Robust Data-driven Prescriptiveness Optimization

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The Forty-first International Conference on Machine Learning (ICML 2024)

Stochastic Programming

- ▶ ξ traffic demand with distribution *F*
- \blacktriangleright *x* shortest path route

Contextual Stochastic Optimization

$$
\text{(CSO)}\,\, \boldsymbol{x}^*(\boldsymbol{\zeta}) \in \underset{\boldsymbol{x} \in \mathcal{X}}{\text{argmin}}\,\, \mathbb{E}_{\boldsymbol{F}}\bigg[h(\boldsymbol{x},\boldsymbol{\xi})\bigg|\boldsymbol{\zeta}\bigg]
$$

Workday **Holiday**

- \triangleright ξ traffic demand
- $\triangleright \zeta \in \{workday, holiday\}$ side information
- **F** is the joint distribution (ζ, ξ) , $F_{\xi|\zeta}$ conditional distribution

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$$

- \blacktriangleright *F*(ξ | ζ) not known in practice
- **►** Estimate conditional distribution $\hat{F}(\xi|\zeta)$, e.g., KDE, random forest, etc.
- \triangleright Can we trust the estimates?

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Distributionally Robust Contextual Stochastic Optimization

(DRCSO)
$$
x^*(\zeta) \in \underset{x \in \mathcal{X}}{\operatorname{argmin}} \underset{F \in \mathcal{D}}{\operatorname{sup}} \mathbb{E}_F\left[h(x,\xi)\big|\zeta\right]
$$

where \overline{D} is admissible set of distributions (ambiguity set)

RELEVANT LITERATURE

Ban and Rudin [2019] The big data newsvendor: Practical insights from machine learning

- ▶ Conditional Stochastic Optimization (CSO)
- ▶ Nadaraya-Watson Kernel regression
- ▶ Decision rules

Hannah et al. [2010] Nonparametric density estimation for stochastic optimization with an observable state variable

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Bertsimas and Van Parys [2022] Bootstrap robust prescriptive analytics

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\implies How to compare different methods?

COEFFICIENT OF PRESCRIPTIVENESS¹

"Recently proposed performance measure"

Given a data-driven policy *x*(·) and distribution *F*

$$
\mathcal{P}_F(\mathbf{x}(\cdot)) := 1 - \frac{\mathbb{E}_F[h(\mathbf{x}(\boldsymbol{\zeta}), \boldsymbol{\xi})] - \mathbb{E}_F[\min_{\mathbf{x}' \in \mathcal{X}} h(\mathbf{x}', \boldsymbol{\xi})]}{\mathbb{E}_F[h(\hat{\mathbf{x}}, \boldsymbol{\xi})] - \mathbb{E}_F[\min_{\mathbf{x}' \in \mathcal{X}} h(\mathbf{x}', \boldsymbol{\xi})]},
$$

where $\hat{x} \in \operatorname{argmin}_{x} \mathbb{E}_{\hat{F}}[h(x,\xi)]$ with \hat{F} as the in-sample empirical distribution that puts equal weights on each observed data point (i.e. the solution of SAA)

¹Bertsimas and Kallus, MS, 2020

COEFFICIENT OF PRESCRIPTIVENESS¹

Given a data-driven policy *x*(·) and distribution *F*

 $\mathcal{P}_F(\pmb{x}(\cdot)) := 1$ **distance from full information** $\mathbb{E}_F[h(x(\zeta), \xi)] - \mathbb{E}_F[\min_{x' \in \mathcal{X}} h(x', \xi)]$ $\frac{\ln \frac{1}{\mathcal{L}}}{\mathbb{E}_F[h(\hat{\pmb{x}}, \pmb{\xi})] - \mathbb{E}_F[\min_{\pmb{x}' \in \mathcal{X}} h(\pmb{x}', \pmb{\xi})]}$, distance from no to full information

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Properties

 \blacktriangleright $\mathcal{P}_F = 1$: $x(\cdot)$ is fully anticipative in terms of ξ .

COEFFICIENT OF PRESCRIPTIVENESS

distance from full information
\n
$$
\mathbb{E}_{F}[h(x(\zeta), \xi)] - \mathbb{E}_{F}[\min_{x' \in \mathcal{X}} h(x', \xi)]
$$
\n
$$
\mathbb{E}_{F}[h(\hat{x}, \xi)] - \mathbb{E}_{F}[\min_{x' \in \mathcal{X}} h(x', \xi)]
$$
\ndistance from no to full information

Properties

 \blacktriangleright $\mathcal{P}_F = 1$: $x(\cdot)$ is fully anticipative in terms of ξ .

► Small $\mathcal{P}_F \approx 0$: $x(\cdot)$ is not able to exploit information.

RISING POPULARITY OF THE COEFFICIENT OF PRESCRIPTIVENESS

Recent papers exploiting P_F for evaluating the superiority of the contextual optimization methods:

- ▶ Bertsimas et al. [2016] Inventory management in the era of big data
- ▶ Bertsimas and Kallus [2020] From predictive to prescriptive analytics
- ▶ Notz and Pibernik [2022] Prescriptive analytics for flexible capacity management
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Can we optimize directly the coefficient of prescriptiveness in a way that is robust to distribution misspecification?

DISTRIBUTIONALLY ROBUST PRESCRIPTIVENESS COMPETITIVE RATIO (DRPCR)

$$
\max_{x(\cdot)\in\mathcal{H}}\inf_{F\in\mathcal{D}}\mathcal{P}_F(x(\cdot)) :=
$$
\n
$$
\max_{x(\cdot)\in\mathcal{H}}\inf_{F\in\mathcal{D}}1 - \frac{\mathbb{E}_F[h(x(\zeta),\xi)] - \mathbb{E}_F[\min_{x'\in\mathcal{X}}h(x',\xi)]}{\mathbb{E}_F[h(\hat{x},\xi)] - \mathbb{E}_F[\min_{x'\in\mathcal{X}}h(x',\xi)]}
$$

▶ Under weak conditions the optimal value of DRPCR is necessarily in the interval [0, 1].

EPIGRAPH FORMULATION FOR DRPCR

DRPCR is equivalent to

$$
\max_{\gamma} \quad \gamma \tag{1a}
$$

subject to
$$
\min_{x(\cdot) \in \mathcal{H}} Q(x(\cdot), \gamma) \le 0
$$
 (1b)

$$
0 \le \gamma \le 1,
$$
 (1c)

where

$$
Q(x(\cdot), \gamma) := \sup_{F \in \mathcal{D}} \mathbb{E}_F \Big[h(x(\zeta), \xi) - \Big((1 - \gamma)h(\hat{x}, \xi) + \gamma \min_{x' \in \mathcal{X}} h(x', \xi) \Big) \Big]
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is a convex increasing function of γ .

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is a convex increasing function of γ .

Idea to solve the problem: use the bisection method to bisect over γ *and solve the LHS of* [\(1b\)](#page-14-1) *to see whether it satisfies the constraint!*

CHOICE OF THE AMBIGUITY SET

Assumption

There is a discrete distribution \bar{F} *, with* $\{\bm{\zeta}_\omega\}_{\omega \in \Omega_\zeta}$ *and* $\{\bm{\xi}_\omega\}_{\omega \in \Omega_\xi}$ *as the set of distinct scenarios for* ζ *and* ξ *respectively, such that the distribution set* D *takes the form of the "nested CVaR ambiguity set" with respect to* $\mathbb{P}_{\bar{r}}$ *and defined as*

$$
\bar{\mathcal{D}}(\bar{F},\alpha) := \left\{ \begin{array}{c} F \in \\ \mathcal{M}(\Omega_{\zeta} \times \Omega_{\xi}) \end{array} \middle| \begin{array}{c} \mathbb{P}_{F}(\zeta = \zeta_{\omega}) = \mathbb{P}_{\bar{F}}(\zeta = \zeta_{\omega}) \ \forall \omega \in \Omega_{\zeta}, \\ \mathbb{P}_{F}(\xi = \xi_{\omega'}|\zeta_{\omega}) \leq (1/(1-\alpha)) \mathbb{P}_{\bar{F}}(\xi = \xi_{\omega'}|\zeta_{\omega}) \\ \forall \omega \in \Omega_{\zeta}, \omega' \in \Omega_{\xi} \end{array} \right\}
$$

where $\mathcal{M}(\Omega_c \times \Omega_f)$ *is the set of all distributions supported on over* the joint space $\{\bm\zeta_\omega\}_{\omega \in \Omega_\zeta} \times \{\bm\xi_\omega\}_{\omega \in \Omega_\xi}.$

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▶ No ambiguity in the marginal distribution of the observed random variable ζ

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- ▶ No ambiguity in the marginal distribution of the observed random variable ζ
- \triangleright Ambiguity solely on the unobserved random variable ξ and is sized using the parameter α

DRPCR UNDER NESTED CVAR

Corollary

Under the nested CVaR ambiguity set we have

$$
\min_{\mathbf{x}(\cdot) \in \mathcal{H}} Q(\mathbf{x}(\cdot), \gamma) = \sum_{\omega \in \Omega_{\zeta}} \mathbb{P}_{\bar{F}}(\zeta = \zeta_{\omega}) \phi_{\omega}(\gamma)
$$

where the optimal value of $\phi_{\omega}(\gamma)$ *can be obtained through solving the following optimization problem*

$$
\min_{x \in \mathcal{X}, t, s \ge 0} \qquad t + \frac{1}{1 - \alpha} \sum_{\omega' \in \Omega_{\xi}} \mathbb{P}_{\overline{F}}(\xi = \xi_{\omega'} | \zeta = \zeta_{\omega}) s_{\omega'}
$$
\n
$$
\text{subject to} \qquad s_{\omega'} \ge h(x, \xi_{\omega'}) - \left((1 - \gamma) h(\overline{x}, \xi_{\omega'}) + \gamma \min_{x' \in \mathcal{X}} h(x', \xi_{\omega'}) \right)
$$
\n
$$
-t, \forall \omega' \in \Omega_{\xi}.
$$

This problem can be reduced to a linear program when X *is polyhedral and* $h(\pmb{x},\pmb{\xi}_{\omega'})$ is linear programming representable for all $\omega' \in \Omega_\xi.$

SHORTEST PATH PROBLEM

SHORTEST PATH PROBLEM WITH CSO OBJECTIVE

$$
x^*(\zeta) \in \operatornamewithlimits{argmin}_{x \in \mathcal{X}} \mathbb{E}_{\hat{F}_{\xi|\zeta}}[x^\top \xi],
$$

$$
\mathcal{X} = \left\{ \mathbf{x} \in \mathbb{R}^{|\mathcal{A}|} \left| \begin{array}{l} x_{(i,j)} \in \{0,1\} & \forall (i,j) \in \mathcal{A} \\ \sum_{j:(i,j) \in \mathcal{A}} x_{(i,j)} - \sum_{j:(j,i) \in \mathcal{A}} x_{(j,i)} = 1 & \text{if } i = o \\ \sum_{j:(i,j) \in \mathcal{A}} x_{(i,j)} - \sum_{j:(j,i) \in \mathcal{A}} x_{(j,i)} = -1 & \text{if } i = d \\ \sum_{j:(i,j) \in \mathcal{A}} x_{(i,j)} - \sum_{j:(j,i) \in \mathcal{A}} x_{(j,i)} = 0 & \forall i \in \mathcal{V} \setminus \{o, d\} \end{array} \right\}
$$

- A directed graph defined as $\mathcal{G} = (\mathcal{V}, \mathcal{A})$, where \mathcal{V} denotes the set of nodes and $A \in V \times V$ is the set of arcs.
- $\blacktriangleright \xi_{(i,j)}$ denotes the travel time of a directed path from node *i* to node *j*.
- \blacktriangleright $x_{(i,i)} = 1$ if we decide to travel from node *i* to node *j* and $x_{(i,i)} = 0$ otherwise.
- \blacktriangleright $\hat{F}_{\xi|\zeta}$ denotes the conditional distribution inferred from the training dataset.
- Adapt to the graph (G) structure employed in Kallus and Mao (2022)

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ALTERNATIVE METHODS TO DRPCR

▶ *Contextual Stochastic Optimization (CSO)* $x^*(\zeta) \in \operatornamewithlimits{argmin}_{x \in \mathcal{X}} \mathbb{E}_{\hat{F}_{\xi|\zeta}}[x^\top \xi]$

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x^*(\zeta) \in \operatornamewithlimits{argmin}_{x \in \mathcal{X}} \mathbb{E}_{\hat{F}_{\xi|\zeta}}[x^\top \xi]
$$

▶ *Distributionally Robust Contextual Stochastic Optimization (DRCSO)* $x^*(\zeta) \in \arg\min_{x \in \mathcal{X}} \sup_{F(x) \in \overline{\mathcal{D}}(\hat{F})}$ $\sup_{F_{\xi|\zeta}\in\bar{\mathcal{D}}(\hat{F}_{\xi|\zeta},\alpha)} \mathbb{E}_{F_{\xi|\zeta}}[x^{\top}\xi]$

ALTERNATIVE METHODS TO DRPCR

▶ *Contextual Stochastic Optimization (CSO)*

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x^*(\zeta) \in \operatornamewithlimits{argmin}_{x \in \mathcal{X}} \mathbb{E}_{\hat{F}_{\xi|\zeta}}[x^\top \xi]
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▶ *Distributionally Robust Contextual Stochastic Optimization (DRCSO)* $x^*(\zeta) \in \arg\min_{x \in \mathcal{X}} \sup_{F(x) \in \overline{\mathcal{D}}(\hat{F})}$ $\sup_{F_{\xi|\zeta}\in\bar{\mathcal{D}}(\hat{F}_{\xi|\zeta},\alpha)} \mathbb{E}_{F_{\xi|\zeta}}[x^{\top}\xi]$

▶ *Distributionally Robust Contextual Regret Optimization (DRCRO)* $x^*(\zeta) \in \arg\min_{x \in \mathcal{X}} \sup_{F(x) \in \overline{\mathcal{D}}(\hat{F})}$ $\sup_{F_{\xi|\zeta}\in\bar{\mathcal{D}}(\hat{F}_{\xi|\zeta},\alpha)}\mathbb{E}_{F_{\xi|\zeta}}[x^{\top}\xi-\min_{x'\in\mathcal{X}}x'^{\top}\xi]$

OUT-OF-SAMPLE COEFFICIENT OF PRESCRIPTIVENESS

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AVERAGE L-1 NORM DISTANCE TO SAA SOLUTION

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▶ Under the nested CVaR ambiguity set, optimization of the coefficient of prescriptiveness in the DRO context leads to the special case of solving a series of linear

programs.

 \triangleright Roughly speaking, when the mean of the unobserved random variable is exposed to a distribution shift, the out-of-sample coefficients of prescriptiveness achieved by DRPCR policies are higher than those obtained by the alternative methods.