

On Positivity Condition for Causal Inference

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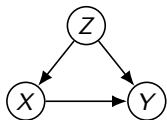
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- Identifying and estimating a **causal effect** is a fundamental task when inferring a causal effect using observational study *without experiments*.
- Just assuming the **strict positivity** ($P(\mathbf{V}) > 0$) of the given distribution under the unconfounded assumption has been a long convention.
- We examine the graphical counterpart of the conventional positivity condition to license the use of identification formula **without strict positivity**.

Motivating Example 1

Backdoor formula:



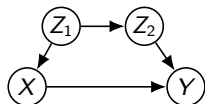
$$P_x(y) = \sum_z P(y | x, z)P(z)$$
$$\Rightarrow \forall \mathbf{z}(P(\mathbf{z}) = 0 \vee P(x | \mathbf{z}) > 0) \equiv \text{adj}(\mathbf{x}; \mathbf{Z})$$

- Under **the strict positivity**, we can identify the causal effect—i.e., we can get the intervened distribution of y ($P_x(y)$) from the observed distribution $P(\mathbf{V})$.
- To estimate average treatment effect for each value of the covariate in the population, there are some subjects that received the treatment—i.e., $P(X | \mathbf{z}) > 0$ for all \mathbf{z} with $P(\mathbf{z}) \neq 0$ (Hernán & Robins, 2006).

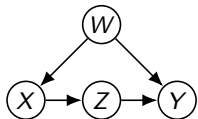
Motivating Example 2

Multiplicity of identification formulae and conditions:

- One may estimate the causal effect with a formula but **not with the other**, which was **not the case** under **strict positivity**.



$$\sum_{z_1} P(y | x, z_1)P(z_1) \quad \text{or} \quad \sum_{z_2} P(y | x, z_2)P(z_2)$$



$$P_x(y) = \sum_w P(y | x, w)P(w) \quad \text{Backdoor}$$

$$P_x(y) = \sum_z P(z) \sum_{x'} P(y | x', z)P(x') \quad \text{Front-door}$$

$$P_x(y) = \sum_z P(z | x)P(y | z, w) \quad \text{IDENTIFY}$$

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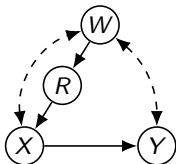
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Causal Identification with Strict Positivity

- The causal effect $P_x(y)$ is **identifiable** if it can be uniquely computed from $P(\mathbf{V})$ in any causal model which induces \mathcal{G} .
- How to identify $P_x(y)$?
 - 1 Do-calculus (Pearl, 1995)
 - 2 Q-decomposition (Tian, 2003)

⇒ These well-known methods of identification heavily rely on $P(\mathbf{V}) > 0$.

⇒ Their validity and mathematical correctness are unclear under **relaxed positivity**.
- e.g., Napkin



$$P_x(y) = \frac{\sum_w P(y, x | r, w) P(w)}{\sum_w P(x | r, w) P(w)}$$

Do-calculus with Strict Positivity

- This calculus (Pearl, 1995) facilitates the identification of causal effects in non-parametric models.
- The following transformation are valid for any **positive** do-distribution induced by a model:

Definition (do-calculus)

- Rule 1 (addition/deletion of observation):
$$P_{\mathbf{x}}(\mathbf{y} \mid \mathbf{z}, \mathbf{w}) = P_{\mathbf{x}}(\mathbf{y} \mid \mathbf{w}) \text{ if } (\mathbf{Y} \perp\!\!\!\perp \mathbf{Z} \mid \mathbf{X}, \mathbf{W})_{\mathcal{G}_{\bar{\mathbf{x}}}}$$
- Rule 2 (exchange of action and observation):
$$P_{\mathbf{x},z}(\mathbf{y} \mid \mathbf{w}) = P_{\mathbf{x}}(\mathbf{y} \mid \mathbf{z}, \mathbf{w}) \text{ if } (\mathbf{Y} \perp\!\!\!\perp \mathbf{Z} \mid \mathbf{X}, \mathbf{W})_{\mathcal{G}_{\bar{\mathbf{x}}z}}$$
- Rule 3 (addition/deletion of action):
$$P_{\mathbf{x},z}(\mathbf{y} \mid \mathbf{w}) = P_{\mathbf{x}}(\mathbf{y} \mid \mathbf{w}) \text{ if } (\mathbf{Y} \perp\!\!\!\perp \mathbf{Z} \mid \mathbf{X}, \mathbf{W})_{\mathcal{G}_{\bar{\mathbf{x}}, \overline{z(\mathbf{w})}}},$$

where $\mathbf{Z}(\mathbf{W}) = \mathbf{Z} \setminus An(\mathbf{W})_{\mathcal{G}_{\bar{\mathbf{x}}}}$.

Q-decomposition with Strict Positivity

- c-factors derived from the given observational distribution $P(\mathbf{V})$ are used to answer the c-factors derived from the query $P_x(y)$ (Tian, 2003).

Theorem (Q-decomposition)

Given $\mathbf{H} \subseteq \mathbf{V}$, let $\mathbf{H}_1, \dots, \mathbf{H}_k$ be the c-components of $\mathcal{G}[\mathbf{H}]$. Let \prec be a topological order over the variables in \mathbf{H} according to $\mathcal{G}[\mathbf{H}]$ such that $V^{(1)} \prec V^{(2)} \dots \prec V^{(|\mathbf{H}|)}$. Let $\mathbf{H}^{\preceq i}$ be the variables in \mathbf{H} that come before $V^{(i)}$ including $V^{(i)}$. Let $\mathbf{H}^{\succ i}$ be the variables in \mathbf{H} that come after $V^{(i)}$.

Given $Q[\mathbf{H}] > 0$,

$$Q[\mathbf{H}_j] = \prod_{V^{(i)} \in \mathbf{H}_j} \frac{Q[\mathbf{H}^{\preceq i}]}{Q[\mathbf{H}^{\preceq i-1}]},$$

where $Q[\mathbf{H}^{\preceq i}] = \sum_{\mathbf{h}^{\succ i}} Q[\mathbf{H}]$.

$$\text{e.g., } Q[W, X, Y] = \frac{Q[W, R, X, Y]}{Q[W, R, X]} \cdot \frac{Q[W, R, X]}{Q[W, R]} \cdot \frac{Q[W]}{Q[\emptyset]}$$

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Post-hoc Analysis (Appendix)

- **We can examine** a **positivity condition** under which the identification formula is well-defined.
- e.g., Napkin

$$\exists r \frac{\sum_w P(y, x | r, w) P(w)}{\sum_w P(x | r, w) P(w)} \geq 0 \quad \Leftarrow \exists r (\textcircled{1} \geq 0 \wedge \textcircled{2} > 0)$$

$$\textcircled{1} \geq 0 \Leftarrow \text{adj}(r; W)$$

$$\textcircled{2} > 0 \Leftarrow \text{adj}(r; W) \wedge P(x, r) > 0$$

$$\therefore \exists r (\text{adj}(r; W) \wedge P(x, r) > 0)$$

- While it is true that the positivity condition derived directly from a formula ensures that the formula is well-defined, yet its validity is unclear for now since the formula is derived under strict positivity.
- Post-hoc analysis yields a sufficient positivity condition for the identification formula derived through **Identify+**.

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Causal Identification with Relaxed Positivity: Do-Calculus

We develop a general and principled approach for **deriving a positivity condition** by examining the conditions for do-calculus (Pearl, 1995).

Definition (Positivity Relaxed do-calculus)

Let \mathcal{G} be the directed acyclic graph (DAG) associated with a causal model, and let $P(\cdot)$ be the probability distribution induced by the model. Then,

- (R1) $P_{\mathbf{x}}(\mathbf{y} \mid \mathbf{z}, \mathbf{w}) = P_{\mathbf{x}}(\mathbf{y} \mid \mathbf{w})$ if $(\mathbf{Y} \perp\!\!\!\perp \mathbf{Z} \mid \mathbf{W})_{(\mathcal{G} \setminus \mathbf{x})}$ and $P_{\mathbf{x}}(\mathbf{z}, \mathbf{w}) > 0$
- (R2) $P_{\mathbf{x}, \mathbf{z}}(\mathbf{y} \mid \mathbf{w}) = P_{\mathbf{x}}(\mathbf{y} \mid \mathbf{z}, \mathbf{w})$ if $(\mathbf{Y} \perp\!\!\!\perp \mathbf{Z} \mid \mathbf{W})_{(\mathcal{G} \setminus \mathbf{x})_{\underline{\mathbf{z}}}}$ and $P_{\mathbf{x}}(\mathbf{z}, \mathbf{w}) > 0$
- (R3) $P_{\mathbf{x}, \mathbf{z}}(\mathbf{y} \mid \mathbf{w}) = P_{\mathbf{x}}(\mathbf{y} \mid \mathbf{w})$ if $(\mathbf{Y} \perp\!\!\!\perp \mathbf{Z} \mid \mathbf{W})_{(\mathcal{G} \setminus \mathbf{x})_{\overline{\mathbf{z}(\mathbf{w})}}}$ and $P_{\mathbf{x}}(\mathbf{w}) > 0$

e.g.,

$$\begin{aligned} P_{\mathbf{x}}(y) &= P_{w,r}(y \mid x) && \text{if } P_{w,r}(x) > 0 \\ &= P_{w,r}(y, x) / P_{w,r}(x) && \text{if } P_{w,r}(x) > 0 \\ &= \frac{\sum_{w'} P(y, x \mid r, w') P(w')}{\sum_{w'} P(x \mid r, w') P(w')} && \text{if } \text{adj}(r; W) \end{aligned}$$

$$\therefore \exists r(\text{adj}(r; W) \wedge P(x, r) > 0)$$

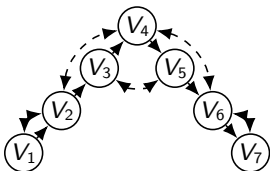
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Causal Identification with Relaxed Positivity: Q-Decomposition

- Given the theoretical underpinnings of the sufficient positivity conditions over do-calculus, we now investigate the feasibility of creating an identification algorithm capable of simultaneously taking a non-strictly positive observational distribution into account.
- The intuition behind the generalization is that the product of fractions often can be shortened by canceling out depending on the topological order.

Relaxed Q-decomposition Motivating Example



- $Q[\mathbf{H}] = Q[\mathbf{H}_1] \cdot Q[\mathbf{H}_2]$ where $\mathbf{H}_1 = \{V_1, V_2, V_4, V_6, V_7\}$ and $\mathbf{H}_2 = \{V_3, V_5\}$.
- Denoting $Q[\mathbf{H}^{\preceq i}]$ as Q_i for brevity, if $Q[\mathbf{H}] = Q_7 > 0$, then $Q[\mathbf{H}_1] = \frac{Q_7}{Q_6} \cdot \frac{Q_6}{Q_5} \cdot \frac{Q_4}{Q_3} \cdot \frac{Q_2}{Q_1} \cdot \frac{Q_1}{Q_0}$ and $Q[\mathbf{H}_2] = \frac{Q_5}{Q_4} \cdot \frac{Q_3}{Q_2}$ by Tian (2003, Lemma 4). Since Q_6 and Q_1 can be canceled out, we can write $Q[\mathbf{H}_1] = \frac{Q_7}{Q_5} \cdot \frac{Q_4}{Q_3} \cdot \frac{Q_2}{Q_0}$.
- We show that this expression is valid if $Q_5 > 0$, and further show that it is still possible to identify $Q[\mathbf{H}_1]$ when some of the denominators are 0, i.e., $Q_5 = 0$ or $Q_3 = 0$, relaxing the strict positivity condition of $Q[\mathbf{H}] > 0$ in (Tian, 2003).

Relaxed Q-decomposition

- We generalize Q-decomposition under **relaxed positivity**.

Theorem (Positivity Relaxed Q-decomposition)

Let $\mathbf{H}' \in \text{cc}(\mathcal{G}[\mathbf{H}])$ where $I_{\mathcal{G}[\mathbf{H}], \prec}(\mathbf{H}') = \{(l_d, r_d)\}_{d=1}^T$. Then, the following holds:

- If $Q[\mathbf{H}^{\preceq l_{\tau-1}}] > 0$, then

$$Q[\mathbf{H}'] = \prod_{d=1}^T \frac{Q[\mathbf{H}^{\preceq r_d}]}{Q[\mathbf{H}^{\preceq l_d-1}]}.$$

- If $Q[\mathbf{H}^{\preceq r_m}] = 0$ and $Q[\mathbf{H}^{\preceq l_m-1}] > 0$ for some m , then

$$Q[\mathbf{H}'] = 0.$$

Relaxed Q-decomposition with Example (Napkin)

$$Q[W, X, Y] = \frac{Q[W, R, X, Y]}{\cancel{Q[W, R, X]}} \cdot \frac{\cancel{Q[W, R, X]}}{Q[W, R]} \cdot \frac{Q[W]}{Q[\emptyset]}$$

$$Q[W, X, Y] = \frac{Q[W, R, X, Y]}{Q[W, R]} \cdot \frac{Q[W]}{Q[\emptyset]} \quad \text{if } Q[W, R] > 0$$

$$Q[W, X, Y] = 0 \quad \text{if } Q[W] = 0$$

$$\Rightarrow P_x(y) = \frac{\sum_w Q[W, X, Y](x, y, w, r)}{\sum_{y', w} Q[W, X, Y](x, y', w, r)}$$

$$\therefore \exists r(\text{adj}(r; W) \wedge P(x, r) > 0)$$

- We devise **Identify+**, a sound algorithm that returns an identification formula with **sufficient positivity**.

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Discussion & Conclusion

- We provide positivity conditions for **do-calculus** and **generalized Q-decomposition**, forming a basis for causal effect identification without $P(\mathbf{V}) > 0$.
- We devise **Identify+** algorithm, incorporating a **relaxed** version of **generalized Q-decomposition** into an existing identification method.
- Towards a positivity-aware identification algorithm— 3 key factors: topological order, fixing values, and latent projection.
- Since we have established sufficient conditions for both do-calculus and identification of marginal effects, our results indeed generalize to conditional causal effects as well.

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