathbf{o}}_T &= \mathcal{A}(\hat{\mathbf{a}}_T) \\
 \hat{\mathbf{a}}_{T-1} &= Q(\mathbf{a}_{T-1} - \hat{\mathbf{a}}_T) + \hat{\mathbf{a}}_T \\
 \hat{\mathbf{o}}_{T-1} &= \mathcal{A}(\hat{\mathbf{a}}_{T-1}) = \mathcal{A}\left(Q(\mathbf{a}_{T-1} - \hat{\mathbf{a}}_T)\right) + \hat{\mathbf{o}}_T \\
 &\dots \\
 \hat{\mathbf{a}}_t &= Q(\mathbf{a}_t - \hat{\mathbf{a}}_{t+1}) + \hat{\mathbf{a}}_{t+1} \\
 \hat{\mathbf{o}}_t &= \mathcal{A}(\hat{\mathbf{a}}_t) = \mathcal{A}\left(Q(\mathbf{a}_t - \hat{\mathbf{a}}_{t+1})\right) + \hat{\mathbf{o}}_{t+1} \\
 &\dots \\
 \hat{\mathbf{a}}_1 &= Q(\mathbf{a}_1 - \hat{\mathbf{a}}_2) + \hat{\mathbf{a}}_2 \\
 \hat{\mathbf{o}}_1 &= \mathcal{A}(\hat{\mathbf{a}}_1) = \mathcal{A}\left(Q(\mathbf{a}_1 - \hat{\mathbf{a}}_2)\right) + \hat{\mathbf{o}}_2
 \end{aligned}$$

Implicitly trace quantization error of modulated quantization.

$$\begin{aligned}
 \mathbf{e}_t &= (\mathbf{a}_t - \hat{\mathbf{a}}_{t+1}) - Q(\mathbf{a}_t - \hat{\mathbf{a}}_{t+1}) \\
 &= (\mathbf{a}_t - \hat{\mathbf{a}}_{t+1}) - (\hat{\mathbf{a}}_t - \hat{\mathbf{a}}_{t+1}) = \mathbf{a}_t - \hat{\mathbf{a}}_t
 \end{aligned}$$



- Theory 1: modulated quantization introduces smaller quantization error by reducing the magnitude of inputs.
- Theory 2: error compensation reduce the accumulated quantization error in an exponential ratio.
- Caching methods are the special cases with 0 bits.
- Our work is **orthogonal** to existing PTQ methods.

Experimental Results and Visualization

LDM-4 on LSUN-Church

Methods	Bits (W/A)	GBops	FID ↓	sFID ↓
Full Prec. (Act)	8/32	5015	4.03	10.89
Q-Diff	8/8	1254	4.24	10.57
Q-Diff+MoDiff (Ours)			3.85	10.82
LCQ			4.02	11.53
LCQ+MoDiff (Ours)			3.99	10.06
Q-Diff	8/6	1254	55.13	30.98
Q-Diff+MoDiff (Ours)			5.43	13.41
LCQ			4.50	12.90
LCQ+MoDiff (Ours)			3.89	10.12
Q-Diff	8/4	1254	355.85	187.56
Q-Diff+MoDiff (Ours)			3.97	11.16
LCQ			198.37	161.03
LCQ+MoDiff (Ours)			34.02	10.59
Q-Diff	8/3	1254	367.51	354.59
Q-Diff+MoDiff (Ours)			5.40	13.81
LCQ			341.62	407.68
LCQ+MoDiff (Ours)			12.05	35.29

Visualization of LSUN-Church (W4A4)
and MS-COCO (W8A6)



Dynamic Quantization



Dynamic Quantization
+MoDiff (ours)



Thanks for your attention!