

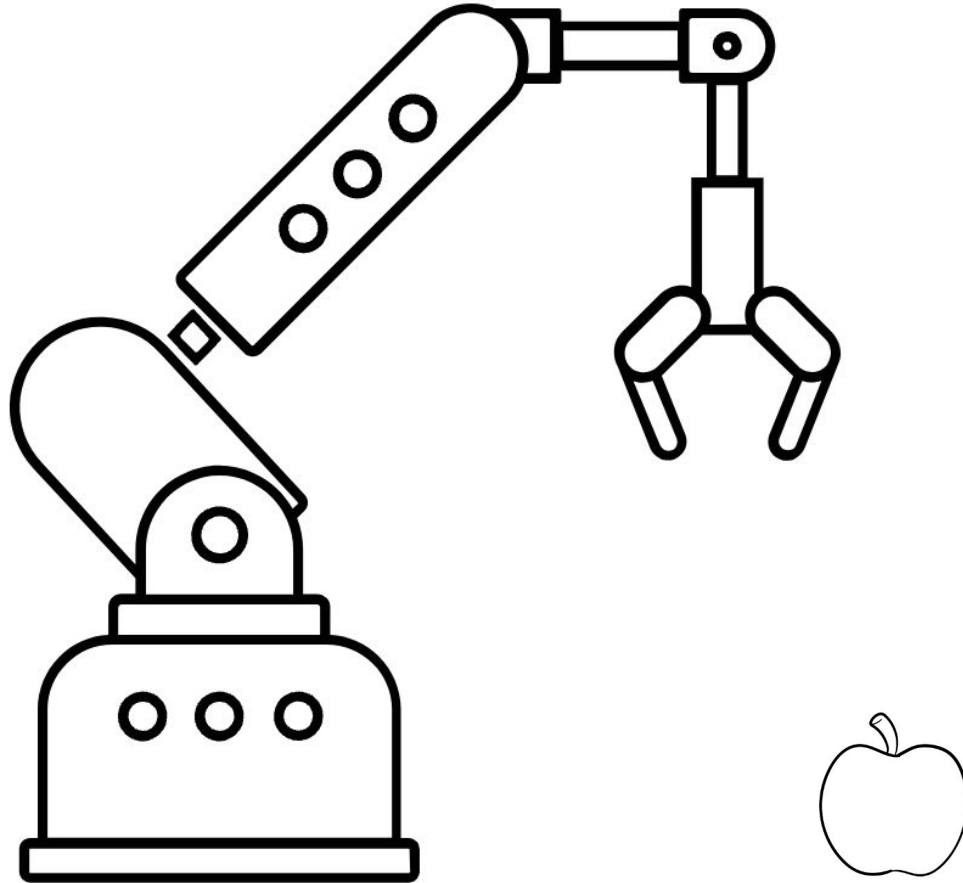
EvIL 🐈: Evolution Strategies for Generalisable Imitation Learning

Silvia Sapora

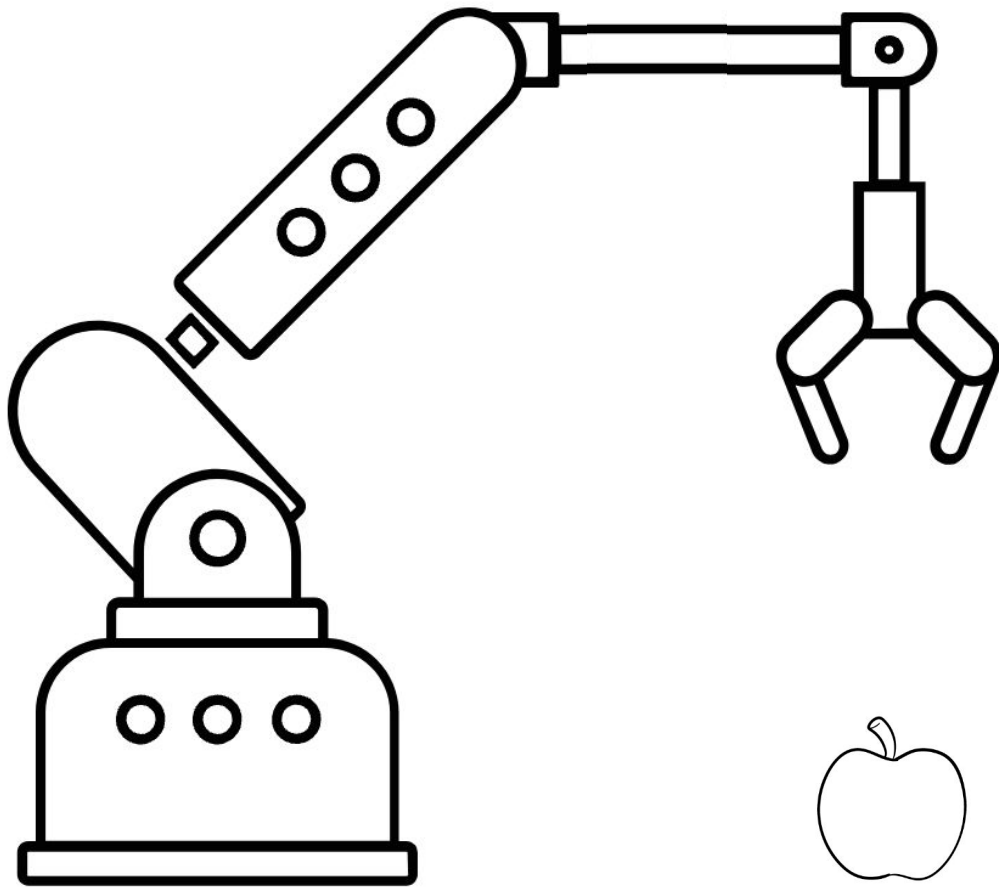


with Gokul Swamy, Chris Lu, Yee Whye Teh and Jakob Foerster

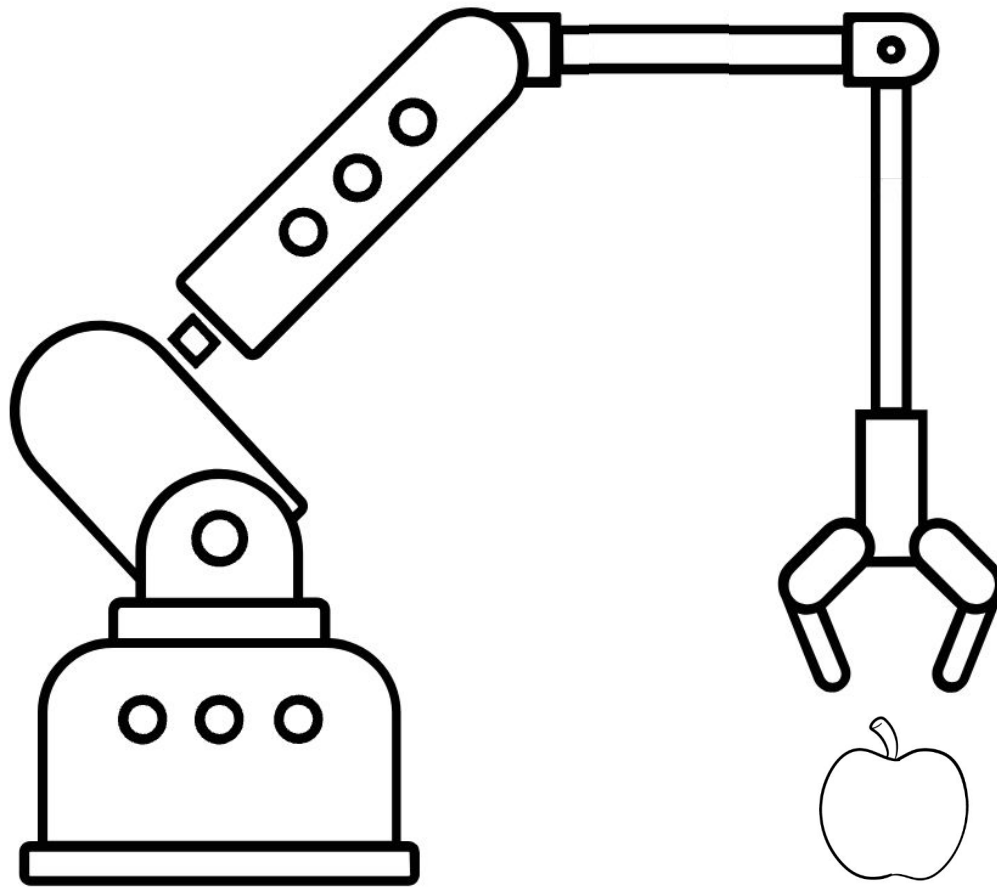
Background: Inverse Reinforcement Learning



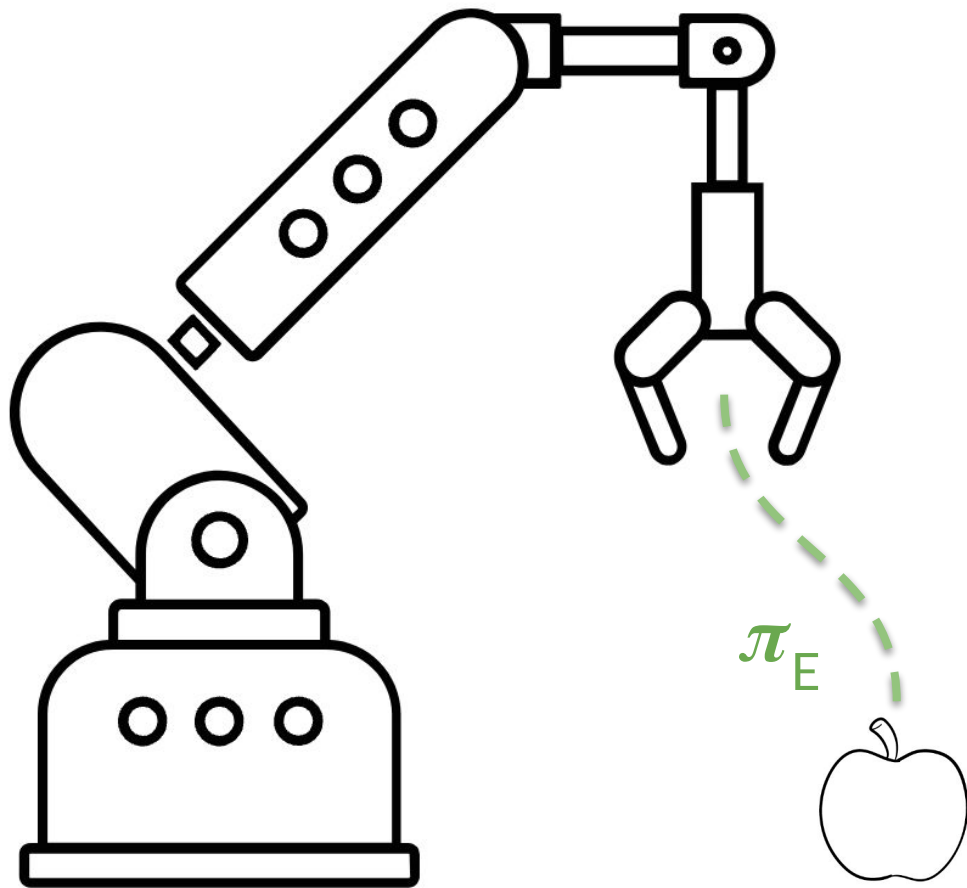
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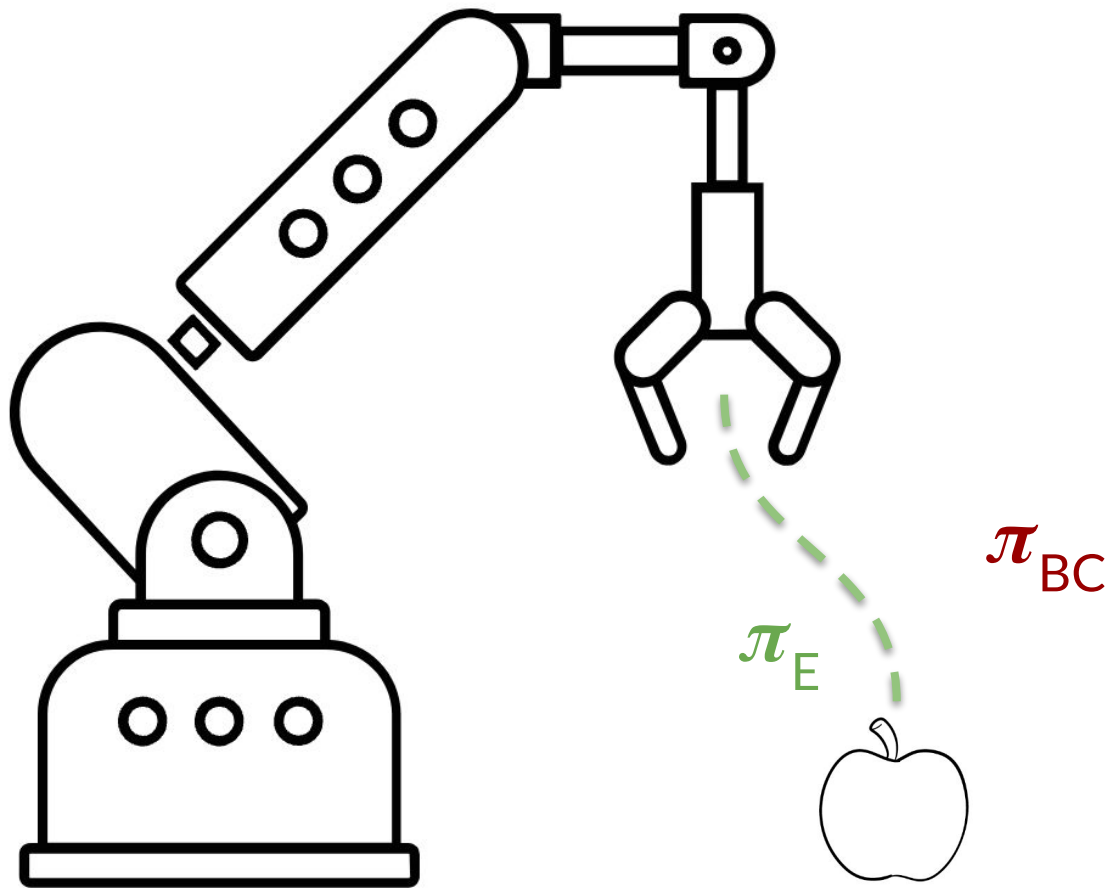
Background: Inverse Reinforcement Learning



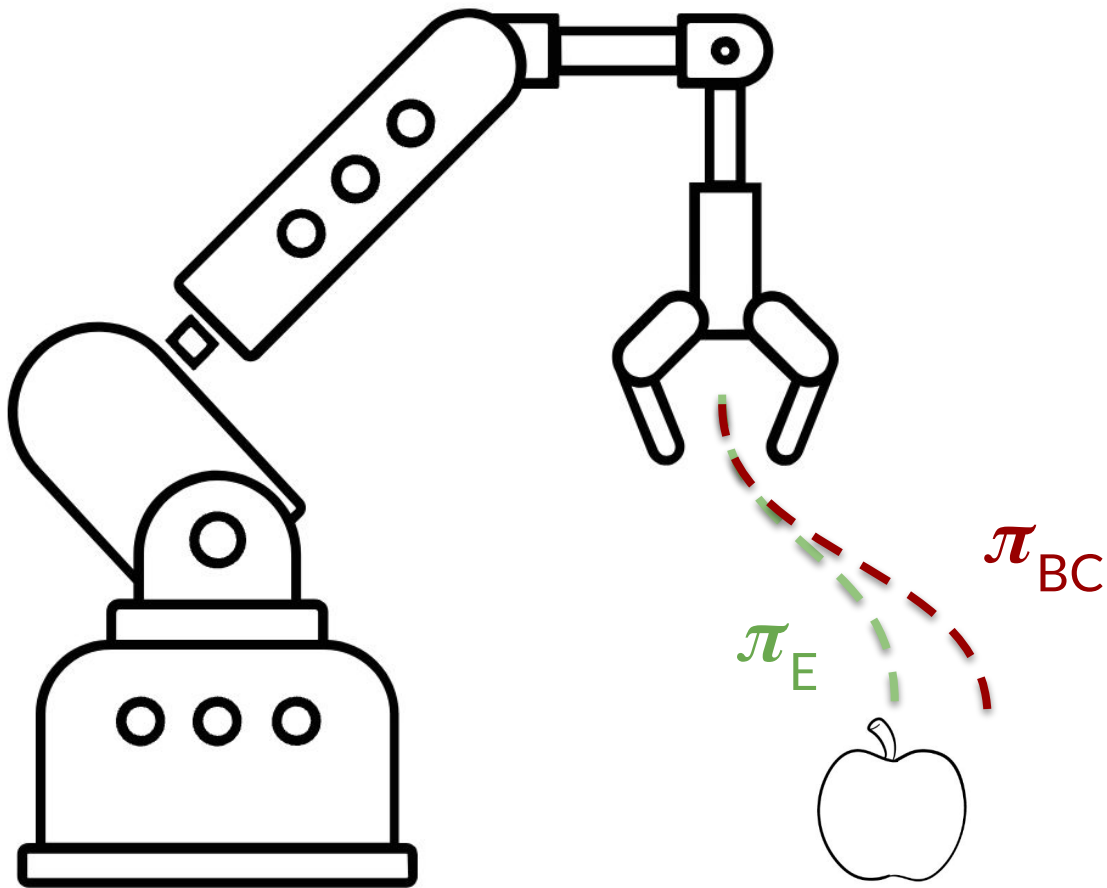
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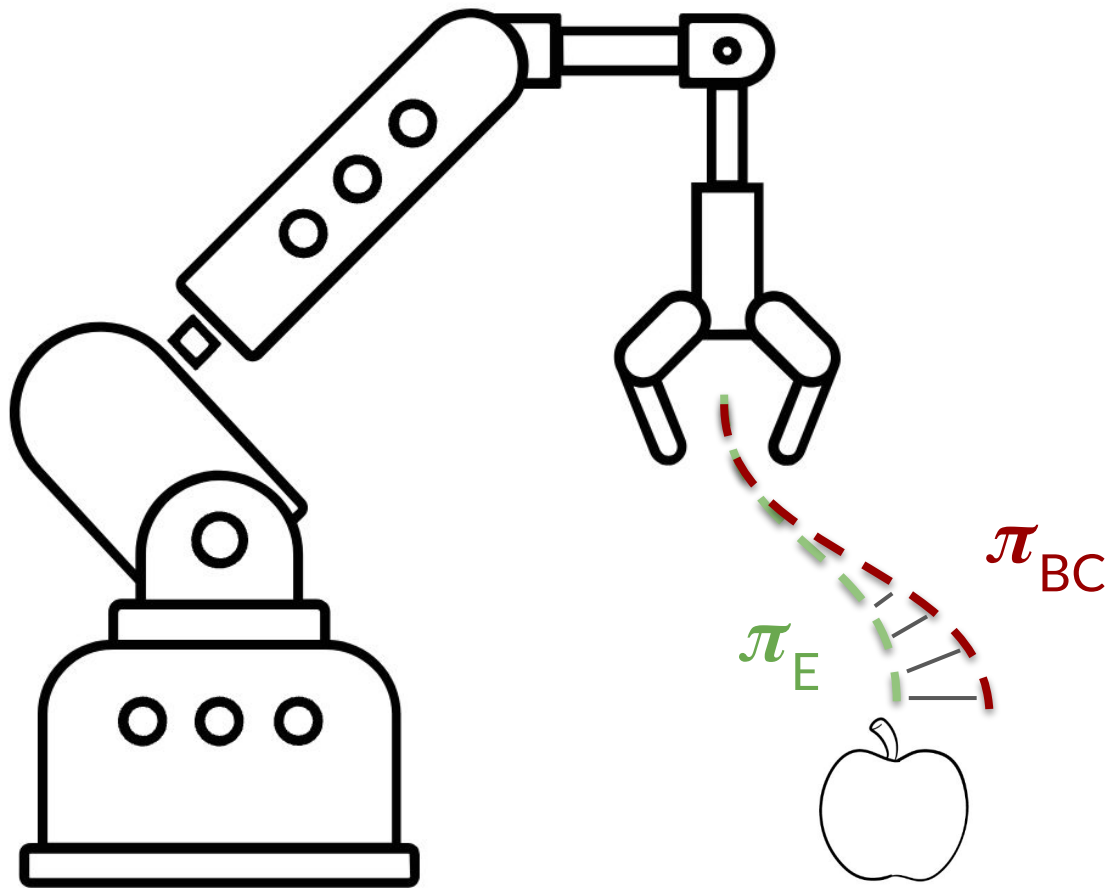
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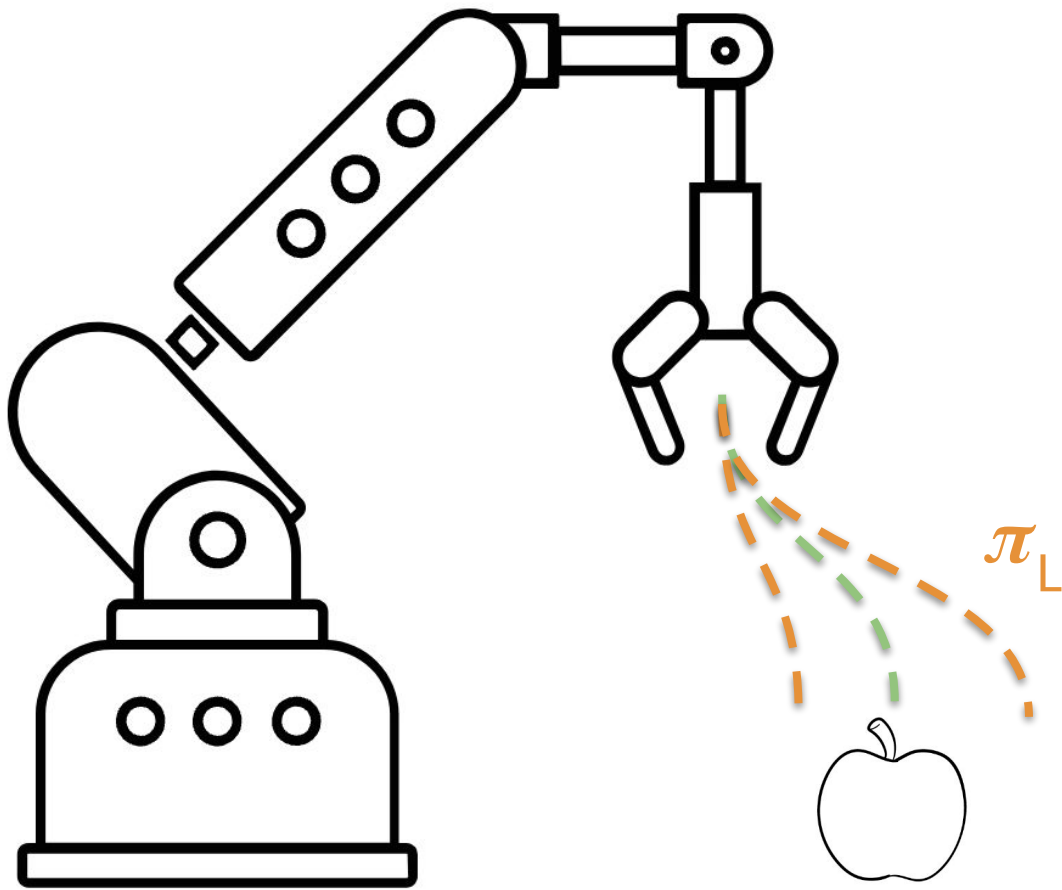
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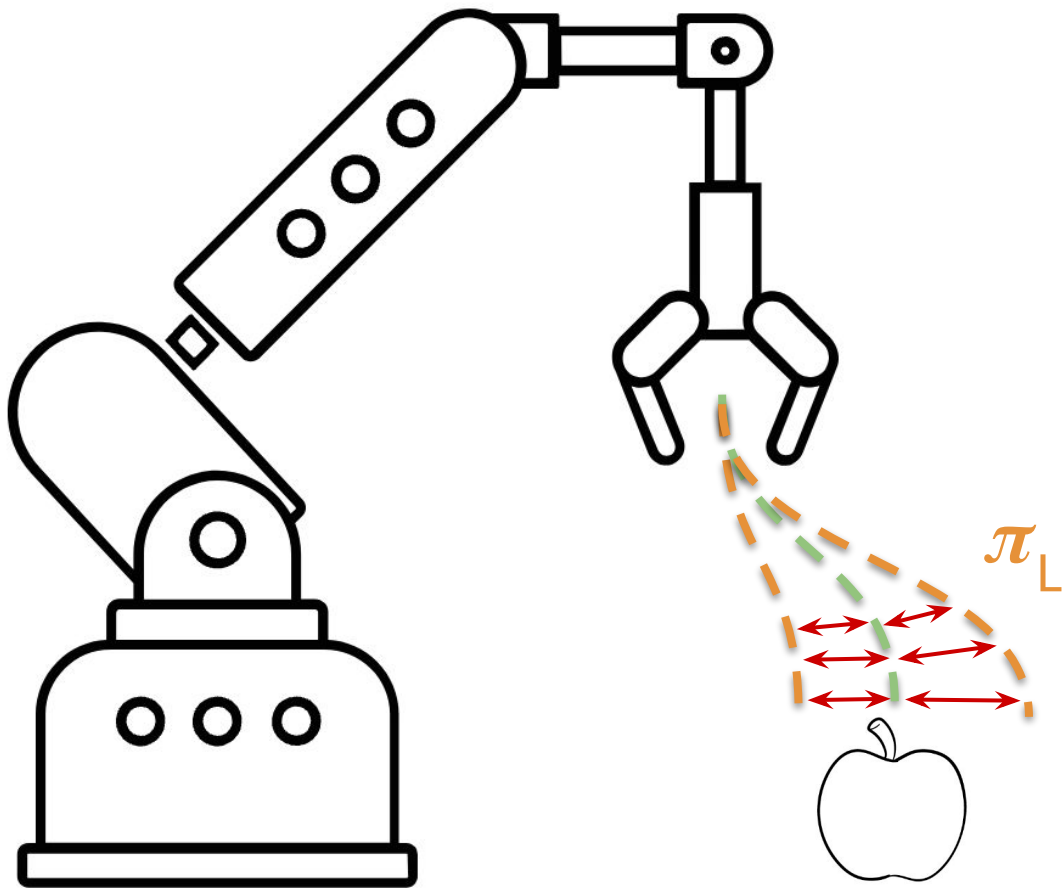
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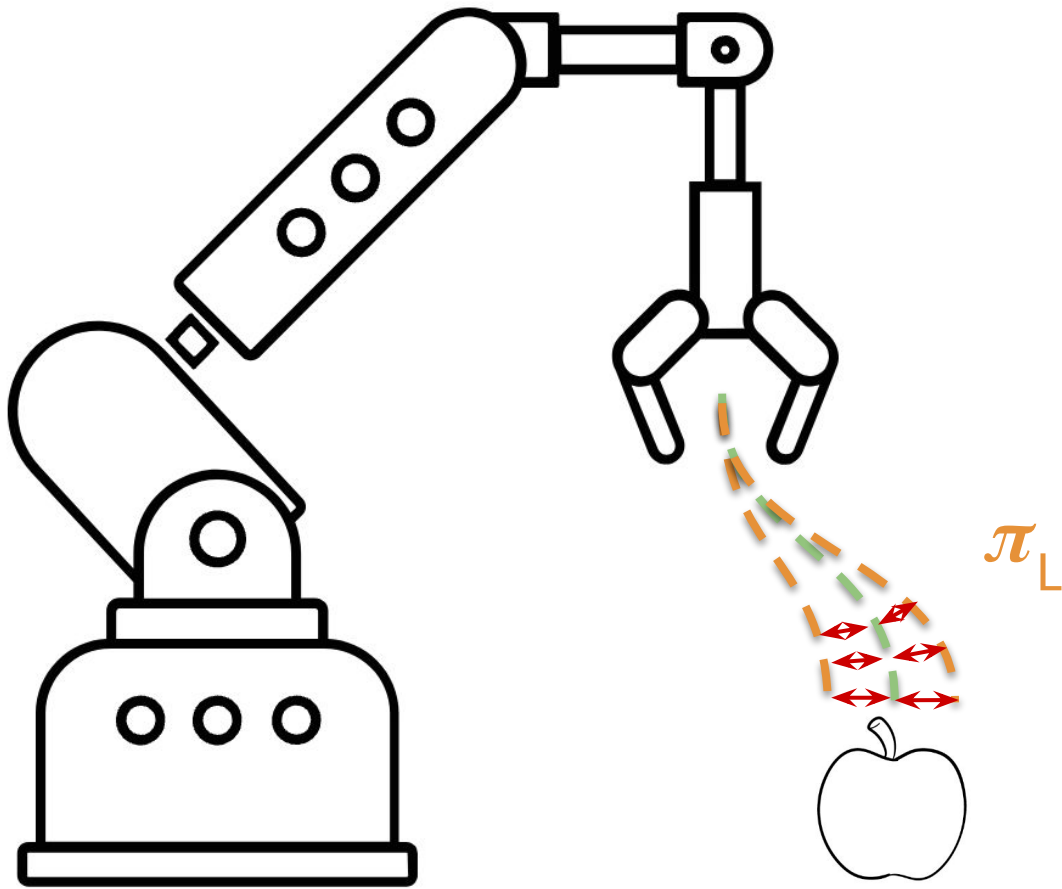
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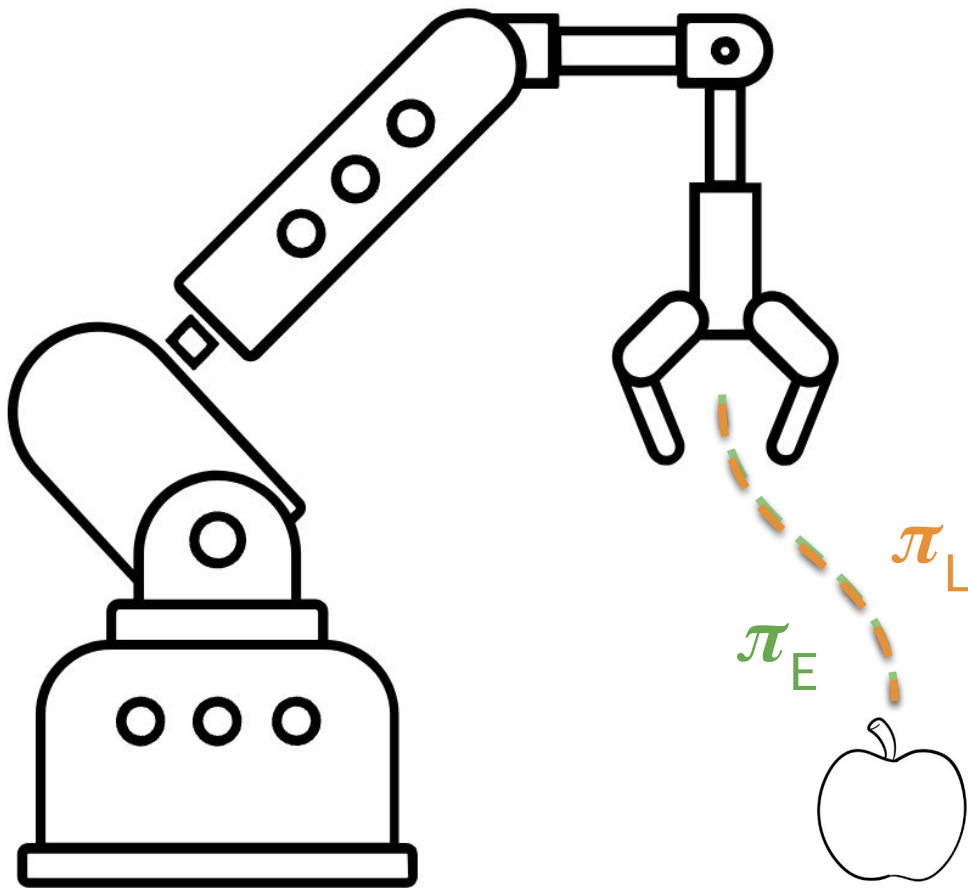
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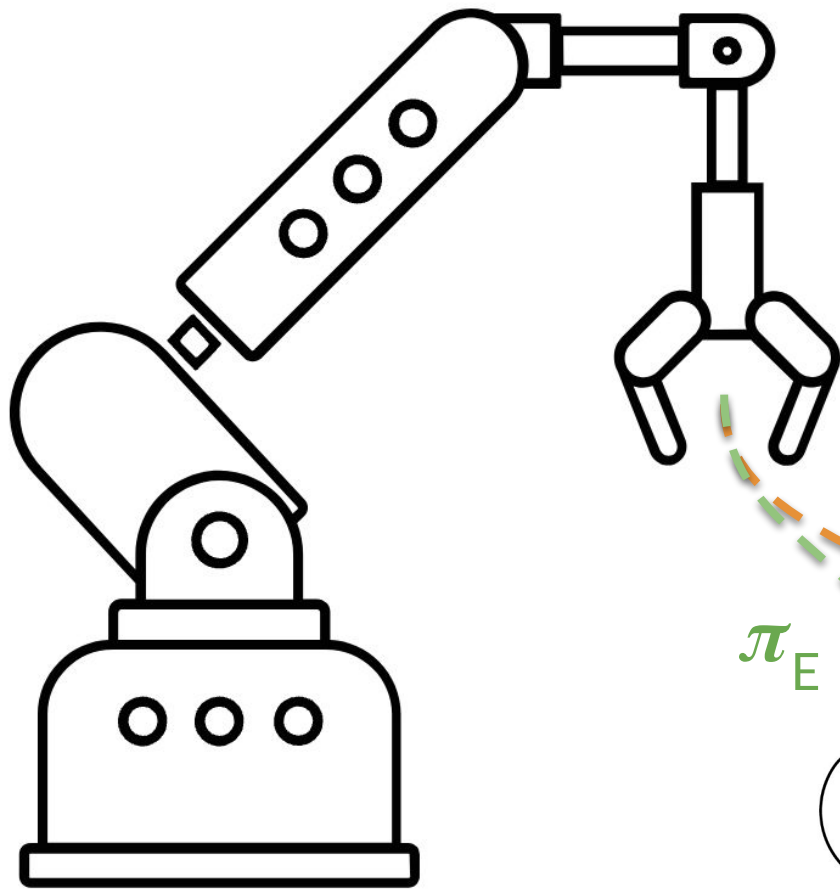
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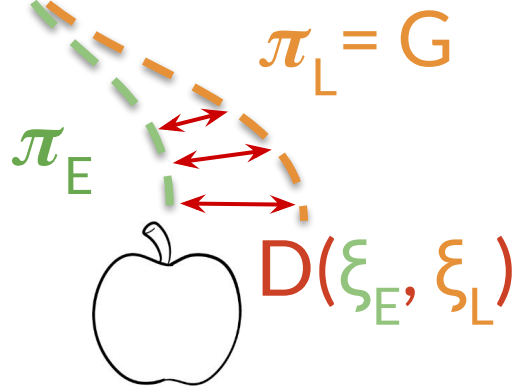


Background: Inverse Reinforcement Learning

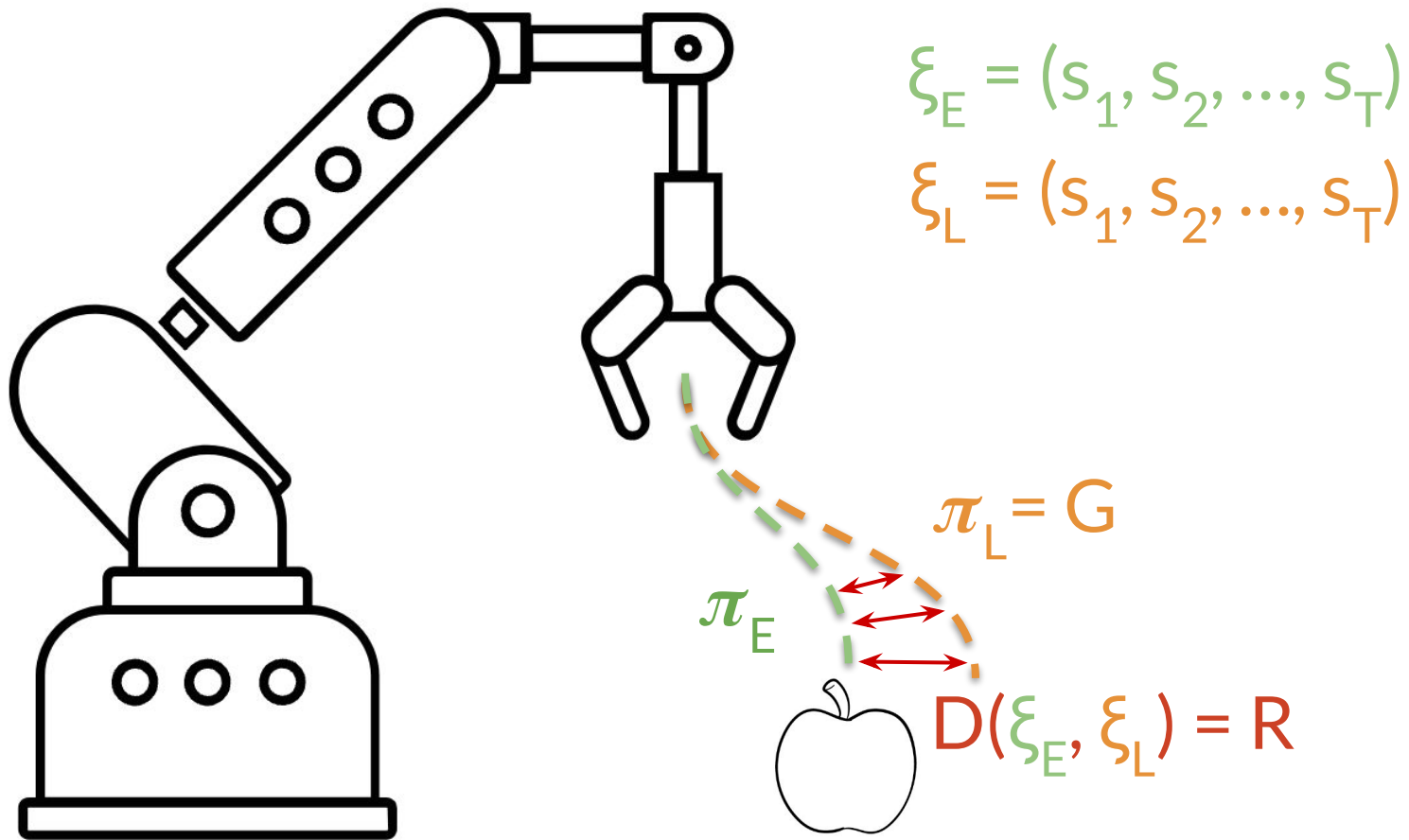


$$\xi_E = (s_1, s_2, \dots, s_T)$$

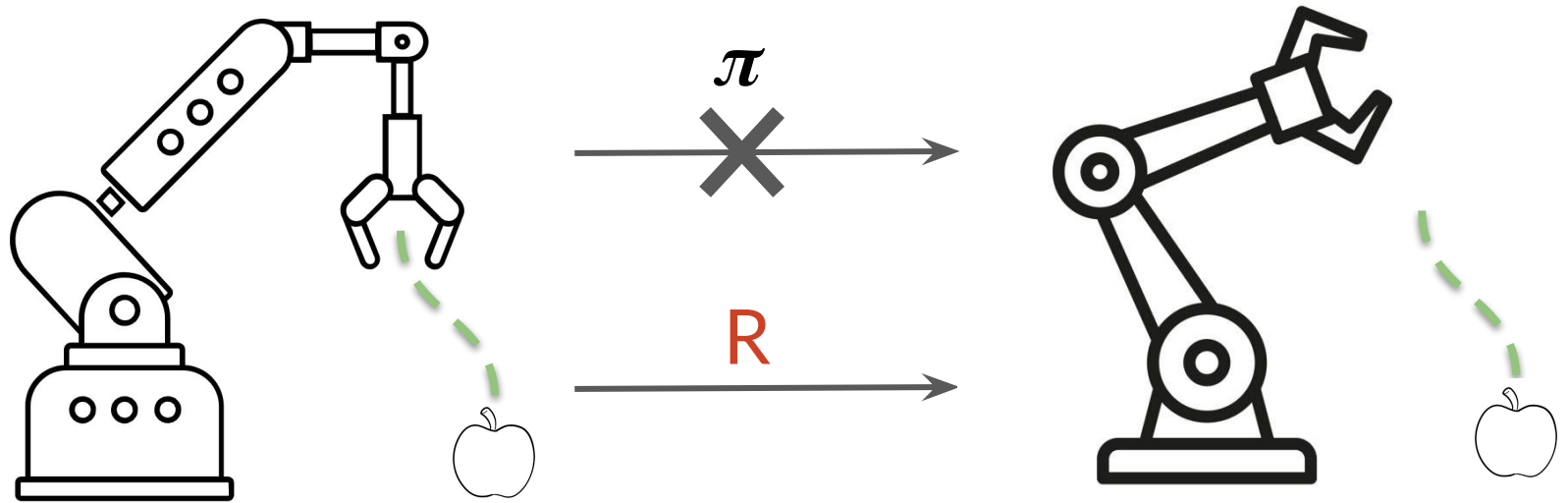
$$\xi_L = (s_1, s_2, \dots, s_T)$$



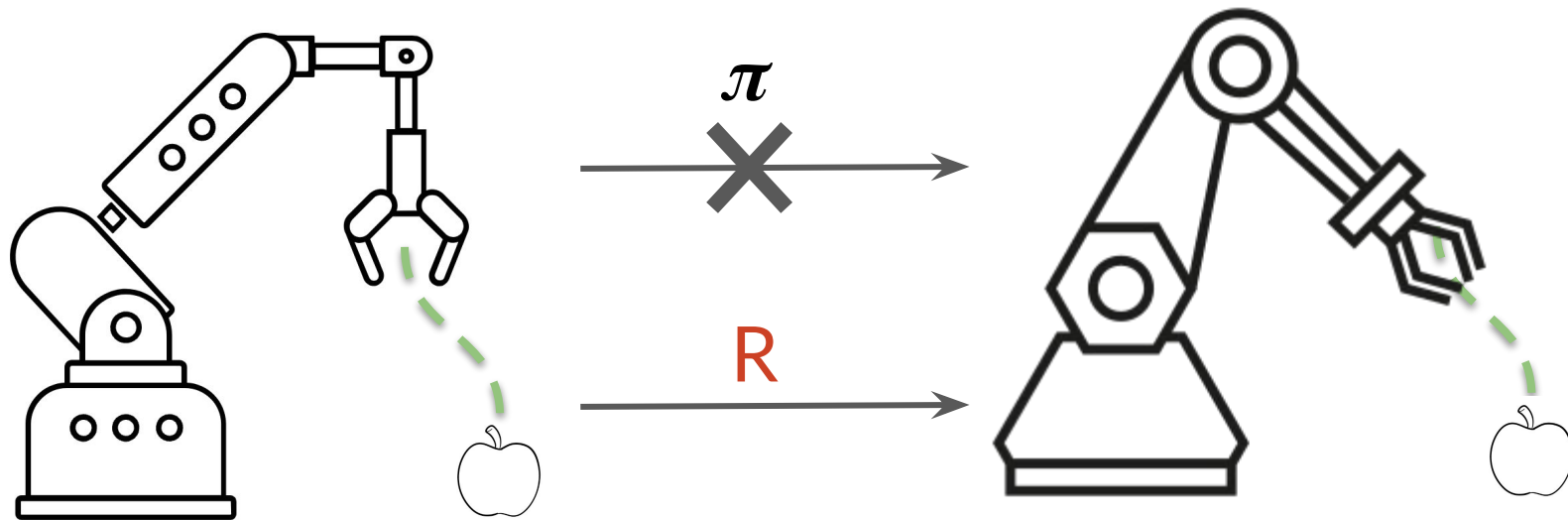
Background: Inverse Reinforcement Learning



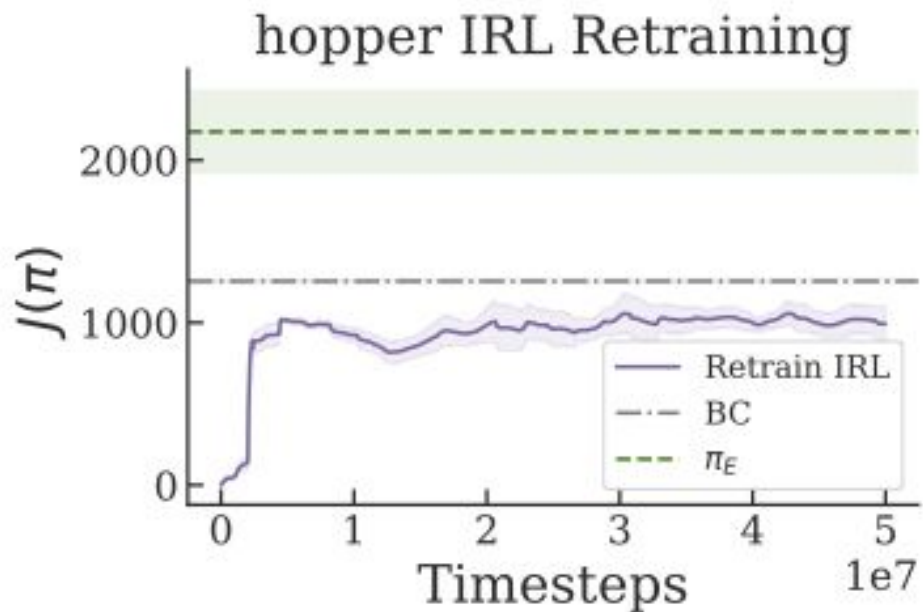
Background: Inverse Reinforcement Learning



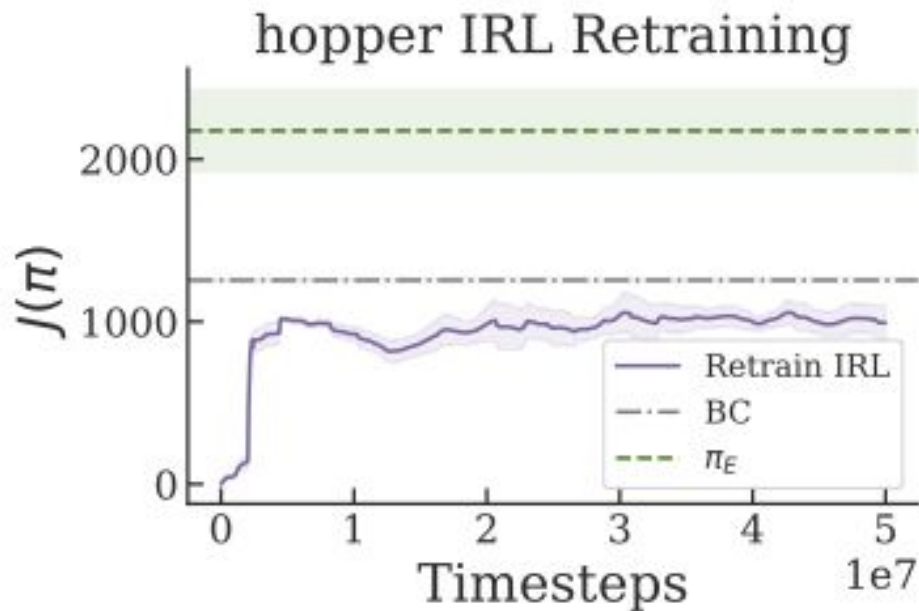
Background: Inverse Reinforcement Learning



🔑 Problems: Inverse Reinforcement Learning

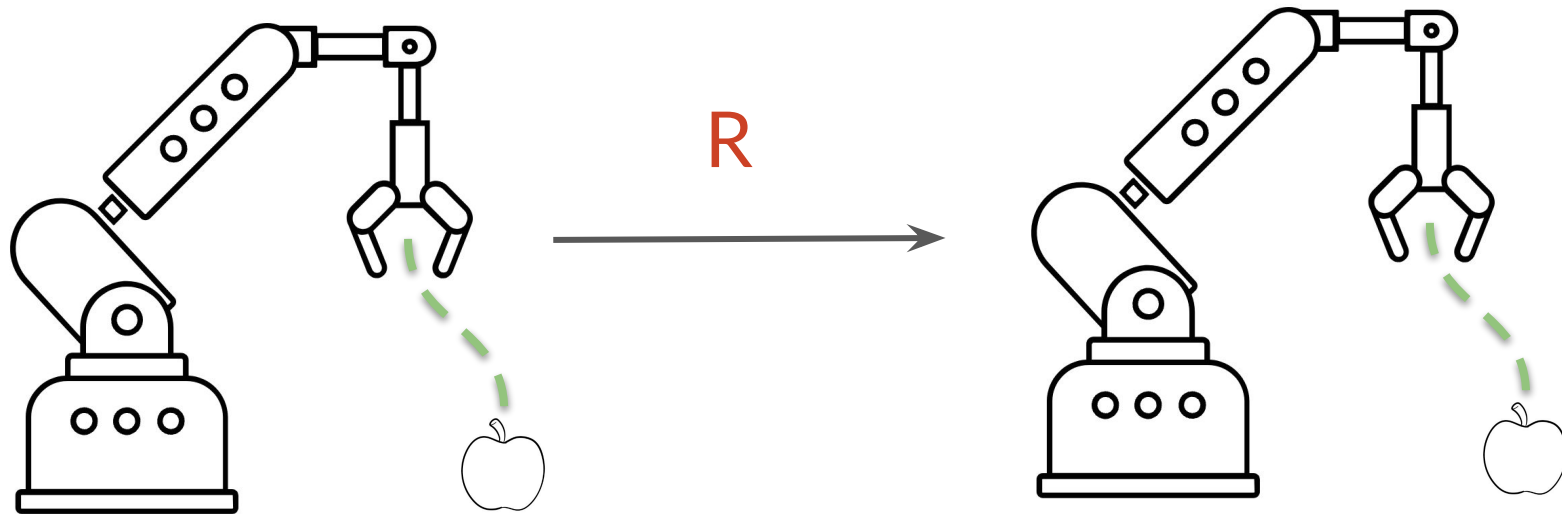


🔑 Problems: Inverse Reinforcement Learning

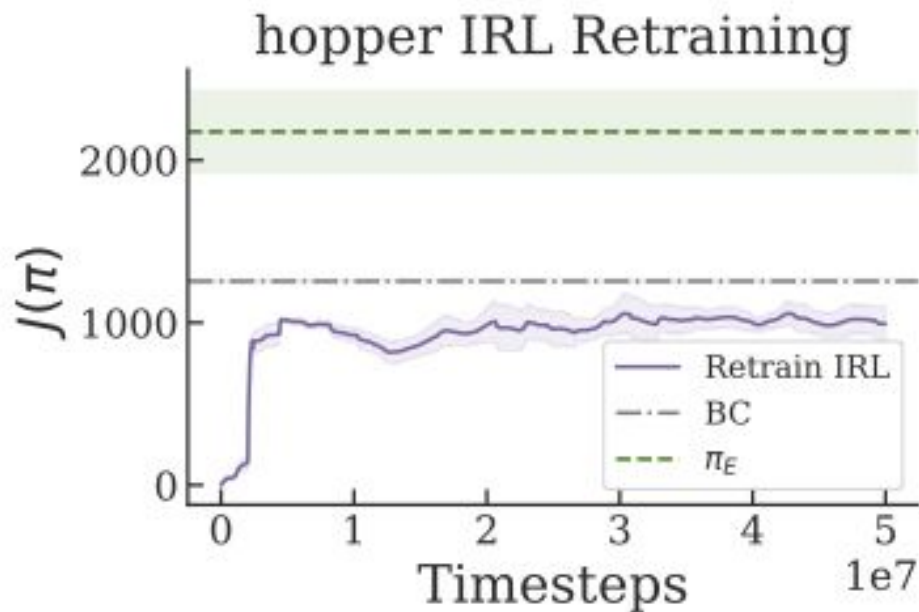


- Not effective

🔑 Problems: Inverse Reinforcement Learning



🔑 Problems: Inverse Reinforcement Learning



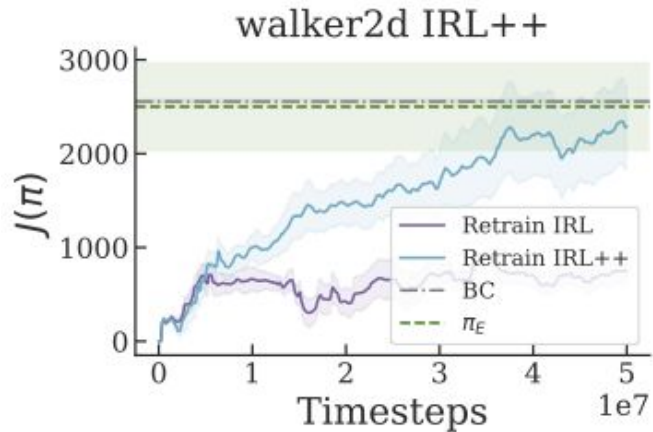
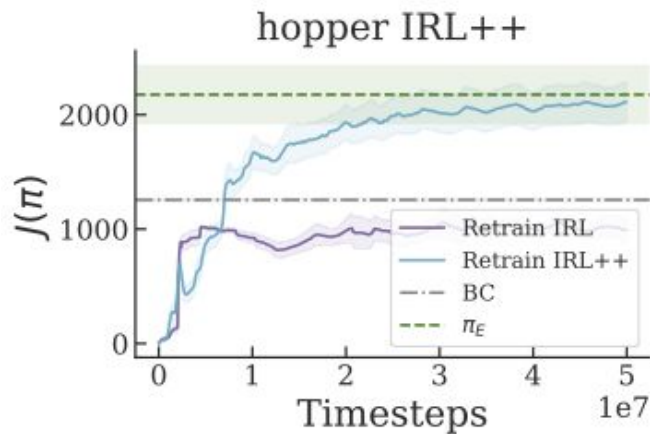
- Not effective
- Not efficient

Idea: IRL++ for Effective Retraining

- **Policy Buffer**
- **Discriminator and Policy Ensembles**
- **Random Policy Resets**

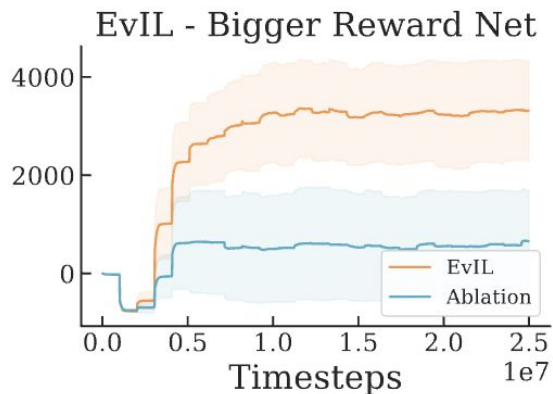
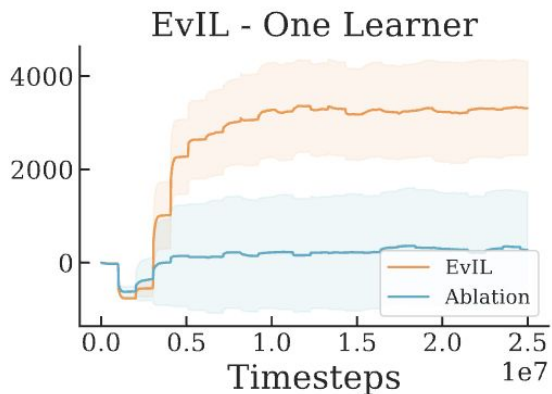
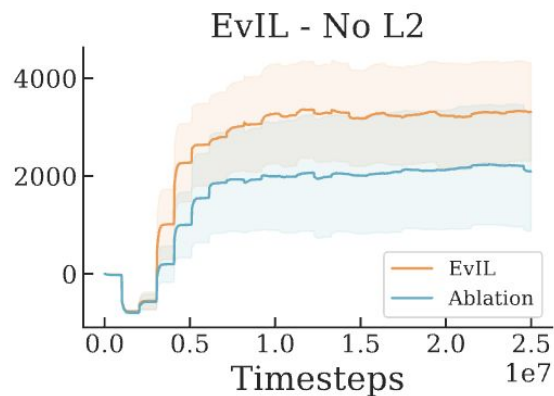
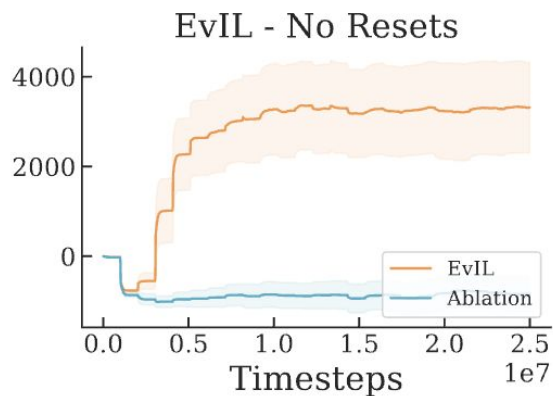
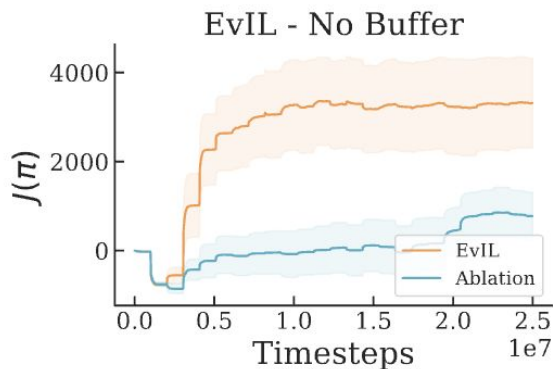
🔑 Idea: IRL++ for Effective Retraining

- Policy Buffer
- Discriminator and Policy Ensembles
- Random Policy Resets

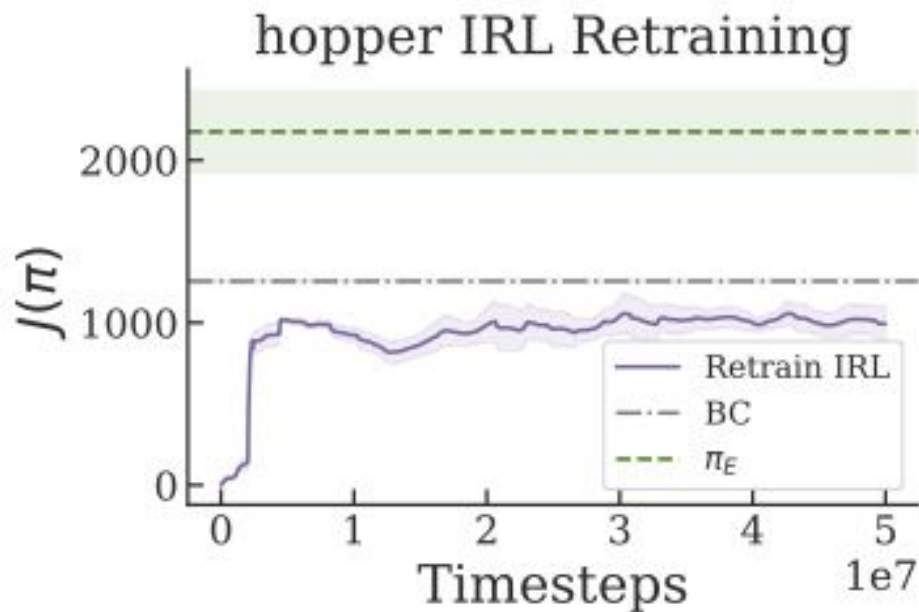




Idea: IRL++ for Effective Retraining

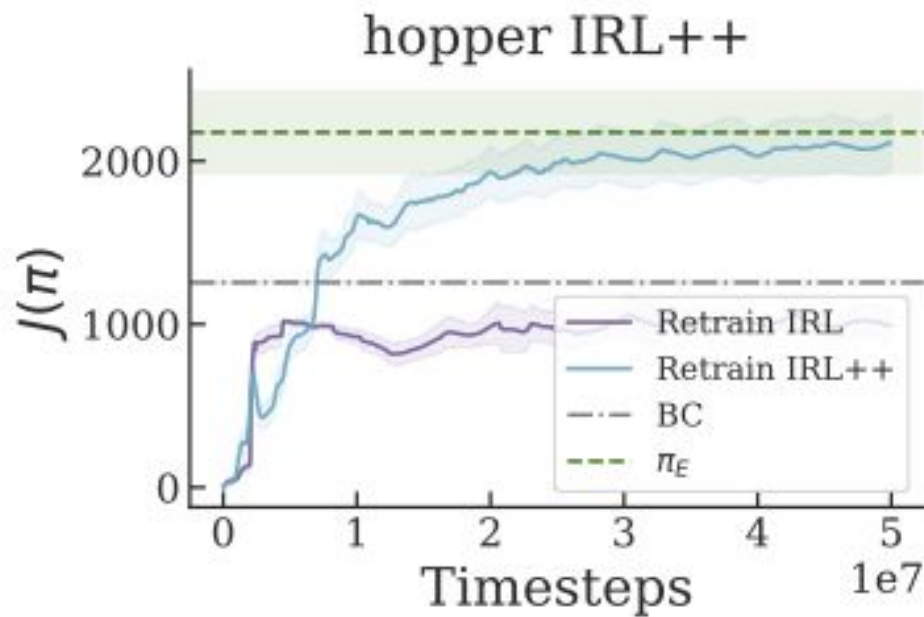


🔑 Problems: Inverse Reinforcement Learning



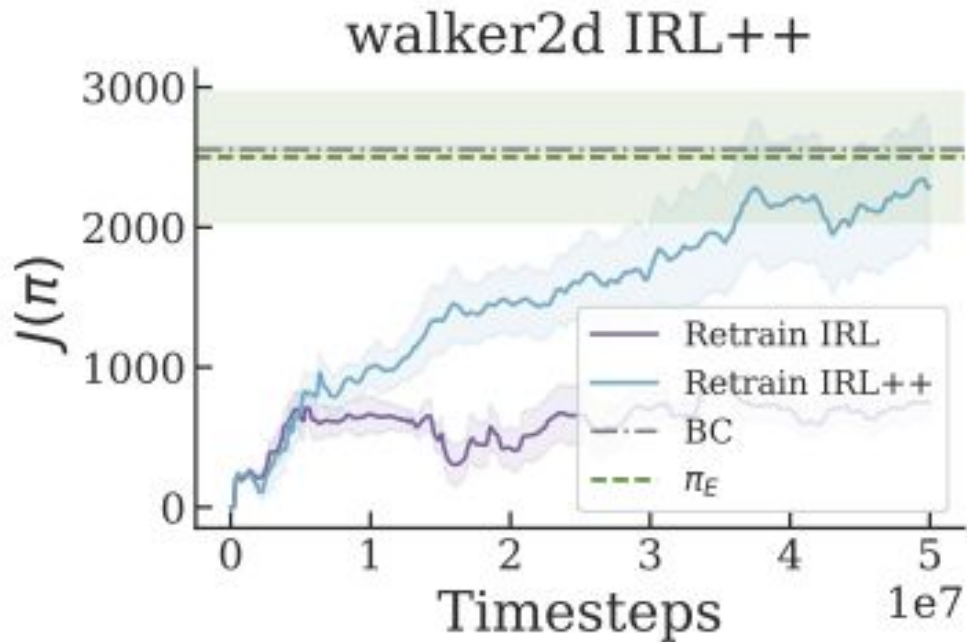
- Not effective
- Not efficient

🔑 Problems: Inverse Reinforcement Learning

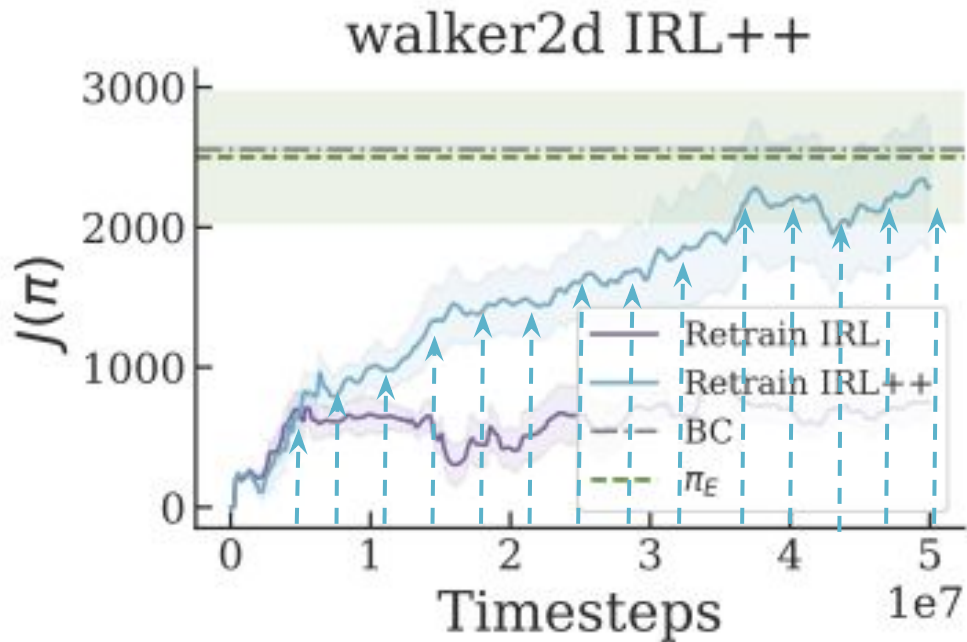


- ~~Not effective~~
- Not efficient

🔑 Idea: Reward Shaping



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Background: Potential-Based Reward Shaping

$$\Phi : \mathcal{S} \rightarrow \mathbb{R} \quad s \in \mathcal{S}$$

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$$\Phi : \mathcal{S} \rightarrow \mathbb{R} \quad s \in \mathcal{S}$$

$$r'(s, a) = r(s, a) + F_{\Phi}(s, s')$$
$$F_{\Phi}(s, s') = \Phi(s') - \Phi(s)$$

Background: Potential-Based Reward Shaping

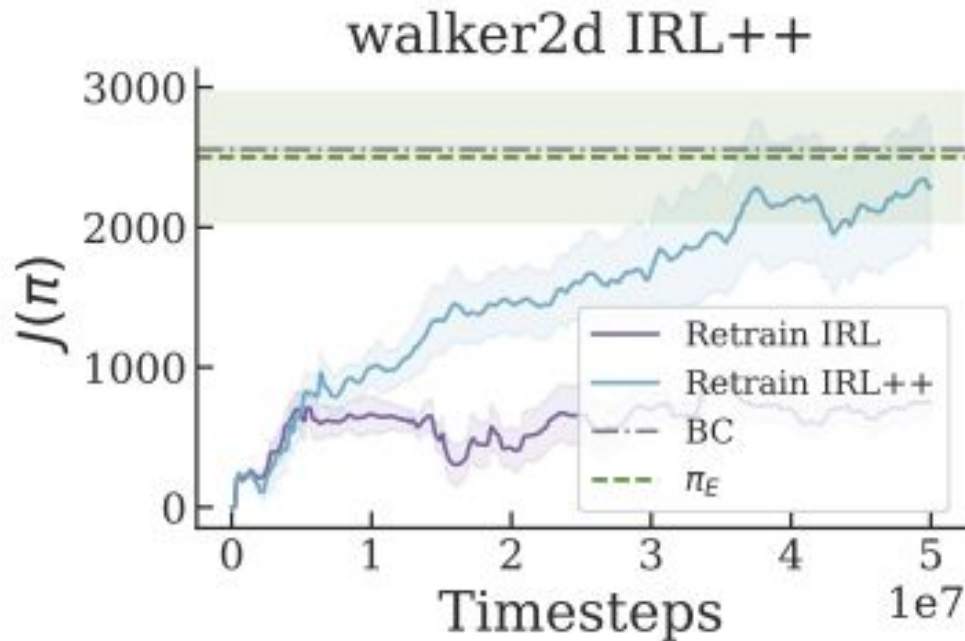
$$r'(s, a) = r(s, a) + F_{\Phi}(s, s')$$

$$F_{\Phi}(s, s') = \Phi(s') - \Phi(s)$$

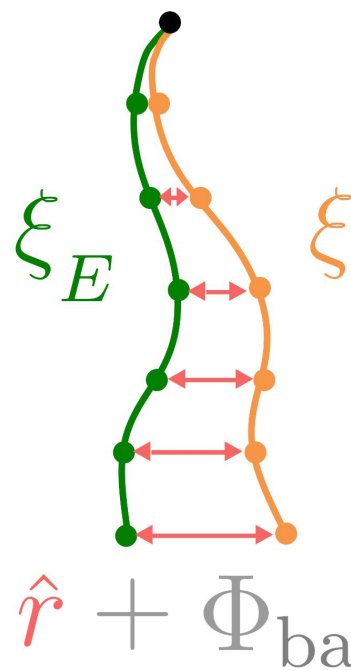
$$\Phi(s) = V^*(s)$$

$$r'(s, a) = r(s, a) + V^*(s') - V^*(s) = A^*(s, a)$$

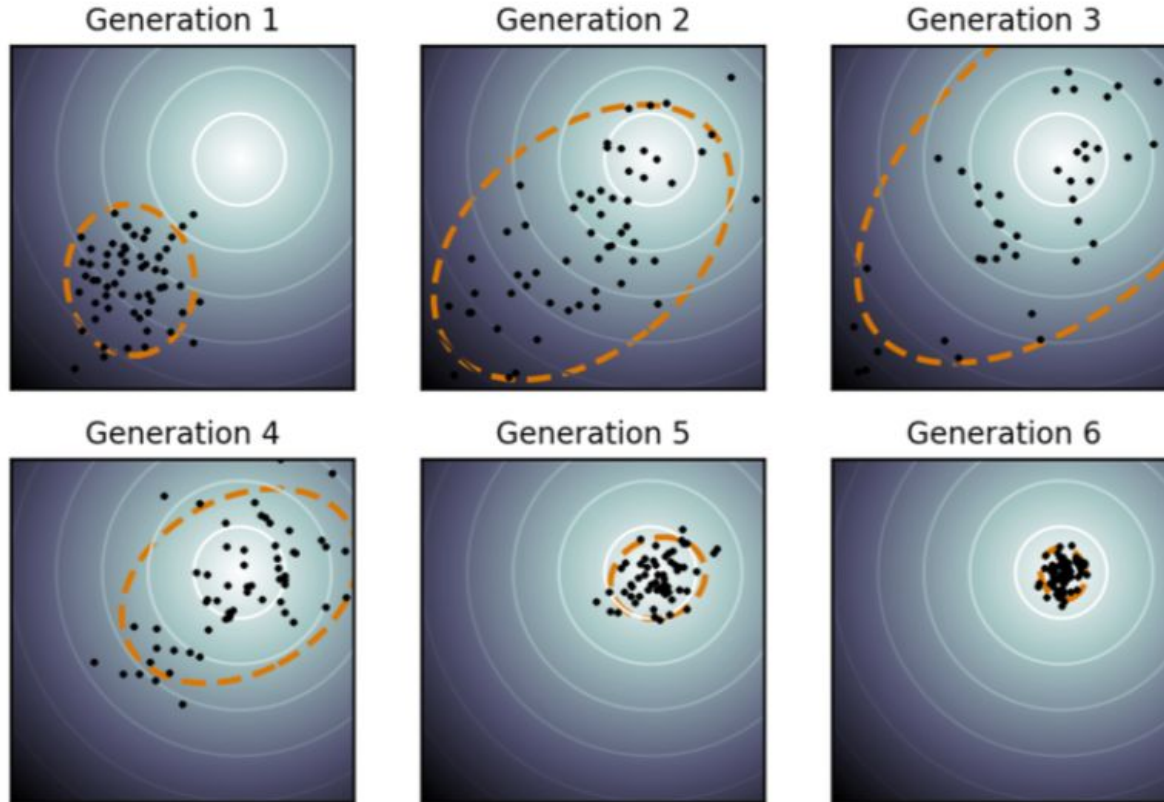
Background: Potential-Based Reward Shaping



1. Inverse RL

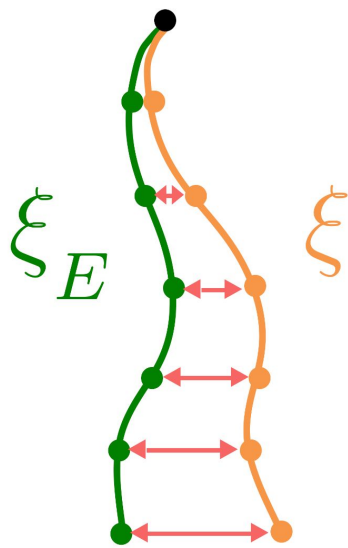


Background: Evolution Strategies



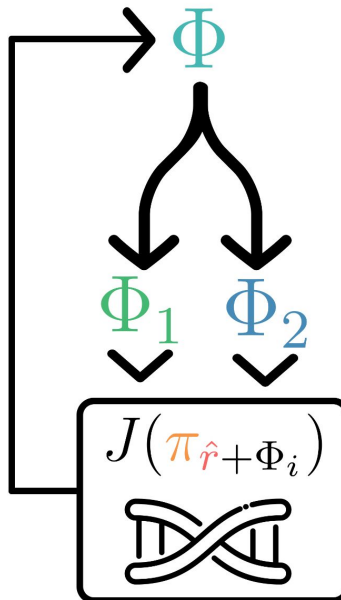
🔑 Idea: Reward Shaping - EvIL 🐈

1. Inverse RL

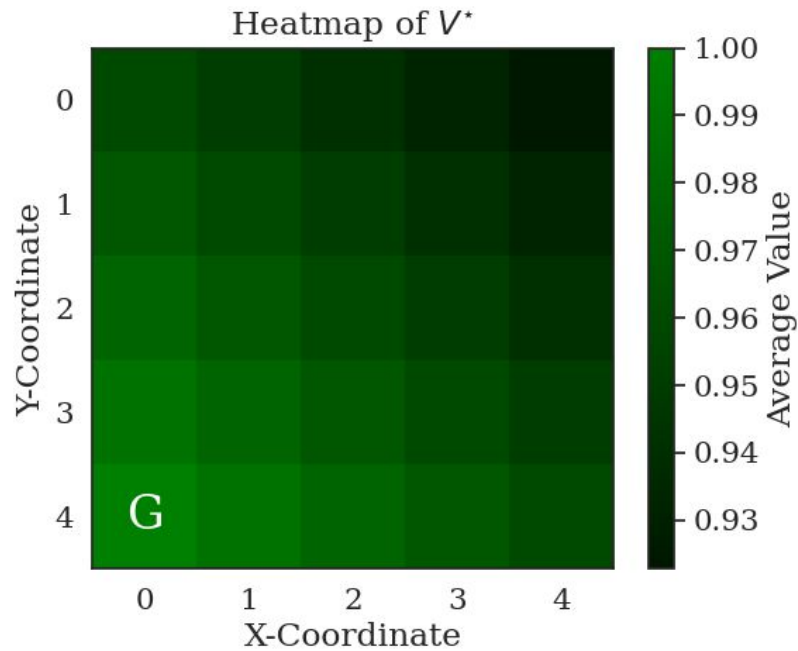
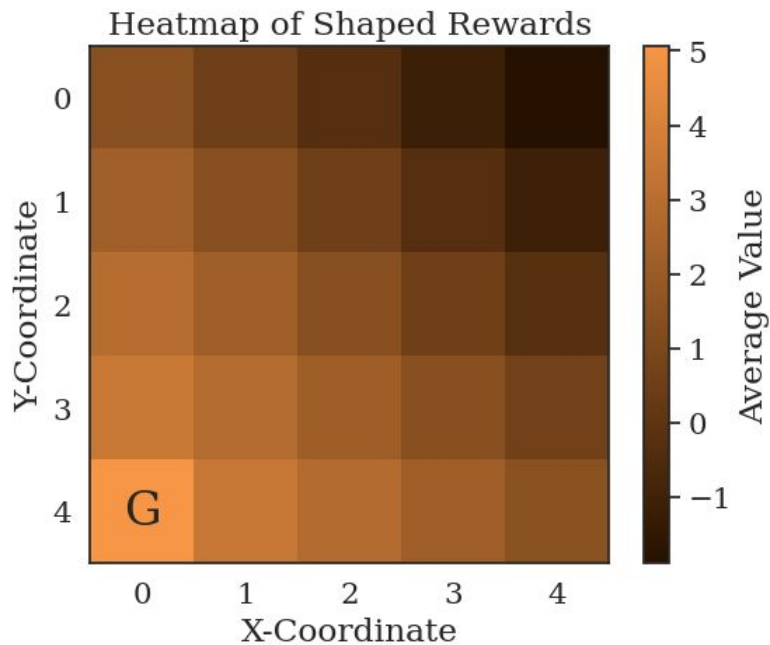


$$\hat{r} + \Phi_{\text{bad}}$$

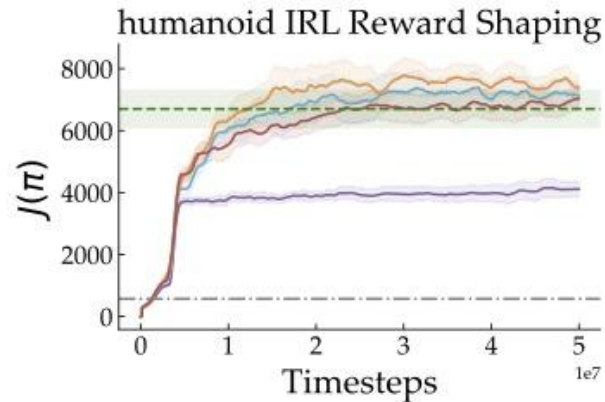
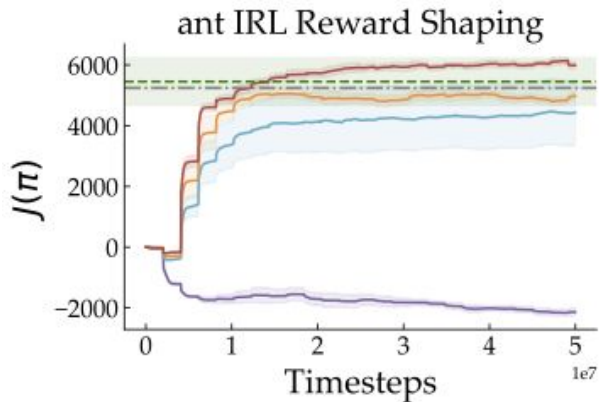
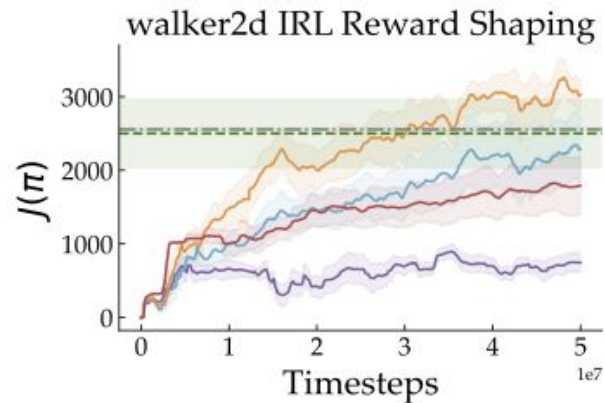
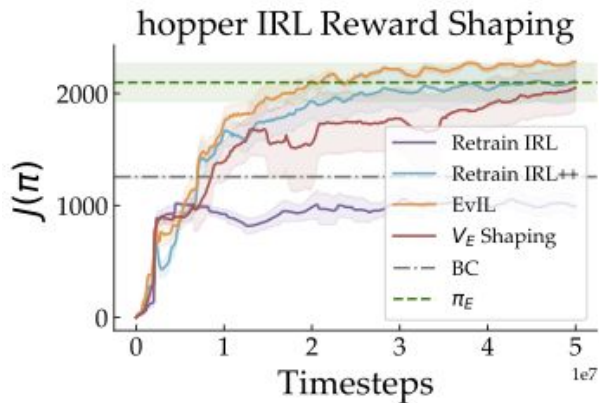
2. Evolve Shaping Term



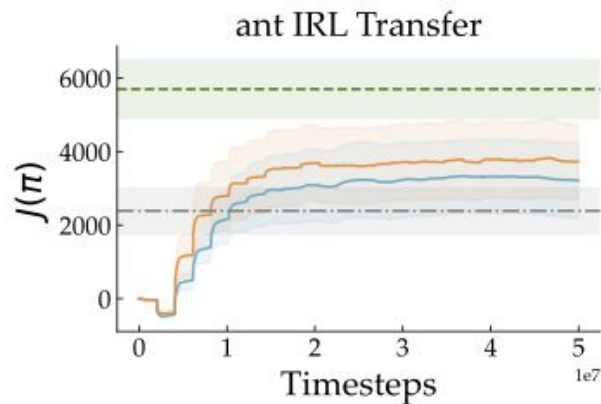
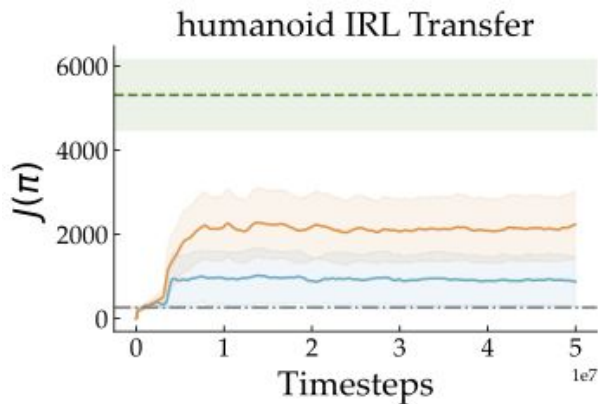
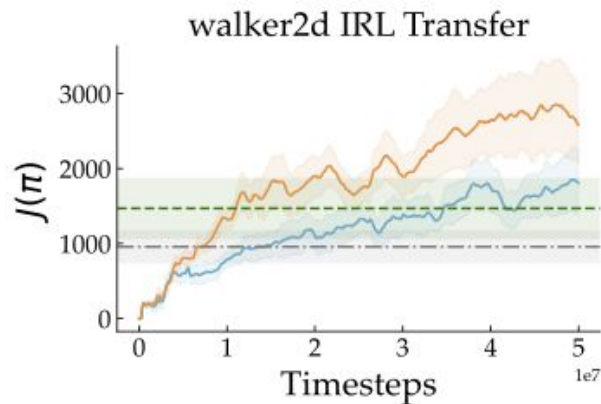
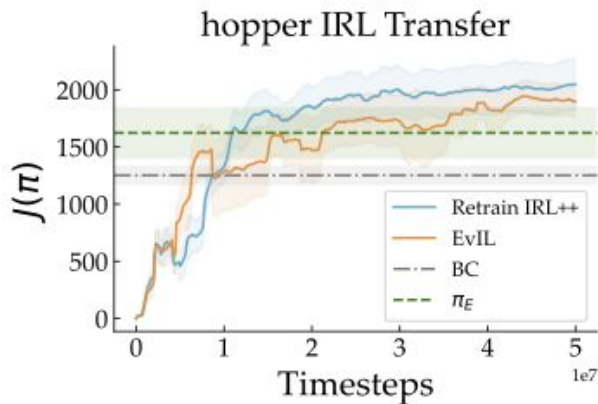
🔑 Idea: Reward Shaping - EvIL 🤩



Results: Reward Shaping - EvIL



Results: Transfer - EvIL



Open Source Code



github.com/SilviaSapora/evil