# The Blessing of Heterogeneity in Federated Q-Learning: Linear Speedup and Beyond

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# Reinforcement learning (RL)

In RL, an agent learns optimal decisions by interacting with an environment.











Real-world applications: autonomous driving, game, clinical trials, ...

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# Challenges: Data and computation

 Sample efficiency: Collecting data samples might be expensive or time-consuming



clinical trials



autonomous driving

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clinical trials



autonomous driving

 Computational efficiency: Training RL algorithms might take a long time

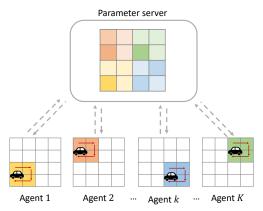




 $many \ CPUs \ / \ GPUs \ / \ TPUs + computing hours$ 

# RL meets federated learning

Can we harness the power of federated learning?



**Federated reinforcement learning** enables multiple agents to collaboratively learn a global policy without sharing datasets.

# This paper

Understand the sample efficiency of Q-learning in federated settings.

### Linear speedup:

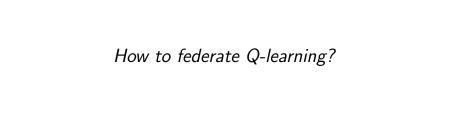
Can we achieve linear speedup when learning with multiple agents?

### **Communication efficiency:**

Can we perform multiple local updates to save communication?

### Taming heterogeneity:

How to combine heterogeneous local updates to accelerate learning?



# Asynchronous Q-learning

**Bellman equation:** The optimal Q-function  $Q^*$  is unique solution to

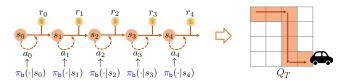
$$Q^{\star}(s,a) = \mathcal{T}(Q^{\star})(s,a) := r(s,a) + \gamma \mathop{\mathbb{E}}_{\substack{s' \sim P(\cdot \mid s,a)}} [\max_{a'} Q^{\star}(s',a')]$$

**Q-learning:** Stochastic approximation for solving Bellman equation. With a transition sample  $(s_t, a_t, r_t, s_{t+1})$ , update  $Q_t$  as

$$Q_{t+1}(s_t, a_t) = (1 - \eta)Q_t(s_t, a_t) + \eta \underbrace{(r_t + \gamma \max_{a' \in \mathcal{A}} Q_t(s_{t+1}, a'))}_{\mathcal{T}_t(Q_t)}, \quad t \ge 0$$

 $\eta$ : step size

**Asynchronous setting**: Update single entry  $(s_t, a_t)$  along a *Markovian trajectory* generated by *behavior policy*  $\pi_b$ 



# Federated asynchronous Q-learning with local updates

Local update (agent): Q-learning updates.

Performs 
$$\tau$$
 rounds of local Q-learning updates. 
$$Q_{t+1}^k(s_t,a_t) \leftarrow (1-\eta)Q_t^k(s_t,a_t) + \eta \mathcal{T}_t(Q_t^k)(s_t,a_t)$$
 Agent 1 Agent 2 ... Agent  $k$  ... Ag

Local trajectories might be heterogeneous!

Parameter server

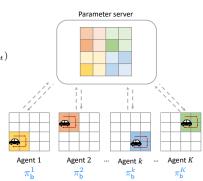
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 Periodic averaging (server): Averages the local Q-tables.

$$Q_t = \frac{1}{K} \sum_{k=1}^K Q_t^k.$$



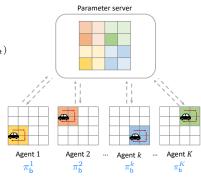
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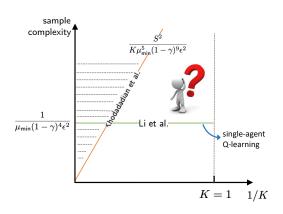
$$Q_t = \frac{1}{K} \sum_{k=1}^K Q_t^k.$$



Can we achieve faster convergence with heterogeneous local updates?

Sample complexity of federated Q-learning

### Prior art



Unfavorable dependencies on salient problem parameters ( $\gamma$ ,  $\mu_{\min}$ ,  $|\mathcal{S}|$ )

### Our theorem

### Theorem (this work)

For sufficiently small  $\epsilon>0$ , if  $\tau$  is not too large, federated asynchronous Q-learning yields  $\|\widehat{Q}-Q^\star\|_\infty \leq \epsilon$  with sample complexity at most

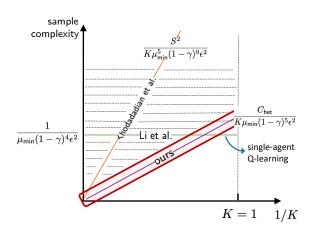
$$\widetilde{O}\left(\frac{C_{\mathsf{het}}}{K\mu_{\mathsf{min}}(1-\gamma)^5\epsilon^2}\right)$$

ignoring the burn-in cost that depends on the mixing times, where

$$\mu_{\min} := \min_{k,s,a} \underbrace{\mu_{\mathsf{b}}^k(s,a)}_{\substack{\text{stationary distribution}}} \quad \text{and } C_{\mathsf{het}} := K \max_{k,s,a} \frac{\mu_{\mathsf{b}}^k(s,a)}{\sum_{k=1}^K \mu_{\mathsf{b}}^k(s,a)}.$$

- $1 \le C_{\rm het} \le \frac{1}{\mu_{\rm min}}$  measures the heterogeneity of local behavior policies.
- $C_{\rm het} \approx 1$  when the local behavior policies are similar.

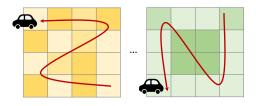
# Near-optimal linear speedup



Linear speedup with near-optimal parameter dependencies!

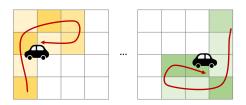
# Curse of heterogeneity?

• Full coverage: The insufficient coverage of *just one* agent can significantly slow down the convergence (i.e.  $\mu_{\min} \approx 0$ )



# Curse of heterogeneity?

- Full coverage: The insufficient coverage of *just one* agent can significantly slow down the convergence (i.e.  $\mu_{\min} \approx 0$ )
- Curse of heterogeneity: Performance degenerates when local behavior policies are heterogeneous (i.e.  $C_{\text{het}} \gg 1$ ).

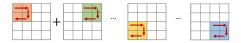


Is it possible to alleviate these limitations?

How to federate Q-learning without the curse of heterogeneity?

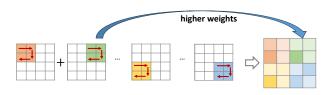
# Importance averaging

**Key observation:** Not all updates are of same quality due to limited visits induced by the behavior policy.



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**Importance averaging:** Averages the local Q-values assigning higher weights on more frequently updated local values via

$$Q_t(s, a) = \frac{1}{K} \sum_{k=1}^{K} \alpha_t^k(s, a) Q_t^k(s, a),$$

where

$$\alpha_t^k = \frac{(1-\eta)^{-N_{t-\tau,t}^k(s,a)}}{\sum_{k=1}^K (1-\eta)^{-N_{t-\tau,t}^k(s,a)}}, \quad N_{t-\tau,t}^k(s,a) = \quad \text{number of visits} \quad \text{in the sync period} \quad .$$

# Sample complexity of federated Q-learning with importance averaging

### Our theorem

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For sufficiently small  $\epsilon>0$ , if  $\tau$  is not too large, federated asynchronous Q-learning with importance averaging yields  $\|\widehat{Q}-Q^\star\|_\infty \leq \epsilon$  with sample complexity at most

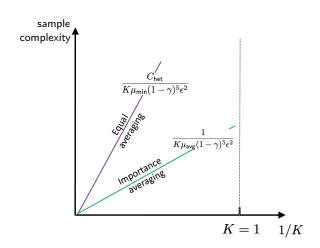
$$\widetilde{O}\left(\frac{1}{K\mu_{\mathsf{avg}}(1-\gamma)^5\epsilon^2}\right)$$

ignoring the burn-in cost that depends on the mixing times, where

$$\mu_{\text{avg}} = \min_{s,a} \frac{1}{K} \sum_{k=1}^K \mu_{\text{b}}^k(s,a).$$

- No performance degeneration due to heterogeneity  $(C_{het})$ .
- Near-optimal linear speedup.

# Equal averaging versus importance averaging

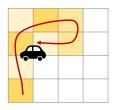


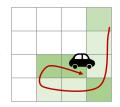
Faster convergence:  $\mu_{\text{avg}} \geq \mu_{\text{min}}$ 

# Partial-coverage

Partial coverage is enough as long as agents collectively cover the entire state-action space, i.e.,

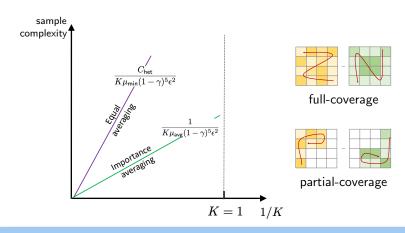
$$\mu_{\mathsf{avg}} = \min_{s,a} \frac{1}{K} \sum_{k=1}^K \mu_{\mathsf{b}}^k(s,a) > 0$$





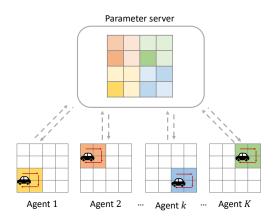
No longer require full coverage of every individual agent!

# Blessing of heterogeneity



Overcome the insufficient coverage of individual agents by exploiting heterogeneity!

### Final remarks



Near-optimal linear speedup of federated Q-learning without full coverage of individual agents!

### Thanks!

 The Blessing of Heterogeneity in Federated Q-Learning: Linear Speedup and Beyond, ICML 2023. (arXiv: 2305.10697)



