

Benefits of Overparameterized Convolutional Residual Networks: Function Approximation under Smoothness Constraint

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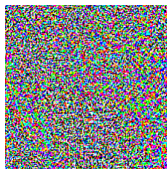
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Adversarial Robustness



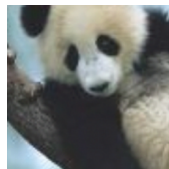
'Panda'

+ .007 ×



noise

=

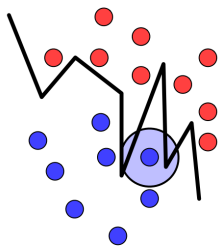


'Gibbon'

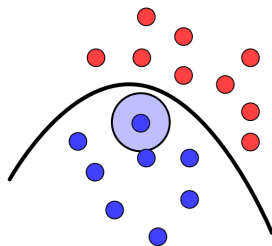
– Credit: Goodfellow et al. ICLR 2015.

Smoothness Ties to Robustness

- A close tie between **smoothness** and adversarial **robustness** [Gu & Rigazio, 2014; Madry et al., 2017; Miyato et al. 2018; Bubeck & Sellke, 2021].



Vulnerable



Robust

Overparameterization Promotes Smoothness

- Large neural networks favor smoothness and yield good robustness [Madry et al., 2017; Bubeck & Sellke, 2021].

Overparameterization Promotes Smoothness

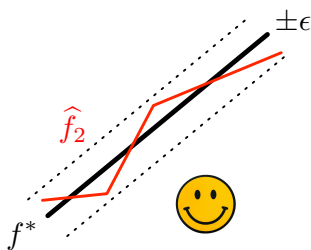
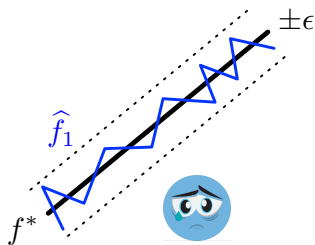
- Large neural networks favor smoothness and yield good robustness [Madry et al., 2017; Bubeck & Sellke, 2021].
- Theoretical explanation is still missing.

Contributions

- **Approximation theory** for *overparameterized* Convolutional Residual Networks, with smoothness guarantees.
- **Adversarial risk bound** of overparameterized Convolutional Residual Networks.
- Extension to low-dimensional manifold data; **no curse of ambient dimensionality**.

Function Approximation Perspective

- Function value approximation [Yarotsky 2017; Suzuki 2019; Zhou 2020; Peterson & Voigtlaender 2020; Oono & Suzuki 2019; Liu et al. 2021].
- Smoothness of approximation [Hornik et al., 1990; Cardaliaguet & Euvrard, 1992; Gühring et al. 2020; Hon and Yang 2021]



Function Approximation with Smoothness Guarantees

Theorem

Width- \tilde{M} depth- \tilde{J} convolutional residual networks can approximate any Sobolev function $f \in W^{\alpha,p}((0,1)^D)$, i.e., there exists \tilde{f} with

$$\begin{aligned}\|\tilde{f} - f\|_{\infty} &\leq C(\tilde{M}\tilde{J})^{-\frac{\alpha-1}{D}} \quad \text{and} \\ \|\tilde{f}\|_{\text{Lip}} &\leq \|f\|_{\text{Lip}} + C\sqrt{D}(\tilde{M}\tilde{J})^{-\frac{\alpha-1}{D}}\end{aligned}$$

for some constant C depending on D, α, p .

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for some constant C depending on D, α, p .

- Increasing \tilde{M}, \tilde{J} amplifies approximation power.
- To achieve an ϵ L^{∞} -error, $\tilde{M}\tilde{J} = O(\epsilon^{-D/(\alpha-1)})$ (v.s. $O(\epsilon^{-D/\alpha})$).
- **Extension:** d -dimensional manifold, $\|\tilde{f} - f\|_{W^{1,\infty}} \leq C(\tilde{M}\tilde{J})^{-\frac{\alpha-1}{d}}$.

Adversarial Risk Bound

Adversarial risk

$$R(\tilde{f}, \delta) = \mathbb{E}_{(\mathbf{x}, y)} \left[\sup_{\mathbf{x}' \in B_\delta(\mathbf{x})} \ell(\tilde{f}(\mathbf{x}'), y) \right]$$

Corollary

Suppose there exists an optimal classifier $f^* \in W^{\alpha, p}((0, 1)^D)$. In the setup of the Theorem above, convolutional residual network gives rise to \tilde{f} with

$$R(\tilde{f}, \delta) \leq \underbrace{R(\tilde{f}, 0)}_{\text{Clean Risk}} + \underbrace{\|\ell\|_{\text{Lip}} \left(\|f^*\|_{\text{Lip}} + C\sqrt{D}(\tilde{M}\tilde{J})^{\frac{\alpha-1}{D}} \right)}_{\text{Smoothness of } \tilde{f}} \delta.$$

Thank You