# <span id="page-0-0"></span>Byzantine Resilient and Fast Federated Few-Shot Learning

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## <span id="page-1-0"></span>Multi-task representation learning/Few-shot Learning

First consider the centralized setting:

- Suppose that there are  $q$  source tasks.
- Each task  $k \in [q]$  associated with a distribution over the input-output space  $\mathcal{X}\times\mathcal{Y}$ , where  $\mathcal{X}\subseteq\real^n$  and  $\mathcal{Y}\subseteq\real$ .
- Each task observes  $m < n$  samples from  $\mathcal{X} \times \mathcal{Y}$ .
- The aim is to learn prediction functions for all tasks simultaneously, leveraging a shared representation  $\varphi : \mathcal{X} \to \mathcal{Z}$  that maps inputs to a Low-Dimensional feature space  $\mathcal{Z} \subseteq \Re^r$   $(r < m)$ .

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• Few-shot learning refers to learning in data-scarce environment  $(m < n)$ .

### Linear Model

<span id="page-2-0"></span>Let the representation function class be Low-Dimensional Linear Representations i.e.,  $\{ \mathbf{x} \mapsto \mathbf{U}^T \mathbf{x} | \mathbf{U} \in \Re^{n \times r} \}$  1.

$$
\mathbf{Y}_{m \times q} = [(\mathbf{y}_1)_{m \times 1}, ..., (\mathbf{y}_q)_{m \times 1}] = [(\mathbf{X}_1)_{m \times n}(\theta_1^*)_{n \times 1}, ..., (\mathbf{X}_q)_{m \times n}(\theta_q^*)_{n \times 1}]
$$
  
= [(\mathbf{X}\_1)\_{m \times n} \mathbf{U}\_{n \times r}^\* (\mathbf{b}\_1^\*)\_{r \times 1}, ..., (\mathbf{X}\_q)\_{m \times n} \mathbf{U}\_{n \times r}^\* (\mathbf{b}\_q^\*)\_{r \times 1}]

- The matrices  $X_k$ s are independent and identically distributed (i.i.d.) over k.
- We assume that each  $X_k$  is a "random Gaussian" matrix, i.e., entry of it is i.i.d. standard Gaussian.
- The goal is to find the optimal representation  $\varphi^*$ , represented by  $\mathsf{U}^*$ .
- $\mathbf{b}_{k}^{*}$  is the new true linear predictor for all tasks  $k \in [q].$

<sup>1</sup>Du et al., Few-shot learning via learning the represen[tat](#page-1-0)i[on,](#page-3-0) [p](#page-1-0)[ro](#page-2-0)[va](#page-3-0)[bly](#page-0-0)  $\rightarrow + + +$ 

<span id="page-3-0"></span>Solving this problem requires solving

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$$
\min_{\substack{\tilde{\mathbf{U}} \in \mathbb{R}^{n \times r} \\ \tilde{\mathbf{B}} \in \mathbb{R}^{r \times q}}}\sum_{k=1}^{q} \left\|\mathbf{y}_{k}-\mathbf{X}_{k}\tilde{\mathbf{U}}\tilde{\mathbf{b}}_{k}\right\|^{2}
$$
(1)

In interesting parallel works  $\mathsf{AltGDmin}^2$  and  $\mathsf{FedRep}^3$ , a fast and communication-efficient GD-based algorithm was introduced for solving the mathematical problem given in [\(1\)](#page-3-1).

<sup>2</sup>Nayer & Vaswani, Fast and sample-efficient federated low rank matrix recovery from column-wise linear and quadratic projections

<sup>&</sup>lt;sup>3</sup>Collins et al., Exploiting Shared Representations for Personalized Federated **KORK ERREST ADAMS** Learning

#### AltGDmin<sup>4</sup> and FedRep<sup>5</sup>

- Use sample splitting: new indep set of samples for each update
- Factorize  $\Theta = \text{UB}$ , initialize U by spectral initialization (think of it as Federated PCA),
- alternate  $b/w$  minimization over **B** and (projected) GD for **U**
- projected GD for U

$$
\textbf{U}^+ \leftarrow \text{QR}(\textbf{U} - \eta \nabla_U f(\textbf{U}, \textbf{B}))
$$

- AltGDmin and FedRep are two parallel works which are functionally equivalent.
- AltGDmin uses a better initialization than FedRep and hence also has a better sample complexity by a factor of r.

<sup>4</sup>Nayer & Vaswani, Fast and sample-efficient federated low rank matrix recovery from column-wise linear and quadratic projections

<sup>5</sup>Collins et al., Exploiting Shared Representations for Personalized Federated Learning**KORKA SERKER YOUR** 

• In the federated setting, we assume that there are a total of L nodes. Each observes a different disjoint subset ( $\widetilde{m} = m/L$ ) of rows of **Y**. At most  $\tau L$  nodes can be Byzantine with  $\tau < 0.4$ . The nodes can only communicate with the center.

Byzantine attack is a "model update poisoning" attack where

- 1. It knows the full state of the center and every node (data and algorithm, including all algorithm parameters).
- 2. Different Byzantine adversaries can also collude.
- 3. They cannot modify the outputs of the other (non-Byzantine) nodes or of the center, or delay communication.

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Byzantine nodes can thus design the worst possible attacks at each algorithm iteration.

#### Algorithm 1 Byz-Fed-AltGDmin-Learn: Complete algorithm

Nodes  $\ell = 1, ..., L$ Compute  $(\mathbf{U}_0)_\ell$  which is the matrix of top r left singular vectors of  $(\hat{\mathbf{\Theta}}_0)_\ell := \sum_{k=1}^q (\mathbf{X}_k)_\ell^\top ((\mathbf{y}_k)_\ell)_{\text{trunc}} \mathbf{e}_k^\top$  $_{k=1}^{q}(\mathsf{X}_{k})_{\ell}$ <sup>T</sup> $((\mathsf{y}_{k})_{\ell})_{\mathrm{trunc}}$ e $_{k}^{\top}$ Key Idea 1: Subspace Median on  $(U_0)_\ell$ 's Central Server: Subspace Median Orthonormalize:  $\mathbf{U}_{\ell} \leftarrow QR((U_{\ell})_0)$ ,  $\ell \in [L]$ Compute  $\mathcal{P}_{\mathsf{U}_\ell} \leftarrow \mathsf{U}_\ell \mathsf{U}_\ell^\top$ ,  $\ell \in [L]$ Compute GM:  $\mathcal{P}_{\mathsf{gm}} \leftarrow \text{GeometricMedian}\{\mathcal{P}_{\mathsf{U}_{\ell}}, \ell \in [\mathsf{L}]\}$ Find  $\ell_{best} = \arg \min_{\ell} ||\mathcal{P}_{\mathsf{U}_{\ell}} - \mathcal{P}_{\mathsf{gm}}||_{\mathsf{F}}$ Output  $U_0 = U_{out} = U_{\ell_{b}}$ for  $t = 1$  to  $T$  do Nodes  $\ell = 1, ..., L$  $\overline{\mathsf{Set}}$   $\mathsf{U} \leftarrow \mathsf{U}_{t-1}$ With **U** fixed, Least-Squares step over  $(\mathbf{b}_k)_\ell$  for all k With **B** fixed, Gradient of  $f(\mathbf{U}, \mathbf{B})$  w.r.t.  $\mathbf{U}$ :  $\nabla f_{\ell}$ Central Server Key Idea 2: Calculate GM of  $\nabla f'_\ell$ s  $\nabla f^{GM} \leftarrow$  GeometricMedian( $\nabla f_{\ell}, \ell = 1, 2, \ldots L$ ). Compute  $\mathbf{U}^+ \leftarrow QR(\mathbf{U}_{t-1} - \frac{\eta}{\rho \widetilde{m}} \nabla f^{GM})$ return Set  $\mathbf{U}_t \leftarrow \mathbf{U}^+$ . Push  $\mathbf{U}_t$  to nodes. end for

### Multi-task representation learning/Few-shot Learning

#### Theorem

(Byz-Fed-AltGDmin-Learn: Complete guarantee) Assume  $\max_k \|\mathbf{b}_k^*\| \leq \mu \sqrt{r/q} \sigma_1(\mathbf{\Theta}^*)$  for a constant  $\mu \geq 1$ . If

$$
\frac{m}{L}q \geq C\kappa^4\mu^2(n+q)r^2\log(1/\epsilon)
$$

then, w.p. at least  $1 - TLn^{-10}$ ,

$$
\text{SD}_F(\textbf{U}^*, \textbf{U}_\mathcal{T}) \leq \epsilon
$$

and  $\|(\theta_k)_\ell - \theta_k^*\| \leq \epsilon \|\theta_k^*\|$  for all  $k \in [q], \ell \in [L]$ . The communication cost per node is order nr  $\log(\frac{n}{\epsilon})$ . The computational cost at any node is order nqr  $\log(\frac{n}{\epsilon})$  while that at the center it is  $n^2 L \log^3(Lr/\epsilon)$ .

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In solving this problem, we also introduce a novel secure solution to the federated subspace learning meta-problem that occurs in many different applications.

Estimate principal subspace span $(U^*)$  of an unknown  $n \times n$  symmetric matrix  $\Phi^*$  in a federated setting, while being resilient to Byzantine **Attacks** 

$$
\mathbf{D}_{n\times q}=[(\mathbf{D}_1)_{n\times q_1},...,(\mathbf{D}_{\ell})_{n\times q_{\ell}},...,(\mathbf{D}_L)_{n\times q_L}]
$$

- 1. U<sup>\*</sup> is an  $n \times r$  matrix denoting the top r eigenvectors of  $\Phi^*$
- 2. **Federated Setting:** Each node  $\ell \in [L]$  observes a data matrix  $\mathbf{D}_{\ell}$ , that allows it
	- $\bullet\,$  To estimate  ${\bf\Phi}^*$  as  ${\bf\Phi}_\ell = {\bf D}_\ell {\bf D}_\ell^\top/q_\ell$
	- To estimate  $\mathsf{U}^*$  as  $\mathsf{U}_\ell$ , which are the top r eigenvectors of  $\mathsf{\Phi}_\ell$

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### Algorithm: Subspace Median

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Algorithm 2 Subspace Median

**Input** Subspace estimates  $\hat{\mathbf{U}}_{\ell}, \, \ell \in [L].$ Parameters  $T_{cm}$ 

- 1: Orthonormalize:  $\bm{\mathsf{U}}_\ell \leftarrow \mathsf{Q}\mathsf{R}(\hat{\bm{\mathsf{U}}}_\ell)$ ,  $\ell \in [L]$
- 2: Compute  $\mathcal{P}_{\mathsf{U}_{\ell}} \leftarrow \mathsf{U}_{\ell} \mathsf{U}_{\ell}^{\top}$ ,  $\ell \in [L]$
- 3: Compute GM:  $\mathcal{P}_{\mathsf{gm}} \leftarrow \mathsf{GM}\{\mathcal{P}_{\mathsf{U}_\ell}, \ell \in [\mathsf{L}]\}$
- 4: Find  $\ell_{best} = \arg \min_{\ell} ||\mathcal{P}_{U_{\ell}} \mathcal{P}_{em}||_{F}$
- 5: Output  $U_{out} = U_{\ell_{best}}$

### Subspace-Median

#### Lemma

Suppose GM can be computed exactly and at least  $60\%$   $\mathbf{U}_\ell$ 's satisfy

 $\mathsf{SD}_{\mathsf{F}}(\mathsf{U}^*,\mathsf{U}_{\ell}) \leq \delta$ 

then,

$$
\text{SD}_F(\textbf{U}^*, \textbf{U}_{\text{out}}) \leq 23\delta
$$

• Including probability argument, If

 $Pr(\text{SD}_F(\textbf{U}^*, \textbf{U}_\ell) \leq \delta) \geq 1 - p$ 

then,

$$
\begin{aligned} \mathsf{Pr}\left(\mathsf{SD}_{\mathsf{F}}(\mathbf{U}^*, \mathbf{U}_{out}) \le 23\delta\right) &\ge 1 - \exp(-L\psi(0.4-\tau, \rho)) \\ \psi(a, b) &:= (1-a)\log\frac{1-a}{1-b} + a\log\frac{a}{b} \end{aligned}
$$

• If GM is approximated using using a linear time algorithm<sup>6</sup> then,  $Pr(SD_F(U^*, U_{out}) \le 23\delta) \ge 1 - c_0 - exp(-L\psi(0.4 - \tau, \rho))$ 

6Cohen et al., Geometric median in nearly linear time  $\longleftrightarrow$  of  $\oplus$   $\longleftrightarrow$   $\oplus$   $\longleftrightarrow$   $\oplus$   $\longrightarrow$   $\oplus$   $\leadsto$   $\otimes$ 

### <span id="page-11-0"></span>Resilient Federated PCA via Subspace Median of Means

In order to implement the "mean" step, we combine samples from  $\rho = \frac{L}{\tilde{L}}$  $(\tilde{L} < L)$  nodes by implementing  $\tilde{L}$  different federated power methods.

#### **Corollary**

Assume that the set of Byzantine nodes remains fixed for all iterations and the size of this set is at most  $\tau L$  with  $\tau < 0.4\tilde{L}/L$ . If

$$
\frac{q}{L} = \widetilde{q} \geq CK^4 \frac{\sigma_1^{*2}}{\Delta^2} \frac{nr}{\epsilon^2} \cdot \frac{\widetilde{L}}{L}
$$

then, then, w.p. at least  $1-c_0-\exp(-L\psi(0.4-\tau,2\exp(-n)+n^{-10})),$ 

$$
\text{SD}_F(\textbf{U}_{\text{out}},\textbf{U}^*)\leq \epsilon
$$

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# <span id="page-12-0"></span>Comparisons for solving the resilient federated PCA problem



- SVD-Resilient Covariance Estimation (SVD-ResCovEst): SVD on GM of Covariance matrices<sup>7</sup>
- Resilient Power Method (ResPowMeth): GM based modification of the power method<sup>8</sup>
- Baseline Power Method for a no-attack setting (PowMeth)

<sup>7</sup>Minsker, Geometric median and robust estimation in Banach spaces

8Hardt and Price, The noisy power method: A meta a[lgo](#page-11-0)r[ith](#page-13-0)[m](#page-11-0) [w](#page-12-0)[it](#page-13-0)[h a](#page-0-0)[ppl](#page-13-0)[ica](#page-0-0)[tio](#page-13-0)[ns](#page-0-0)  $\equiv$  $QQ$ 

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