



# ICML

International Conference  
On Machine Learning

# Parameterized Physics-informed Neural Networks for Parameterized PDEs

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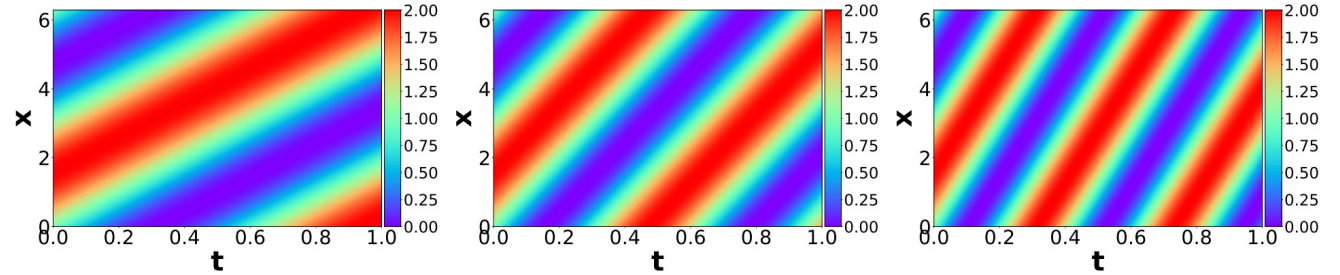


# Preliminaries: Parameterized PDEs

## Example: Convection equation

Governing Equation: 
$$\frac{\partial u}{\partial t} + \beta \frac{\partial u}{\partial x} = 0$$

PDE parameter:  $\beta$

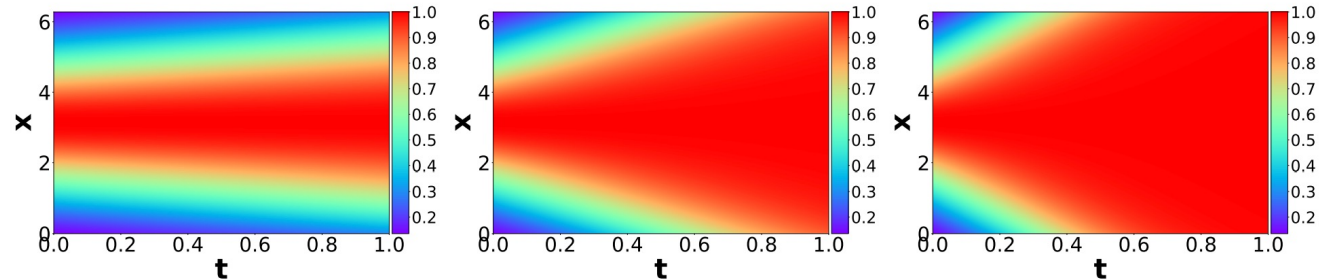


(a) Conv. ( $\beta = 5$ )   (b) Conv. ( $\beta = 10$ )   (c) Conv. ( $\beta = 15$ )

## Example: Reaction equation

Governing Equation: 
$$\frac{\partial u}{\partial t} - \rho u(1 - u) = 0$$

PDE parameter:  $\rho$



(d) Reac. ( $\rho = 1$ )   (e) Reac. ( $\rho = 4$ )   (f) Reac. ( $\rho = 7$ )

**Parameterized PDEs** are a type of partial differential equation that include specific parameters within the equation. These PDE parameters can reflect the physical properties of the system.

# Preliminaries: Physics-informed Neural Networks

Solving PDE with coordinate-based MLP (PINN)



## How to train?

- $L \stackrel{\text{def}}{=} \alpha L_u + \beta L_f$  (**Total loss**)

$$\left[ \begin{array}{l} \bullet L_f = \frac{1}{N_f} \sum_{i=1}^{N_f} |F(x_f^i, t_f^i, \tilde{u}; \theta)|^2 \text{ (PDE residual loss)} \\ \bullet L_u = \frac{1}{N_u} \sum_{i=1}^{N_u} |u(x_u^i, t_u^i) - \tilde{u}(x_u^i, t_u^i; \theta)|^2 \text{ (Boundary loss)} \end{array} \right]$$

$F$ : PDE operator

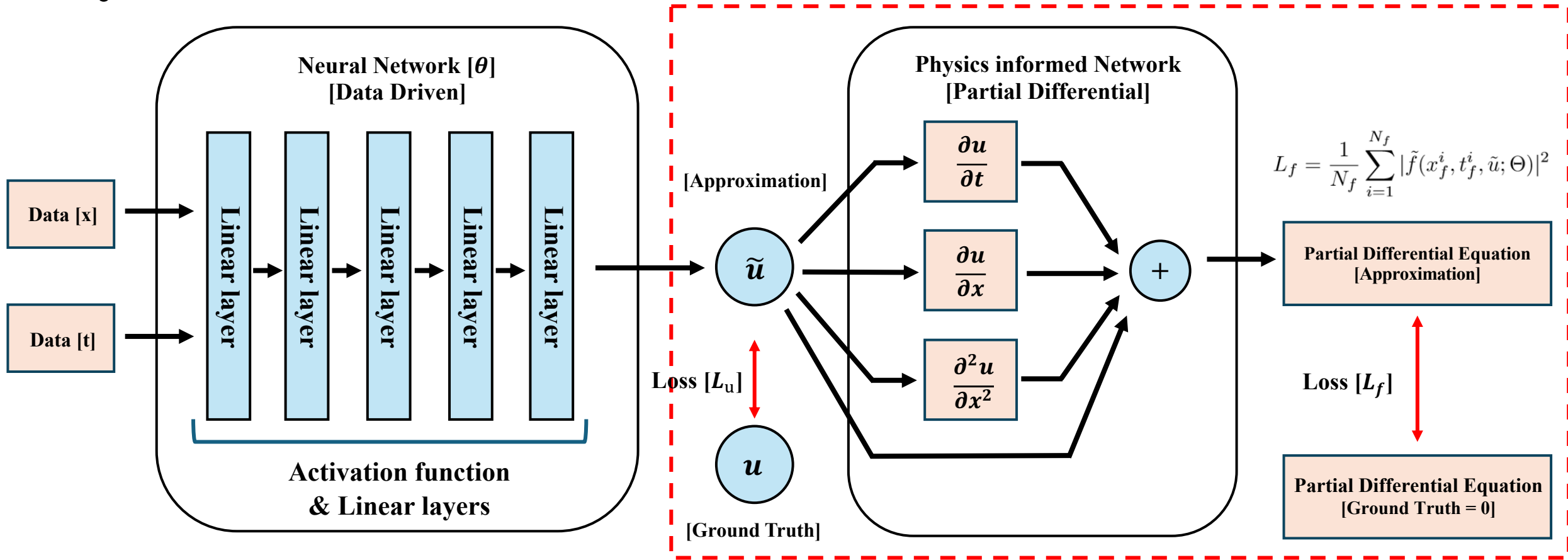
$(x_f, t_f)$ : collocation points

$(x_u, t_u)$ : initial & boundary points

$N_f$ : # collocation points

$N_u$ : # initial & boundary points

# Physics informed Neural Network

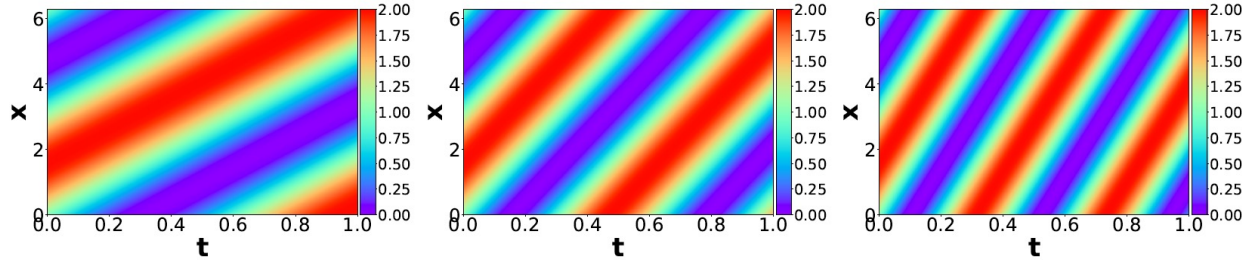


## Weaknesses of PINNs

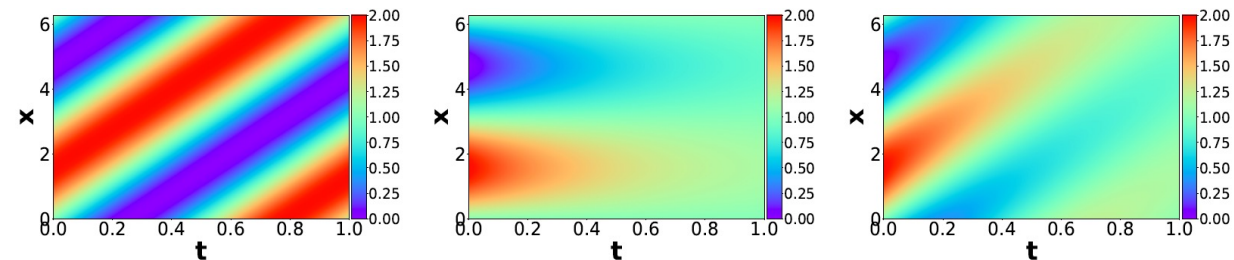
**W1.** PINNs rely on the PDE loss, and this loss function is a non-convex function.

**W2.** A single PINN can learn only one governing equation.

# Motivations



(a) Conv. ( $\beta = 5$ ) (b) Conv. ( $\beta = 10$ ) (c) Conv. ( $\beta = 15$ )



(a) Conv. (b) Diff. (c) Conv.-Diff.

1. A latent space of parameterized PDEs may exist.

2. It will be more effective to solve similar problems simultaneously.

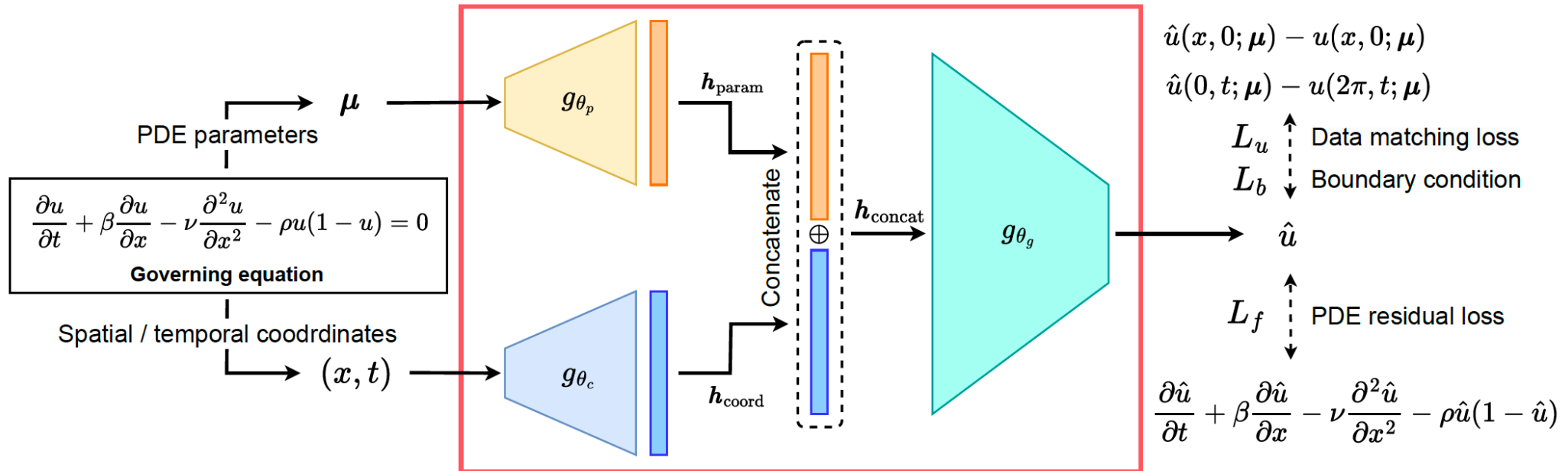
## Contributions

- 1) We show that the proposed method **addresses the failure modes** of PINNs.
- 2) We present a new efficient PINN framework for **multi-query** scenarios.
- 3) We develop a **SVD modulation** for solving multiple PDEs.

# Proposed Method

## Overall architecture of P<sup>2</sup>INN

$$\hat{u}(x, t; \mu) = g_{\theta_g}([h_{\text{coord}}, h_{\text{param}}])$$



$$u_{\theta}(x, t; \mu) = g_{\theta_g} \left( [g_{\theta_c}(x, t); g_{\theta_p}(\mu)] \right),$$

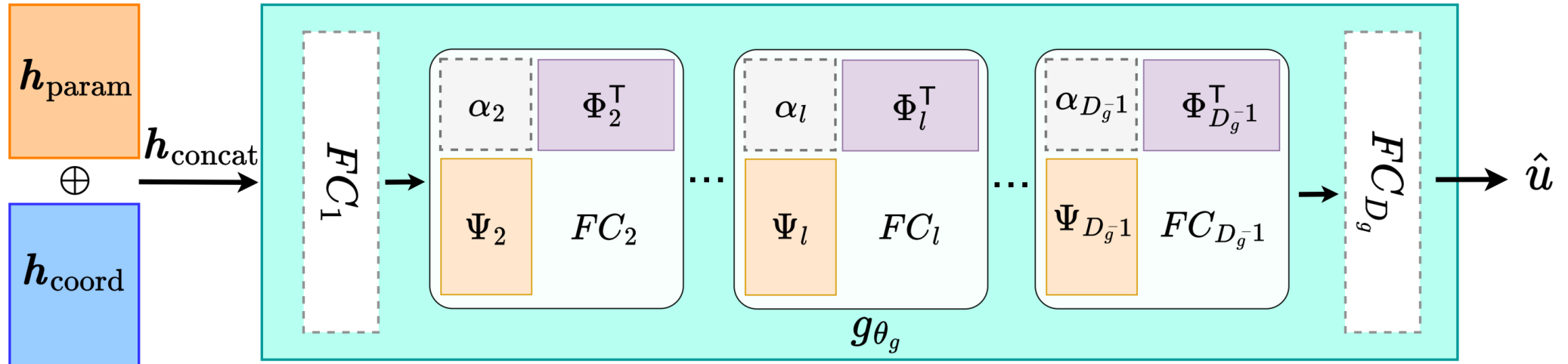
$$h_{\text{param}} = g_{\theta_p}(\mu) \text{ and } h_{\text{coord}} = g_{\theta_c}(x, t)$$

$$\left\{ \begin{array}{l} h_{\text{param}} = \sigma(\text{FC}_{D_p} \cdots (\sigma(\text{FC}_2(\sigma(\text{FC}_1(\mu)))))) \\ h_{\text{coord}} = \sigma(\text{FC}_{D_c} \cdots (\sigma(\text{FC}_2(\sigma(\text{FC}_1(x, t)))))) \end{array} \right\}$$

The manifold network  $g_{\theta_g}$  reads the two hidden representations,  $h_{\text{param}}$  and  $h_{\text{coord}}$ , and infer the input equation's solution at  $(x, t)$ .

# Proposed Method

## Singular Value Decomposition (SVD) Modulation



$$FC_l = \psi_l \alpha_l \phi_l^T, \quad l = 2, 3, \dots, D_g - 1$$

From the pre-trained decoder layer of  $P^2INN$ , we obtain the bases  $\psi_l, \phi_l$  for parameterized PDEs through SVD. During fine-tuning, we set  $\{\alpha_l\}_{l=2}^{D_g-1}$  to be learnable, while keeping all other parameters in the network fixed. It is an option to fix the parameters of  $FC_1$  and  $FC_{D_g}$ .

# Experimental Results

Addressing W1: PINNs rely on the PDE loss, and this loss function is a non-convex function.

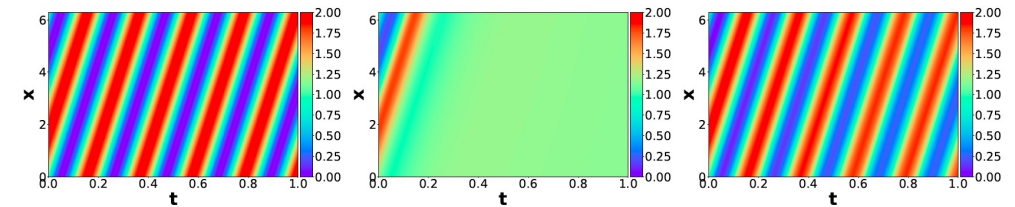
<1D CDR equations>

The relative and absolute  $L_2$  errors

	PDE type	Metric	PINN	LargePINN	PINN-P	P <sup>2</sup> INN
Class 1	Convection	Abs. err.	0.1140	0.1191	0.0209	<b>0.0198</b>
		Rel. err.	0.1978	0.2084	<b>0.0410</b>	0.0464
	Diffusion	Abs. err.	0.6782	0.5868	0.3800	<b>0.1916</b>
		Rel. err.	1.2825	1.0994	0.7912	<b>0.3745</b>
	Reaction	Abs. err.	0.7902	0.7910	0.8975	<b>0.0042</b>
		Rel. err.	0.8460	0.8469	0.9908	<b>0.0092</b>
Class 2	Conv.-Diff.	Abs. err.	0.2735	0.1626	0.1253	<b>0.0622</b>
		Rel. err.	0.5106	0.3189	0.3009	<b>0.1495</b>
	Reac.-Diff.	Abs. err.	0.7167	0.7399	0.1756	<b>0.0898</b>
		Rel. err.	0.7998	0.8186	0.2632	<b>0.1411</b>
Class 3	Conv.-Diff.-Reac.	Abs. err.	0.7450	0.7415	0.8590	<b>0.0353</b>
		Rel. err.	0.7960	0.7915	0.9532	<b>0.0812</b>

Failure modes

Convection equation ( $\beta = 30$ )

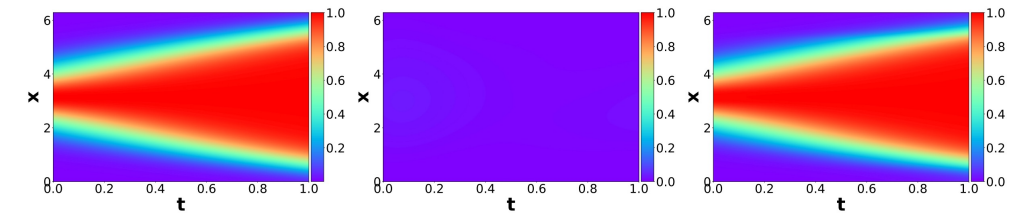


(a) Exact

(b) PINN

(c) P<sup>2</sup>INN

Reaction equation ( $\rho = 5$ )



(d) Exact

(e) PINN

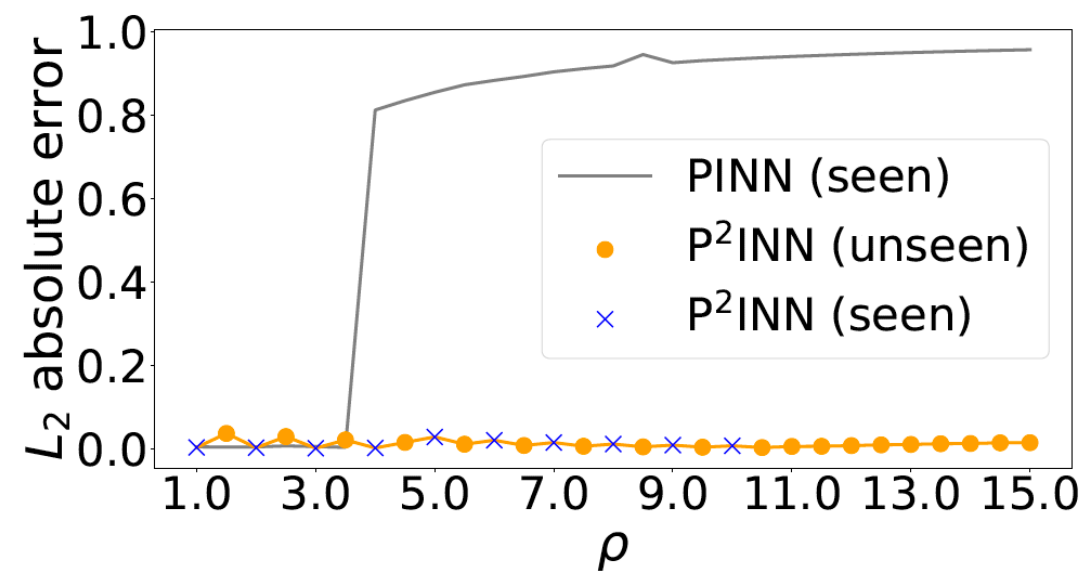
(f) P<sup>2</sup>INN



# Experimental Results

Addressing W2: A single PINN can learn only one governing equation

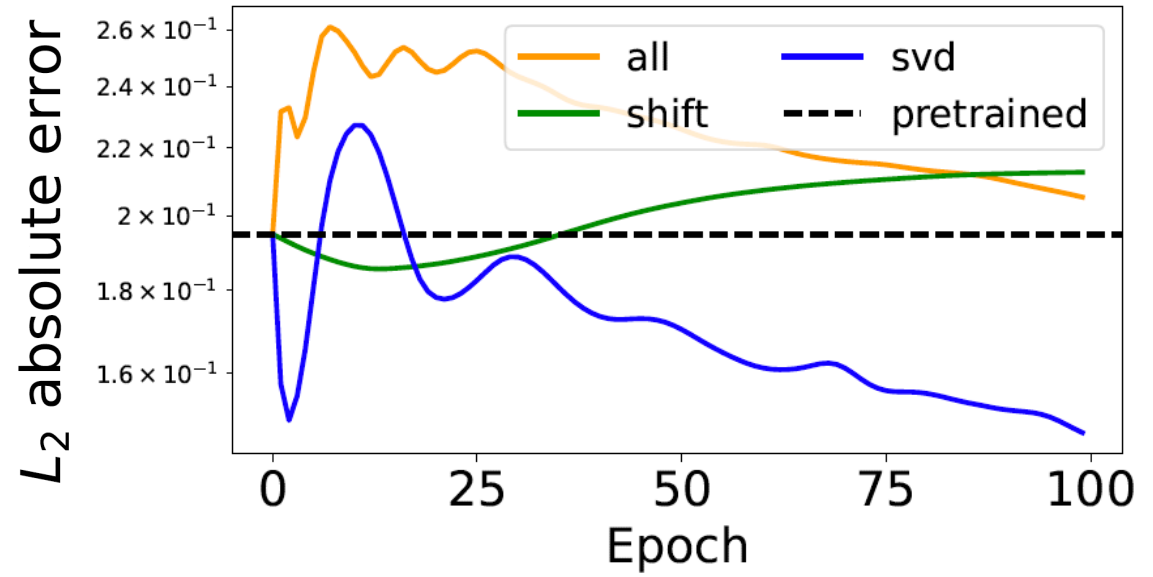
## Real-time multi-query scenarios



<Reaction equation>

## Fine-tuning phase

(unseen PDE parameter)



<Convection equation ( $\beta=8$ )>

Pretrained model is trained using convection equations with  $\beta=1 \sim 5$

# Conclusion

- We design a novel neural network architecture for solving parameterized PDEs, P2INNs, which significantly improves the performance of PINNs overcoming the well-known weaknesses.
- We demonstrate that P2INNs can learn all benchmark PDEs in a single training run and significantly outperform existing PINN methods in prediction accuracy.

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**Poster Presentation Schedule: Thu, July 25, 11:30 am - 1:00 pm**

**Paper**



## **Reference**

Physics-informed neural networks: A deep learning framework for solving forward and inverse problems involving nonlinear partial differential equation, **Journal of Computational Physics 2019**

Characterizing possible failure modes in physics-informed neural networks, **NeurIPS 2021**