



Massachusetts
Institute of
Technology

EquiBind

Geometric Deep Learning for Drug Binding Structure Prediction

Hannes Stärk, Octavian-Eugen Ganea, Lagnajit Pattanaik, Regina Barzilay, Tommi Jaakkola

Protein ABL1



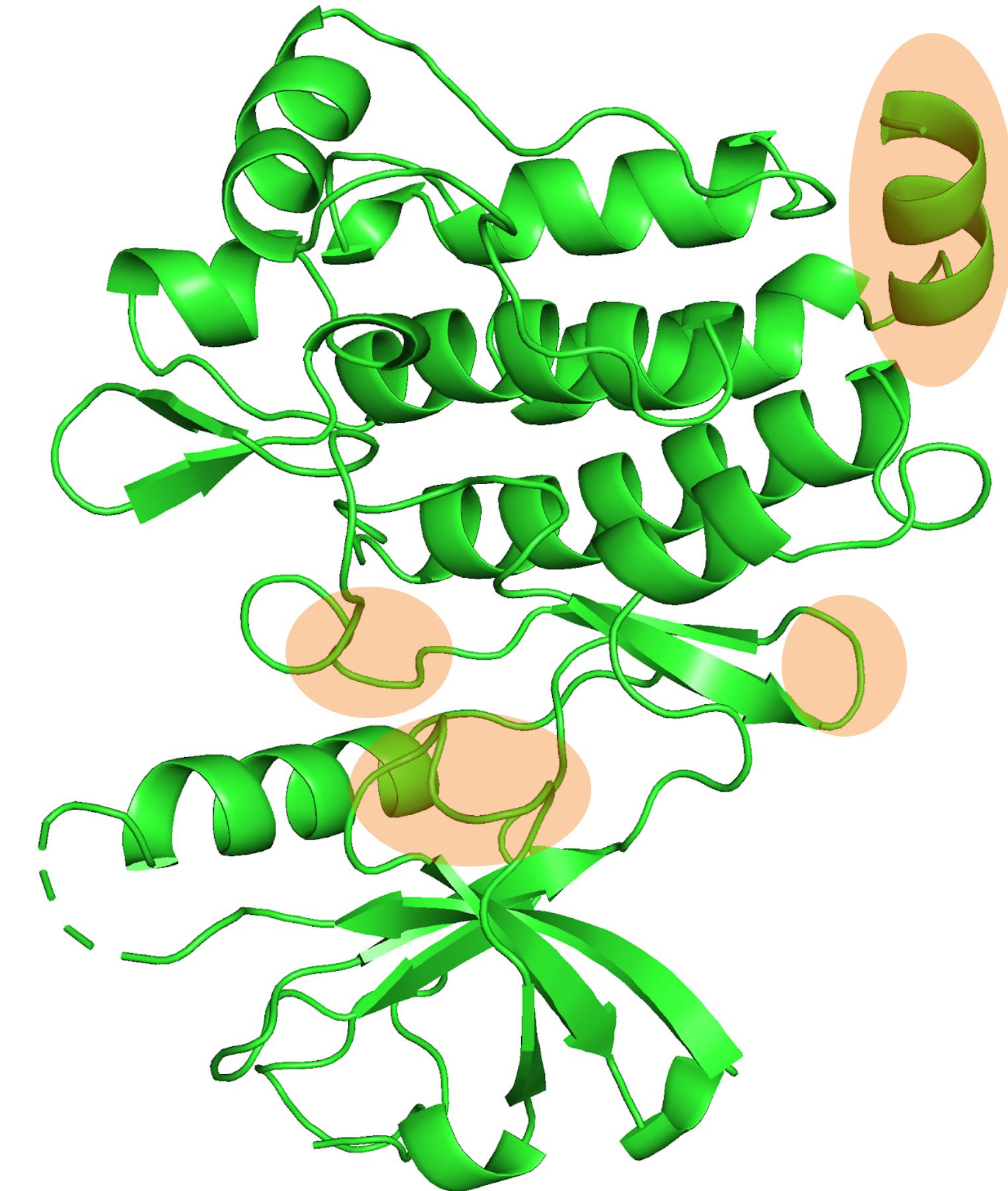
Controlled cell growth

Protein ABL1



Controlled cell growth

Mutated ABL1



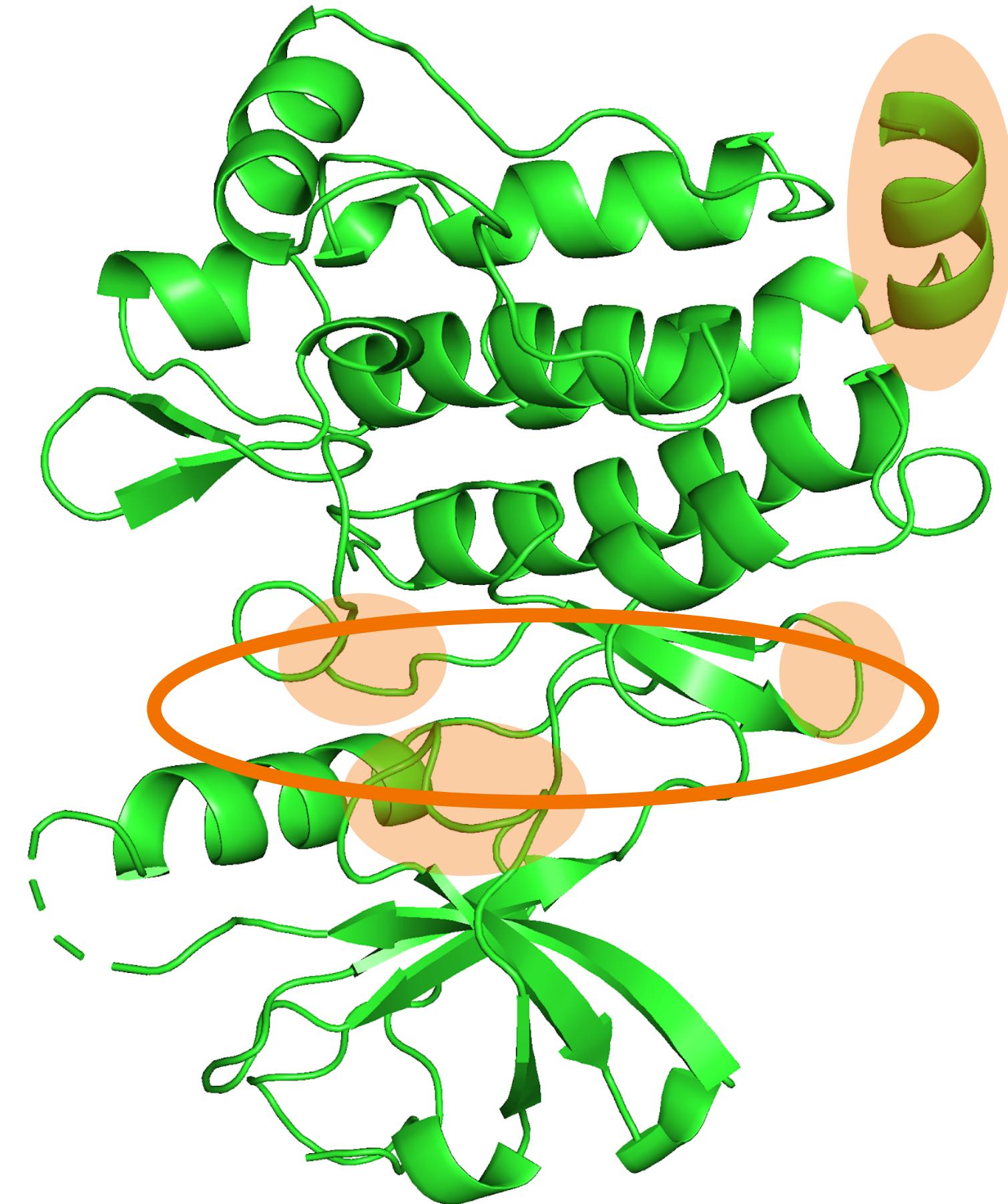
Uncontrolled cell growth

Protein ABL1



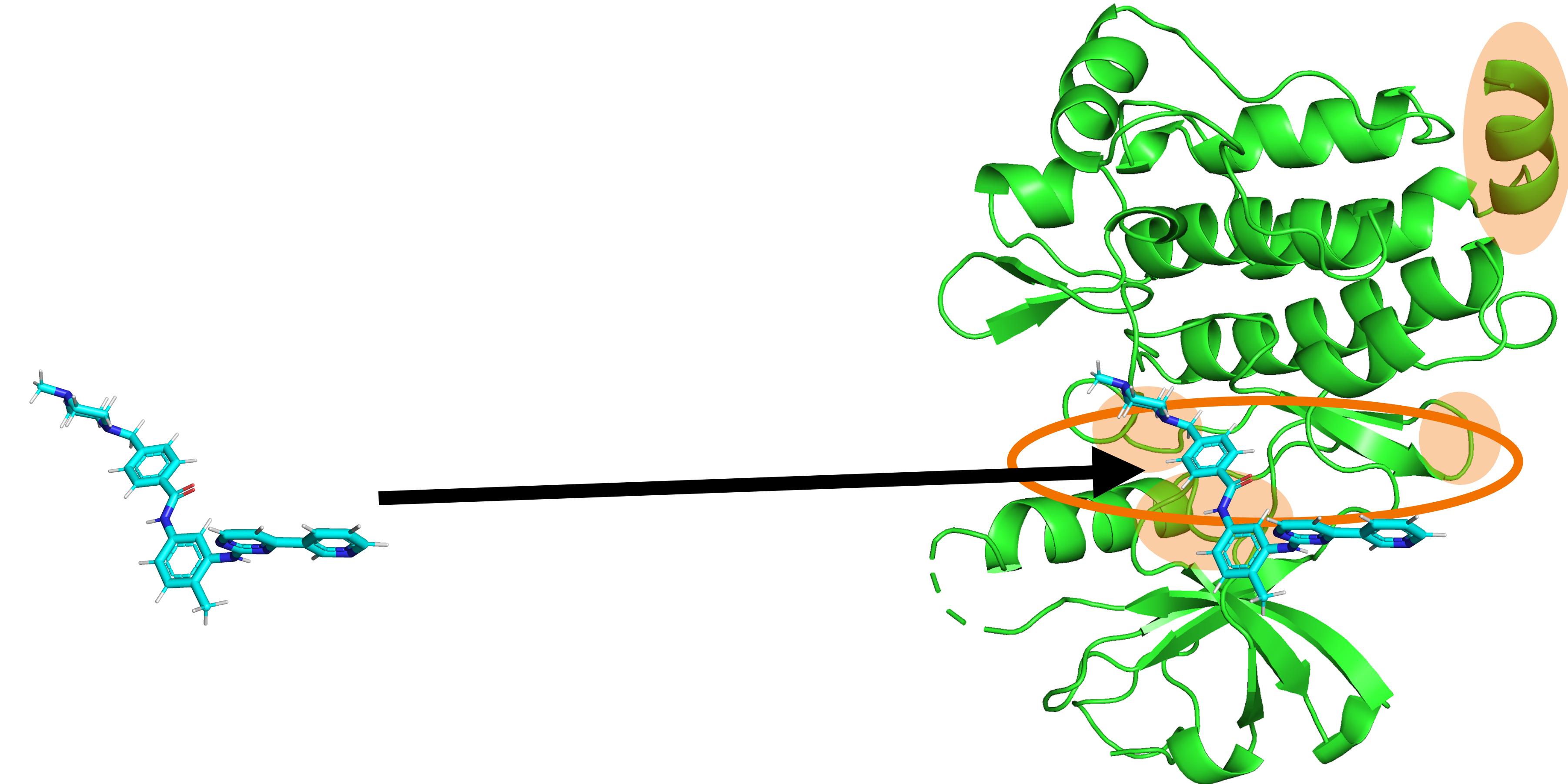
Controlled cell growth

Mutated ABL1



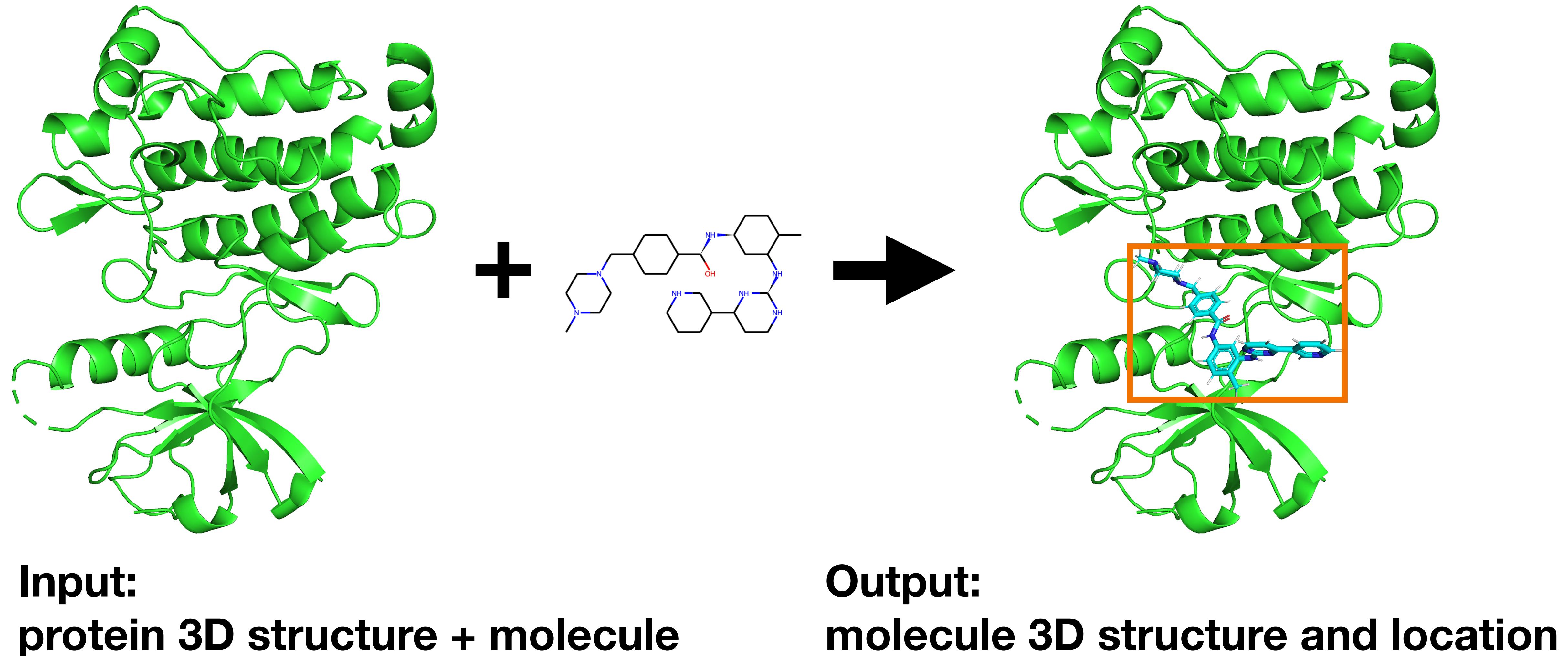
Uncontrolled cell growth

Restoring function

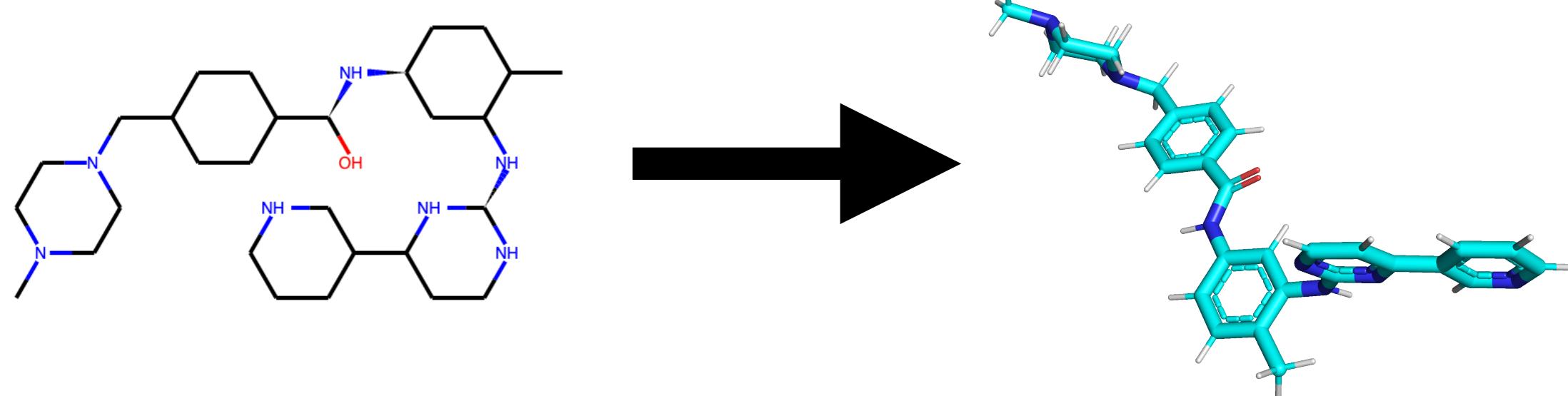


Small molecule binds to key region to stop abnormal behavior

EquiBind: Binding Structure Prediction

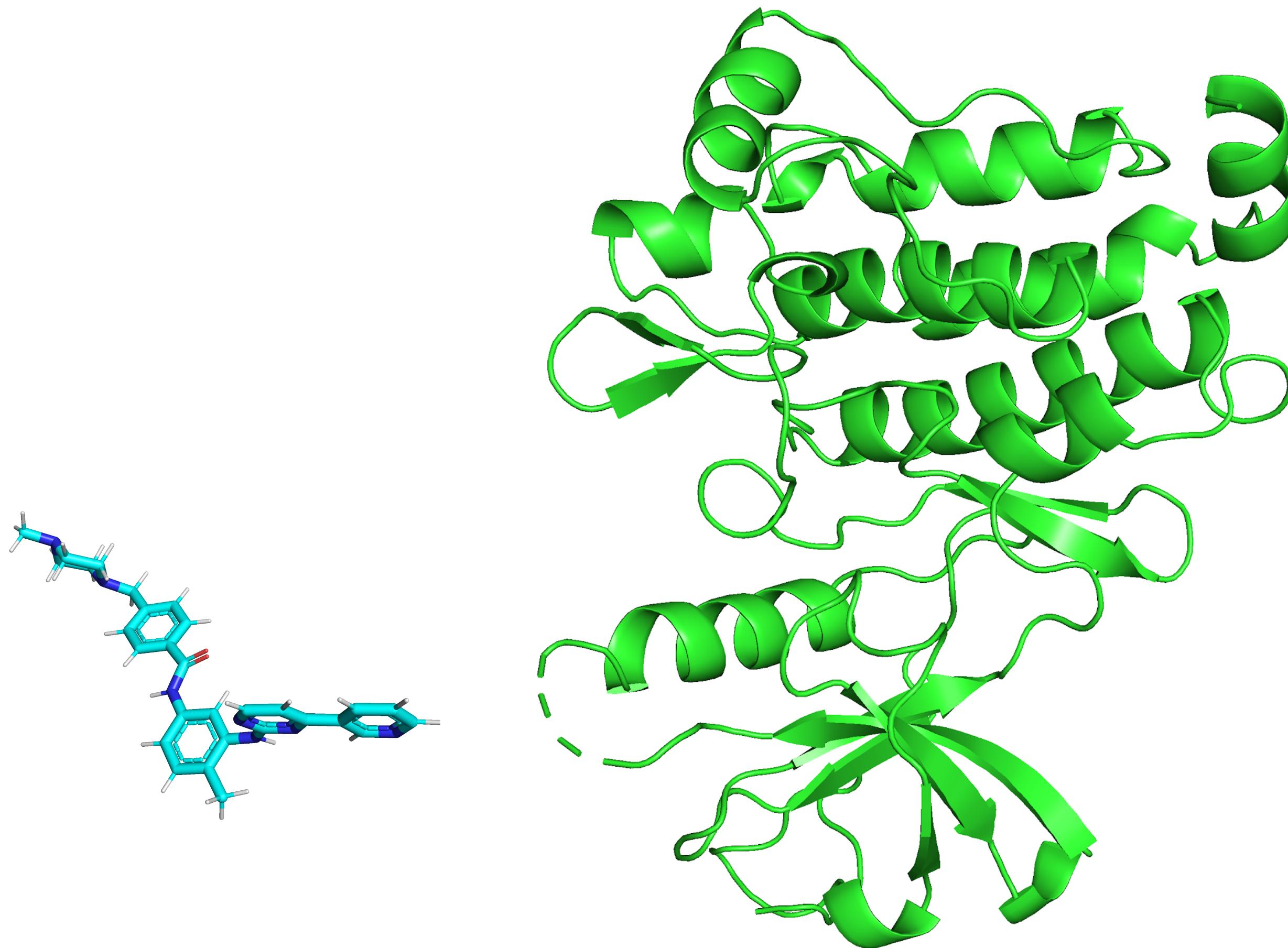


Symmetries the method needs to respect



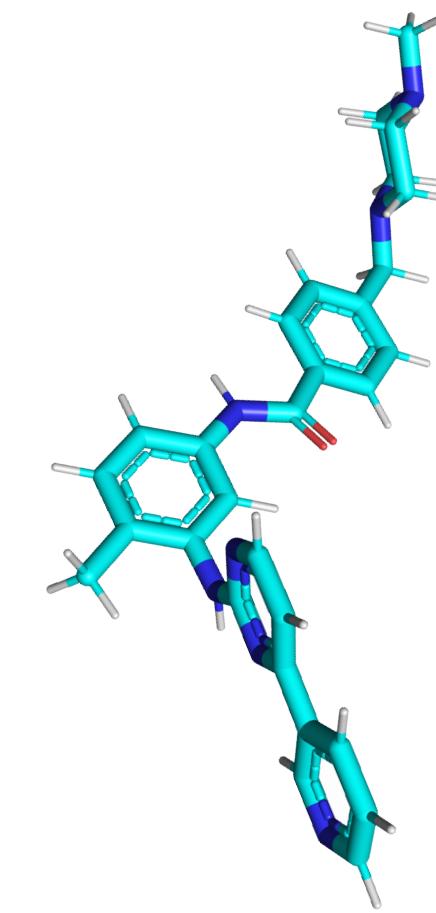
Translation and rotation invariance of initial molecule structure

Symmetries the method needs to respect



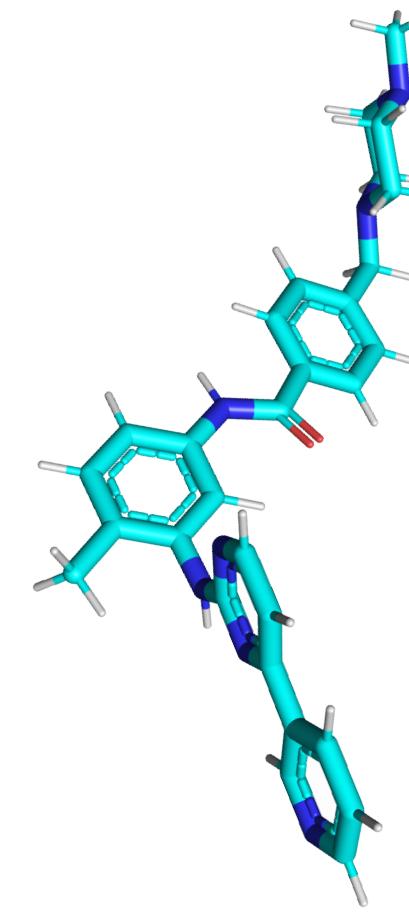
Translation and rotation invariance of initial molecule structure

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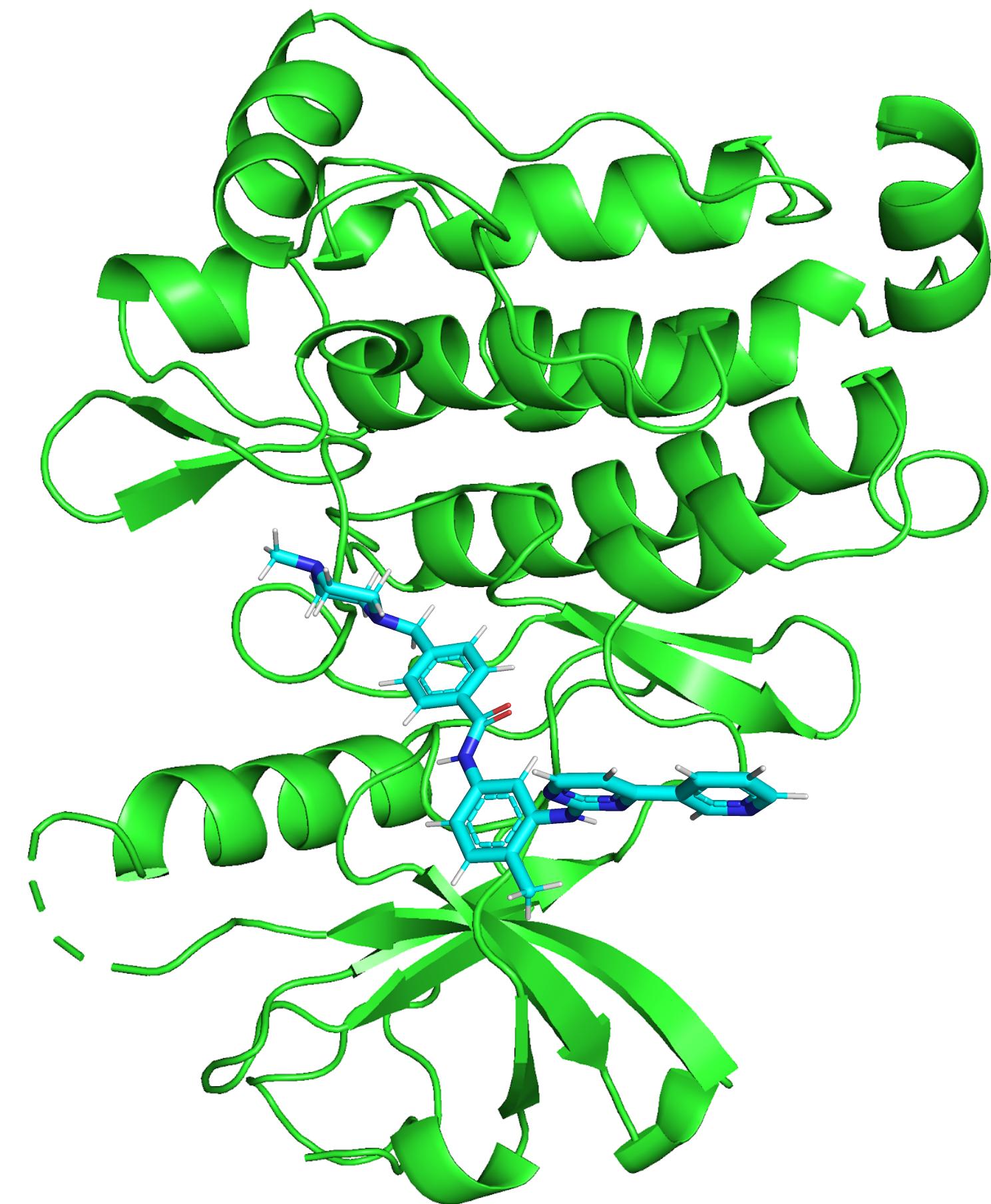
Translation and rotation invariance of initial molecule structure

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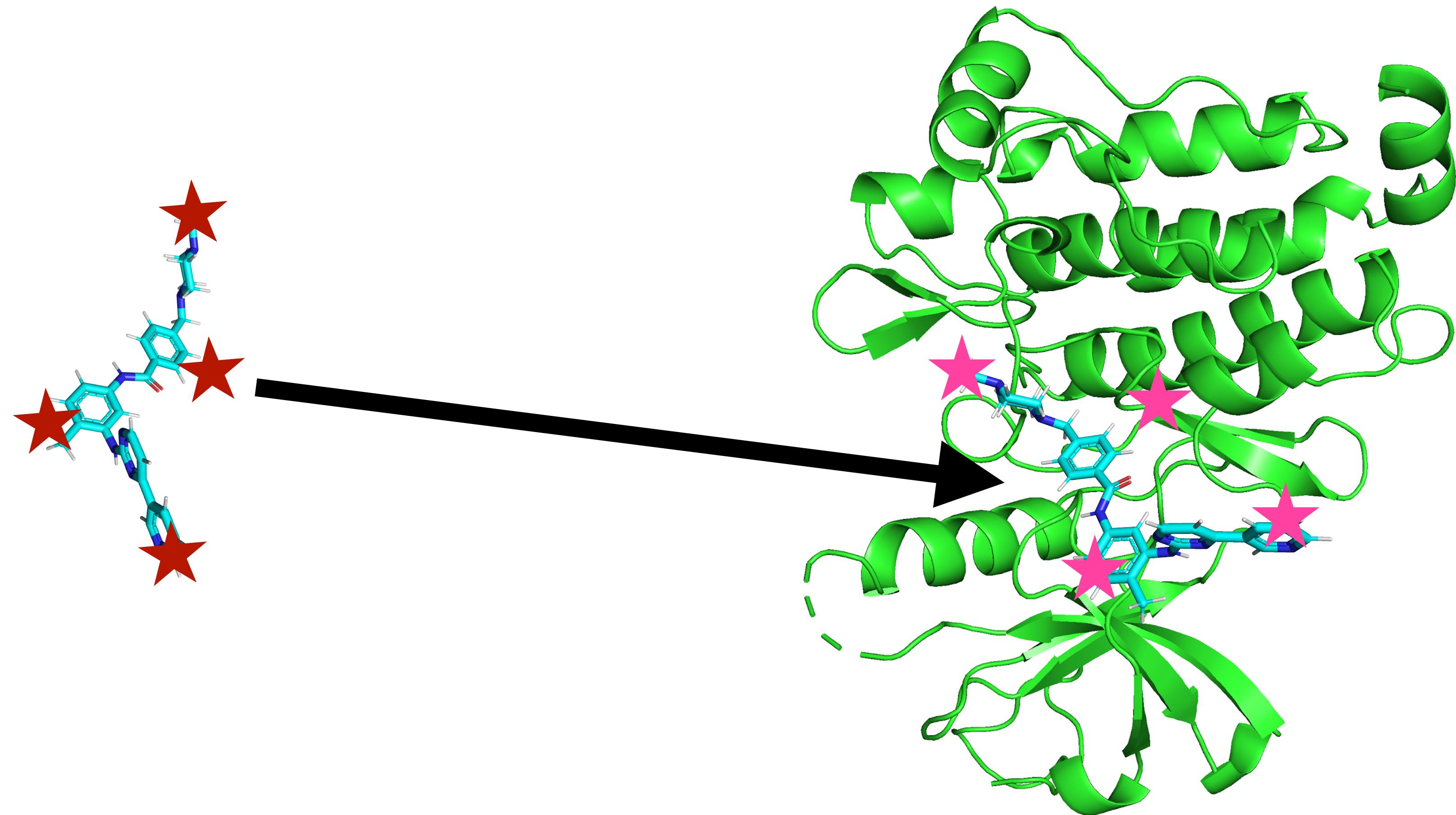
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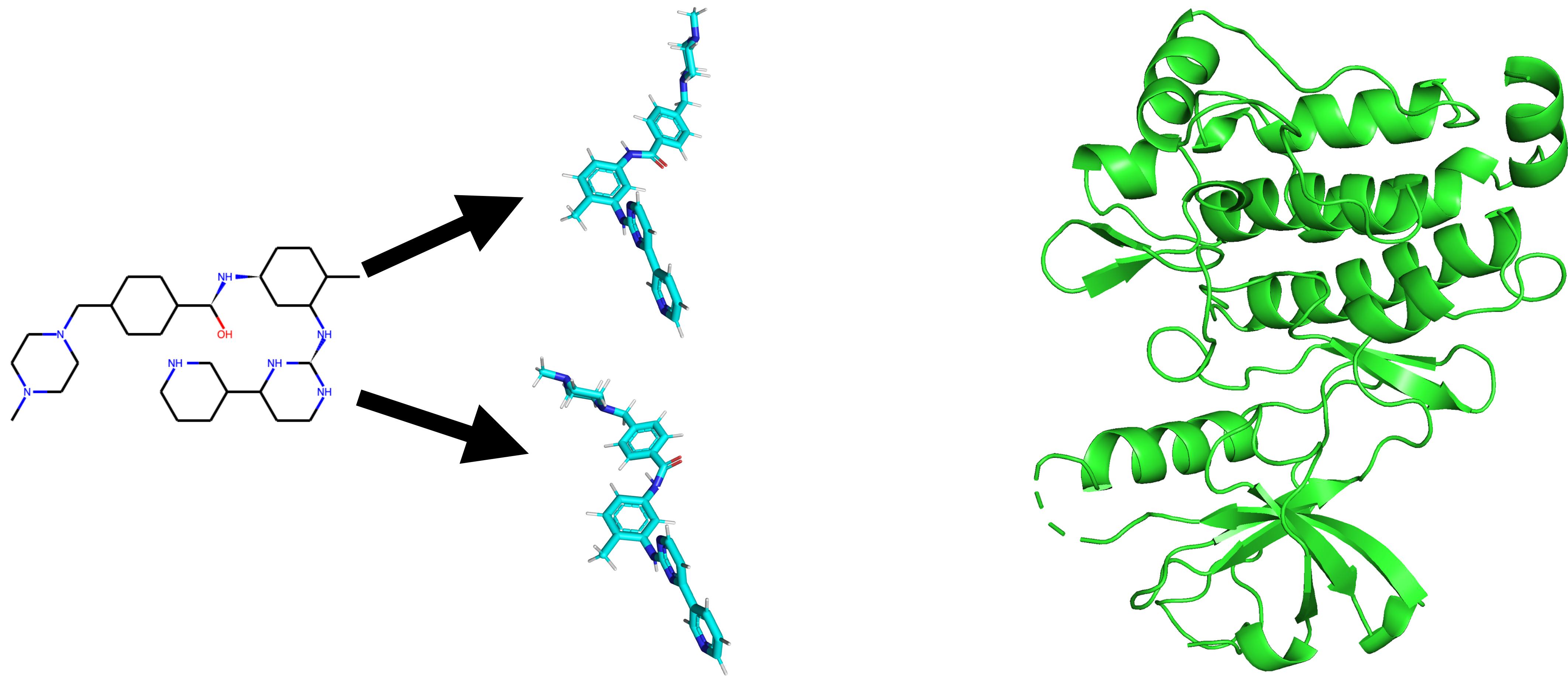
Translation and rotation invariance of initial molecule structure

EquiDock: invariant rototranslation prediction



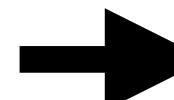
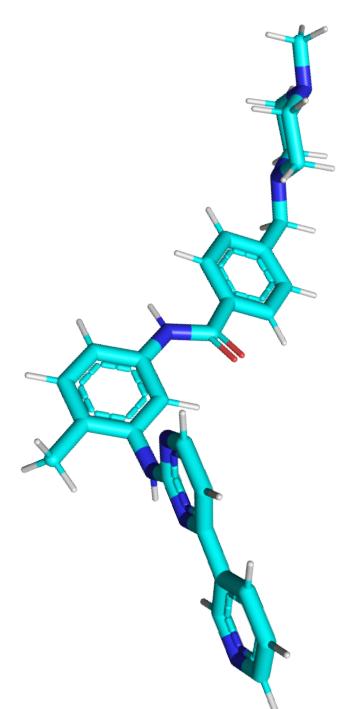
Kabsch algorithm calculates rototranslation to match keypoints

Finding the correct 3D molecule structure

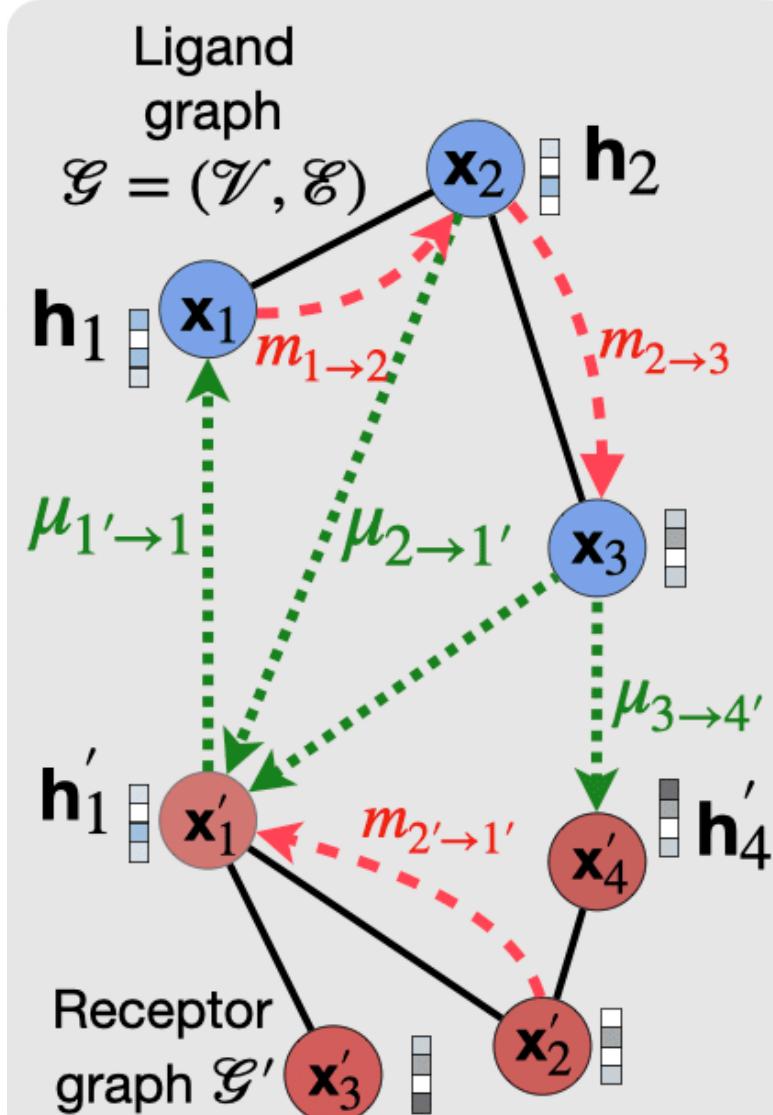


3D structure of small molecule is not rigid => model flexibility

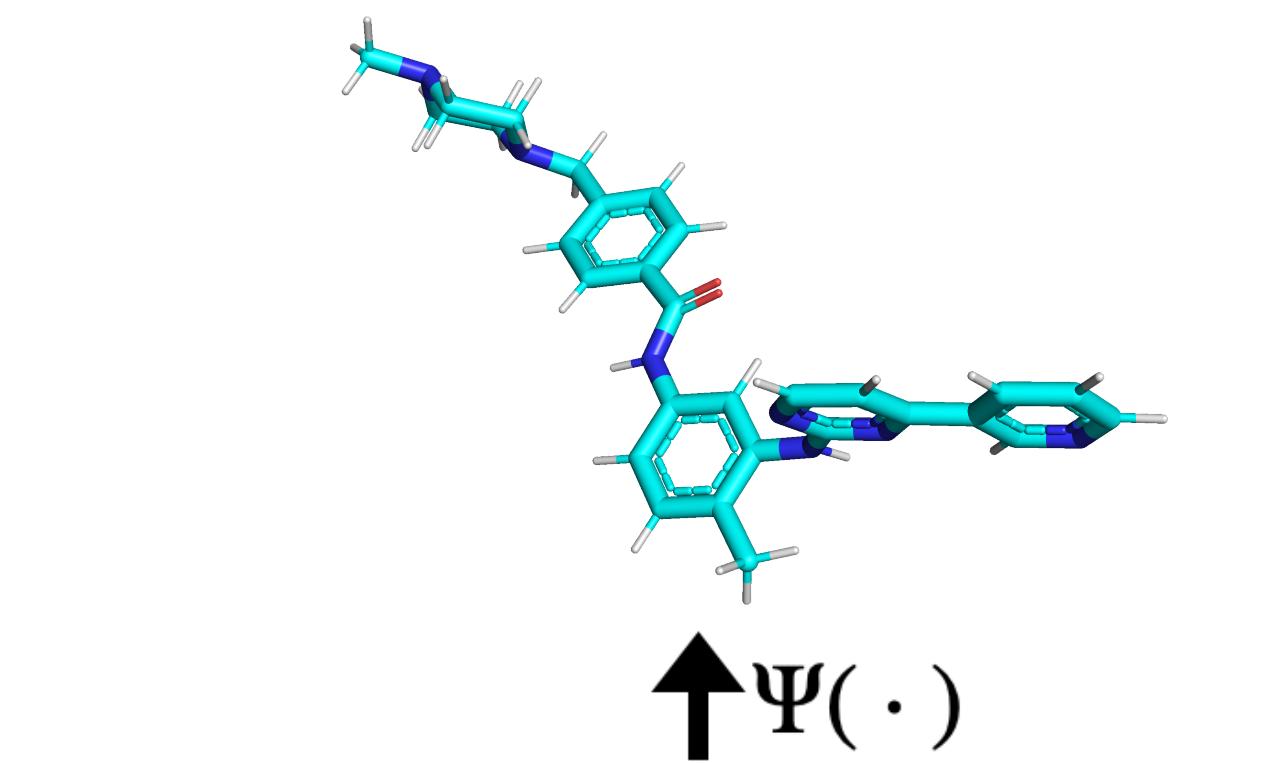
Chemically plausible molecule flexibility



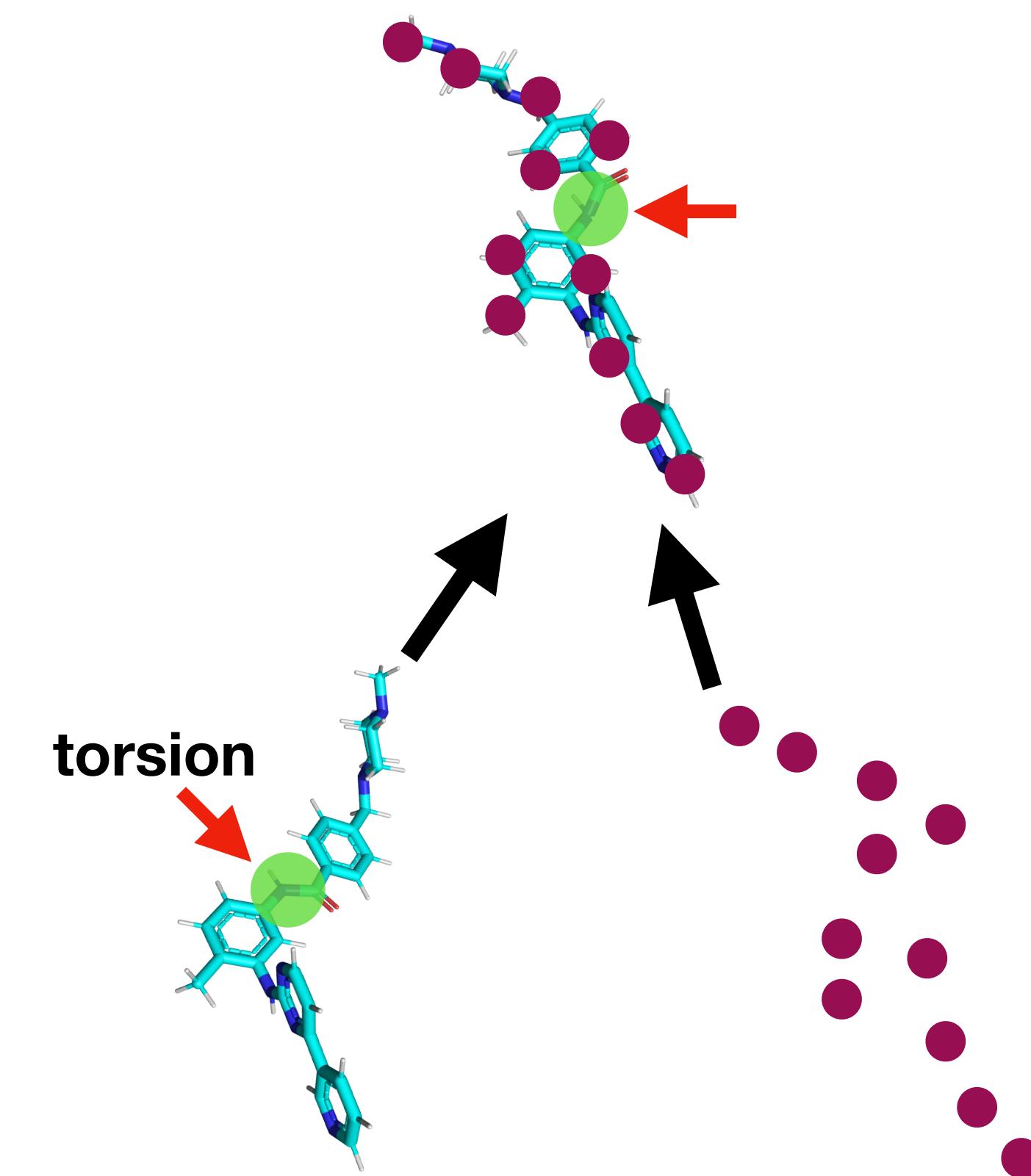
Independent SE(3)-equivariant GMNs



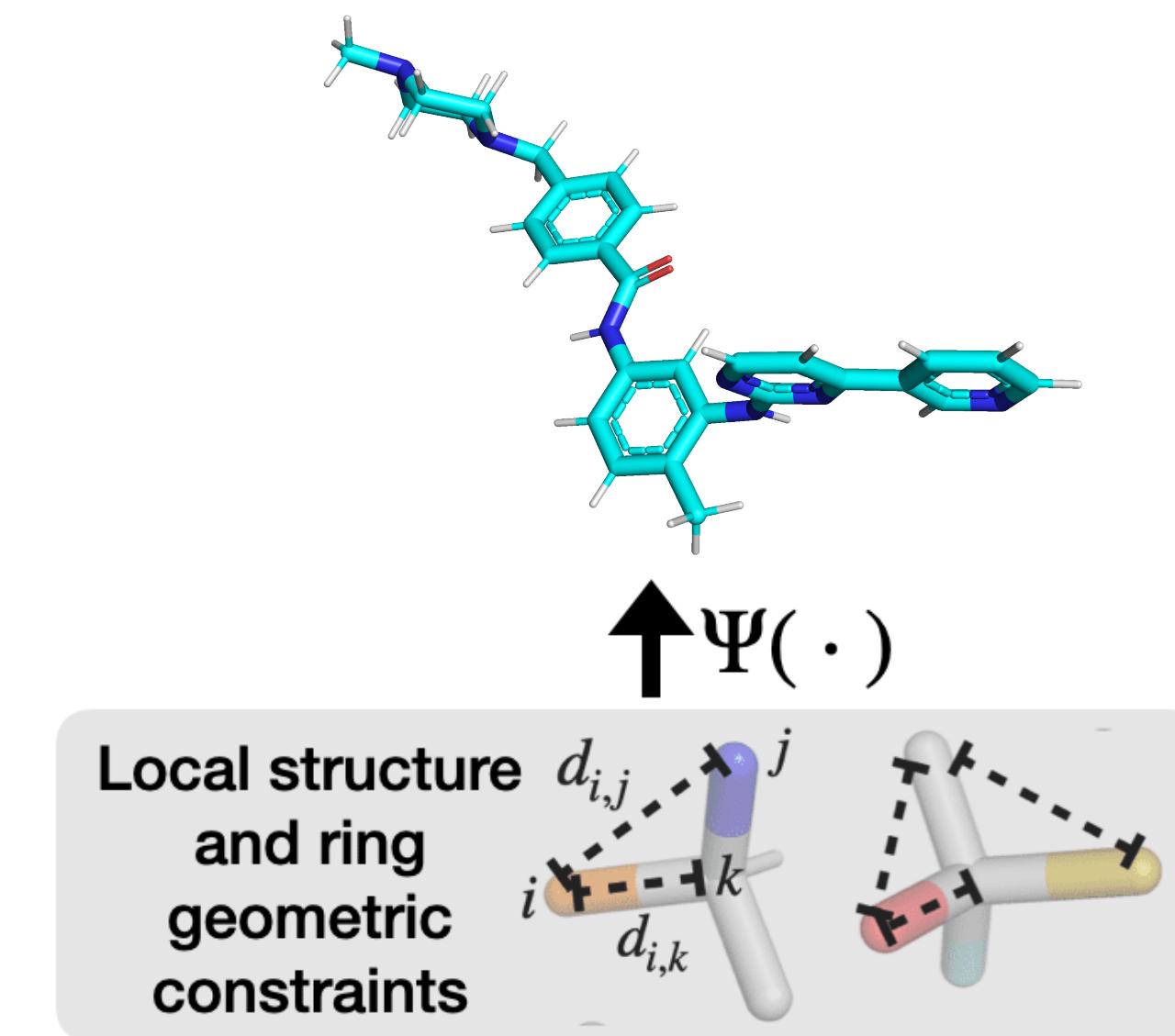
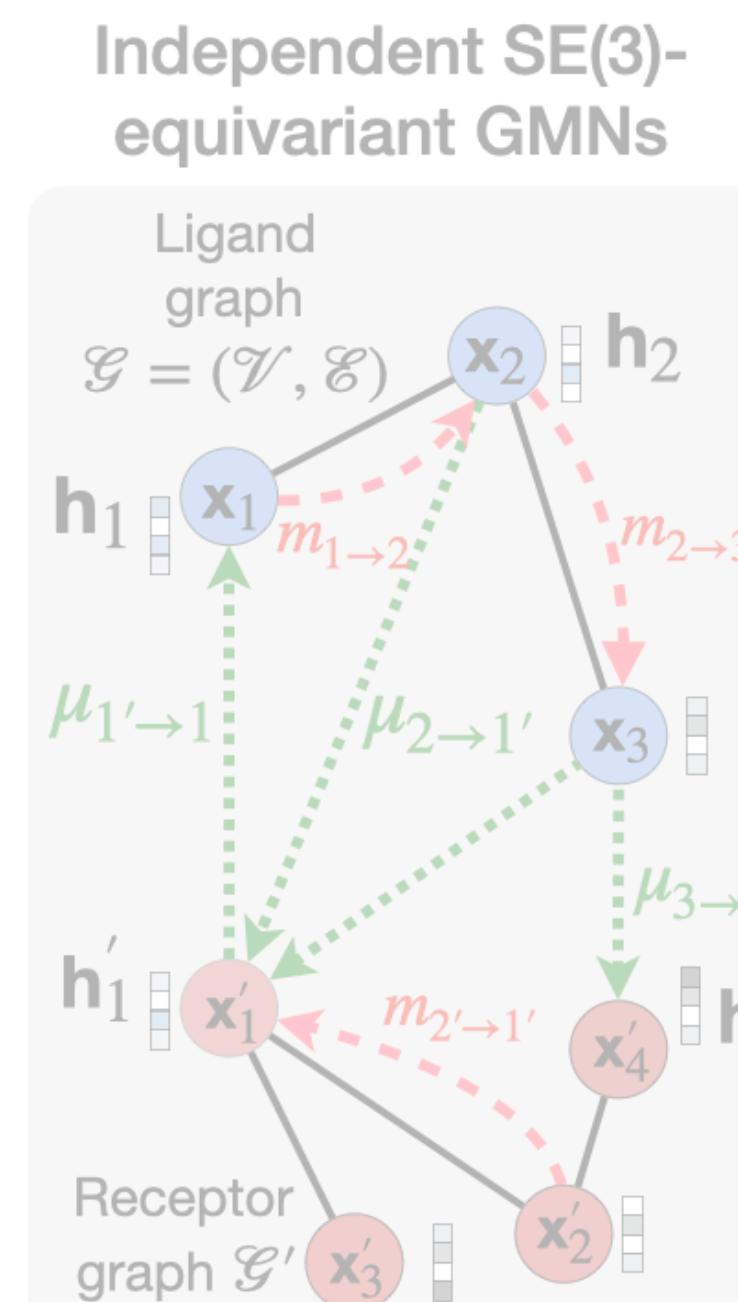
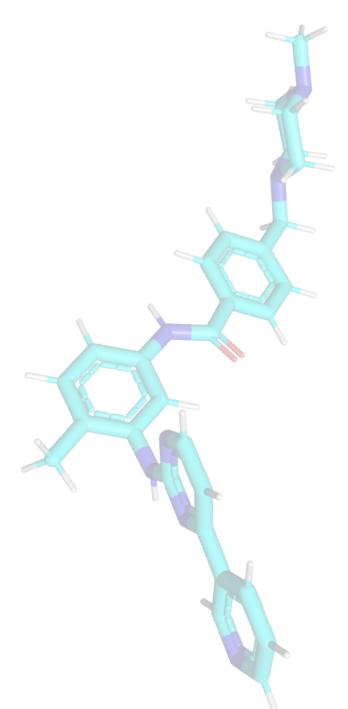
Local structure and ring geometric constraints



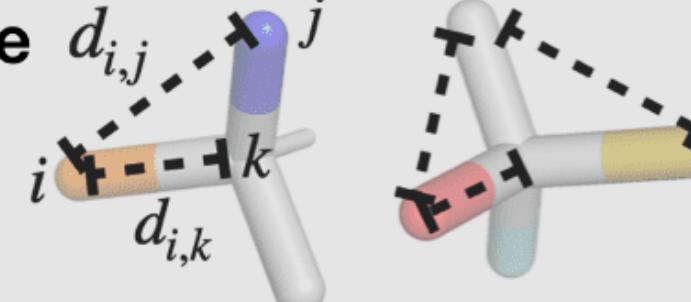
Efficiently change only torsion angles to fit molecule into atom point cloud



Chemically plausible molecule flexibility

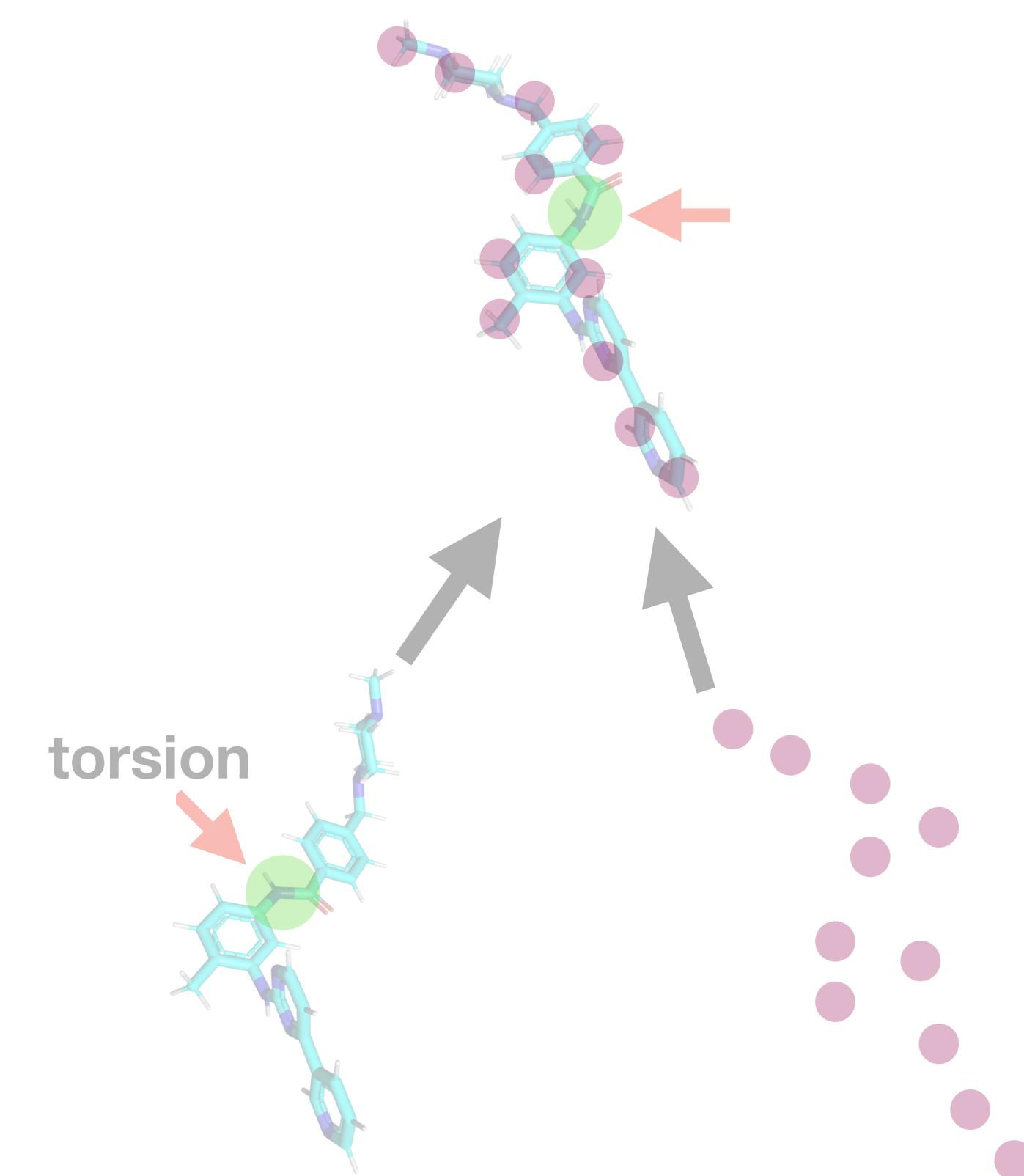


Local structure and ring geometric constraints

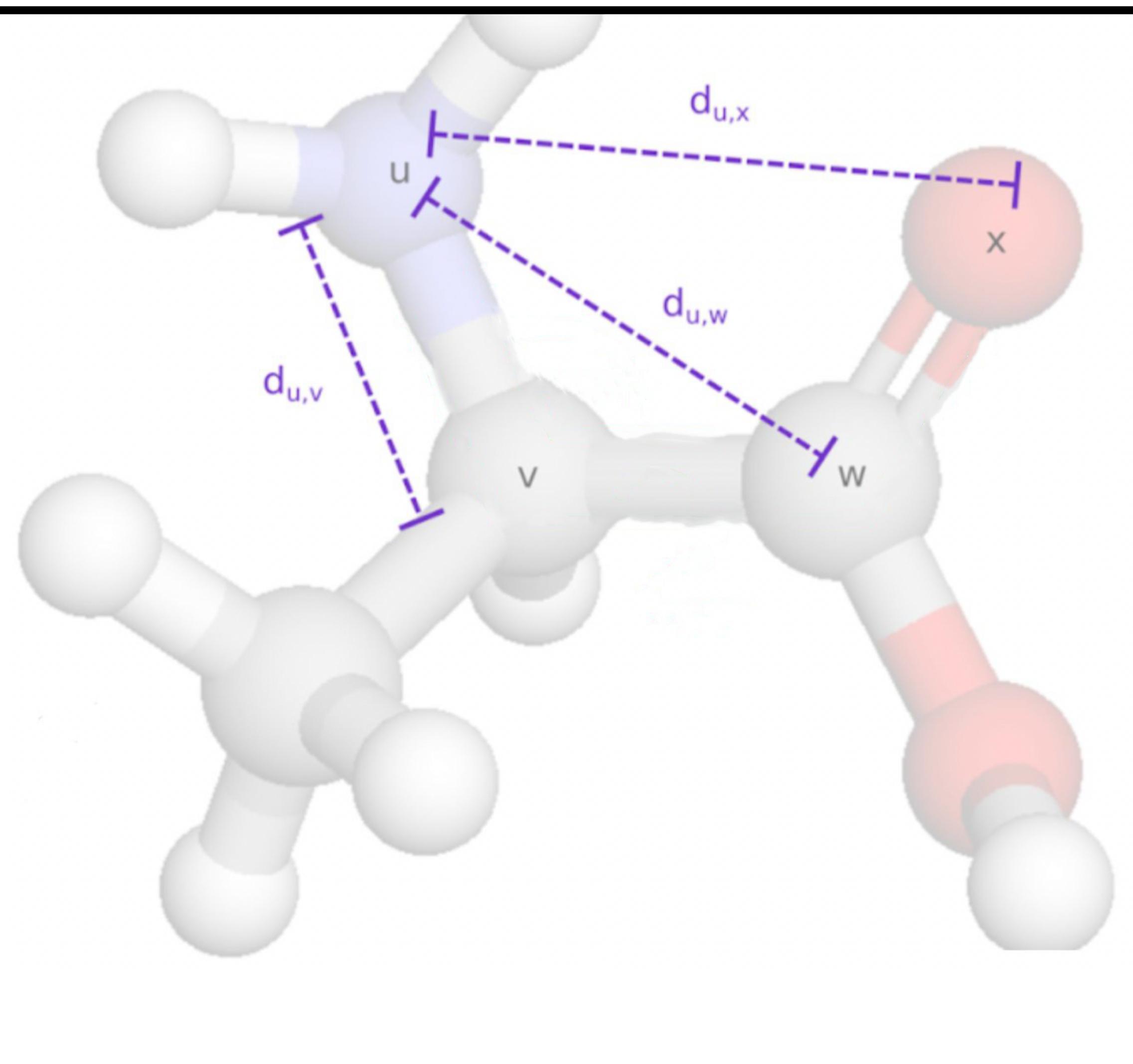


$$\Psi(\cdot)$$

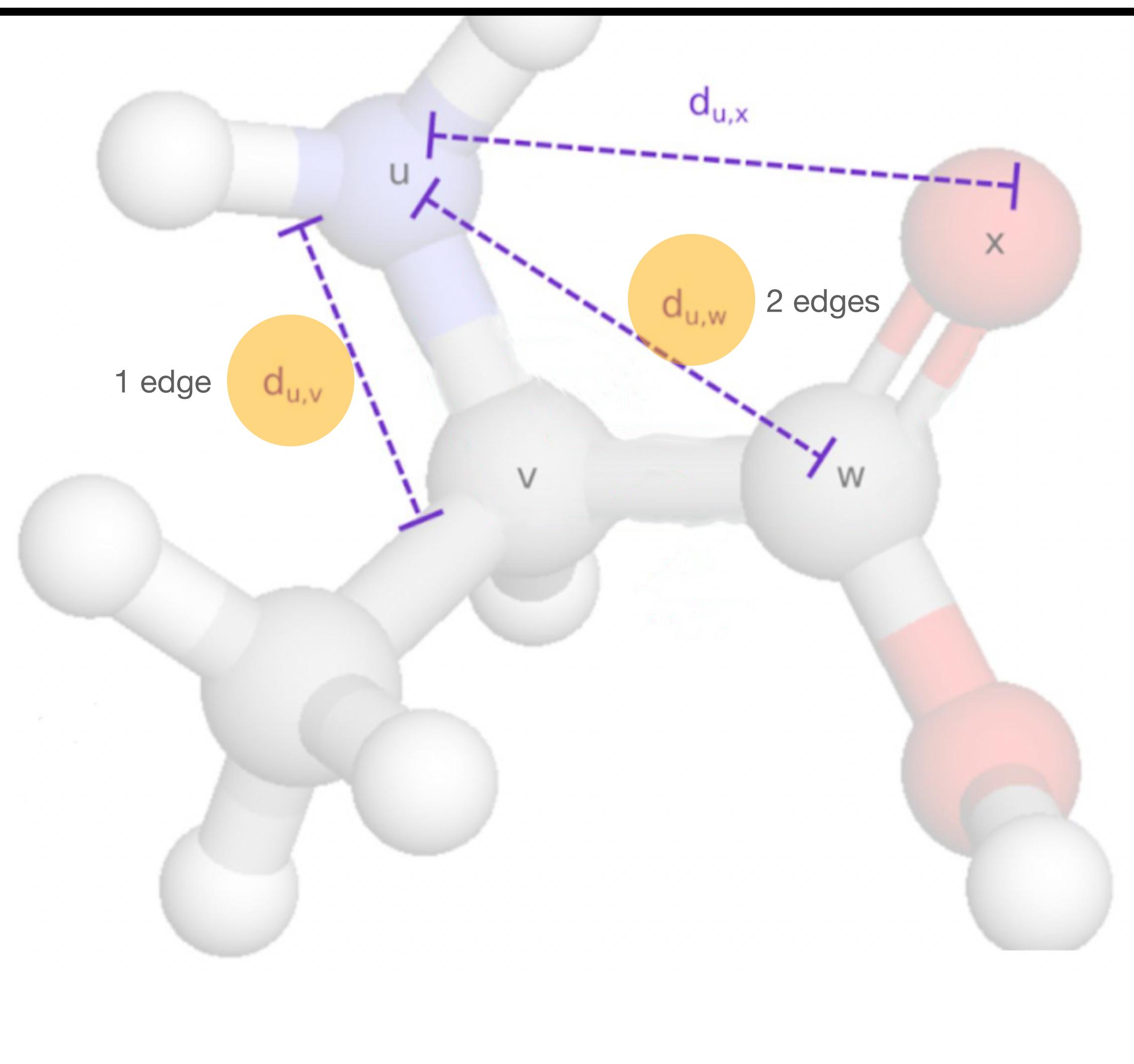
Efficiently change only torsion angles to fit molecule into atom point cloud



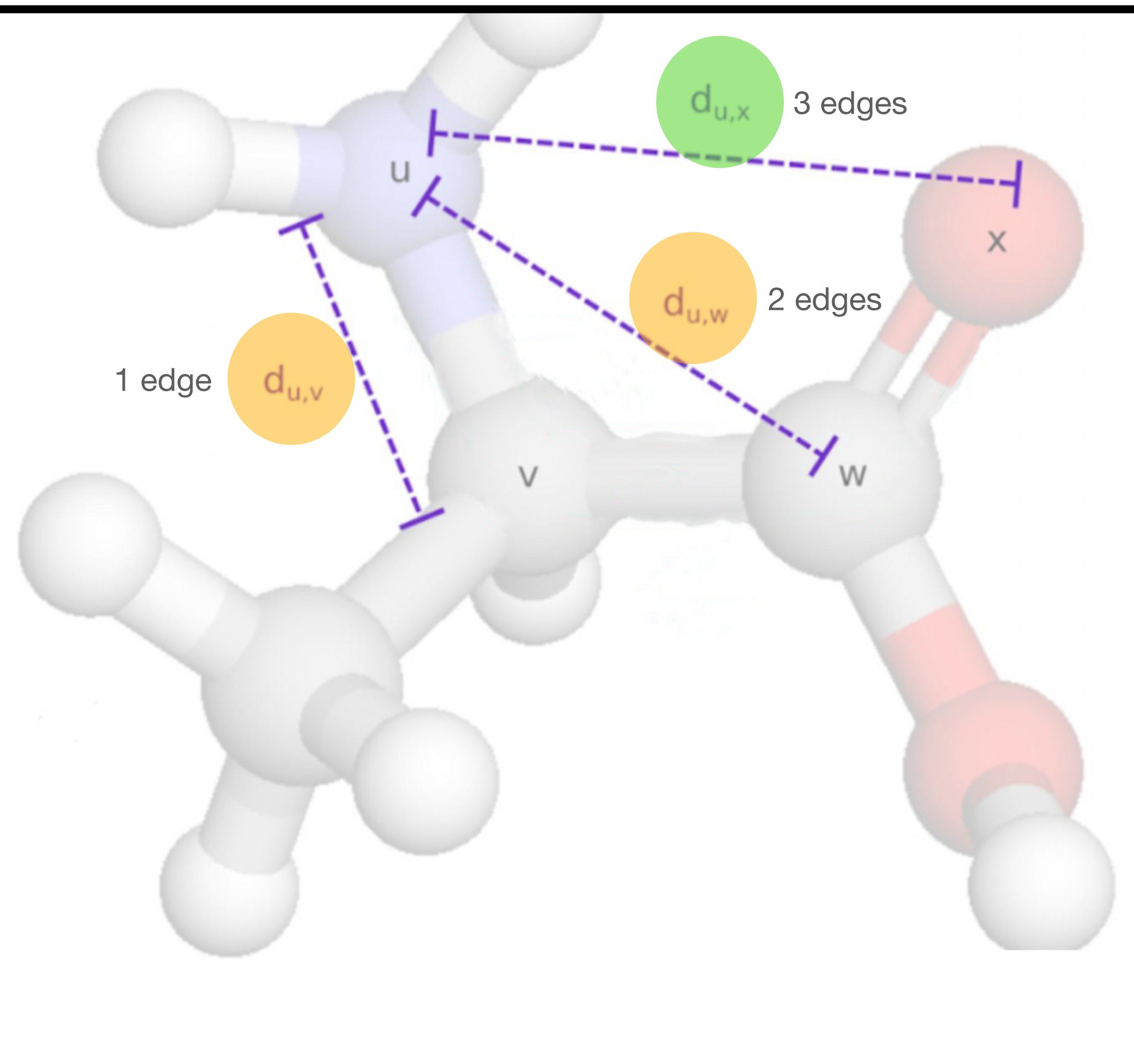
Realistic inter-atom distance changes



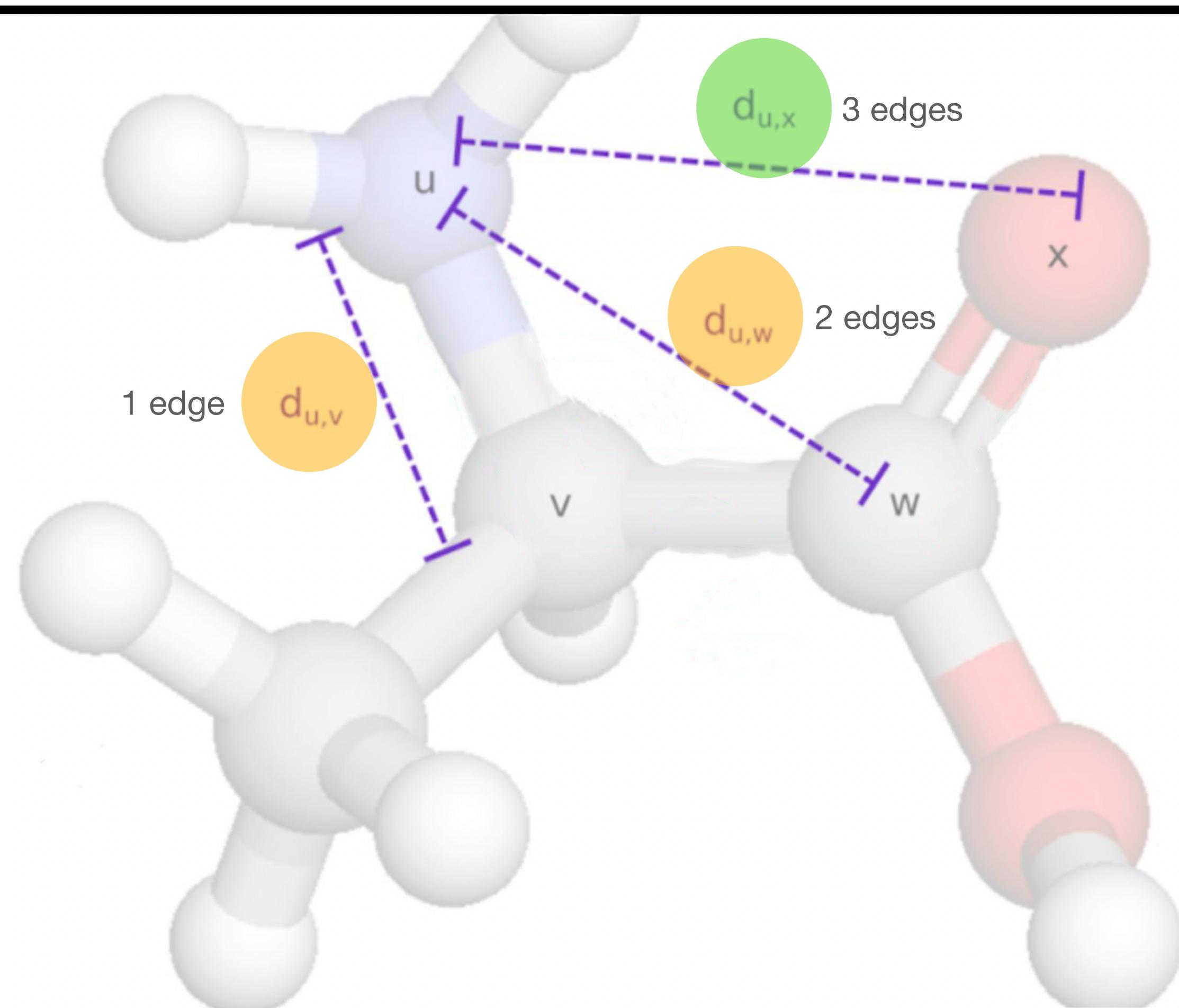
Realistic inter-atom distance changes



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Realistic inter-atom distance changes

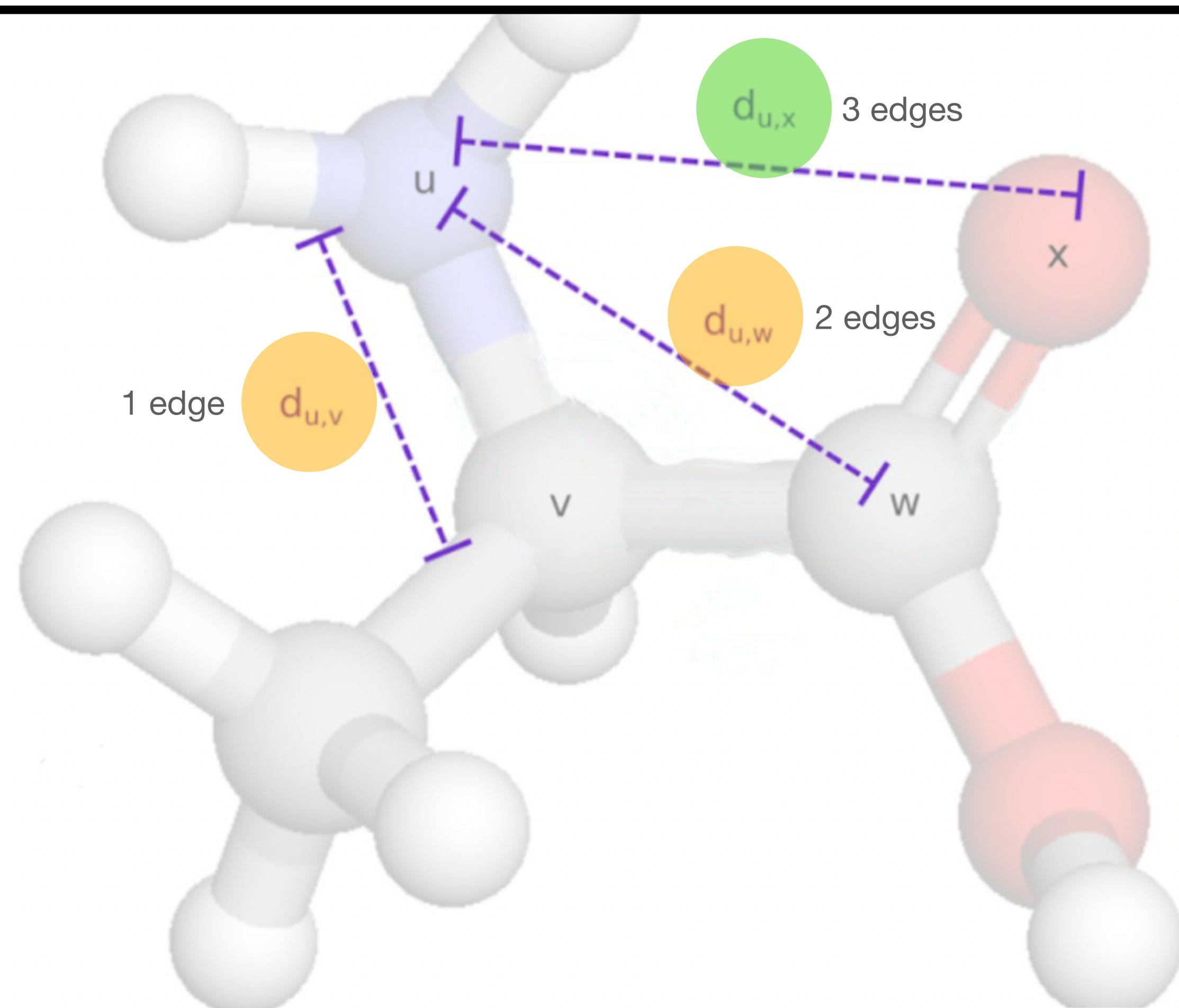


Z: transformed coordinates

X: original coordinates

$$\begin{aligned} S(\mathbf{Z}, \mathbf{X}) = & \sum_{\{(i,j) \in \mathcal{E}\}} (d_{\mathbf{X}}^2(i, j) - d_{\mathbf{Z}}^2(i, j))^2 \\ & + \sum_{\{i, j: 2\text{-hops away in } \mathcal{G}\}} (d_{\mathbf{X}}^2(i, j) - d_{\mathbf{Z}}^2(i, j))^2 \end{aligned}$$

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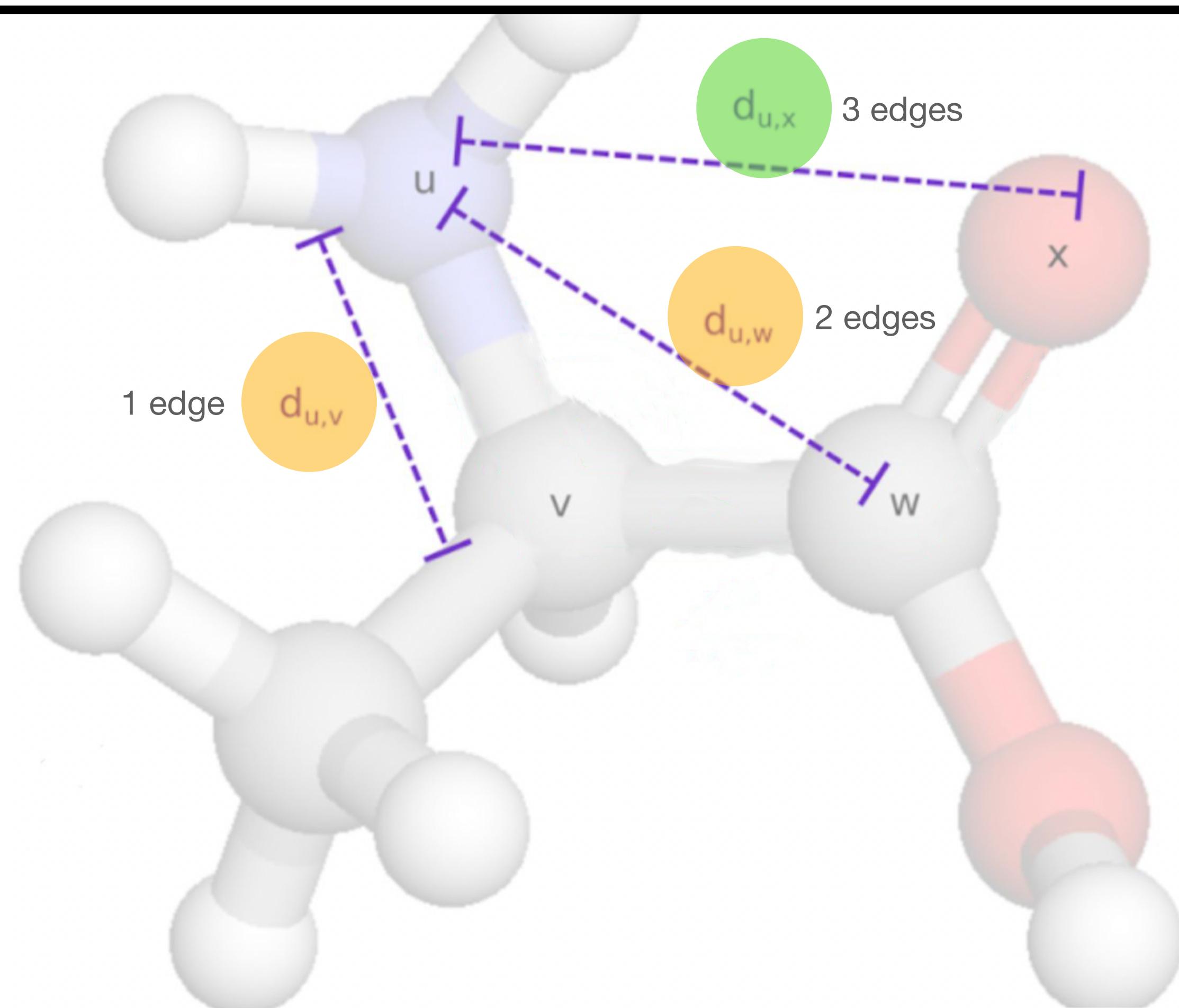


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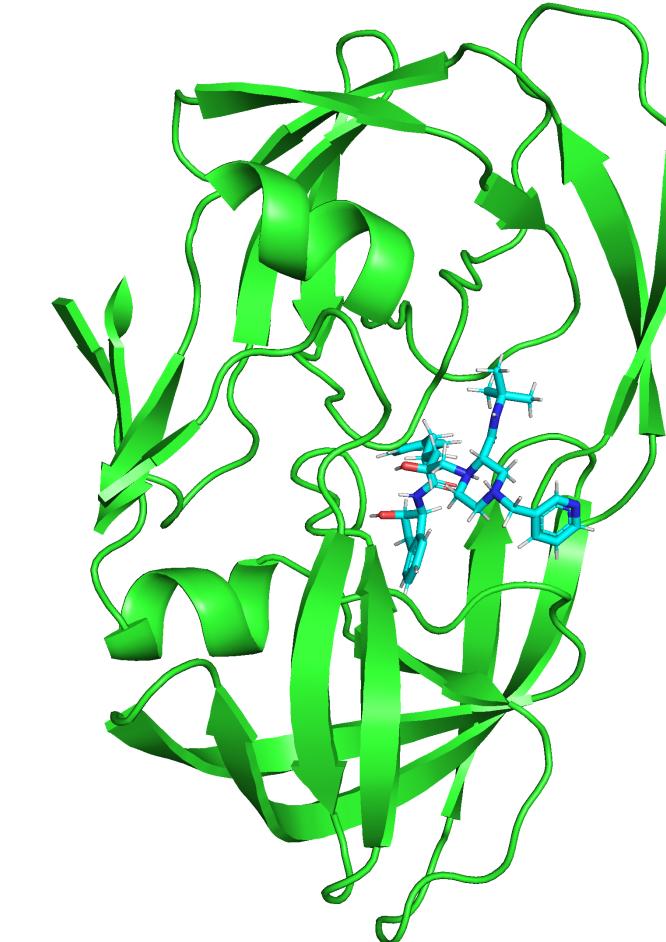
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Standard dataset PDDBBind

Experimentally determined structures of small molecules + proteins



Baselines: 4 commonly used tools

GNINA
(deep learning)

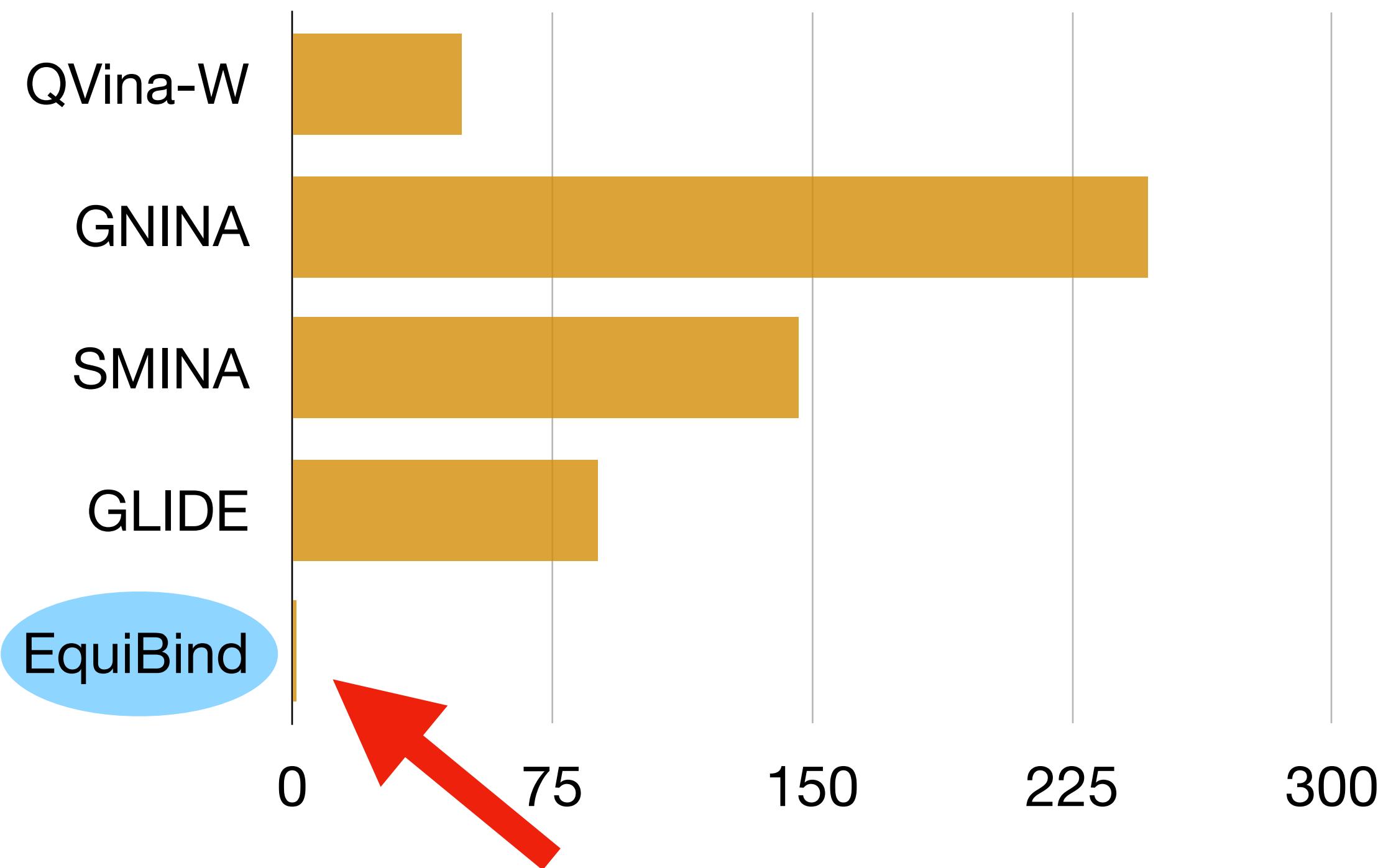
SMINA

QuickVina-W

GLIDE
(commercial)

Results

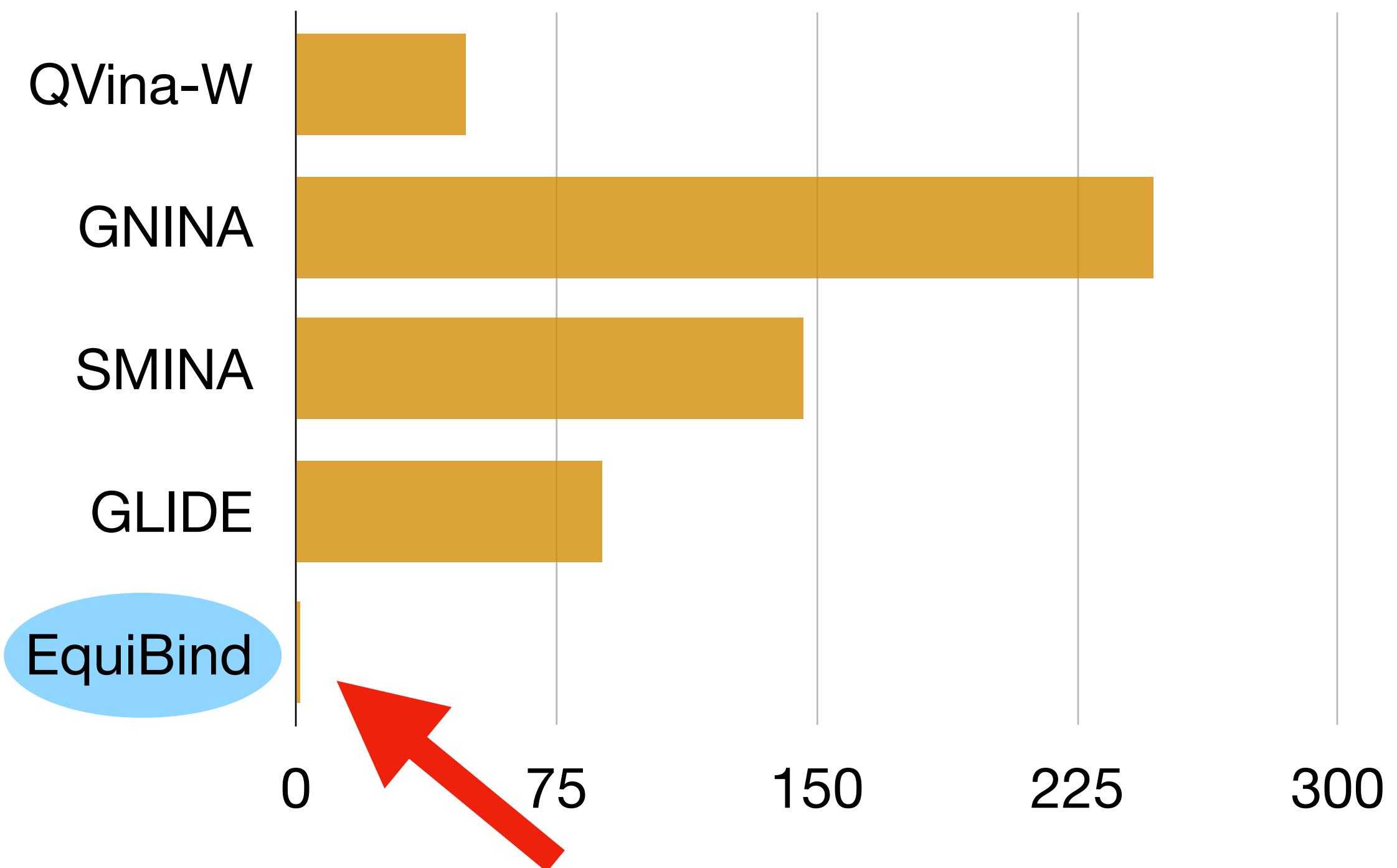
Average seconds for 1 complex with 16 CPUs



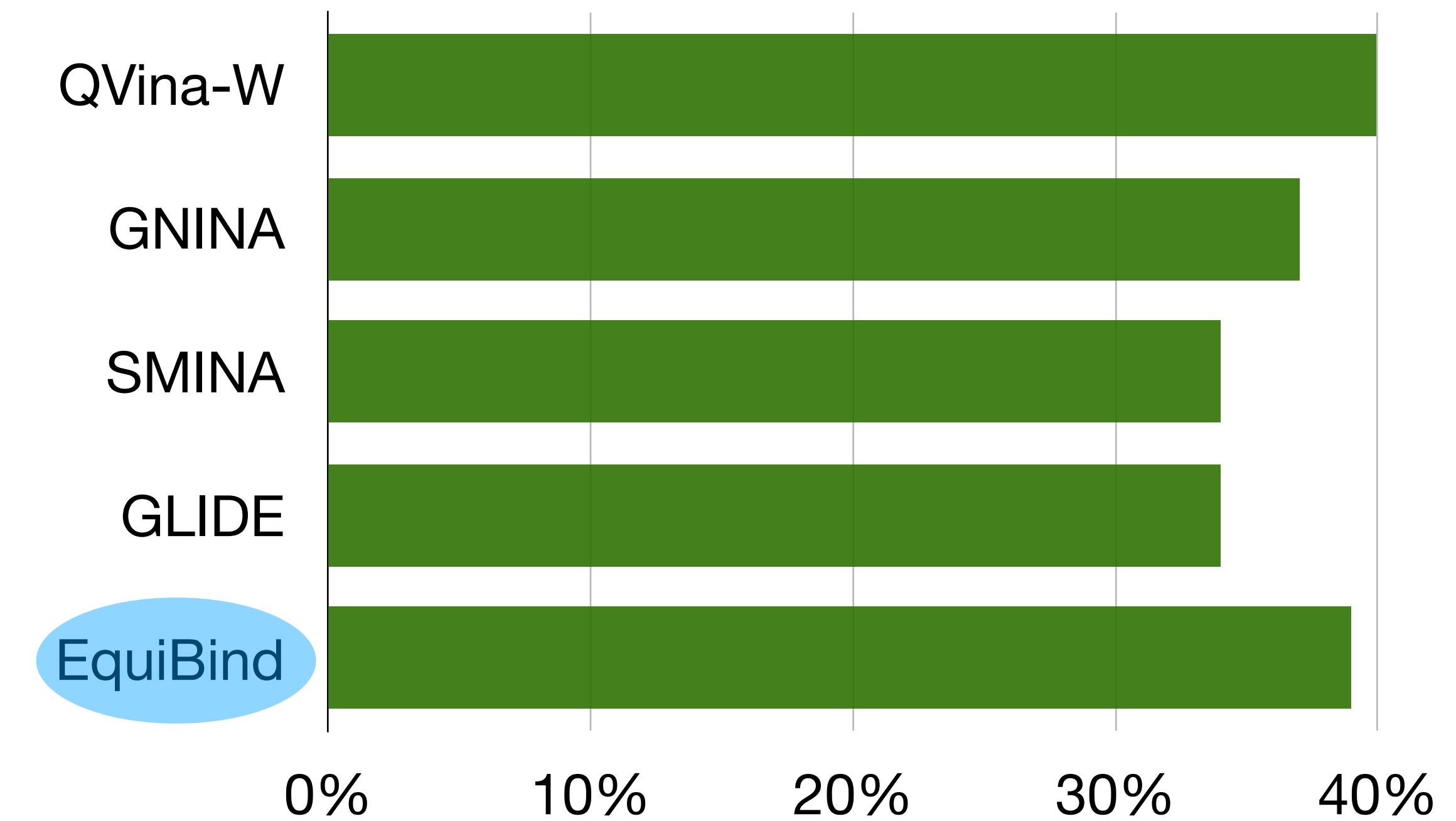
1200x speedup while retaining accuracy

Results

Average seconds for 1 complex with 16 CPUs



Fraction of test examples with RMSD less than 5Å



1200x speedup while retaining accuracy



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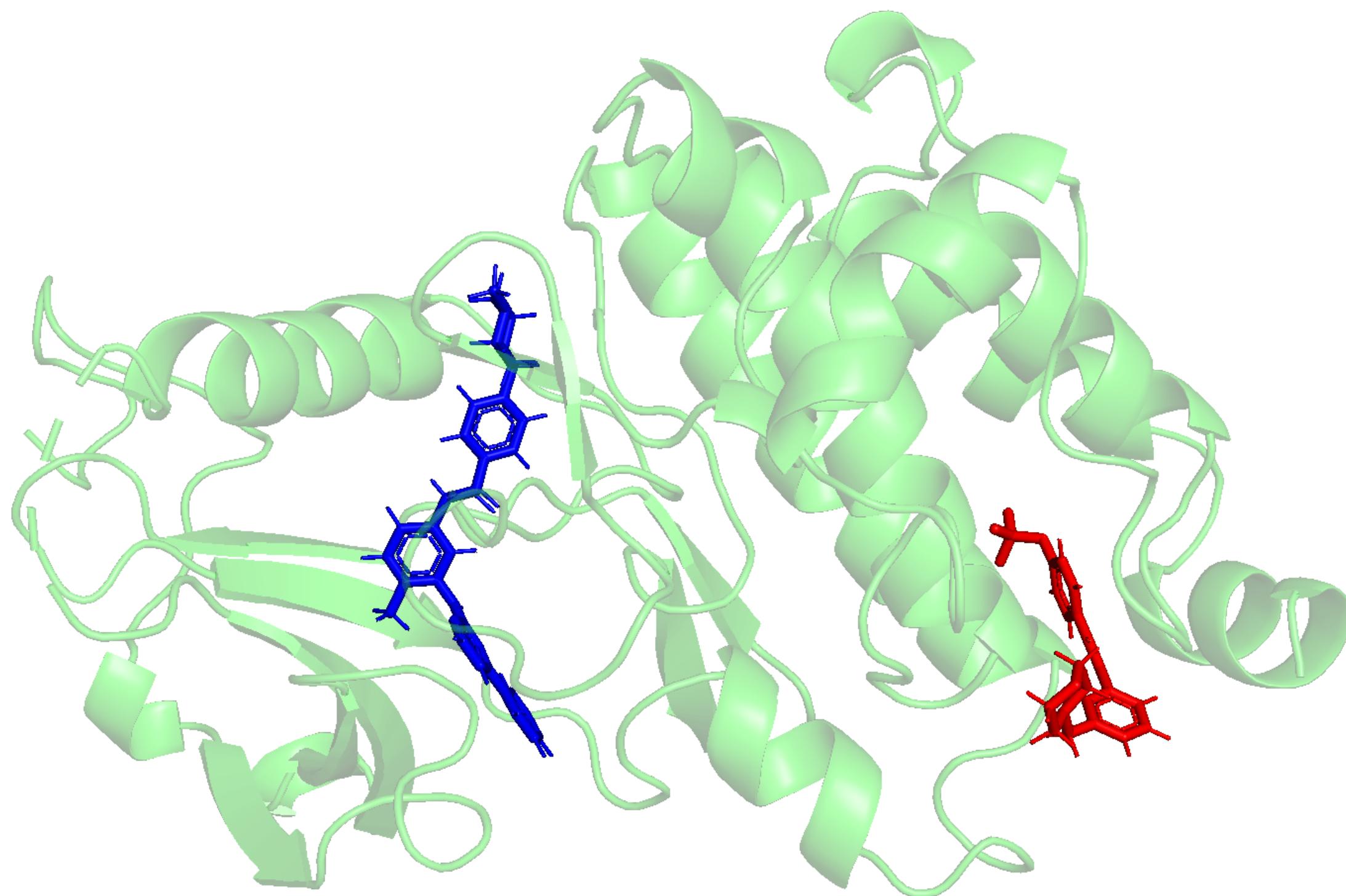
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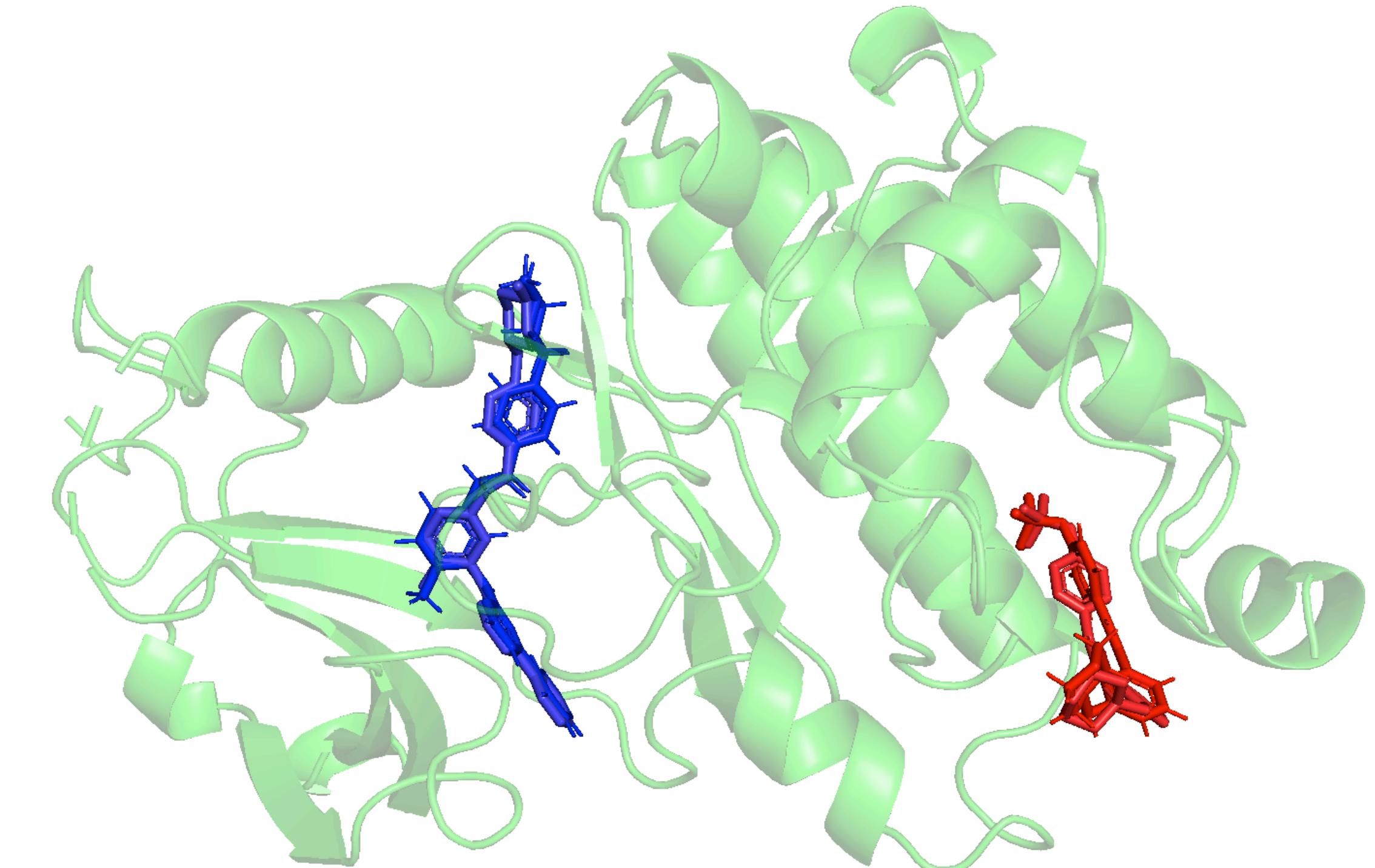
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Case Study

Ground Truth



EquiBind + S



Suggested from industry: ABL1 Tyrosine Kinase. Important leukemia drug target