

Multi-Sender Persuasion

A Computational Perspective

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Information Design

How can an agent with informational advantage, strategically reveal this information to another agent to influence their behaviour?



1. Bayesian Persuasion

- Two player game between a **sender**, who gets to observe a **world state** $\theta \in \Theta$, and a **receiver** who gets to take an **action** [1].
- The **utility** of both players depend on this action along with the world state.
 - Complete Information - sender knows receiver utility
- Both players share a common **prior** belief μ about the possible world states θ .
- The sender can commit to strategically revealing her knowledge of the world state through **signaling**.





Sender - Professor

- θ - student quality {good, bad}
- $a \in \{\text{hire, not hire}\}$
- Utility $u(a, \theta)$: +1 if student is hired
- Utility $w(a, \theta)$: +1 if hiring good student or not hiring bad ones



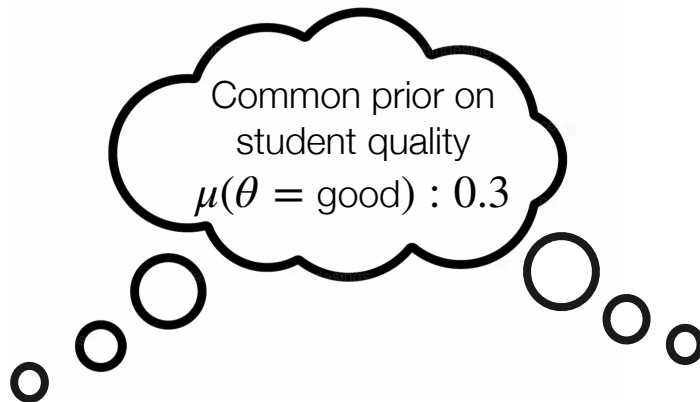
Receiver - Hiring Manager





Sender - Professor

$u(a, \theta) : +1$ if student hired



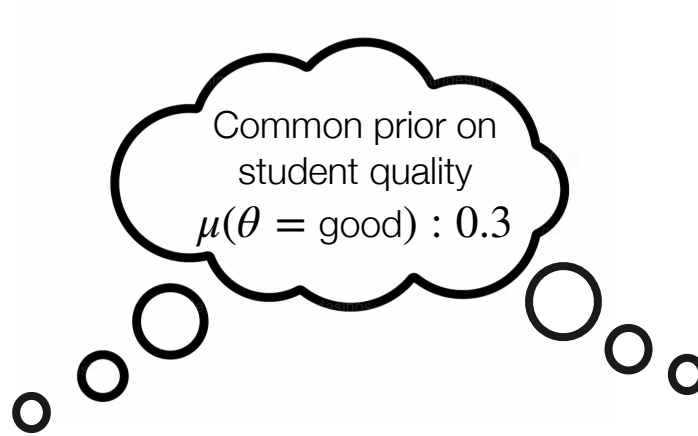
Receiver - Hiring Manager

$w(a, \theta) : +1$ if right decision is made





Sender - Professor
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But I get to see the quality



$$\mathbb{E}[u(a^*, \theta)] = 0$$

Sender - Professor

$u(a, \theta) : +1$ if student hired

Common prior on student quality
 $\mu(\theta = \text{good}) : 0.3$

I commit to signaling as follows
Always say hire the student!

$a^* = \text{not hire}$

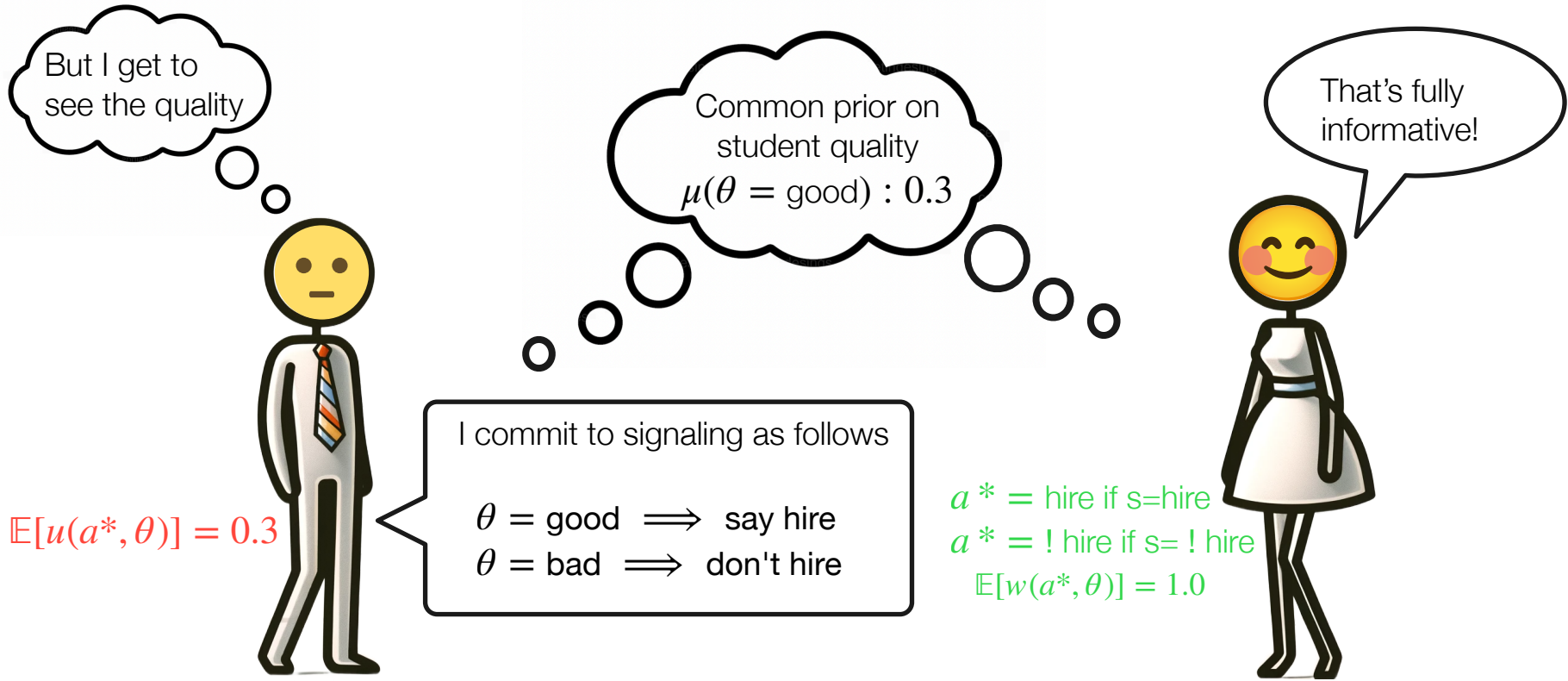
$$\mathbb{E}[w(a^*, \theta)] = 0.7$$

Receiver - Hiring Manager

$w(a, \theta) : +1$ if right decision is made

That's totally uninformative!





Sender - Professor

$u(a, \theta) : +1$ if student hired

Receiver - Hiring Manager

$w(a, \theta) : +1$ if right decision is made



But I get to
see the quality



Common prior on
student quality
 $\mu(\theta = \text{good}) : 0.3$

I commit to signaling as follows

$\theta = \text{good} \implies \text{say hire}$
 $\theta = \text{bad} \implies \text{say hire 42\% of the time}$



Sender - Professor

$u(a, \theta) : +1$ if student hired

Receiver - Hiring Manager

$w(a, \theta) : +1$ if right decision is made



But I get to
see the quality



Common prior on
student quality
 $\mu(\theta = \text{good}) : 0.3$

I commit to signaling as follows

$$\pi(s = \text{hire} \mid \theta = \text{good}) = 1$$
$$\pi(s = \text{hire} \mid \theta = \text{bad}) = 0.42$$

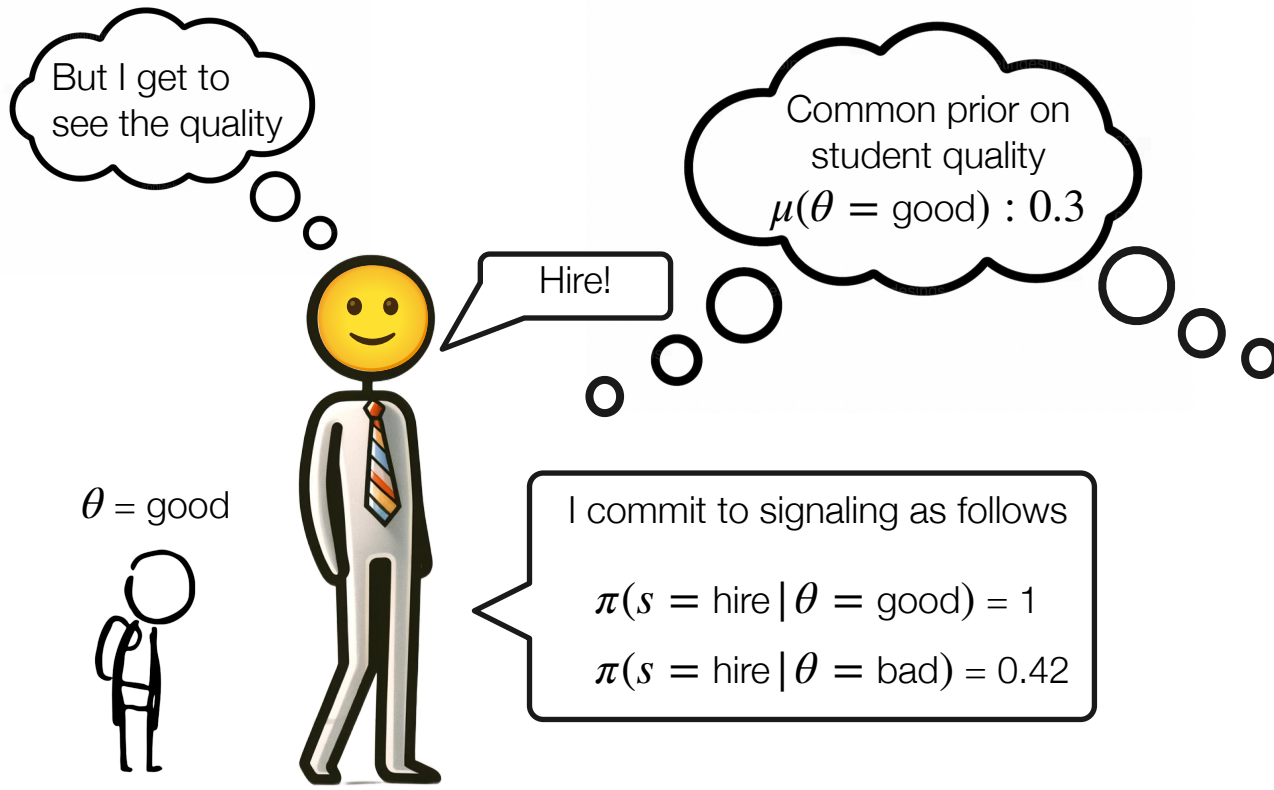

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Receiver - Hiring Manager

$w(a, \theta) : +1$ if right decision is made





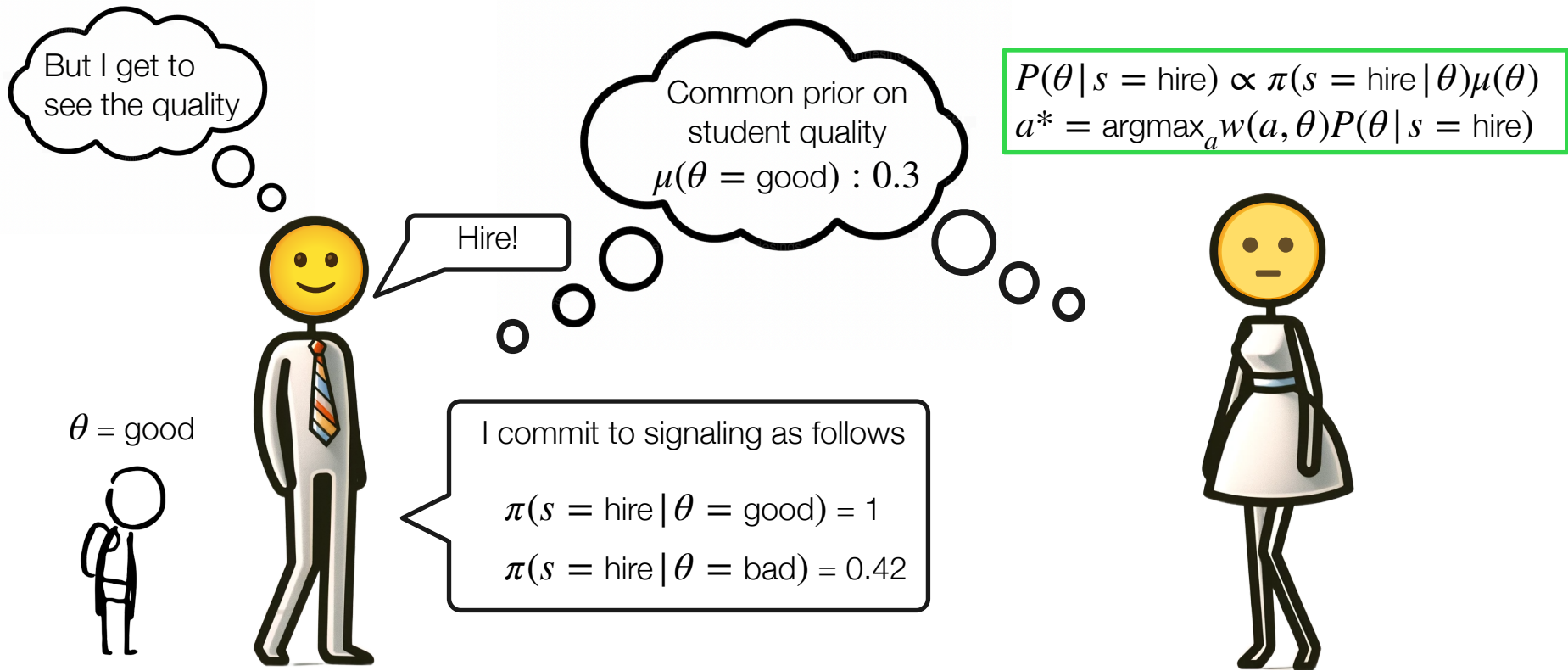
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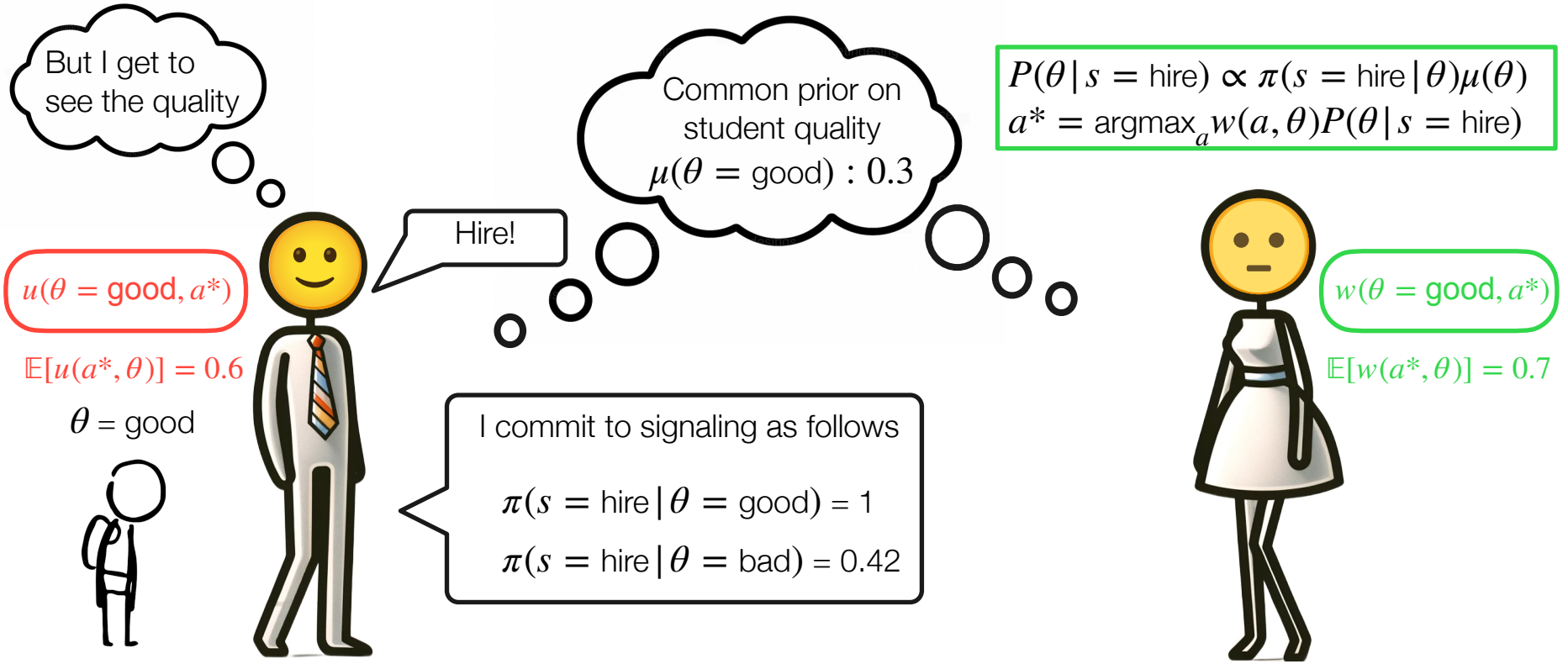
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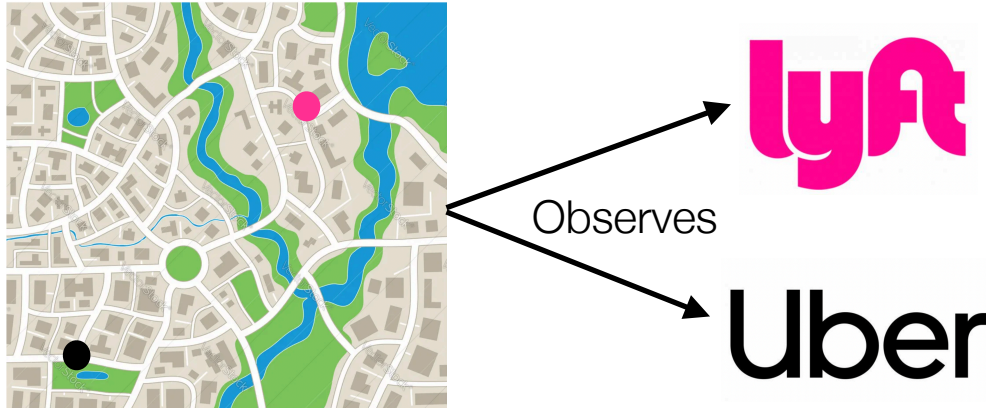
1. Bayesian Persuasion - Details

- Sender must commit to signaling scheme **before** realization
- When sender is designing/choosing signaling scheme they have no more information than receiver.
 - Chooses a scheme to maximize **expected ex-ante utility**
- In the standard setting, under mild assumptions optimal scheme can be solved using a linear program [2].



2. Motivations

- In many settings involving persuasion, there maybe multiple informationally advantageous senders looking to persuade a single agent.

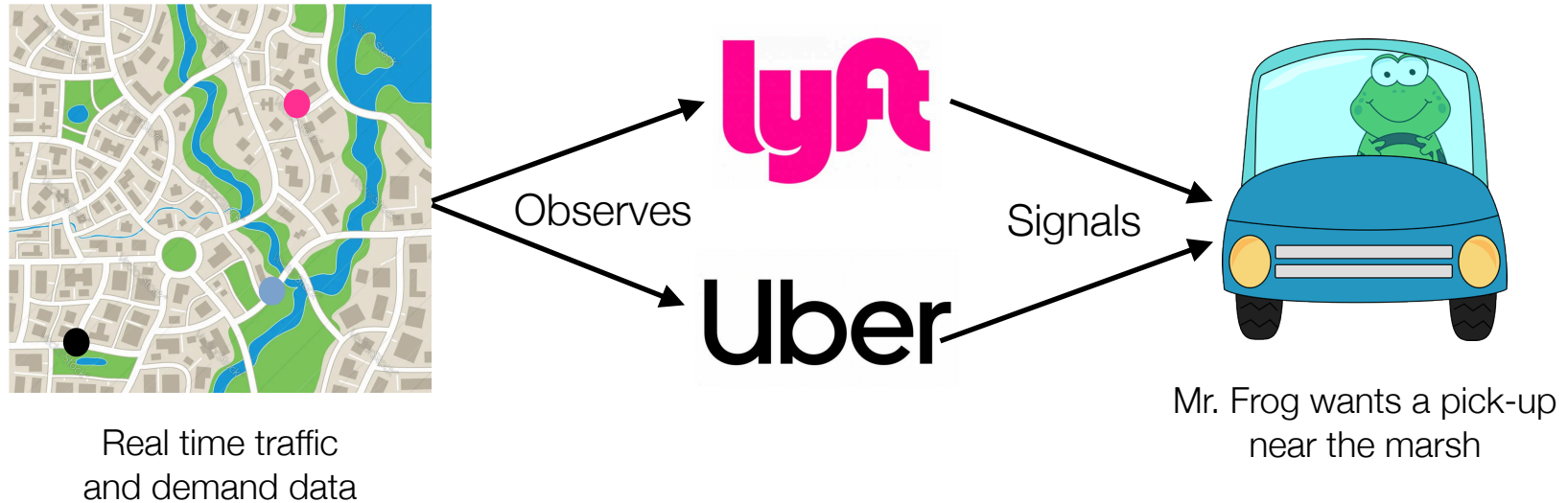


Real time traffic
and demand data



2. Motivations

- In many settings involving persuasion, there maybe multiple informationally advantageous senders looking to persuade a single agent.



2. Multi-Sender Persuasion Model

- n senders with utility $u_i(\theta, a)$, and 1 receiver with utility $w(\theta, a)$
- All senders and receiver have a common prior $\mu(\theta)$
- Senders **jointly observe** a realization $\theta \sim \mu$,
- Sender **simultaneously** commit to signaling $\pi_i(s | \theta)$; receiver observes $\bar{s} \sim \prod \pi_i$
 - Receiver updates belief based on joint signal and takes their optimal action.

Multi-leader single follower Stackelberg game.

Simultaneous interaction between senders; sequential interaction with receiver



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- Sender **simultaneously** commit to signaling $\pi_i(s | \theta)$; receiver observes $\bar{s} \sim \prod \pi_i$
 - Receiver updates belief based on joint signal and takes their optimal action.
- Sender utility: $u_i(\pi_i, \pi_{-i}) = \sum_{\theta} \sum_{\bar{s} \in \mathcal{S}^n} \bar{\pi}(\bar{s} | \theta) u_i(\theta, a^*)$

Nash equilibrium between sender's signaling strategy given receiver best responds.

$$\forall i \forall \pi_i \quad u_i(\pi_i^{eq}, \bar{\pi}_{-i}^{eq}) \geq u_i(\pi_i, \bar{\pi}_{-i}^{eq})$$



2. Related Works

[7] studies multi-sender setting wherein senders can arbitrarily correlate their signals by conditioning on others realizations - leads to some simplifications.

[8] studies multi-sender persuasion where senders commit to schemes sequentially. Different solution concept: sub-game perfect equilibrium.

[9] Study a simultaneous and independent model, but with zero sum sender utilities.

- We consider senders committing to **simultaneous and independent schemes**, but with no restriction on utility or state/action/signal structure.
- Prior works provide little computational insights on the problem.



2. Equilibrium Characterization

- [6] notes that **under two conditions** an equilibrium exists that **fully reveals** the realized state to the receiver, allowing them to achieve maximal utility:
 - (1) there is a unique optimal action for the receiver at each state.
 - (2) The signal space $|\mathcal{S}| = |\Theta|$, the state space.
- (Equilibrium): Any sender chooses to deterministically map state to signal.



2. Equilibrium Characterization

- [6] notes that under two conditions a full information equilibrium exists:
 - (1) there is a unique optimal action for the receiver at each state.
 - (2) The signal space $|S| = |\Theta|$, the state space.
- We prove that condition 2 can be significantly relaxed.
- **Theorem:** A full information equilibrium exists if:
 - (1) there is a unique optimal action for the receiver at each state.
 - (2') The signal space $|S| \geq \min(|\Theta|^{1/n-1}, |A|^{1/n-1})$



2. Equilibrium Characterization

- **Theorem:** A full information equilibrium exists if:
 - (1) there is a unique optimal action for the receiver at each state.
 - (2') The signal space $|S| \geq \min(|\Theta|^{1/n-1}, |A|^{1/n-1})$
- Map each state to a deterministic set of signals such that:
 - each state is uniquely identifiable by $n - 1$ signals.
 - Leverages an idea from error correcting codes.
- If $|\Theta| > |A|$, can interpret full information as revealing optimal action at each state.



2. Equilibrium Characterization

- **Theorem:** A full information equilibrium exists if:
 - (1) there is a unique optimal action for the receiver at each state.
 - (2') The signal space $|S| \geq \min(|\Theta|^{1/n-1}, |A|^{1/n-1})$
- We have relaxed the 2nd conditions. But how about the first?
- **Theorem:** If condition (1) does not hold, then under some tie-breaking rule, computing the Nash equilibrium is PPAD-Hard.
 - Reduction from finding equilibrium in two-player games with binary utilities.



2. Best Response

- In single sender persuasion, optimal signaling scheme (i.e. sender's best strategy) can be expressed as a linear program.
- In multi-sender persuasion, a sender i 's best response is their optimal signaling scheme for a fixed set of scheme of other senders, $\bar{\pi}_{-i}$.

Theorem: Even for 2 senders, computing a single sender's best response is NP-Hard. Further, it is NP-Hard to even approximate the best response.



2. Best Response Hardness

- An involved reduction from the hardness of public persuasion with k receivers.

Public Persuasion

- 1 sender k receivers; public scheme
- Common prior $\mu(\theta)$ with $|\Theta|$ states.
- Binary action receivers with utility $w_j(\theta, a)$
- Sender utility depends on receiver $u_j(\theta, a)$

Equivalent Multi-Sender Persuasion

- 2 senders and 1 receiver
- $\Theta' = \Theta \cup \{\bar{\theta}_1, \dots, \bar{\theta}_k\}$ states
- The receiver action space $A = A_+ \cup A_- \cup a_\infty$ where $|A_+| = |A_-| = k$



2. Best Response Hardness

- $\Theta' = \Theta \cup \{\bar{\theta}_1, \dots, \bar{\theta}_k\}$ states:
 - When $\theta \in \Theta$ happens, single receiver utility $w(a_j^+, \theta) = w_j(a^+, \theta)$
 - When $\bar{\theta}_j$ happens, very bad for receiver to take anything except $\{a_j^+, a_j^-\}$
- Non-best responding sender's signaling scheme uses k signals such that:
 - Realization s_j implies receiver will take action $\{a_j^+, a_j^-\}$

$\forall k$ possible signal realization of non-best responding sender, the single receiver's plausible actions mimic that of the k^{th} receiver in public persuasion



2. Deep Learning Approach

Given the difficulty of best-response and non trivial equilibrium in this setting, we propose **deep learning** methods for finding **local equilibria**.

- Challenging due to the non-convex discontinuous utility landscape



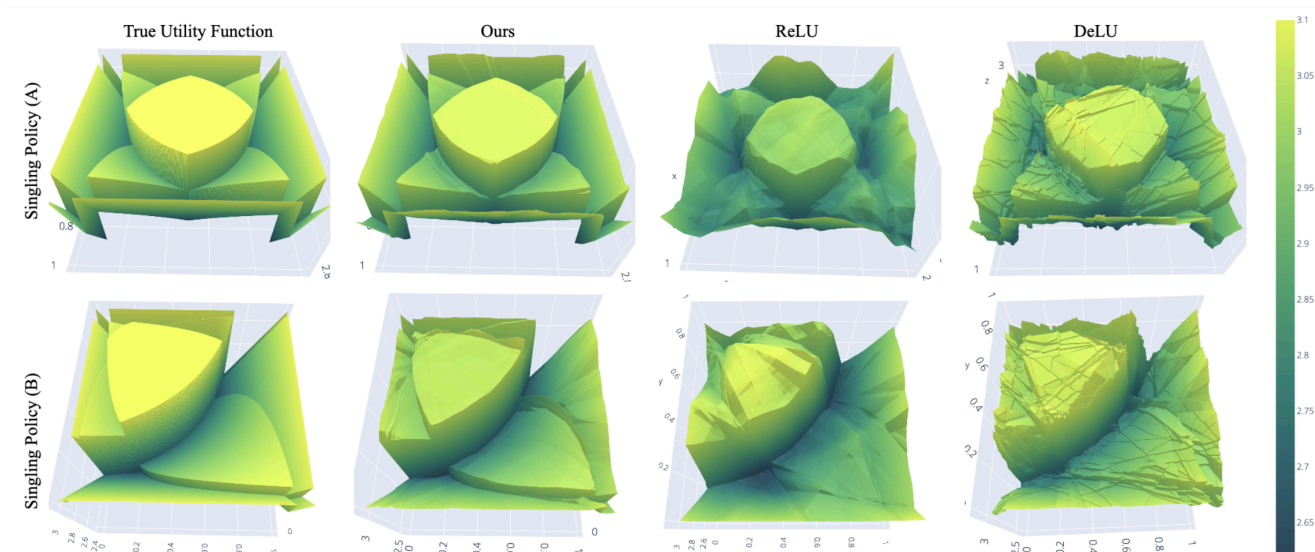
2. Deep Learning Approach

- Established the difficulty of computing equilibrium in the general setting, even with access to complete information.
- **Local Equilibrium:** No profitable deviation in a local neighborhood. Popular notion in deep learning for game.
- Can we use deep learning methods to find local equilibrium of this game with only sample access to utility?
 - **Key Challenge:** Joint utility landscape is non-convex and discontinuous.



2. Experimental Results

Propose novel architecture to approximate this utility with sample access.



2. Experimental Results

When paired with extra-gradient algorithm, we find local equilibria that outperforms other methods as well as full revelation equilibrium.

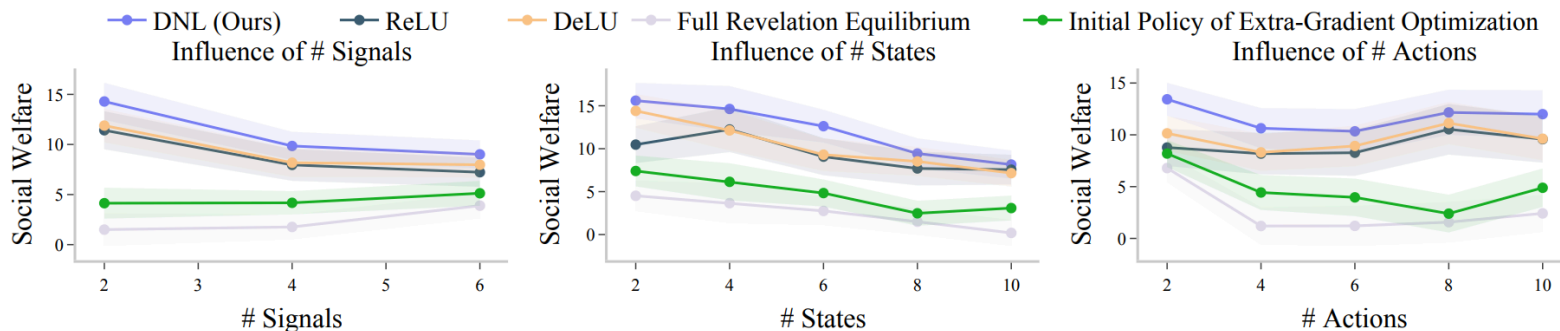


Figure 5: Our method achieves higher social welfare compared against baselines and full-revelation solutions in games with 4 senders.



Thank you!

References:

- [7]: Matthew Gentzkow, Emir Kamenica. **Bayesian persuasion with multiple senders and rich signal spaces**. Games and Economic Behavior. 2017
- [8]: Fei Li, Peter Norman. **Sequential persuasion**. Theoretical Economics. 2021
- [9]: Dilip Ravindran, Zhihan Cui. **Competing Persuaders in Zero-Sum Games**. Preprint. 2020

