

# A Differentiable POGLM with Forward-Backward Message Passing

Chengrui Li, Weihan Li, Yule Wang, Anqi Wu @ GaTech CSE



# Contents

1. Partially observable generalized linear model (POGLM)
2. Variational inference (VI)
  - Inference methods
  - Sampling schemes
3. Experiments



# 1 Partially observable generalized linear model (POGLM)



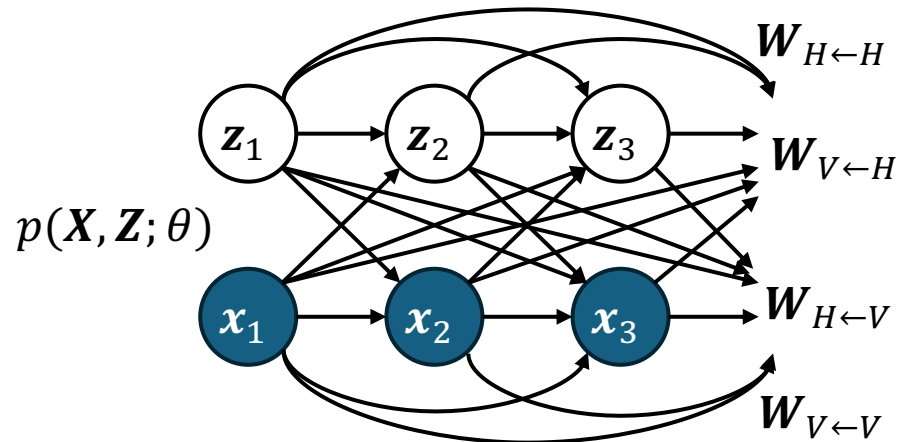
# Introduction

- The partially observable generalized linear model (POGLM) is a powerful tool for understanding neural connectivity under the assumption of existing hidden neurons.
- POGLM itself is a difficult problem.
- Two main issues and our contributions:
  - The gradient estimator used in variational inference (VI).
  - The sampling scheme of the variational model.
- Comprehensive experiments on one synthetic and two real-world datasets.



# POGLM

- $V$  visible neurons and  $H = N - V$  hidden neurons.



visible/hidden spike counts  $\begin{bmatrix} \mathbf{x}_t \\ \mathbf{z}_t \end{bmatrix} \sim \text{Pois} \left( \begin{bmatrix} \mathbf{f}_t \\ \mathbf{g}_t \end{bmatrix} \right)$  visible/hidden firing rates

$$\begin{bmatrix} \mathbf{f}_t \\ \mathbf{g}_t \end{bmatrix} = \sigma \left( \begin{bmatrix} \mathbf{b}_V \\ \mathbf{b}_H \end{bmatrix} + \begin{bmatrix} \mathbf{W}_{V \leftarrow V} & \mathbf{W}_{V \leftarrow H} \\ \mathbf{W}_{H \leftarrow V} & \mathbf{W}_{H \leftarrow H} \end{bmatrix} \left( \sum_{l=1}^L \psi_l \begin{bmatrix} \mathbf{x}_{t-l} \\ \mathbf{z}_{t-l} \end{bmatrix} \right) \right)$$

bias                      weight                      convolved history

- Observed variable: visible spike train  $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_T]^T \in \mathbb{N}^{T \times V}$ .
- Latent variable: hidden spike train  $\mathbf{Z} = [\mathbf{z}_1, \dots, \mathbf{z}_T]^T \in \mathbb{N}^{T \times H}$ .
- Generative parameter set:  $\theta = \{ \mathbf{b} \in \mathbb{R}^{V+H}, \mathbf{W} \in \mathbb{R}^{(V+H) \times (V+H)} \}$ .



# 2 Variational inference (VI)



# Variational inference (VI)

- Variational model  $q(\mathbf{Z}|\mathbf{X}; \phi)$  parameterized by  $\phi$ .
- **Inference methods:**  $\mathbf{z}_t \sim \text{Pois}(\mathbf{g}_t)$ .
- **Sampling schemes:**  $\mathbf{g}_t = \text{function}(\mathbf{X}; \phi)$ .
- Evidence lower bound:

$$\text{ELBO}(\mathbf{X}; \theta, \phi) = \mathbb{E}_q[\ln p(\mathbf{X}, \mathbf{Z}; \theta) - \ln q(\mathbf{Z}|\mathbf{X}; \phi)]$$



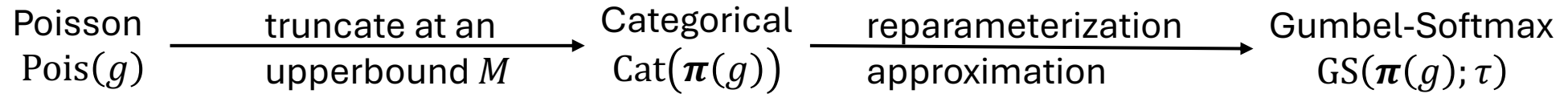
# Inference methods: Gradient estimators

	score function	pathwise
distribution	any distribution	continuous distribution with reparameterization trick $\mathbf{Z} \mathbf{X}; \phi = r(\boldsymbol{\epsilon} \mathbf{X}; \phi)$
samples	$\{\mathbf{Z}^{(k)}\}_{k=1}^K \sim q(\mathbf{Z} \mathbf{X}; \phi)$	$\{\boldsymbol{\epsilon}^{(k)}\}_{k=1}^K \sim R(\boldsymbol{\epsilon})$
$\frac{\partial \text{ELBO}(\mathbf{X}; \theta, \phi)}{\partial \phi} \approx$	$\frac{\partial}{\partial \phi} \frac{-1}{2K} \sum_{k=1}^K [\ln p(\mathbf{X}, \mathbf{Z}^{(k)}; \theta) - \ln q(\mathbf{Z}^{(k)} \mathbf{X}; \phi)]$	$\frac{\partial}{\partial \phi} \frac{1}{K} \sum_{k=1}^K [\ln p(\mathbf{X}, r(\boldsymbol{\epsilon}^{(k)} \mathbf{X}; \phi); \theta) - \ln q(r(\boldsymbol{\epsilon}^{(k)} \mathbf{X}; \phi) \mathbf{X}; \phi)]$





# Inference methods: Relaxation



- Truncation:

$$\boldsymbol{\pi}(g) = \left( 1 - \sum_{m=1}^{M-1} \frac{g^m e^{-g}}{m!}, \frac{g^1 e^{-g}}{1!}, \dots, \frac{g^{M-1} e^{-g}}{(M-1)!} \right)$$

- Gumbel-Softmax soft spike:

$$\tilde{\mathbf{z}}_{t,h} = (\tilde{z}_{t,h,0}, \dots, \tilde{z}_{t,h,M-1}) \sim \text{GS}(\boldsymbol{\pi}(g_{t,h}); \tau)$$

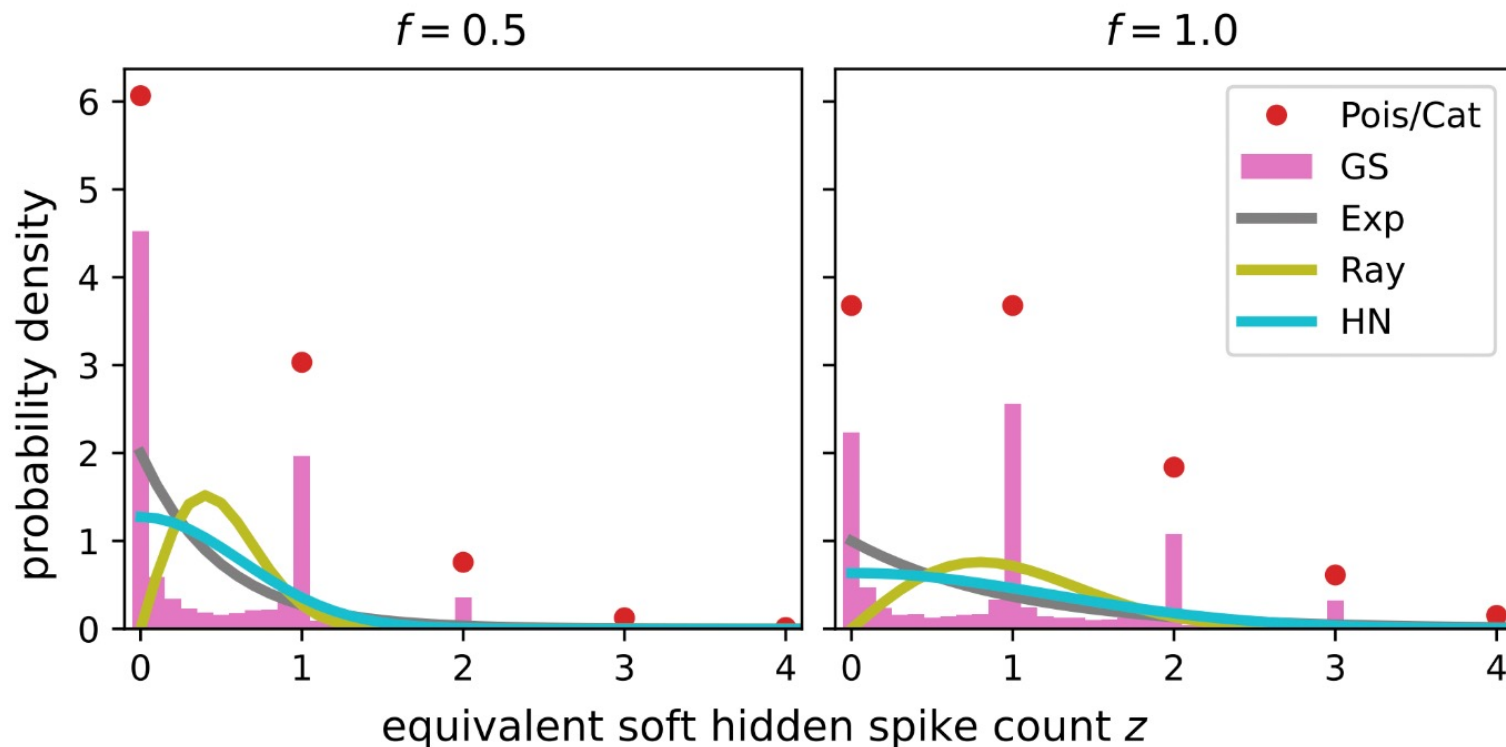
- Equivalent soft spike count:

$$z_{t,h} = \sum_{m=0}^{M-1} m \cdot \tilde{z}_{t,h,m}$$



# Inference methods: Candidate distributions

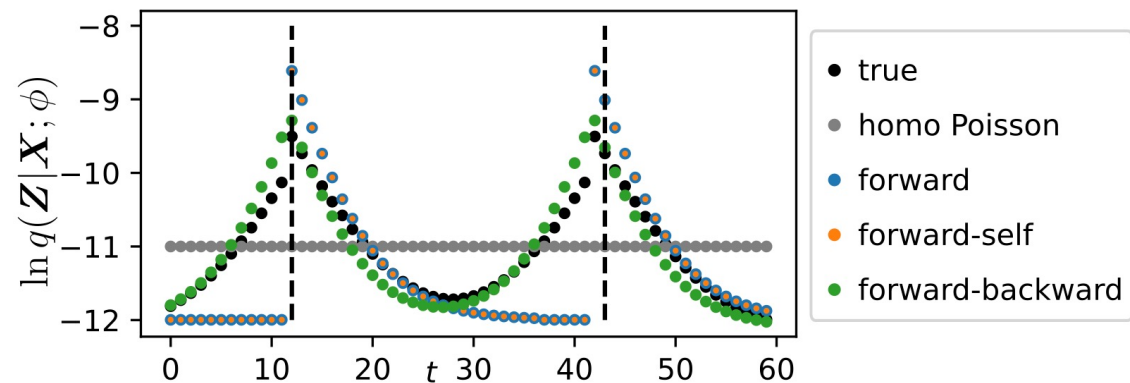
- Replace the distribution  $\mathbb{P}[z; g]$  in the generative and variational model with the following distributions governed by  $\mathbb{E}[z] = g$ .



distribution	can pathwise
$\text{Pois}(g)$	X
$\text{Cat}(\boldsymbol{\pi}(g))$	X
$\text{GS}(\boldsymbol{\pi}(g); \tau)$	✓
$\text{Exp}\left(\frac{1}{g}\right)$	✓
$\text{Ray}\left(\sqrt{\frac{2}{\pi}}g\right)$	✓
$\text{HN}\left(\sqrt{\frac{\pi}{2}}g\right)$	✓



# Sampling schemes



- Three message passing designs where  $\mathbf{c}$  mimicking the bias  $\mathbf{b}$ , and  $\mathbf{A}$  mimicking the weight  $\mathbf{W}$ .

- Forward-self (FS)

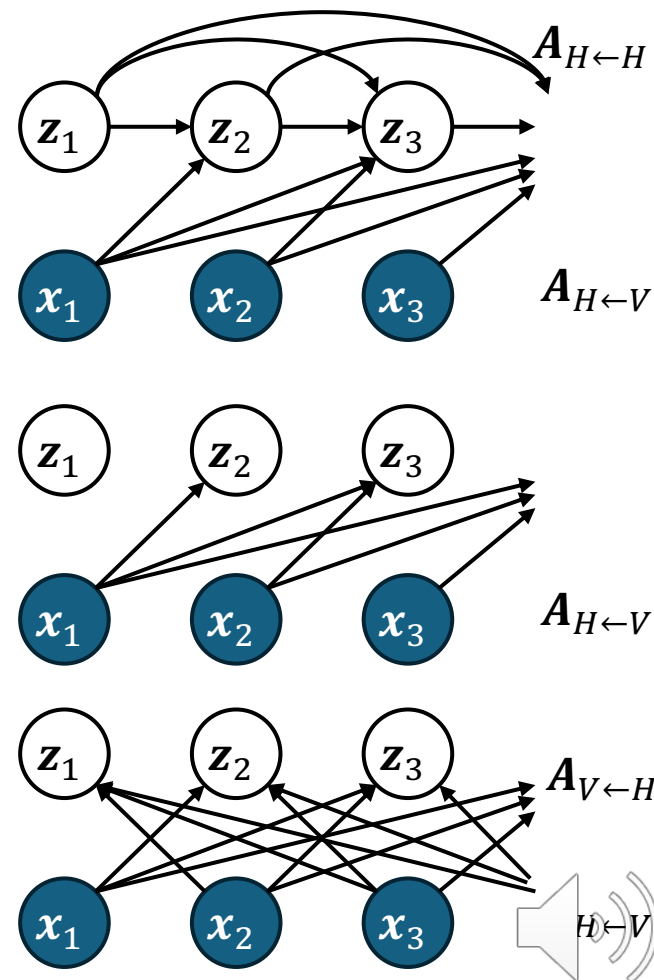
- $\mathbf{g}_t = \sigma \left( \mathbf{c}_H + \mathbf{A}_{H \leftarrow V} \left( \sum_{l=1}^L \psi_l \mathbf{x}_{t-l} \right) + \mathbf{A}_{H \leftarrow H} \left( \sum_{l=1}^L \psi_l \mathbf{z}_{t-l} \right) \right)$
- $\phi = \{ \mathbf{c}_H \in \mathbb{R}^H, \mathbf{A}_{H \leftarrow V} \in \mathbb{R}^{H \times V}, \mathbf{A}_{H \leftarrow H} \in \mathbb{R}^{H \times H} \}$

- Forward (F)

- $\mathbf{g}_t = \sigma \left( \mathbf{c}_H + \mathbf{A}_{H \leftarrow V} \left( \sum_{l=1}^L \psi_l \mathbf{x}_{t-l} \right) \right)$
- $\phi = \{ \mathbf{c}_H \in \mathbb{R}^H, \mathbf{A}_{H \leftarrow V} \in \mathbb{R}^{H \times V} \}$

- Forward-backward (FB)

- $\mathbf{g}_t = \sigma \left( \mathbf{c}_H + \mathbf{A}_{H \leftarrow V} \left( \sum_{l=1}^L \psi_l \mathbf{x}_{t-l} \right) + \mathbf{A}_{V \leftarrow H} \left( \sum_{l=1}^L \psi_l \mathbf{x}_{t+l} \right) \right)$
- $\phi = \{ \mathbf{c}_H \in \mathbb{R}^H, \mathbf{A}_{H \leftarrow V} \in \mathbb{R}^{H \times V}, \mathbf{A}_{V \leftarrow H} \in \mathbb{R}^{V \times H} \}$



# 3 Experiments



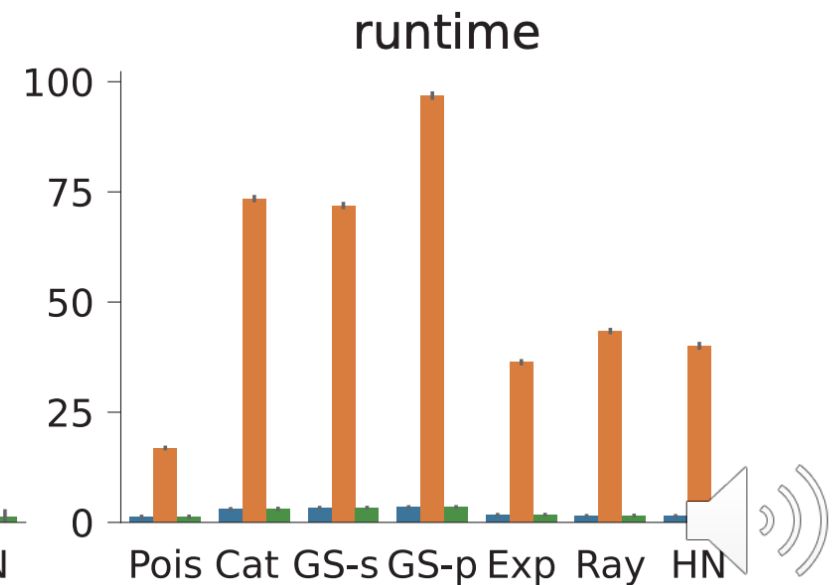
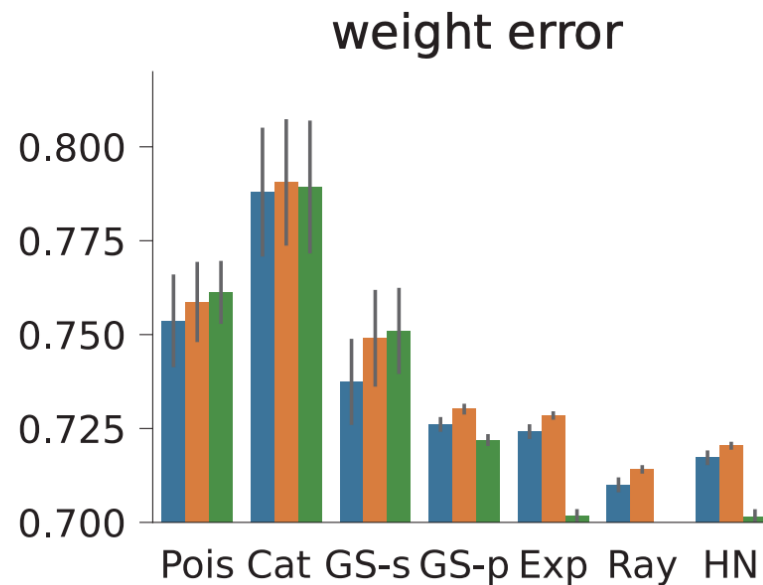
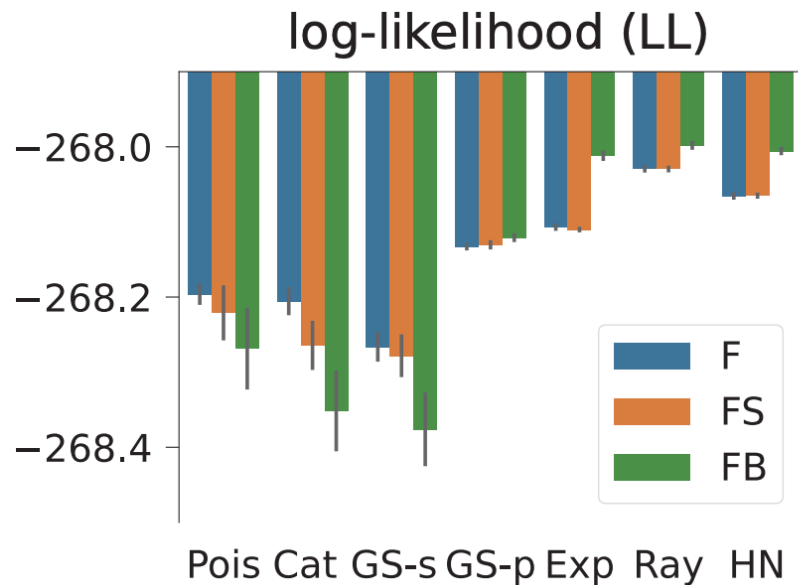
# Method combinations

- 7 inference methods
  - Poisson (Pois)
  - Categorical (Cat)
  - Gumbel-Softmax-score (GS-s)
  - Gumbel-Softmax-pathwise (GS-p)
  - Exponential (Exp)
  - Rayleigh (Ray)
  - Half-normal (HN)
- 3 variational sampling schemes
  - Forward (F)
  - Forward-self (FS)
  - Forward-backward (FB)



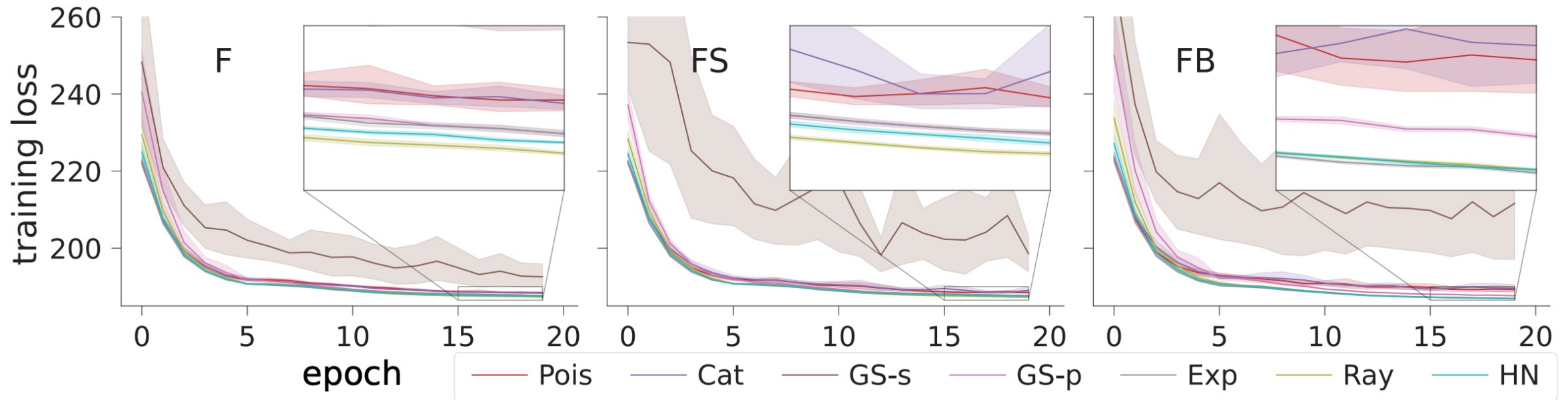
# Synthetic

- 3-visible-2-hidden.
- High likelihood and low weight error for differentiable inference methods (GS-pathwise, Exp, Ray, HN) with FB sampling schemes.
- Fast runtime for forward (F) and forward-backward (FB).



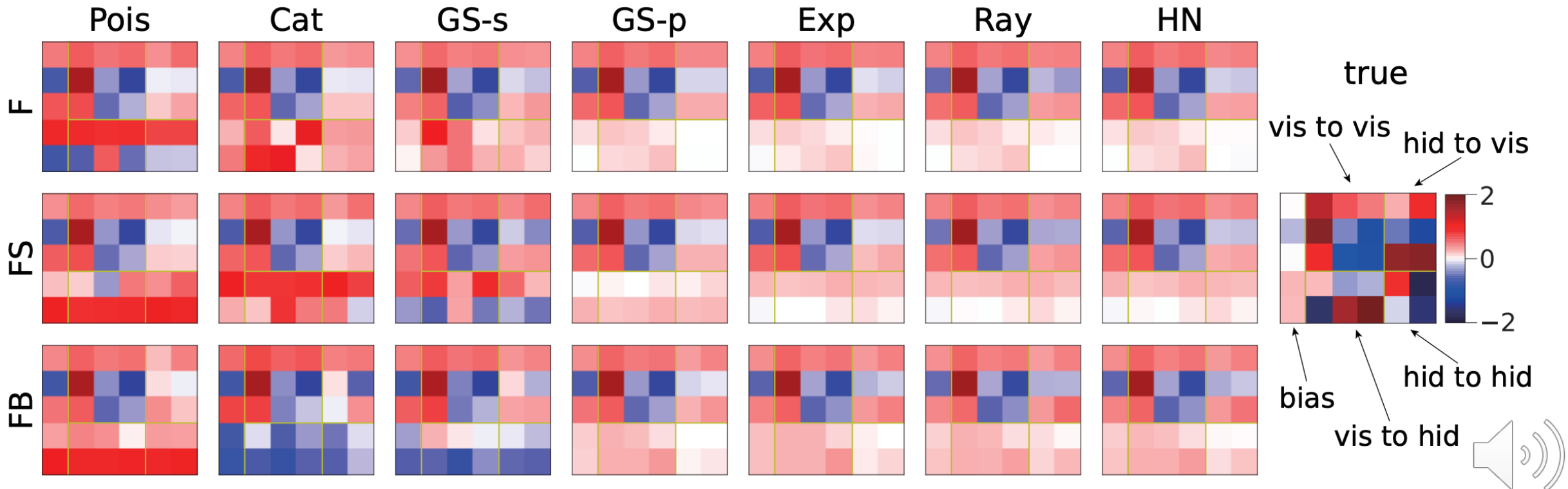
# Synthetic

- Better convergence for differentiable inference methods.



# Synthetic

- Differentiable inference methods  $\times$  FB have better parameter estimation, especially in the hidden to visible block.





# Retinal ganglion neurons (Pillow & Scott, 2012)

- Neuron 1-16: OFF cell. Neuron 17-27: ON cell.
- 20 minutes of a visual task on a mouse.
- Assuming  $H \in \{1,2,3\}$  hidden neurons.

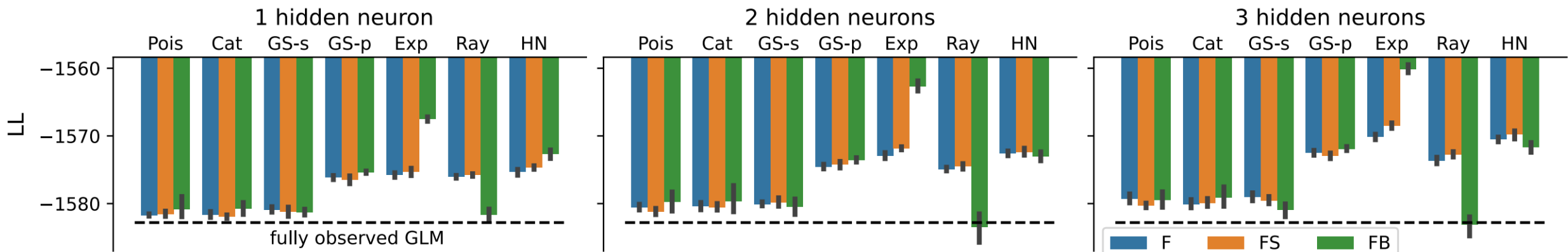
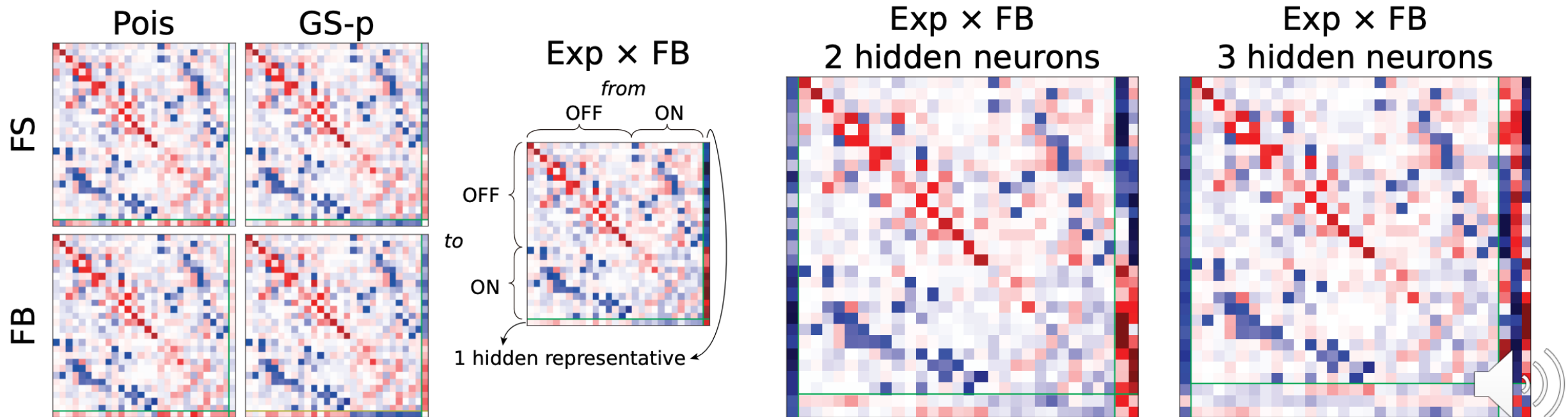


Figure 5. The test log-likelihood (LL) of different method combinations under  $H \in \{1, 2, 3\}$  hidden neurons. The dashed black line represents the test LL of the fully observed GLM as the baseline.



# Retinal ganglion neurons (Pillow & Scott, 2012)

- The learned weight matrix.
- The learned one hidden representative from  $\text{Exp} \times \text{FB}$  serves as a negative feed back regulating unit.



# Primary visual cortex (cnrcs: PVC-5)

- Primary visual cortex (V1) recordings from a macaque monkey over a 15-minute duration without presenting any stimuli.
- Only 3 visible neurons
- Assuming  $H \in \{1, \dots, 9\}$  hidden neurons. Containing cases where  $H \gg V$ .

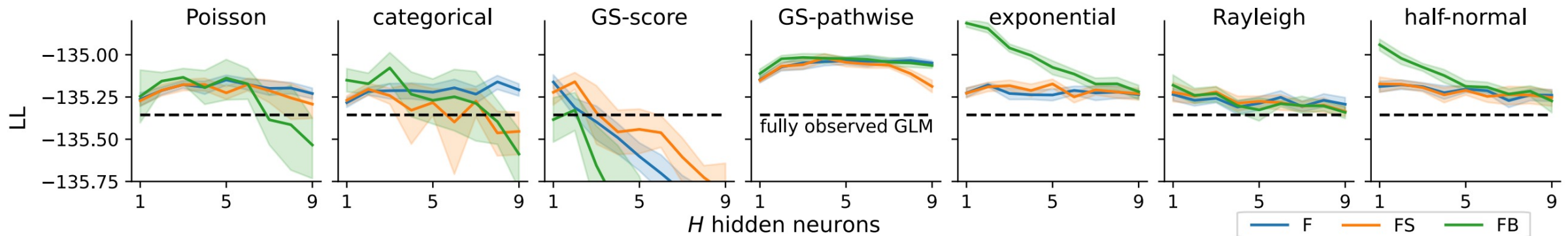


Figure 7. The curves of the test log-likelihood (LL) v.s. the number of hidden neurons  $H$ , for different method combinations.



# Summary

- We propose a differentiable version of the partially observable generalized linear model (POGLM), in which the pathwise gradient estimator becomes applicable when doing variational inference (VI).
- The new forward-backward message passing sampling scheme is faster and more expressive.
- Note that the relaxation from Gumbel-Softmax distribution to general continuous distributions loses the meaning of  $\mathbf{Z}$  as representing spike counts, but can produce better performance. This is worth to be investigated in the future.



**Thanks for listening!**

