



ICML
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On Machine Learning

Stochastic Conditional Diffusion Models for Robust Semantic Image Synthesis

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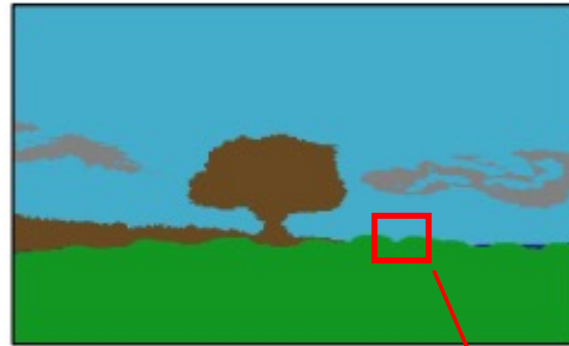


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Semantic Image Synthesis (SIS)

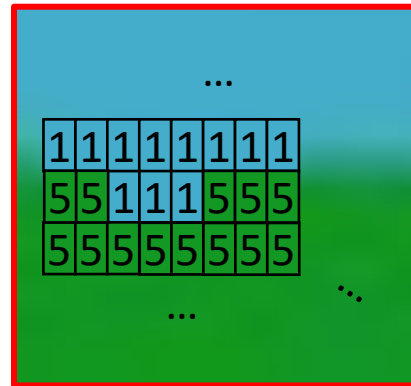


Semantic map y
(Label)

generate



Image X



1: sky
2: tree
...
5: grass
...

approximate

$$q(X|Y)$$



$$p_{\theta}(X|Y)$$

Motivation

Photo editing



Content creation

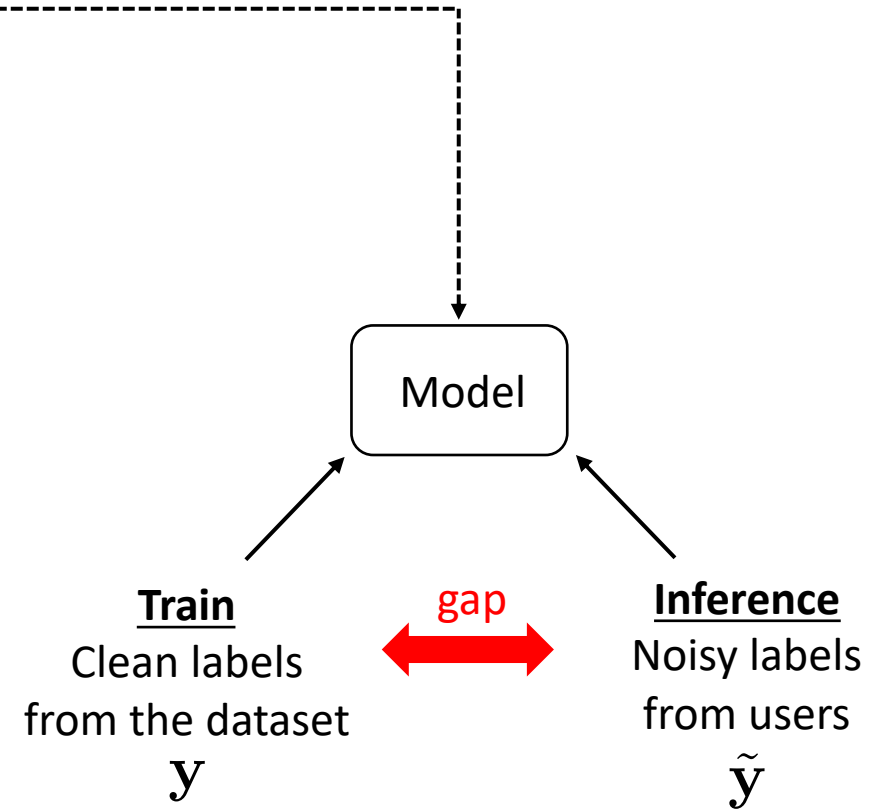
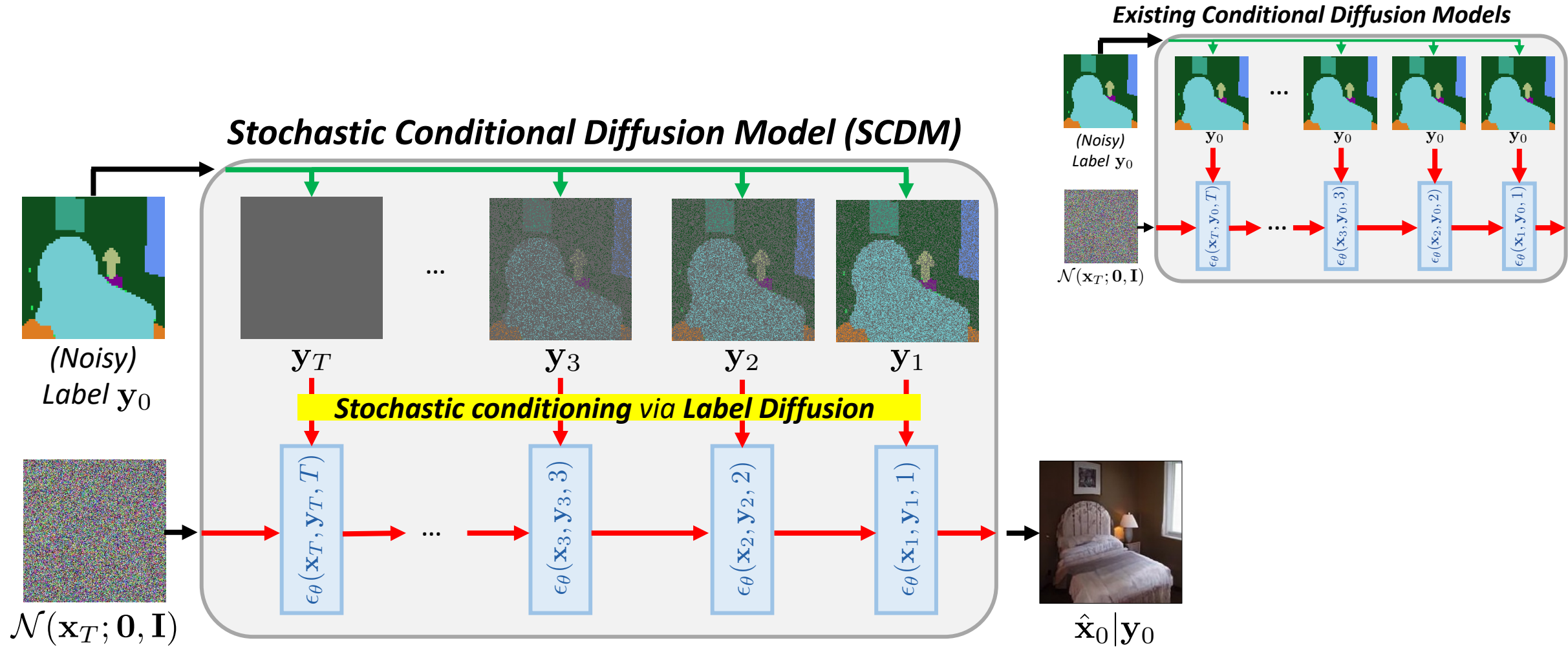


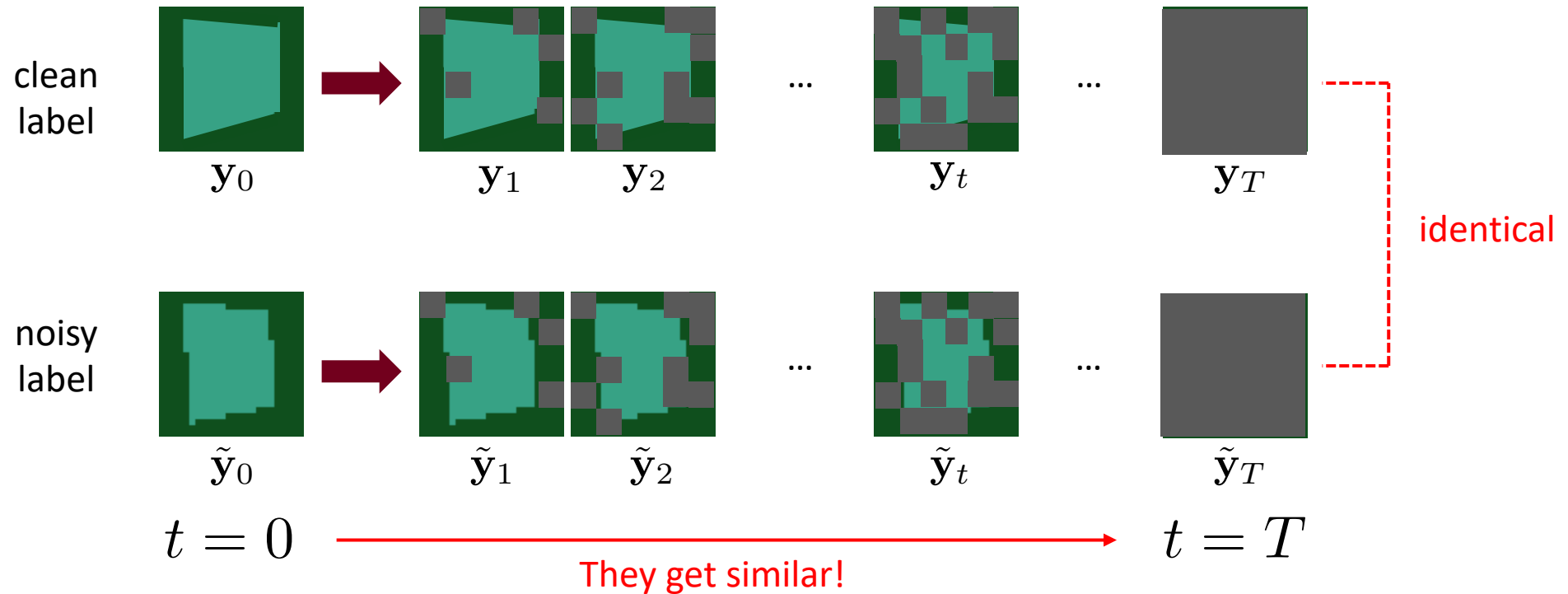
Image credit: <https://tech.hindustantimes.com/tech/news/this-photoshop-ai-feature-will-change-the-way-you-edit-photos-know-what-is-generative-fill-71686747616850.html>

Stochastic Conditional Diffusion Models (SCDM)



Label Diffusion

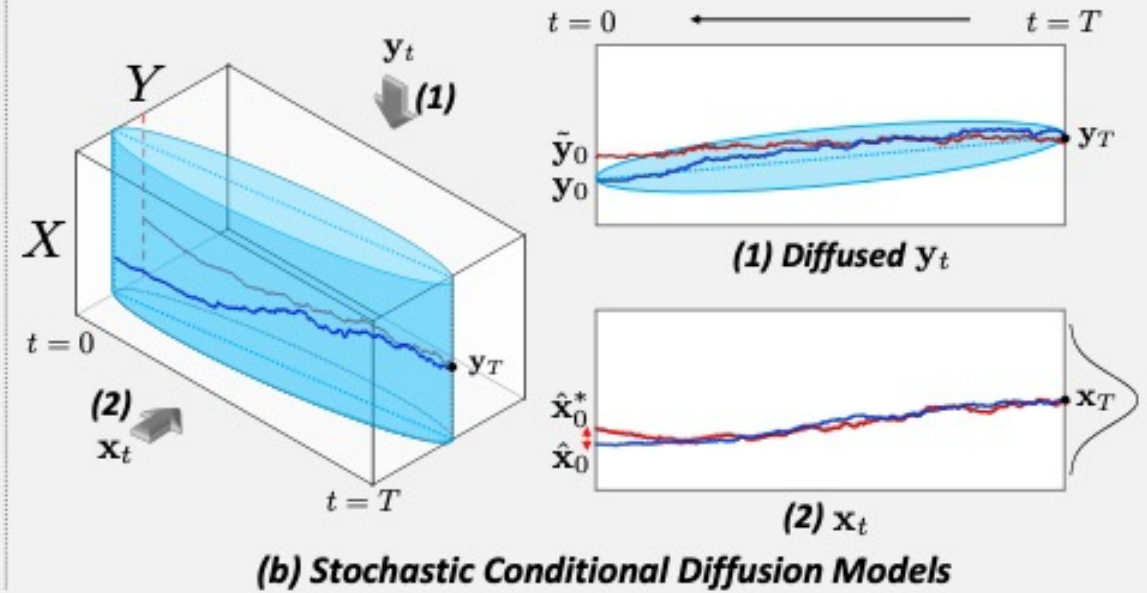
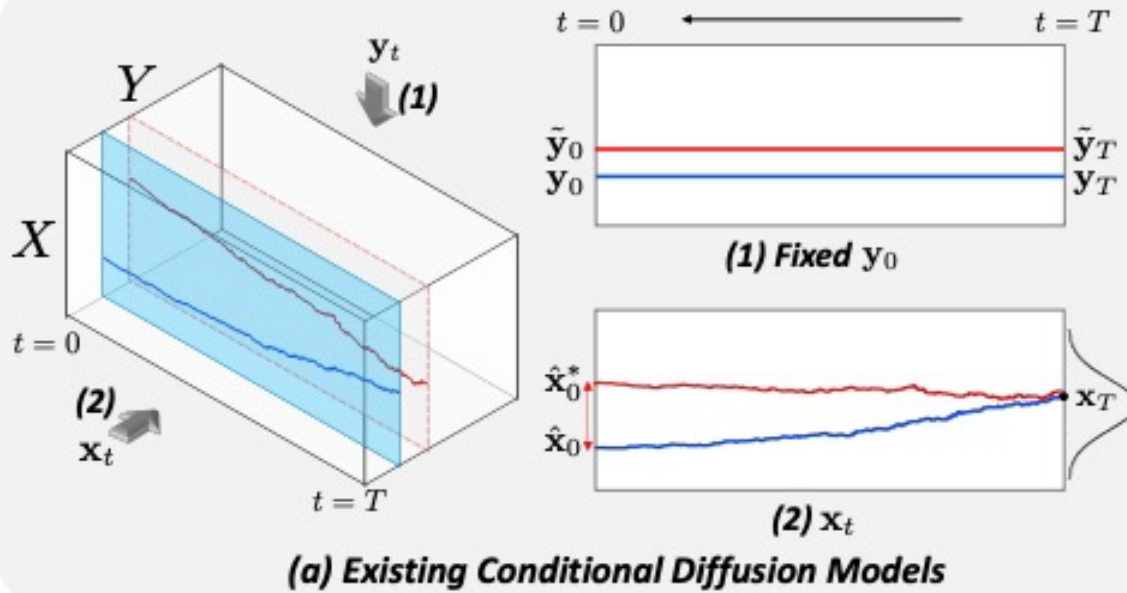
- Discrete diffusion for the labels, $q(\mathbf{z}_t | \mathbf{z}_{t-1}) := \text{Cat}(\mathbf{z}_t; \mathbf{p} = \mathbf{Q}_t \mathbf{z}_{t-1})$
- Noise = [MASK] (absorbing state)



Label Diffusion

y_0 : **Clean** semantic map (e.g., ) , $\hat{x}_0$: Generated image

$\tilde{y}_0$: **Noisy** semantic map (e.g., ) , $\hat{x}_0^*$: Generated image



- The trajectories $y_{1:T}$ and $\tilde{y}_{1:T}$ provided to the model during generation process are similar.
- The generated image is close to the clean image.

Forward process and Generation process

- Forward process

$$q(\mathbf{x}_{1:T}, \mathbf{y}_{1:T} | \mathbf{x}_0, \mathbf{y}_0) := \prod_{t=1}^T q(\mathbf{x}_t, \mathbf{y}_t | \mathbf{x}_{t-1}, \mathbf{y}_{t-1}),$$
$$q(\mathbf{x}_t, \mathbf{y}_t | \mathbf{x}_{t-1}, \mathbf{y}_{t-1}) := \underbrace{q(\mathbf{x}_t | \mathbf{x}_{t-1})}_{\text{continuous}} \underbrace{q(\mathbf{y}_t | \mathbf{y}_{t-1})}_{\text{discrete}}.$$

Label Diffusion

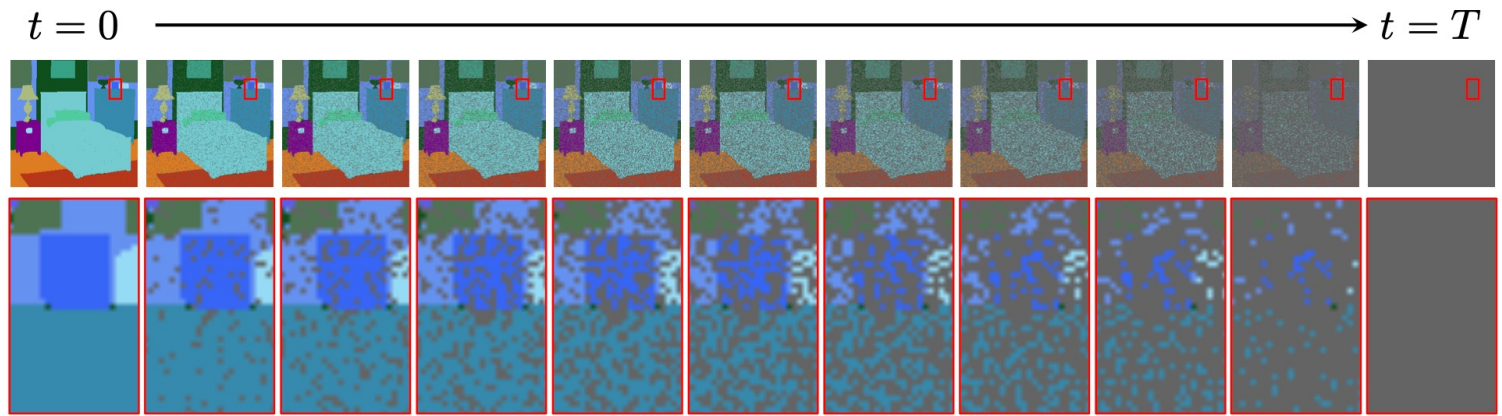
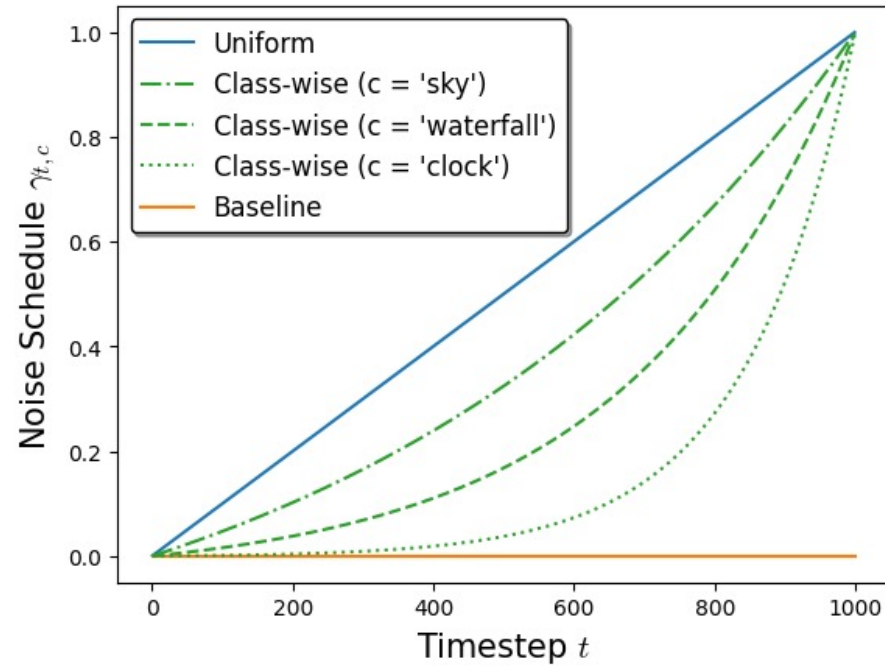
- Generation process

- *discrete*
- *forward*

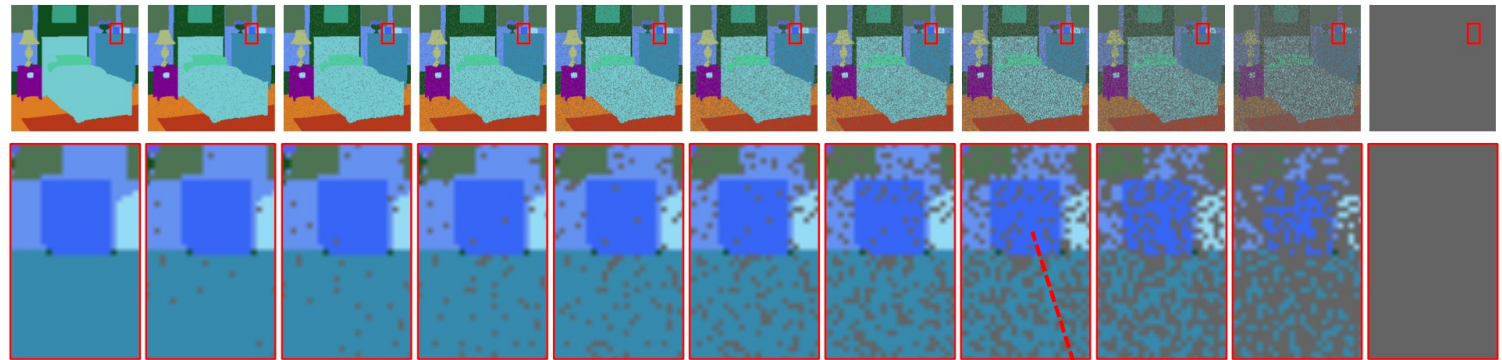
- *continuous*
- *reverse*

$$p_{\theta}(\mathbf{x}_{0:T}, \mathbf{y}_{1:T} | \mathbf{y}_0) := p(\mathbf{x}_T) \underbrace{q(\mathbf{y}_{1:T} | \mathbf{y}_0)}_{\text{Label Diffusion}} \prod_{t=1}^T p_{\theta}(\mathbf{x}_{t-1} | \mathbf{x}_t, \mathbf{y}_t),$$
$$p_{\theta}(\mathbf{x}_{t-1} | \mathbf{x}_t, \mathbf{y}_t) := \mathcal{N}(\mathbf{x}_{t-1}; \mu_{\theta}(\mathbf{x}_t, \mathbf{y}_t, t), \Sigma_{\theta}(\mathbf{x}_t, \mathbf{y}_t, t)),$$

Class-wise Noise Schedule



(a) Uniform noise schedule.



(b) Class-wise noise schedule.

Slowly diffuse small/rare classes

Noisy SIS Benchmark

- We introduce a new benchmark to assess generation performance under noisy conditions, simulating human errors that can occur during real-world applications.

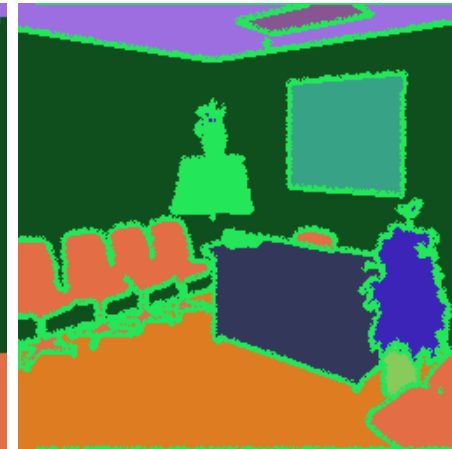
- Three setups:



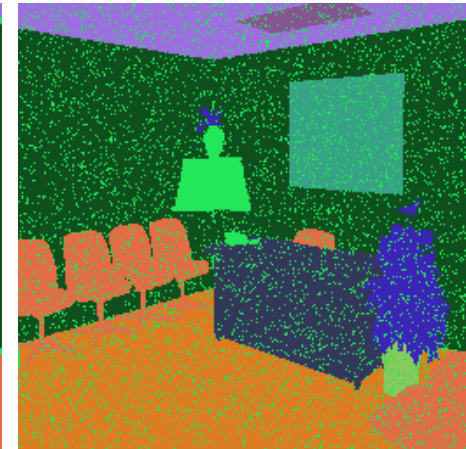
[DS]



[Edge]



[Random]



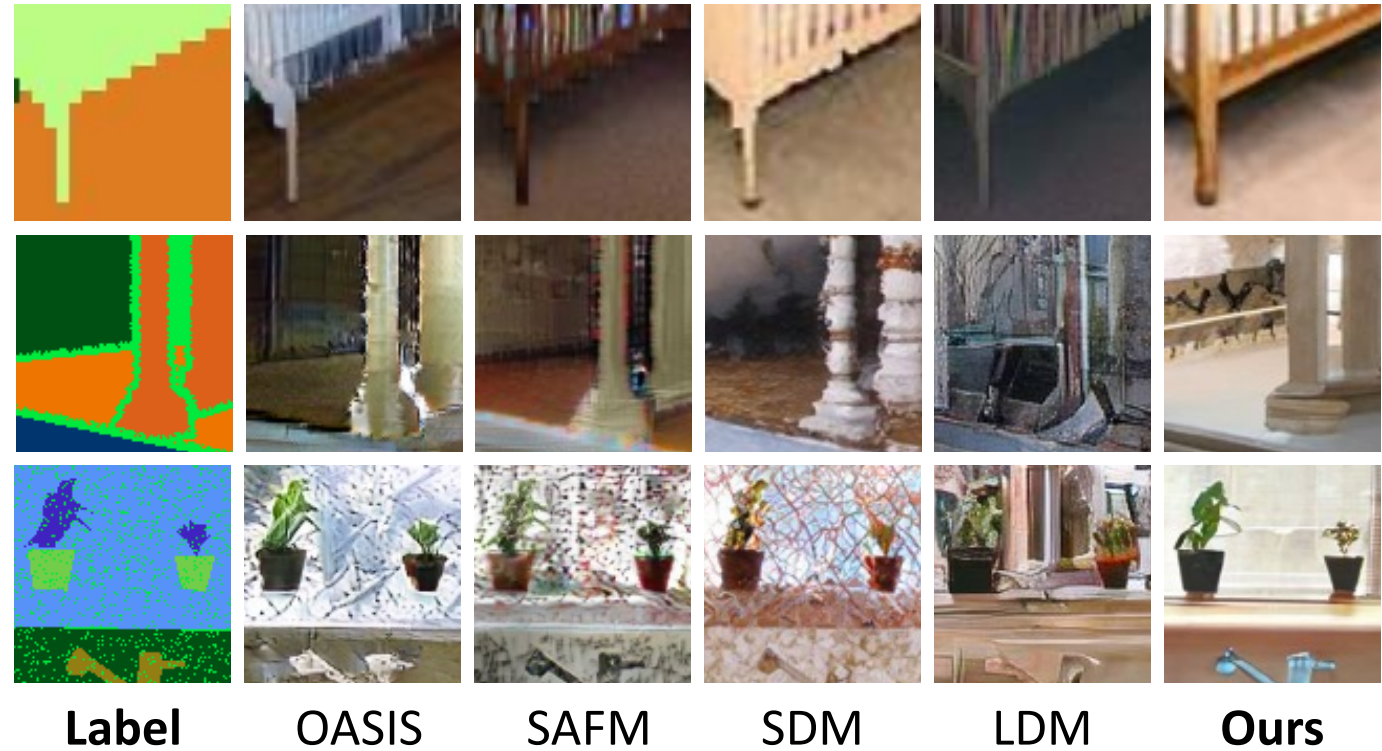
1. [DS] downsampled semantic maps

2. [Edge] masking the edges of instances

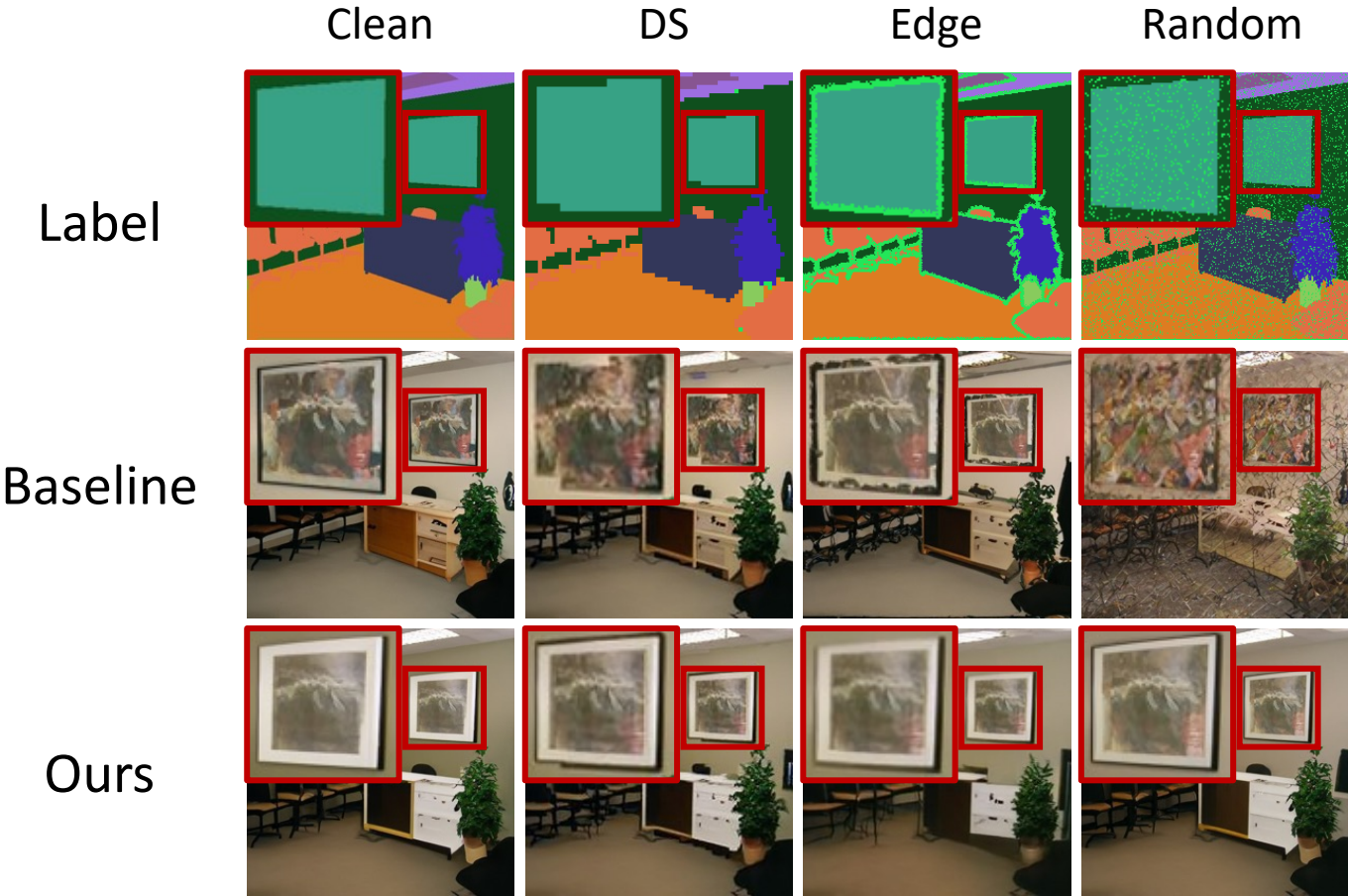
3. [Random] randomly adding unlabeled class to the semantic maps (10%)

Experiments - Noisy SIS

Category	Methods	DS		Edge		Random	
		F(↓)	M(↑)	F(↓)	M(↑)	F(↓)	M(↑)
GAN	SPADE	36.6	41.0	40.2	39.7	92.7	18.5
	CC-FPSE	42.0	40.4	38.7	41.7	141.3	16.2
	DAGAN	37.6	41.3	42.2	39.0	109.1	16.4
	GroupDNet	45.9	28.9	49.9	28.0	76.0	21.2
	OASIS	34.5	48.1	37.6	<u>47.4</u>	54.2	42.1
	CLADE	37.4	41.8	41.9	40.1	71.8	29.9
	INADE	36.1	38.3	40.3	35.6	61.3	30.2
	SCGAN	38.1	44.0	63.9	43.3	40.9	38.6
	SAFM*	36.7	<u>50.1</u>	40.0	44.9	80.6	34.1
DM	SDM	35.5	43.8	39.4	39.4	141.9	11.8
	LDM	38.9	28.1	39.5	26.0	36.3	27.1
	Ours	<u>32.4</u>	<u>44.7</u>	<u>31.2</u>	<u>40.1</u>	<u>28.1</u>	<u>45.2</u>



Analysis – Label Diffusion and Robustness



Dataset	Method	Metric			
		LPIPS(↓)	SSIM(↑)	PSNR(↑)	FID(↓)
DS	Baseline	0.221	0.823	30.4	24.2
	Ours	0.180	0.865	31.3	19.0
Edge	Baseline	0.248	0.771	29.7	32.7
	Ours	0.223	0.825	30.2	20.0
Random	Baseline	0.560	0.427	28.1	145.6
	Ours	0.076	0.944	32.9	10.0

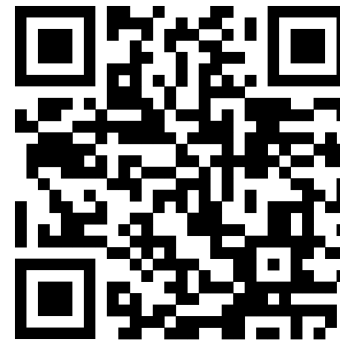
Conclusion

- We first address a significant challenge for SIS models in real-world applications: dealing with noisy input from users.
- We propose a novel conditional diffusion model, SCDM, specifically designed to enhance robustness on noisy labels.
- We present a new benchmark setting to assess performance under noisy conditions.
- SCDM improves generation quality through its Label Diffusion and class-wise noise schedule.

Thank You



Paper



GitHub