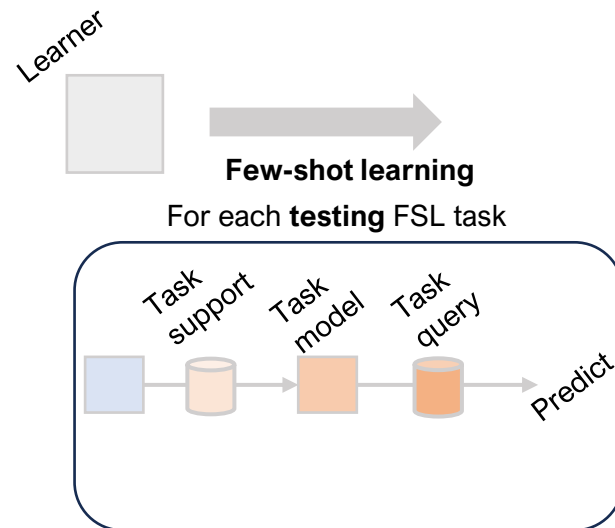


Sparse Meta-Tuning

Problem of interest

Few-shot classification (FSL): learning a model to perform classification from a few labelled examples

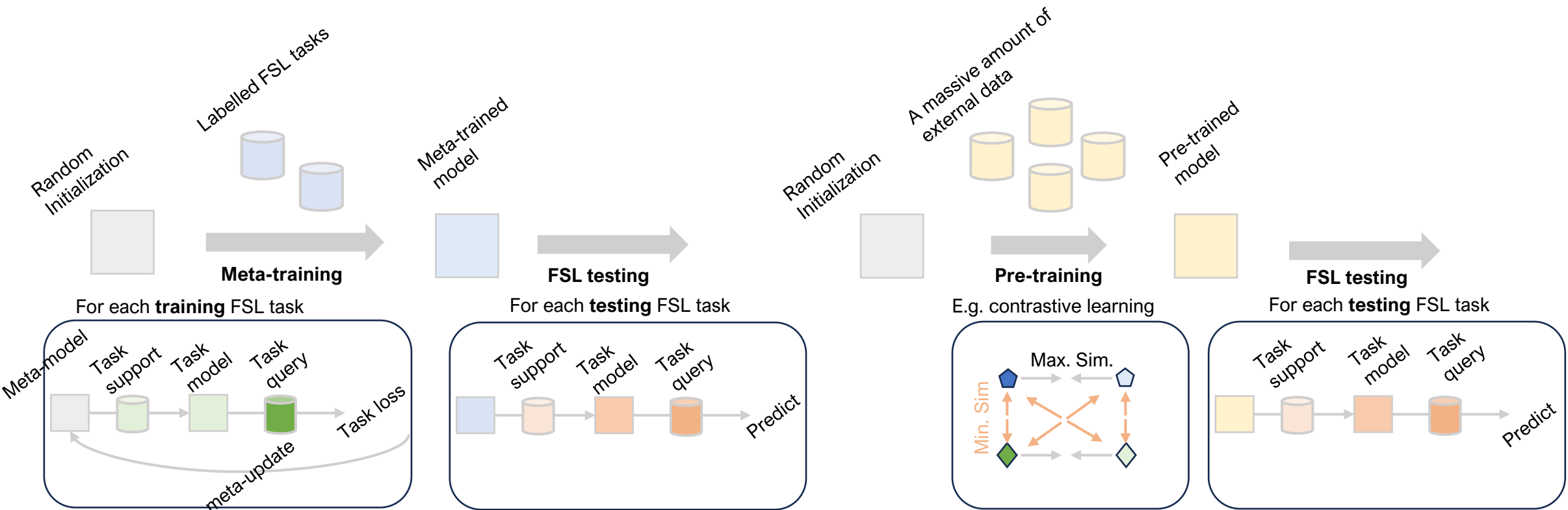


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Few-shot classification (FSL): learning a model to perform classification from a few labelled examples

Two typical approaches:

- **Meta-learning:** train from scratch over labelled few-shot task episodes by maximizing the FSL objective
- **Transfer-learning:** finetune a powerful pre-trained model directly on the few labelled example

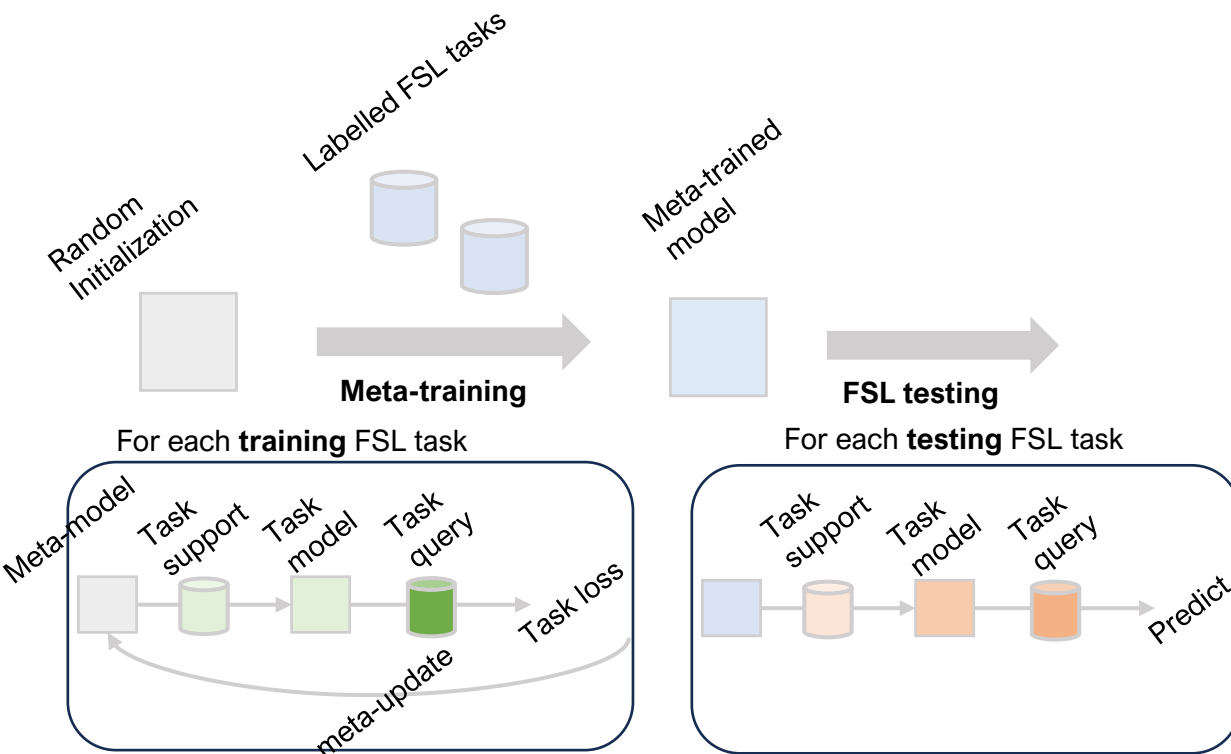


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Challenges:

- **Difficult optimization:** ...second-order optimization...high complexity...from scratch...
- **Suboptimal performance:** typically get outperformed by transfer-learning approaches... especially nowadays in the era of big data and foundation models

Problem of interest

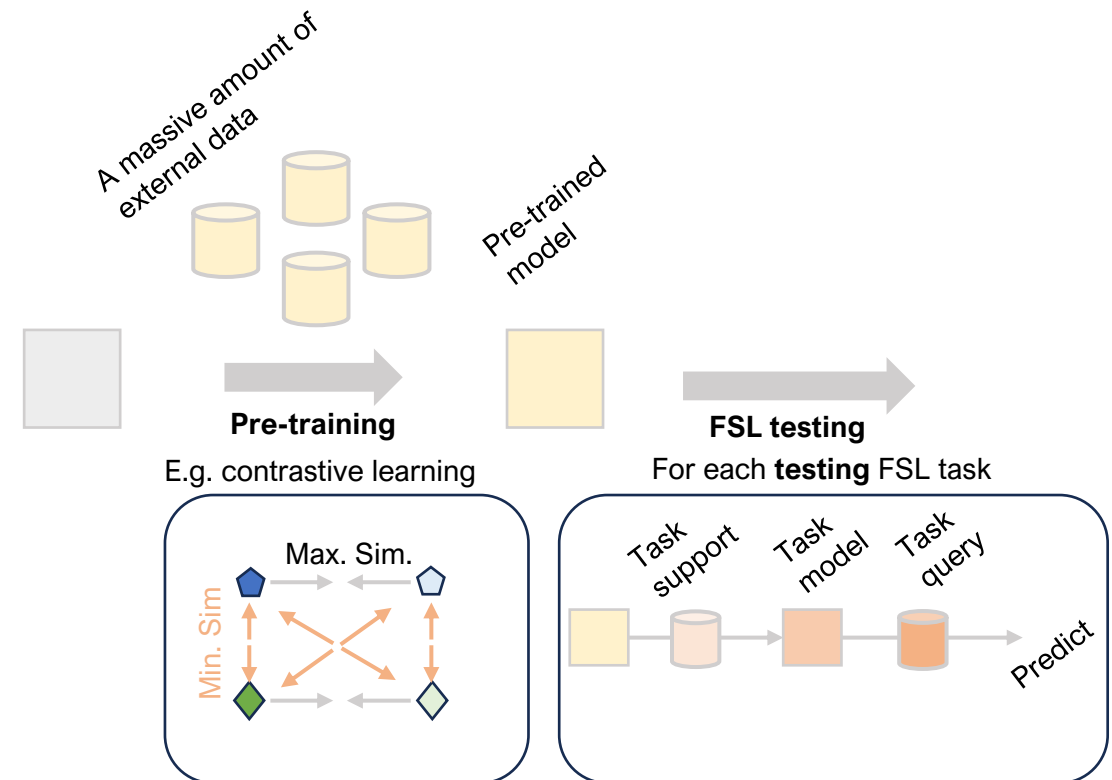
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Challenges:

- **Misaligned objectives** between pre-training and downstream FSL ...
- Therefore, **FSL performance can still be unsatisfactory / suboptimal...**



Problem of interest

Few-shot classification (FSL): learning a model to perform classification from a few labelled examples

Two typical approaches:

- **Meta-learning:** train from scratch over labelled few-shot task episodes by maximizing the FSL objective
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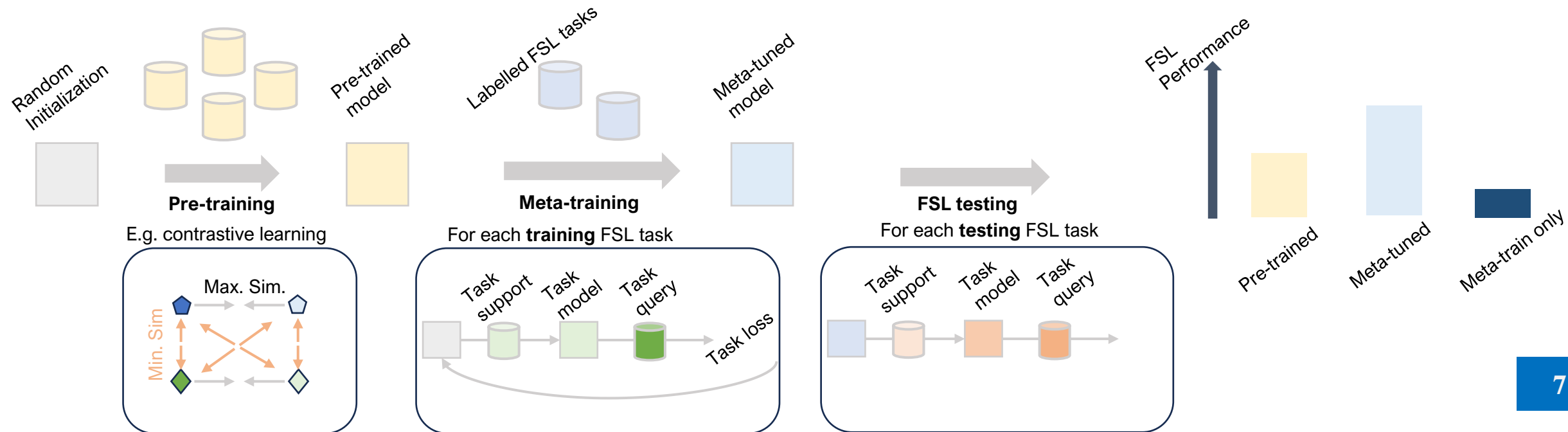
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- **Meta-tuning:** meta-training starting from a pre-trained model



PMF: a previous approach

PMF[†] \equiv Pre-train (DINO) \rightarrow Meta-train (ProtoNet) \rightarrow Fine-tune

- **Simple-yet-effective**: the state-of-the-art approach on the Meta-dataset benchmark

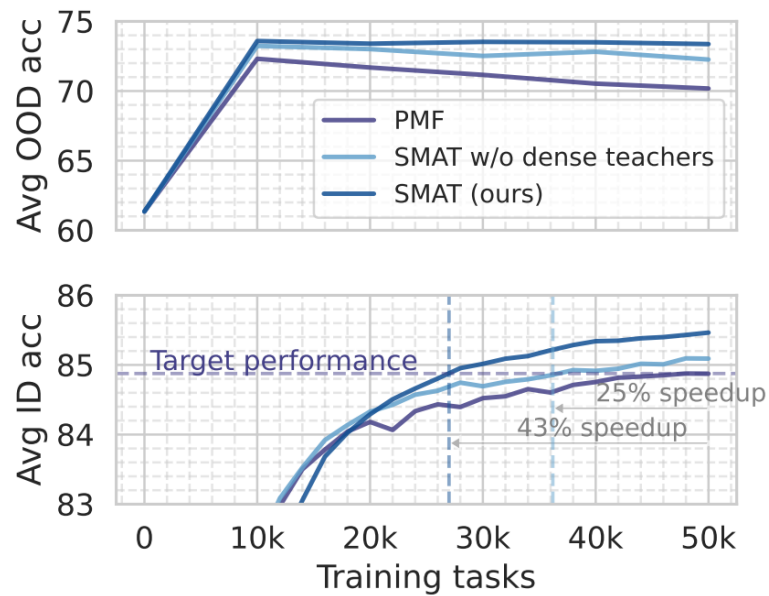
[†] Hu et. al, Pushing the Limits of Simple Pipelines for Few-Shot Learning, CVPR 2022

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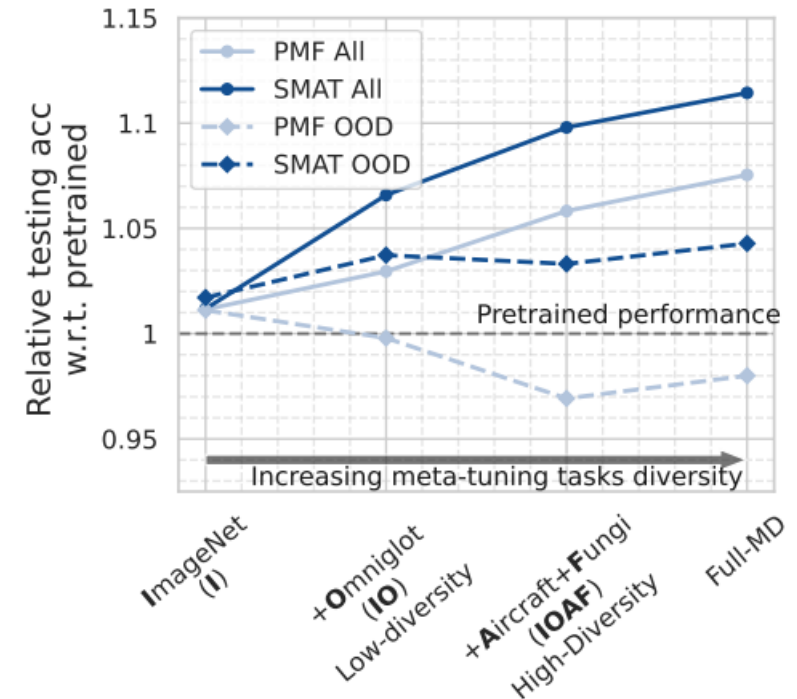
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- Simple-yet-effective: the state-of-the-art approach on the Meta-dataset benchmark
- However, it still suffers from **two major drawbacks**

Meta-overfitting



Task interference



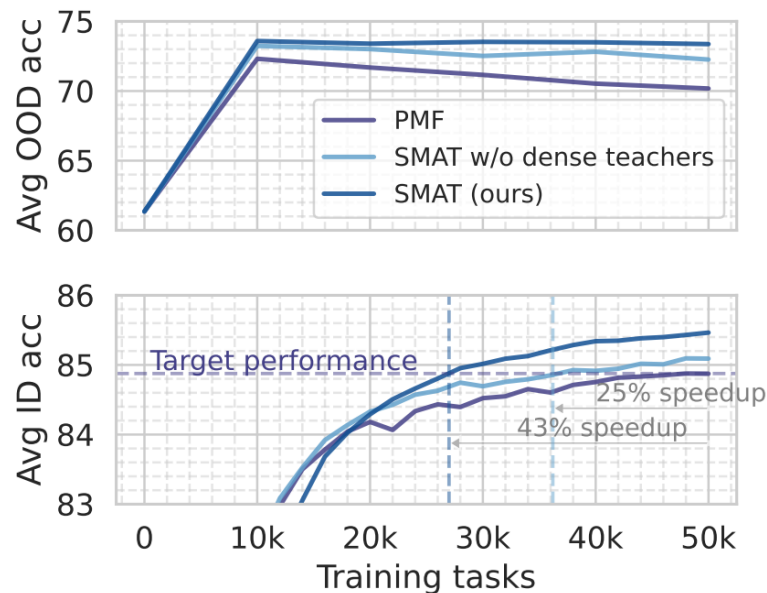
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Meta-overfitting



Improved ID generalization performance



But, at a **significant cost of OOD** performance

[†] Hu et. al, Pushing the Limits of Simple Pipelines for Few-Shot Learning, CVPR 2022

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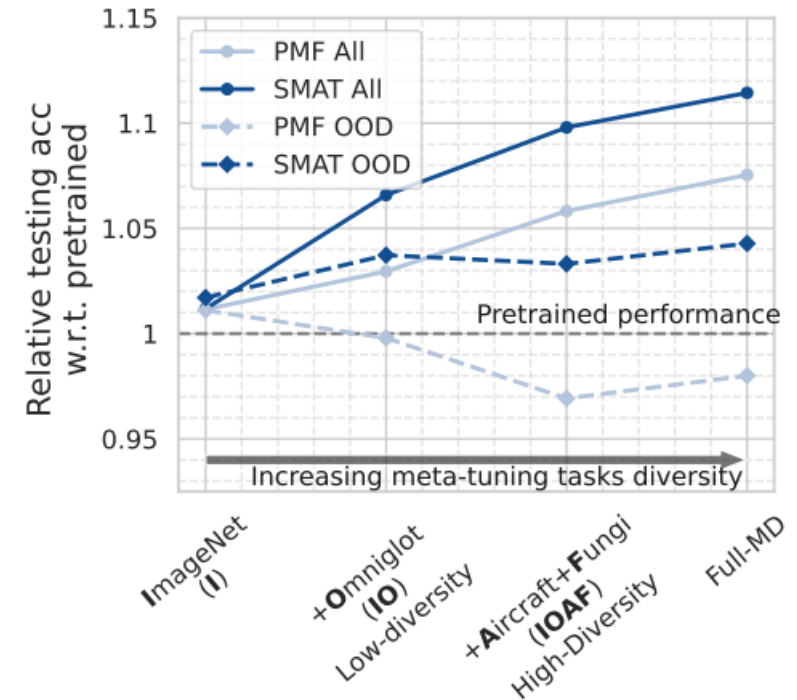
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- **Simple-yet-effective**: the state-of-the-art approach on the Meta-dataset benchmark
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↑ **Improved overall** generalization performance

↓ But, the improvement **scales less-well** with more meta-training datasets

Task interference



[†] Hu et. al, Pushing the Limits of Simple Pipelines for Few-Shot Learning, CVPR 2022

How can we improve it?

Our goal: a meta-tuning method that pushes toward the ID/OOD performance Pareto front

Sparse MeTa-Tuning (SMAT) key ideas:

- 1. Meta-learn sparsely interpolated experts:**
 - Sparse weight interpolation finds optimal ID and OOD performance
- 2. Mixture-of-expert (MoE)-inspired model:**
 - A balanced point between fully task-agnostic and task-specific

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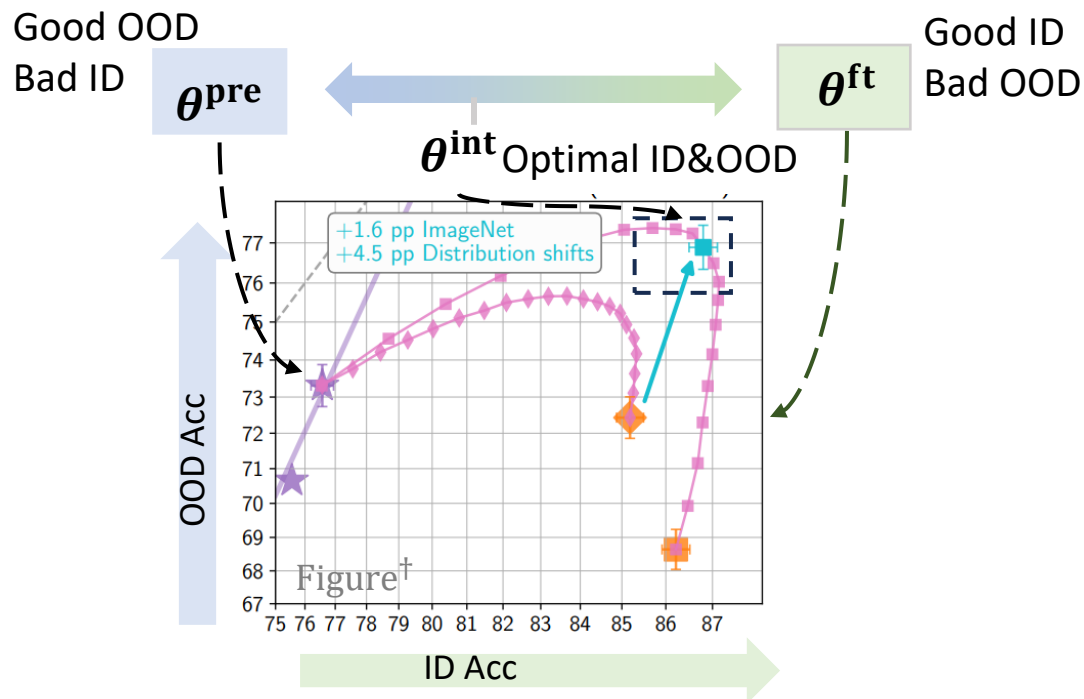
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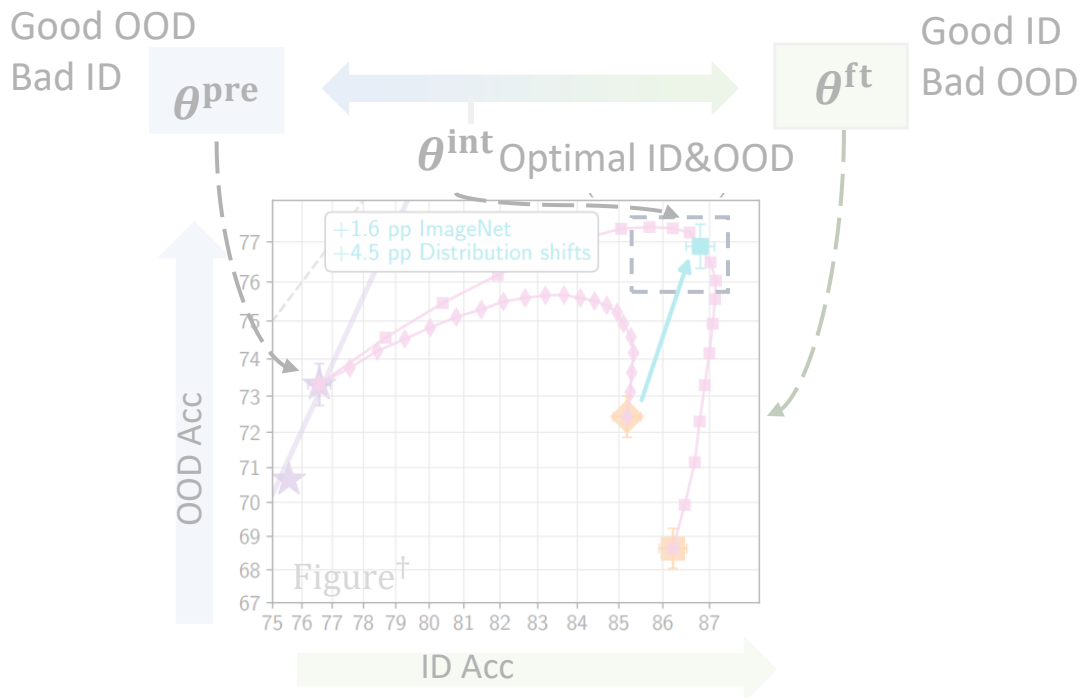


[†] Wortsman et. al, Robust fine-tuning of zero-shot models, CVPR 2022

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Fully **task-agnostic** ← **Partitioned:** → Fully **task-specific**
 E.g., PMF E.g., Task experts

task-specific & task-agnostic
 E.g., SMAT

$$\theta_1 = \theta_2 = \theta_3$$

$$\theta_i = \sum_m \alpha_{i,m} \cdot \theta_m^{\text{expert}}$$

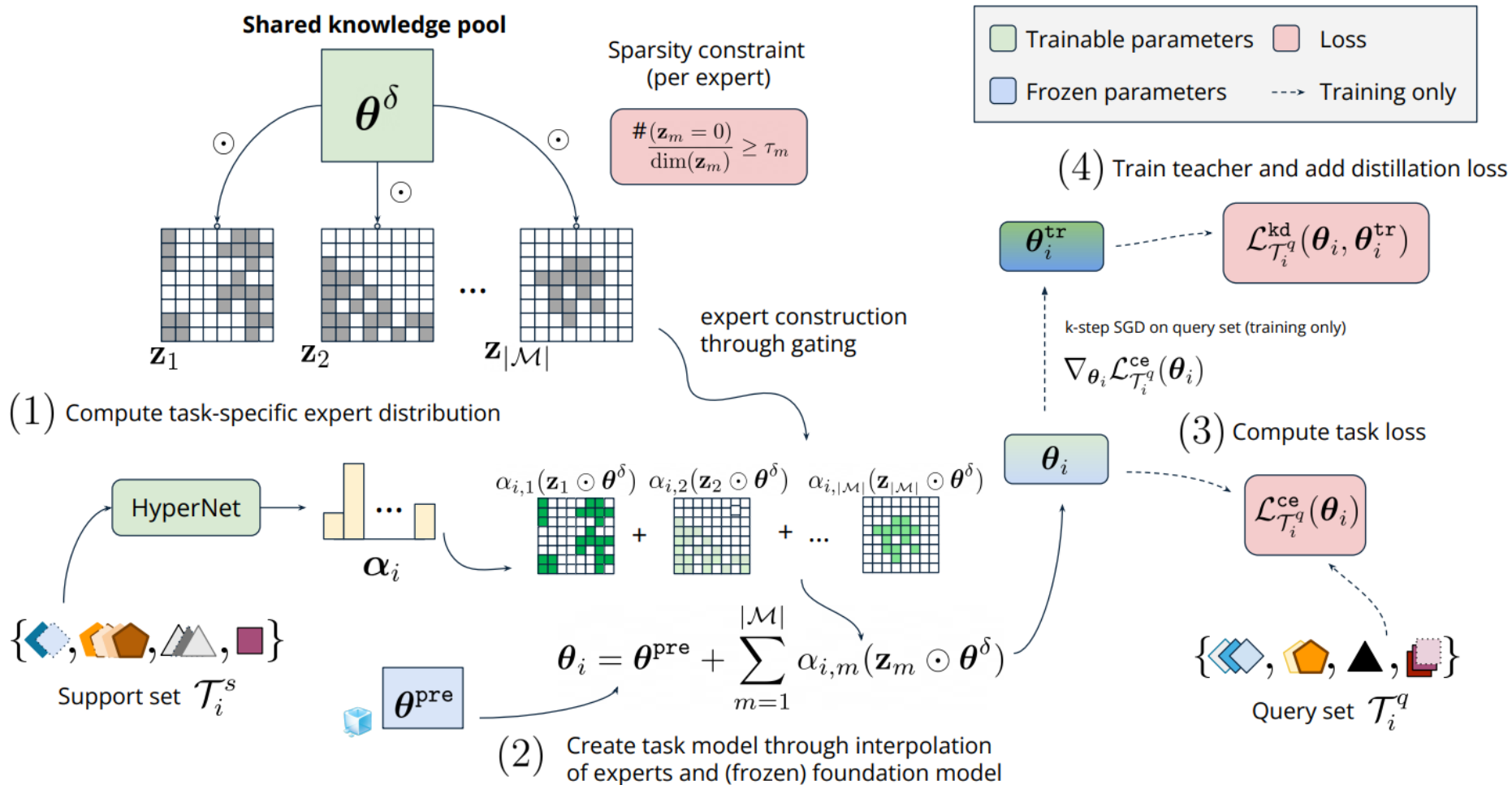
$$\theta_1 \quad \theta_2 \quad \theta_3$$

High interference
Allow transfer

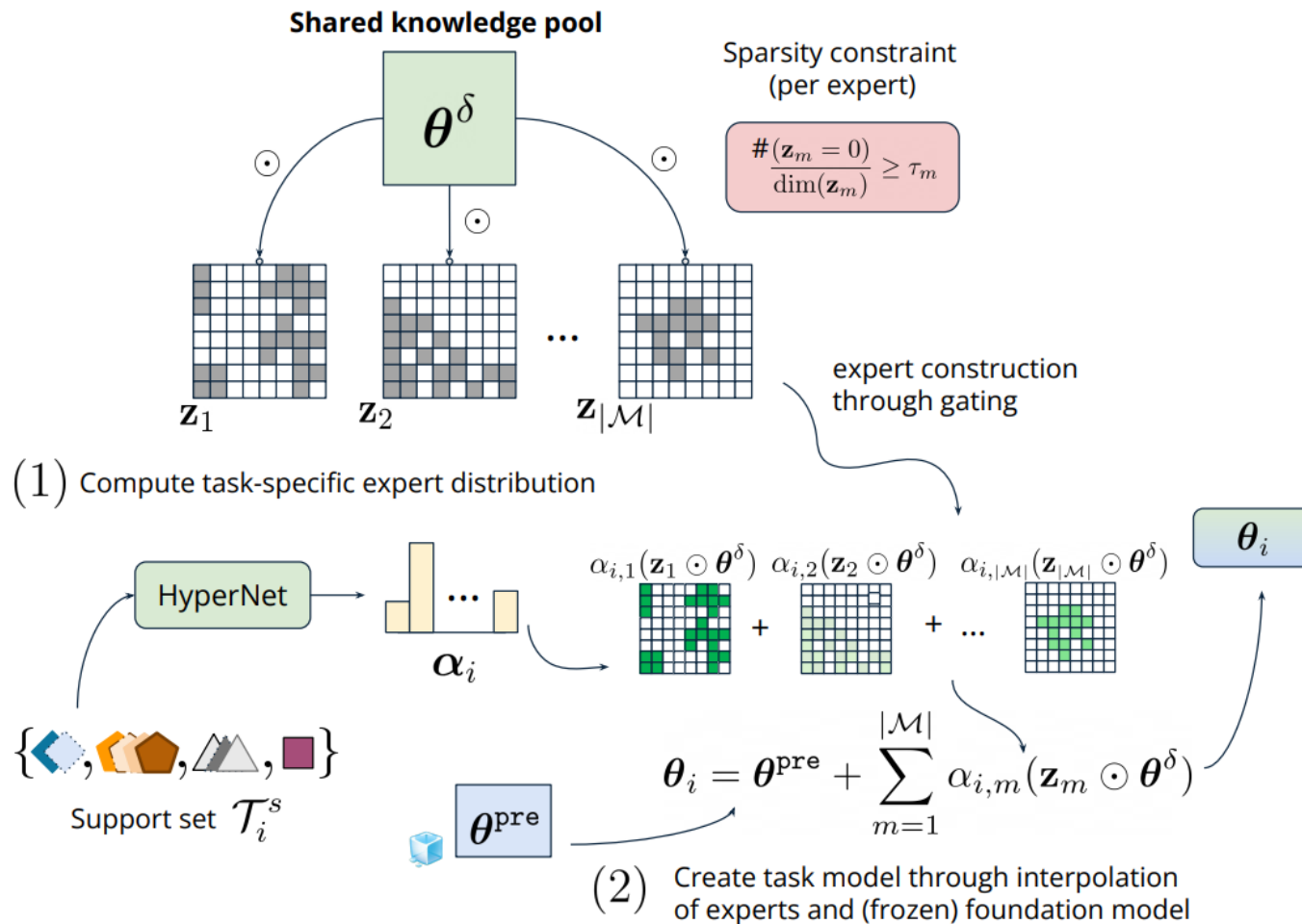
Reduced interference
Allow transfer

No interference
No transfer

SMAT: overview



SMAT: meta-training



Task-specific expert merging

- $|\mathcal{M}|$ distinct sparse experts, $(\mathbf{z}_m \odot \theta^\delta)$
- a common merging rule defined by a hypernetwork that outputs task-specific expert distribution α_i based on the task support set.

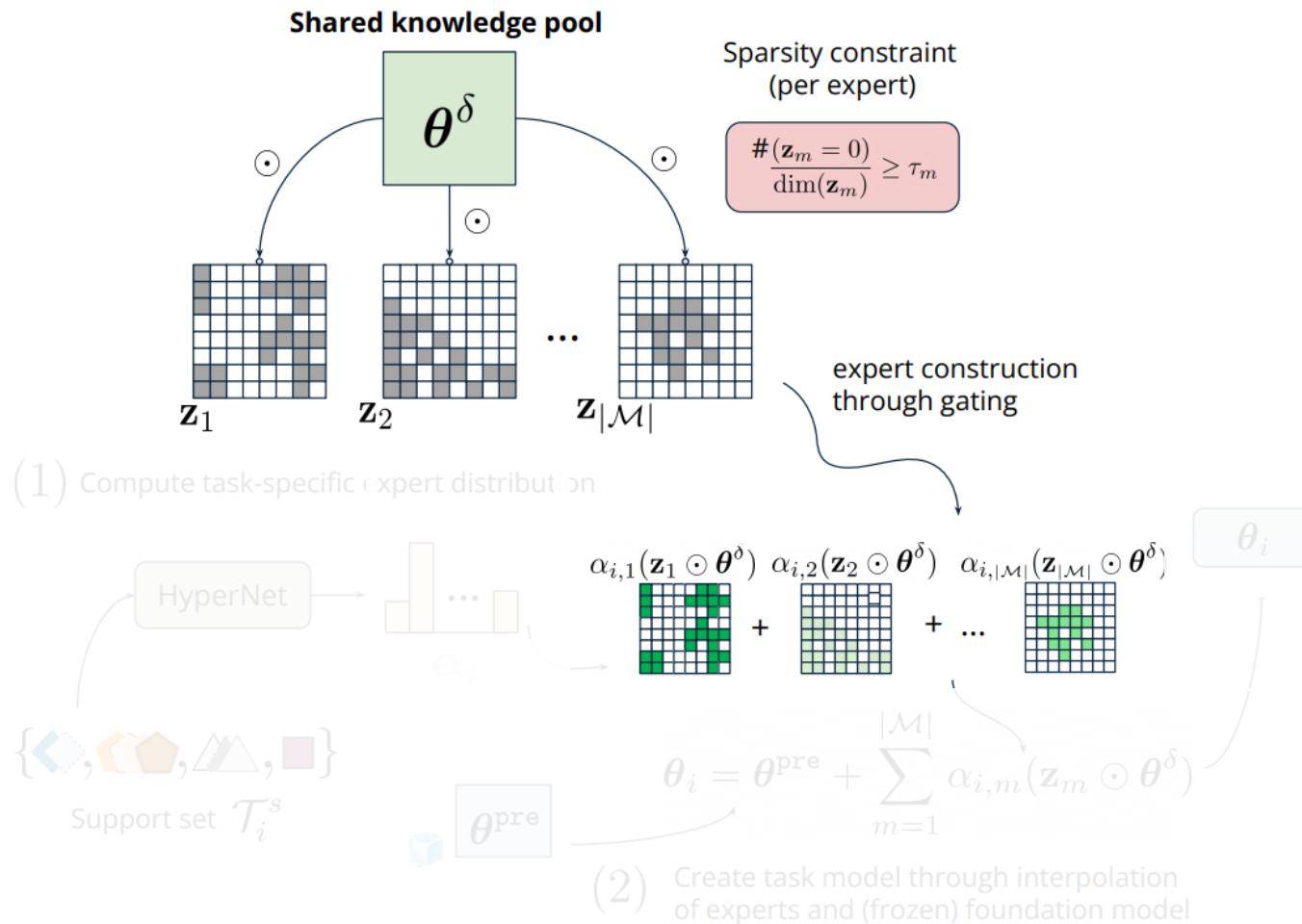
Meta-learn sparse reparameterization

- $\{\mathbf{z}_m\}$: **distinct, sparse**, binary gates $\in [0,1]^{|\theta|}$
- θ^δ : a **shared, dense** reparameterization
- Thus, meta-learn \mathbf{z}_m end-to-end effectively discover *where-to-share* and *where-to-specialize*.
- **No bias** as in hand-crafted task-specific/task-agnostic partition

Interpolation between common θ^{pre} and θ^δ

- Sparsity of $\{\mathbf{z}_m\}$ (also α_i) controls the relative interpolation strength
- $\{\mathbf{z}_m\}$ define the big picture:
 - More 1s = More like the meta-tuned model
 - More 0s = More like the pre-trained model
- α_i allows local, task-specific variation:
 - Different expert distribution across tasks

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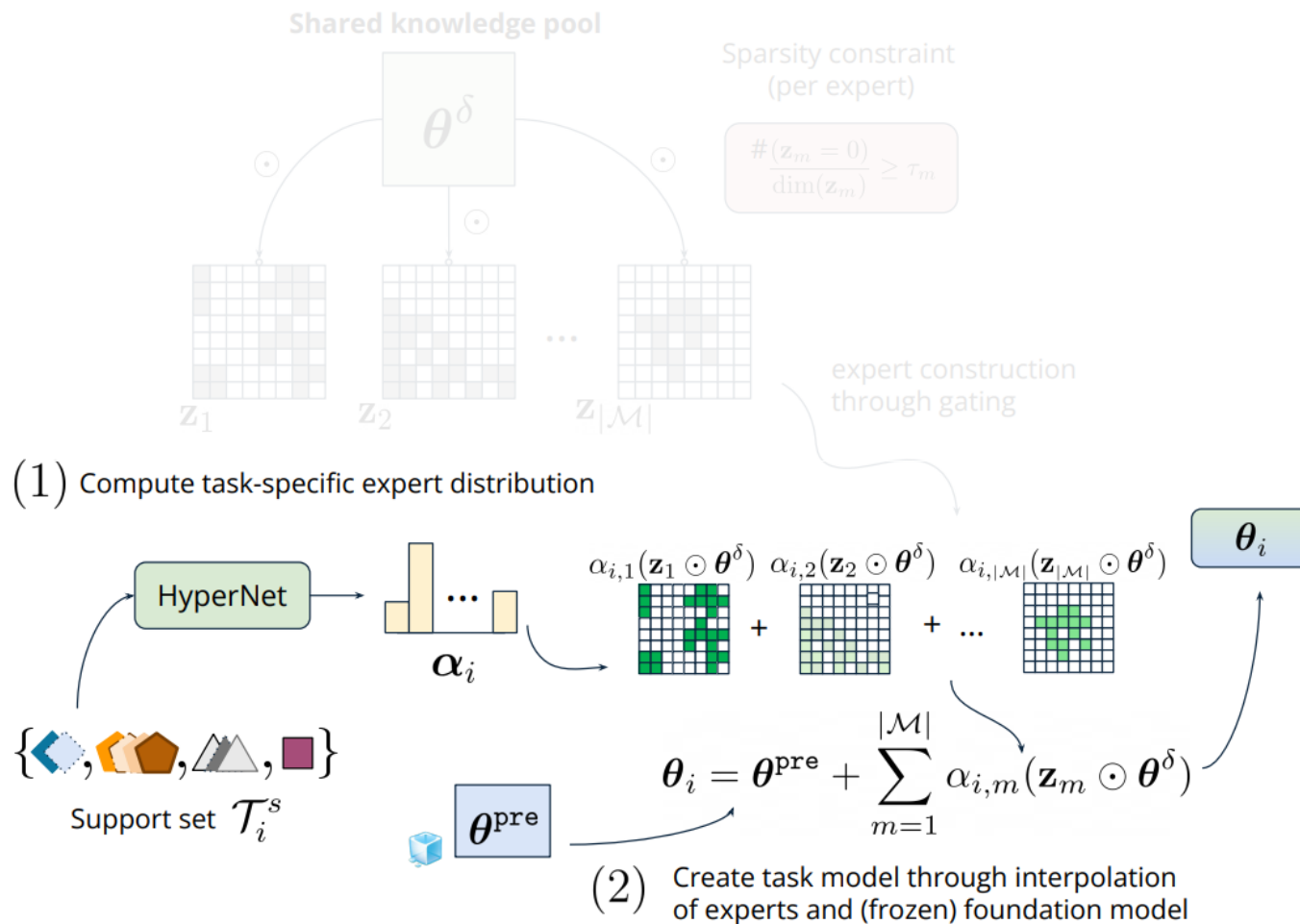
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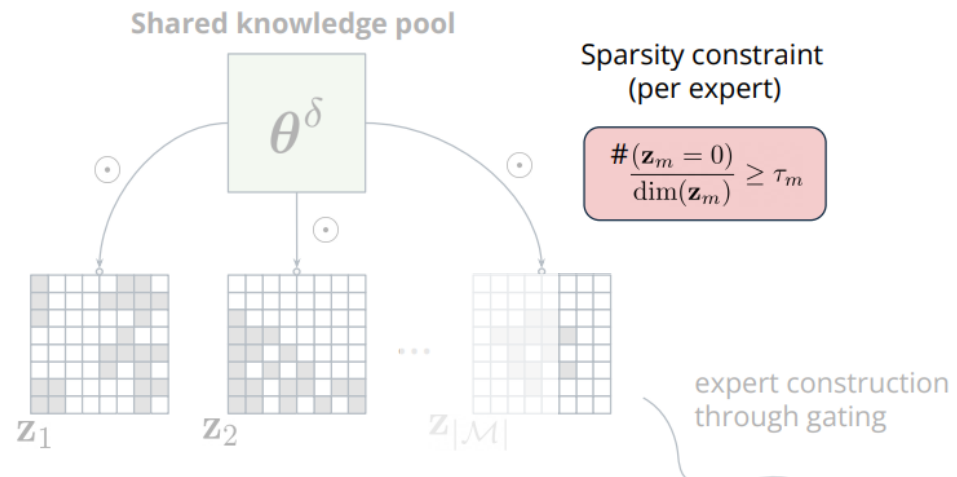
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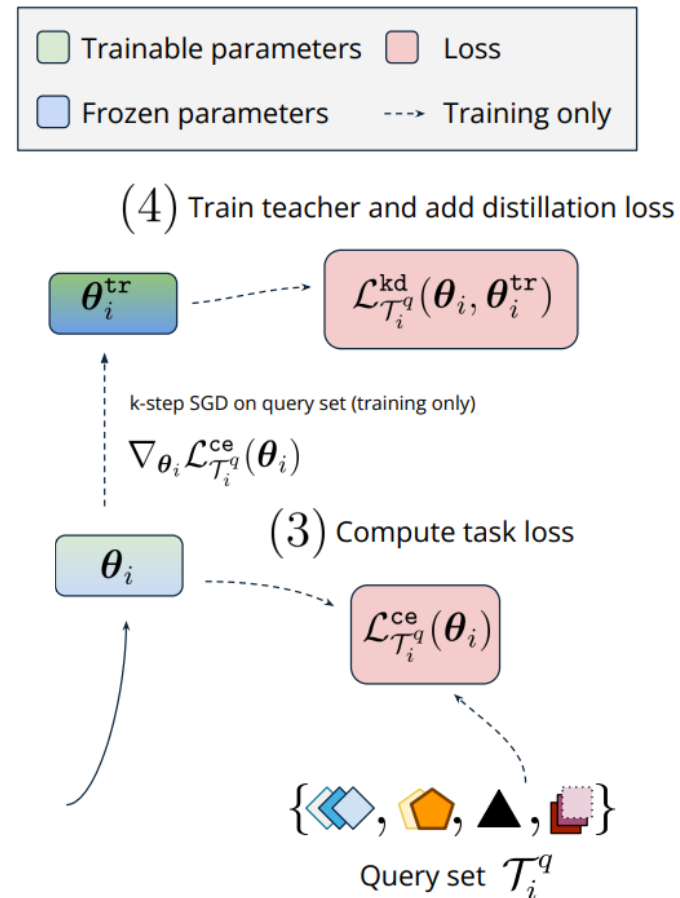
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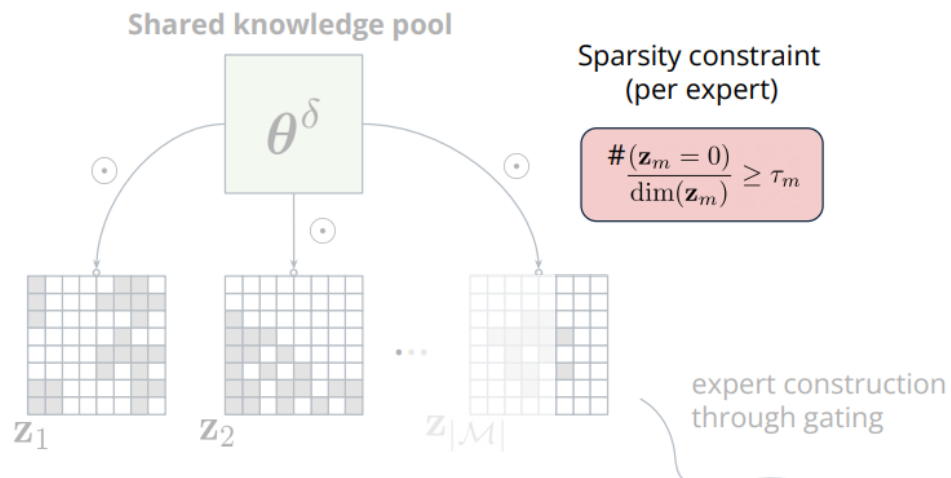


Task-specific dense teachers

- θ_i^{tr} : a **unconstrained, highly task-specific** teacher
- θ_i : merged model, **implicitly constrained** by sparsity constraints on individual experts.
- **Knowledge distillation** enforces the student to mimic the teacher, therefore encourages specialization and cooperation among experts.



SMAT: meta-training



Everything together into a Lagrangian

$$\min_{\theta^\delta, \zeta, \Phi} \max_{\lambda \geq 0} \mathbb{E}_{\mathcal{T}_i \sim \mathcal{P}_{ID}} [\mathcal{L}_{\mathcal{T}_i^q}^{\text{ce}}(\theta_i) + \mathcal{L}_{\mathcal{T}_i^q}^{\text{kd}}(\theta_i, \theta_i^{\text{tr}})]$$

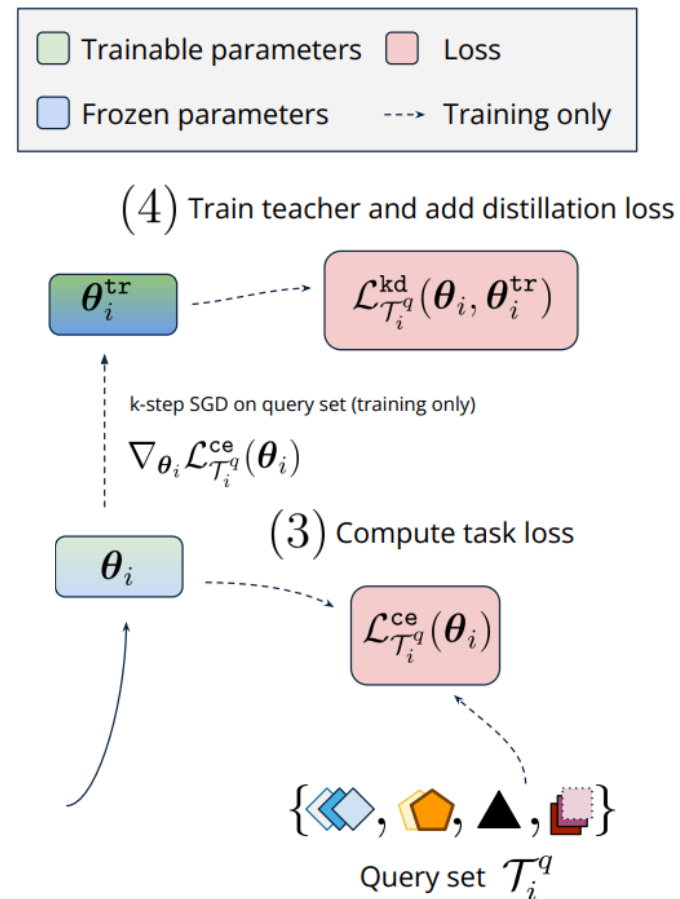
$$+ \sum_{m=1}^{|\mathcal{M}|} \lambda_m \left(\frac{1}{|\phi_m|} \sum_{k=1}^{|\phi_m|} \tau - Q_{\phi_m}(s_k \leq 0) \right)$$

where $\theta_i = \theta^{\text{pre}} + \sum_{m=1}^{|\mathcal{M}|} \alpha_{i,m} (\mathbf{z}_m \odot \theta^\delta)$,

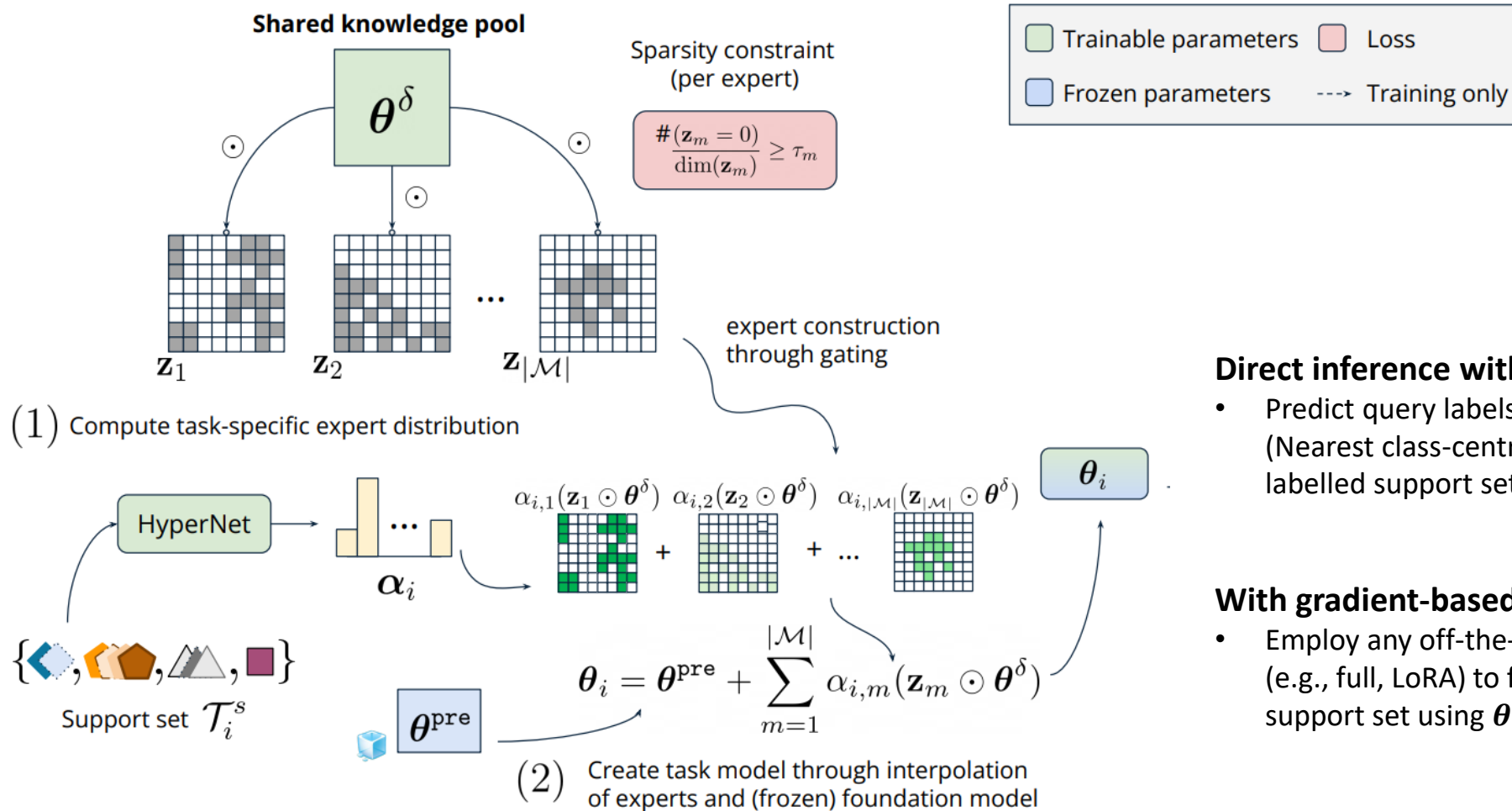
$$\mathbf{z}_m \sim q_{\phi_m}; \alpha_i \sim h_\zeta(\mathcal{T}_i^s),$$

Q_{ϕ_m} : The CDF of the variational distribution for optimization \mathbf{z}_m

We share the sparsity constraint τ for all experts for simplicity



SMAT: inference



Direct inference without fine-tuning

- Predict query labels by constructing a ProtoNet (Nearest class-centroid) classifier with θ_i and the labelled support set

With gradient-based fine-tuning

- Employ any off-the-shelf fine-tuning techniques (e.g., full, LoRA) to fine-tune the model on the support set using θ_i as an initialization.

Experimental results

Comparing with the SOTA on Meta-dataset

- **SMAT (Ours) outperforms baselines under all evaluation scenarios**

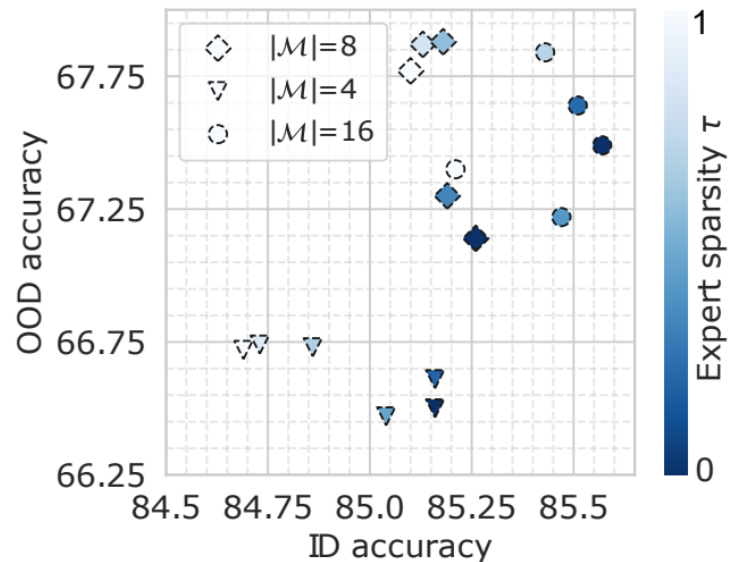
Table 1. Few-shot testing results on the Meta-dataset benchmark and additional OOD testing datasets for methods using DINO-ViT-Small backbone. [†] and [‡] respectively indicate published results in [†](Hu et al., 2022) and [‡](Basu et al., 2023). Gray indicates our method.

Datasets	w/o fine-tuning				with gradient-based fine-tuning						
	[†] Pre	[†] PMF	SoftMerge	SMAT	[‡] Pre+full	[†] PMF+full	SoftMerge+full	SMAT+full	[‡] Pre+LoRA	PMF+LoRA	SMAT+LoRA
ImageNet	73.48	73.54	74.33	74.94	73.54	74.59	74.71	75.24	74.22	73.54	75.72
Aircraft	62.17	88.33	88.80	89.49	75.4	88.33	90.6	90.78	80.8	89.75	90.71
Omniglot	54.33	91.79	91.24	89.54	78.7	91.79	92.01	90.83	80.8	92.78	90.99
CUB	85.37	91.02	91.54	92.48	85.4	91.02	91.95	92.48	85.8	91.17	92.42
DTD	83.67	81.64	80.98	85.86	86.9	86.61	86.84	88.34	86.8	86.73	88.28
Quickdraw	60.59	79.23	78.98	78.83	73.6	79.23	79.90	78.83	72.7	79.23	78.83
Fungi	56.26	74.2	72.40	72.8	54.7	74.20	72.40	72.80	59.8	75.44	72.80
VGGFlower	94.45	94.12	96.89	97.19	94.2	94.12	97.01	97.19	94.8	96.05	97.25
ID Avg	71.29	84.23	84.40	85.14	77.81	84.99	85.56	85.81	79.47	85.59	85.88
TrafficSig	53.7	54.37	56.21	58.51	87.3	88.85	89.91	90.83	88.1	89.14	90.18
MSCOCO	54.58	57.04	55.75	57.35	61.5	62.59	62.15	63.07	62.1	61.71	63.38
Cifar10	85.64	80.82	84.58	83.95	92.48	89.61	91.84	92.08	93.33	91.53	92.46
Cifar100	76.86	69.11	70.85	74.85	86.13	82.54	85.88	85.91	86.17	85.06	85.88
MNIST	78.57	93.33	94.16	94.53	92.54	96.44	96.20	96.73	94.98	96.41	96.46
Sketch	47.25	41.10	43.30	48.91	56.39	49.65	53.85	56.55	57.34	47.59	55.63
Food	91.73	91.37	89.84	92.31	92.03	91.73	90.48	92.31	92.06	92.01	92.31
Clipart	55.19	53.92	54.83	59.87	67.18	62.83	65.50	65.76	66.51	60.6	66.07
Pet	62.64	61.89	63.04	65.59	65.08	62.97	63.36	67.43	65.06	62.71	67.77
Cars	34.58	38.00	36.21	36.79	40.98	40.07	41.62	42.39	39.49	42.37	40.05
OOD Avg	64.07	64.10	64.87	67.27	74.16	72.73	74.08	75.31	74.51	72.91	75.02

More analysis

The roles of sparsity level τ for SMAT

1. Sparsity level establishes a trade-off between ID and OOD generalization performance
2. Appropriate sparsity level encourages expert specialization

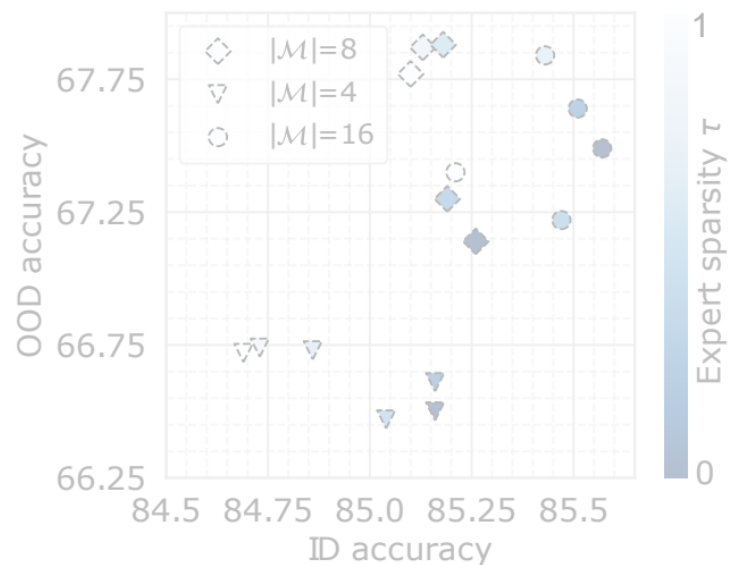


(a) Average performance tradeoff on sampled ID vs OOD tasks as a function of (color) expert sparsity level τ , and (marker) number of experts.

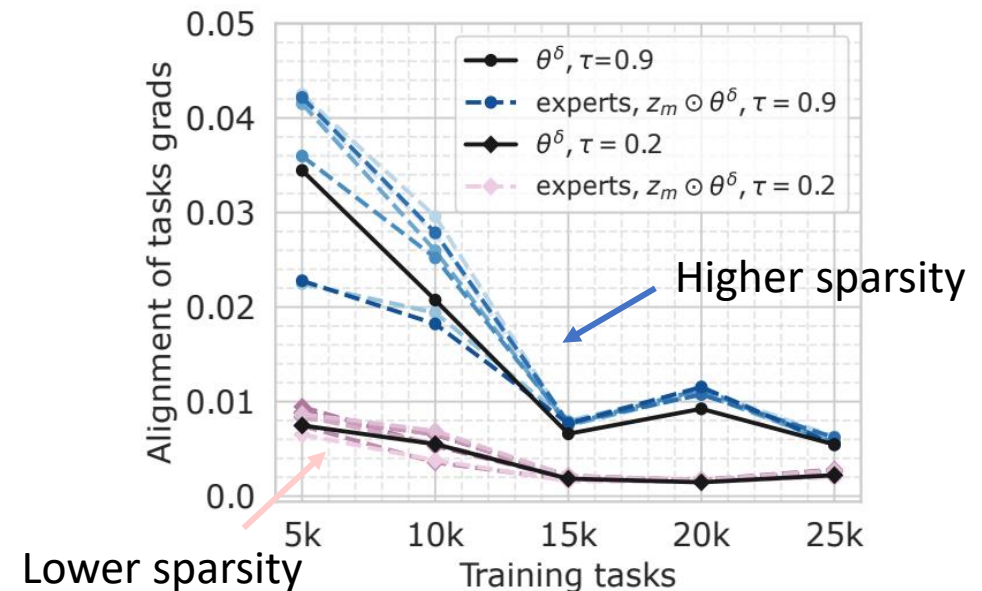
More analysis

The roles of sparsity level τ for SMAT

1. Sparsity level controls the trade-off between ID and OOD performance
2. Appropriate sparsity level encourages gradient alignment between tasks



(a) Average performance tradeoff on sampled ID vs OOD tasks as a function of (color) expert sparsity level τ , and (marker) number of experts.



(b) Meta-gradients alignment between tasks throughout for SMAT with low and high sparsity levels. Meta-gradients are calculated w.r.t. the parameters shown in the legend.

Qualitative visualization

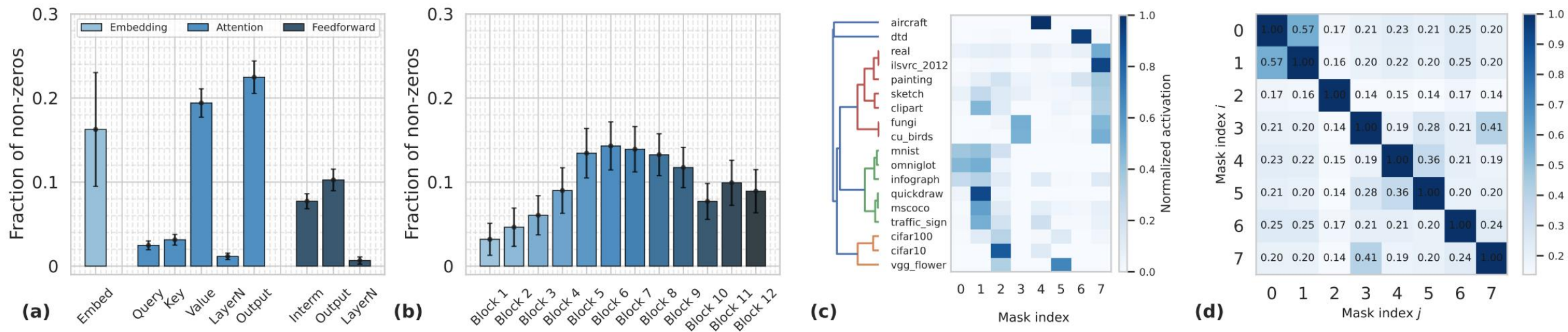
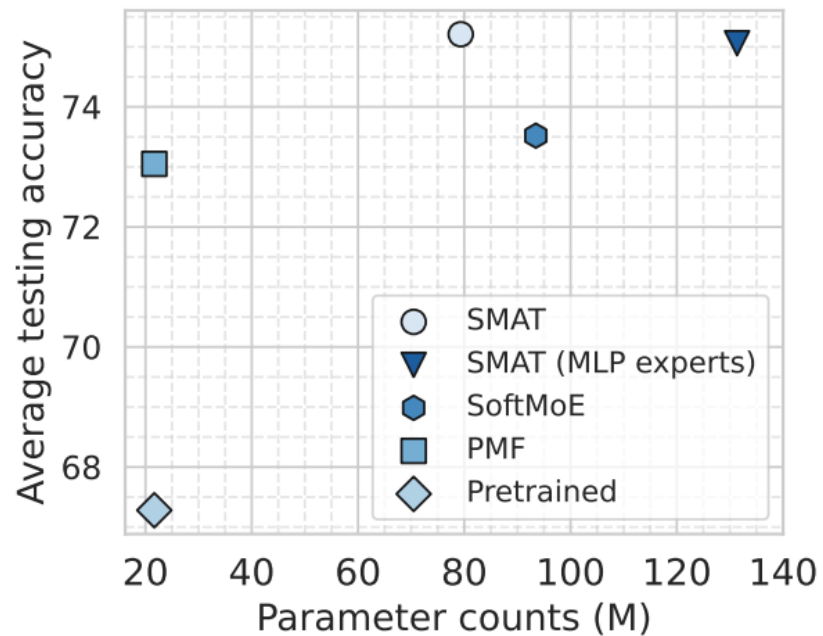


Figure 5. (a-b) Model capacity (i.e., number of non-zero parameters) grouped by *a*): layer types, and *b*): layer depth. (c-d) Expert specialisation. *c*) Dendrogram of task similarity computed on different tasks. *d*) Overlap between masks.

More ablation study

Performance vs scale for different models



Ablation experiments

Table 2. Ablation studies on different components of SMAT. **MLS** meta-learned sparsity, **Meta**: Meta-training using support and query splits (otherwise no split), **DT**: dense teachers. **IE**: interpolated experts

ID	MODEL	MLS	META	DT	IE	ID	OOD	AVG
1	SMAT	✓	✓	✓	✓	85.14	67.27	75.21
2		✓	✓	✗	✓	85.07	66.44	74.74
3		✓	✓	✓	✗	84.77	67.02	74.90
4		✓	✗	✓	✓	82.35	63.64	71.95
5		✗	✓	✓	✗	85.21	66.21	74.75
6	PMF	✗	✗	✗	✗	84.23	64.09	73.05