

# Efficient Distributionally Robust Bayesian Optimization with Worst-case Sensitivity

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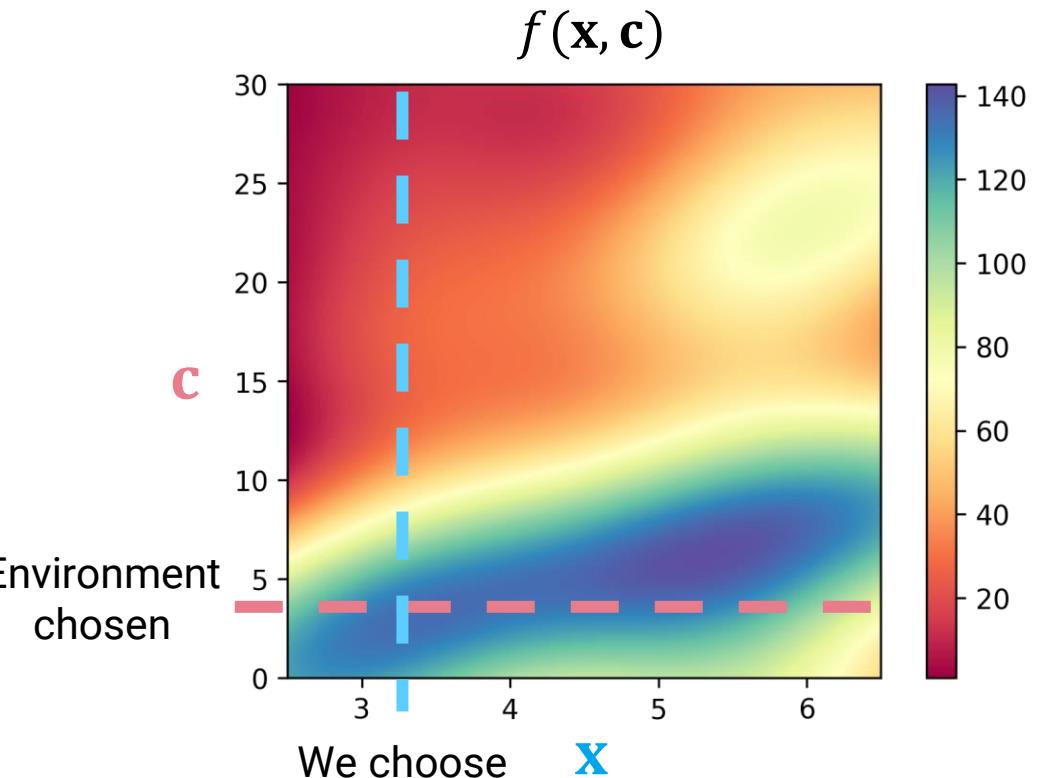
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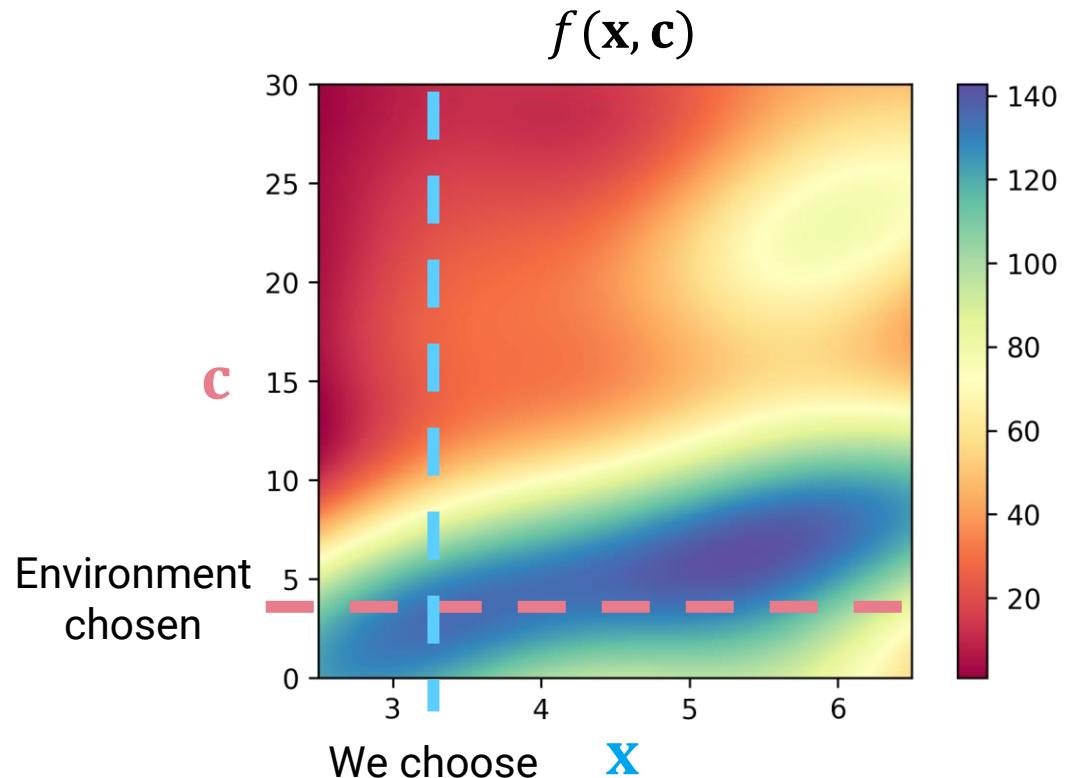
# Motivation

- We have a **decision variable  $x$**  (within our control, e.g., crop nutrients) and a **context variable  $c$**  (uncontrollable, e.g., amount of sunlight in a day).



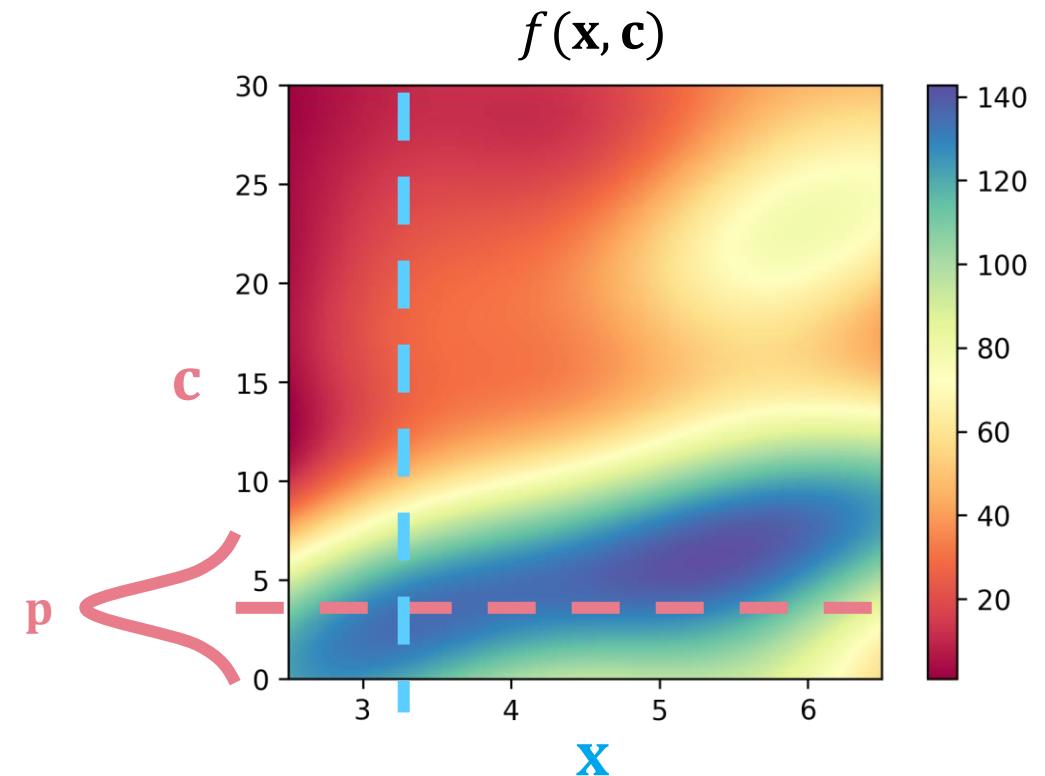
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- We desire large  $f(x, c)$  (e.g., final size of crop).  $f$  is **unknown** and **costly to evaluate** (in terms of time, money etc.).



# Stochastic BO

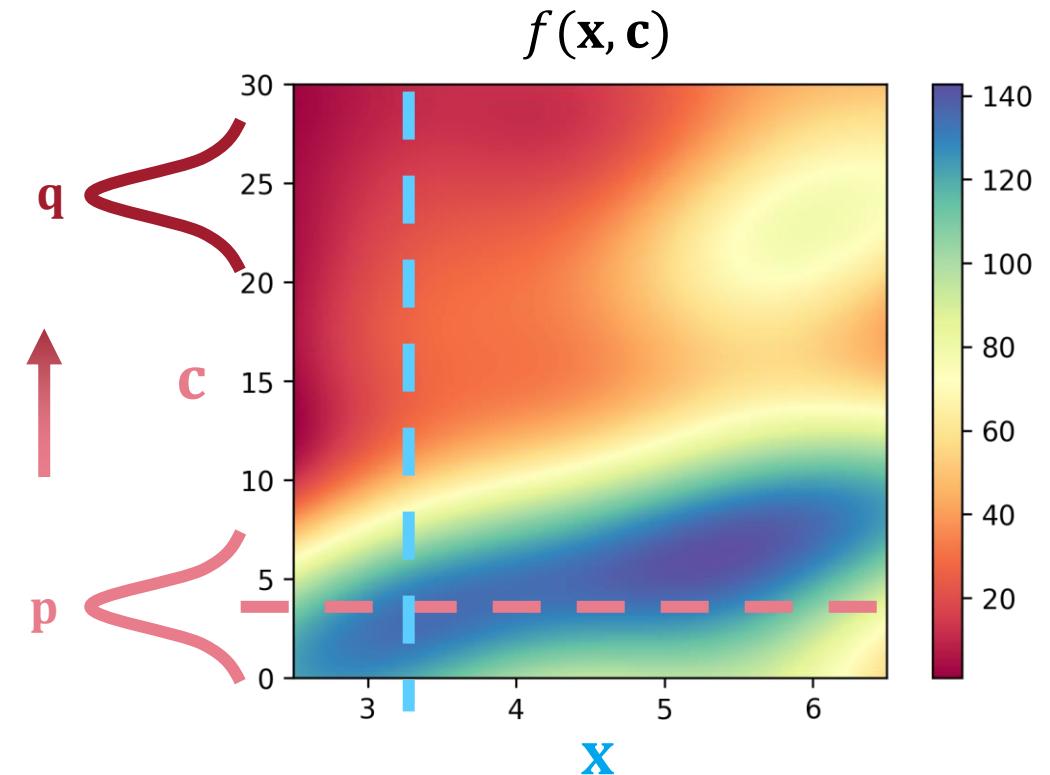
- The same idea applies if  $\mathbf{c}$  is a random vector distributed according to **known distribution  $p$** . We may then desire to maximize the expected value  $\mathbb{E}_{\mathbf{c} \sim p}[f(\mathbf{x}, \mathbf{c})]$ .



# Distributionally robust BO

- Suppose the environment is an adversary that is allowed to choose the true distribution among a set of distributions known as the uncertainty set  $\mathcal{U}$ :

$$\mathcal{U} := \{q' \mid d(p, q') \leq \epsilon\}$$

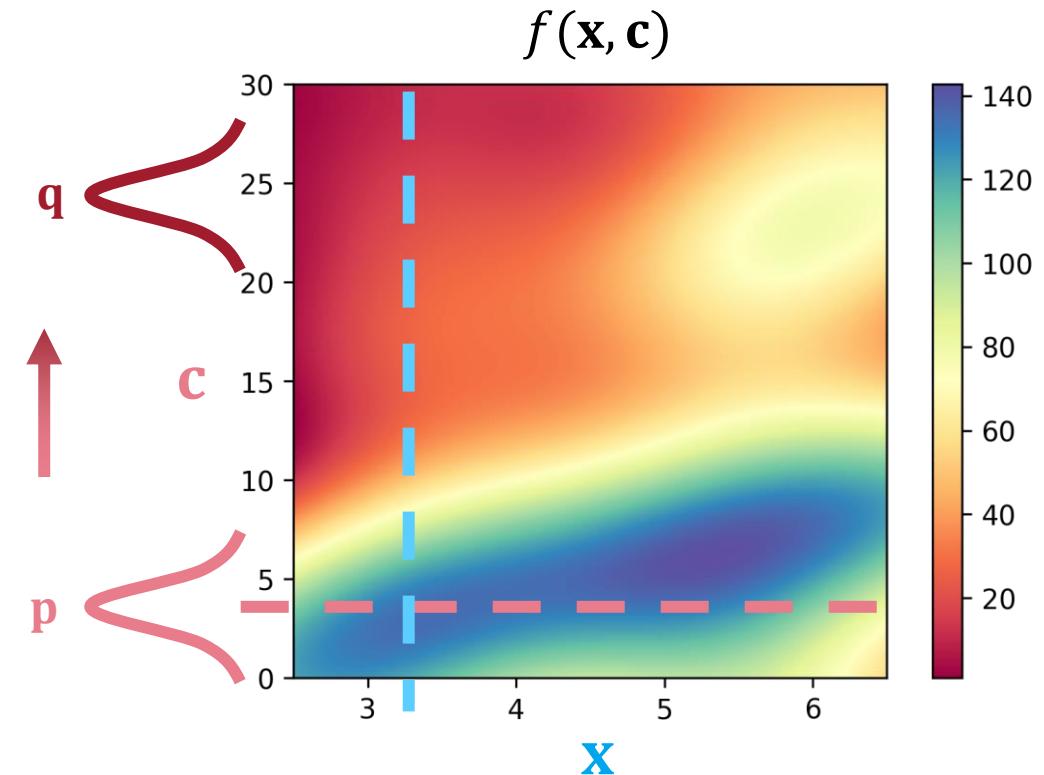


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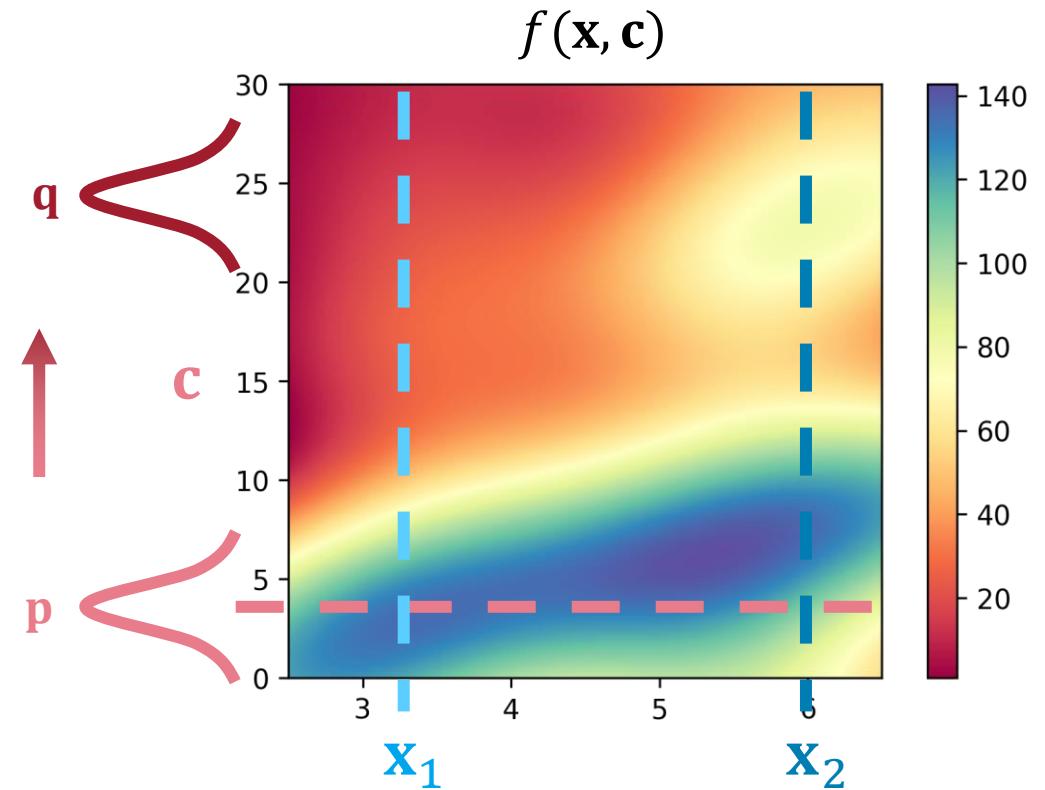
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- In the worst case, it chooses the distribution that minimizes our expected value, called the **worst-case distribution  $q$** .



# Distributionally robust BO

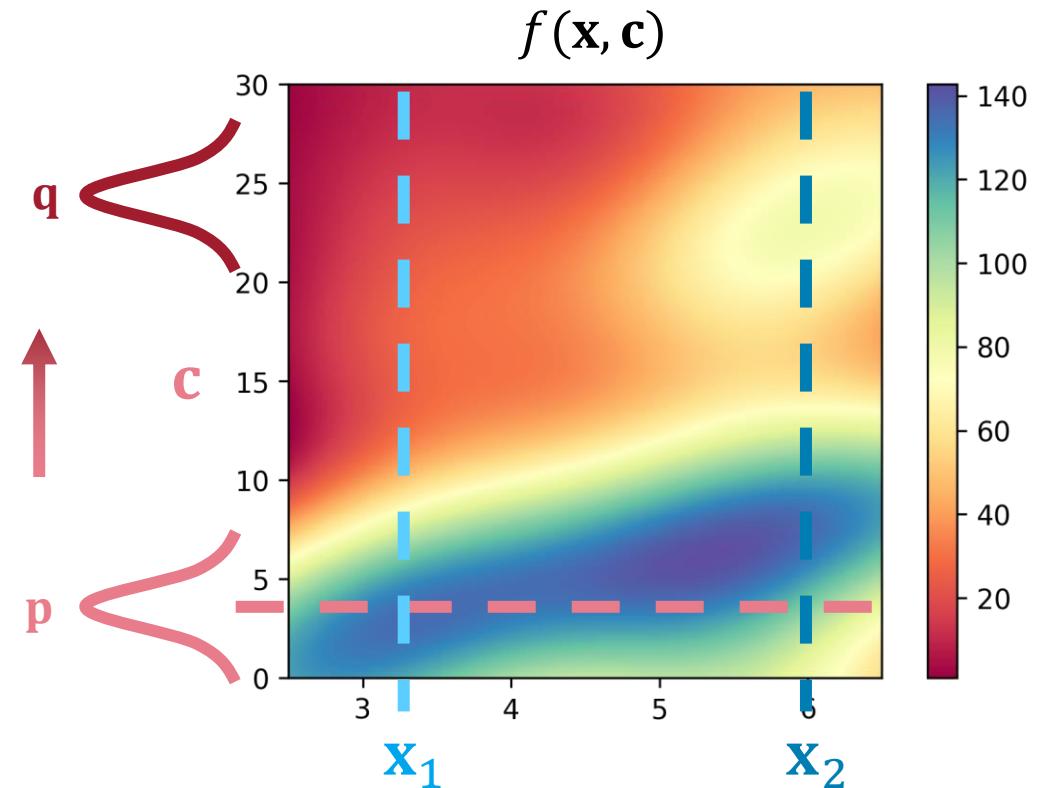
- $\mathbb{E}_{\mathbf{c} \sim \mathbf{p}}[f(\mathbf{x}_1, \mathbf{c})] > \mathbb{E}_{\mathbf{c} \sim \mathbf{p}}[f(\mathbf{x}_2, \mathbf{c})]$ , but  
 $\min_{\mathbf{q} \in \mathcal{U}} \mathbb{E}_{\mathbf{c} \sim \mathbf{q}}[f(\mathbf{x}_1, \mathbf{c})] < \min_{\mathbf{q} \in \mathcal{U}} \mathbb{E}_{\mathbf{c} \sim \mathbf{q}}[f(\mathbf{x}_2, \mathbf{c})]$ ,  
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- The learner is required to learn the optimal distributionally robust point

$$\mathbf{x}^* := \max_{\mathbf{x} \in \mathcal{X}} \min_{\mathbf{q} \in \mathcal{U}} \mathbb{E}_{\mathbf{c} \sim \mathbf{q}}[f(\mathbf{x}, \mathbf{c})].$$



# General algorithm

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**Algorithm 1** Generalized DRBO (Kirschner et al., 2020)

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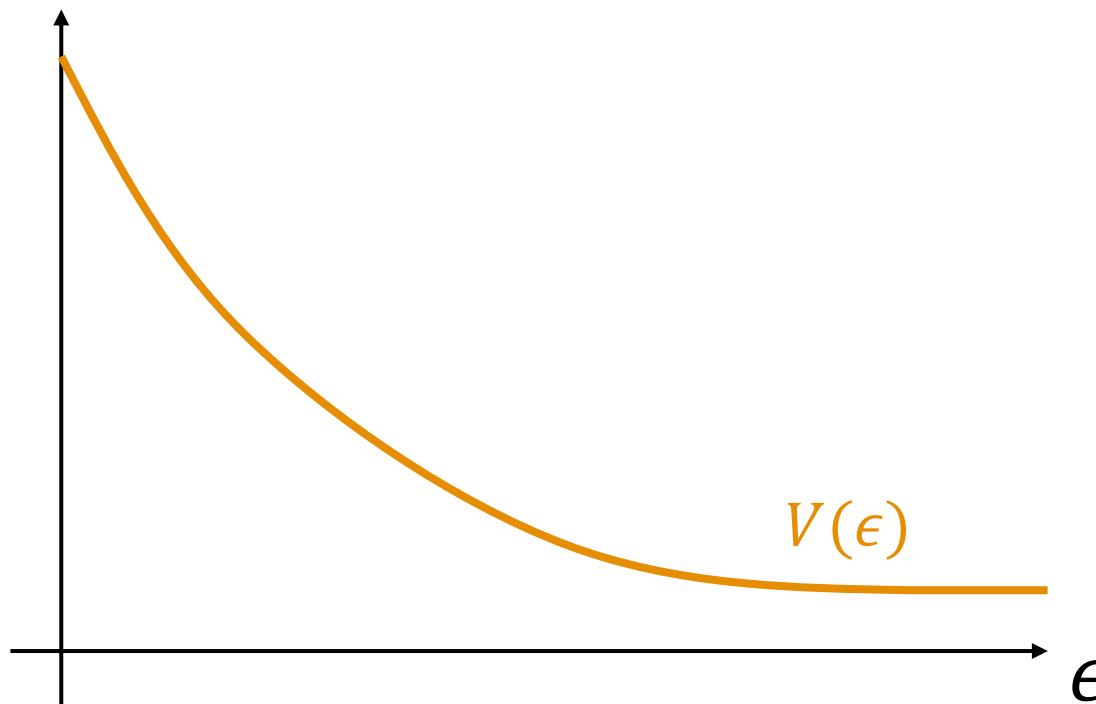
- 1: **Input:** GP with kernel  $k$ , score function  $\alpha$
- 2: **for** iteration  $t = 1$  **to**  $T$  **do**
- 3:   Obtain reference distribution  $p_t$  and margin  $\epsilon_t$
- 4:   Compute  $\text{ucb}_x^t := (\mu_t(x, \mathcal{C}_j) + \beta_t \sigma_t(x, \mathcal{C}_j))_{j=1, \dots, |\mathcal{C}|}^\top$
- 5:   Select action  $x_t = \text{argmax}_{x \in \mathcal{X}} \alpha(\text{ucb}_x^t, p_t, \epsilon_t)$
- 6:   Observe  $c_t \sim p_t^*$  and  $y_t = f(x_t, c_t) + \xi_t$
- 7:   Update GP posterior with  $\mathcal{D}_{t+1} := \{(x_i, c_i, y_i)\}_{i=1}^t$
- 8: **end for**

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- In Kirschner et al.<sup>1</sup>,  $\alpha = \min_{\mathbf{q} \in \mathcal{U}_t} \mathbb{E}_{\mathbf{c} \sim \mathbf{q}}[\text{ucb}^t(\mathbf{x}, \mathbf{c})]$  which requires solving a convex optimization problem with a discretized context set  $\mathcal{C}$
- Solving general convex optimization problems with interior-point methods incurs  $\mathcal{O}(|\mathcal{C}|^3)$  time. Scales poorly with  $|\mathcal{C}|$

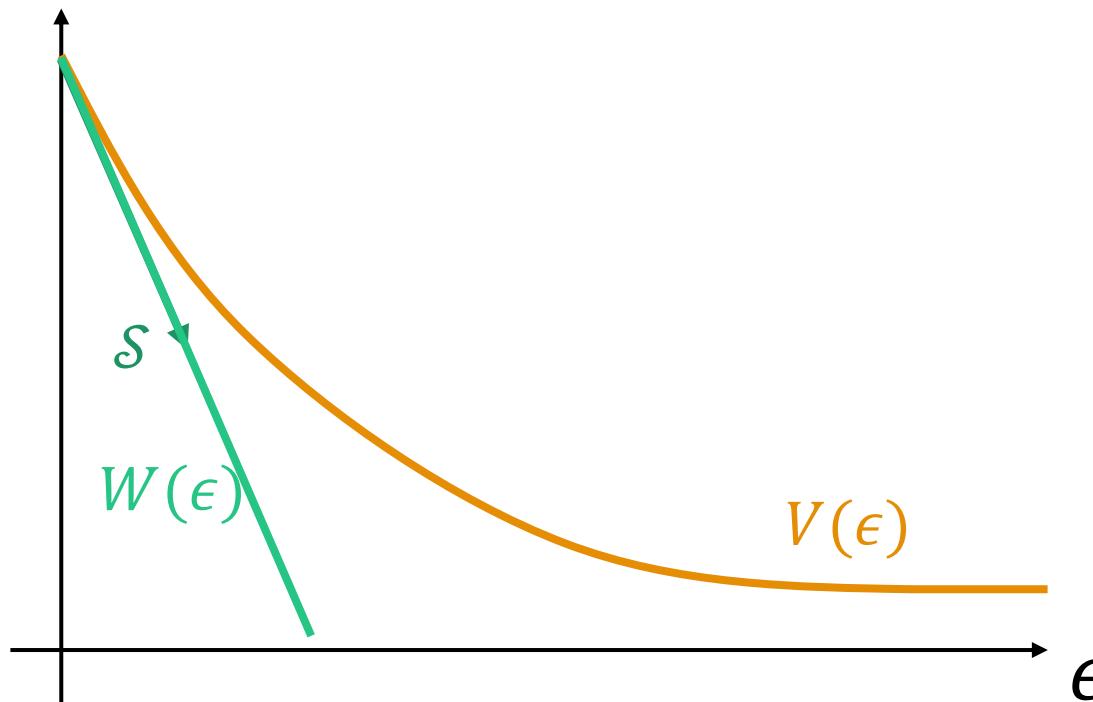
<sup>1</sup> Kirschner, J., Bogunovic, I., Jegelka, S., & Krause, A. (2020, June). Distributionally robust Bayesian optimization. In *International Conference on Artificial Intelligence and Statistics* (pp. 2174-2184). PMLR.

# Approximating the convex opt. solution



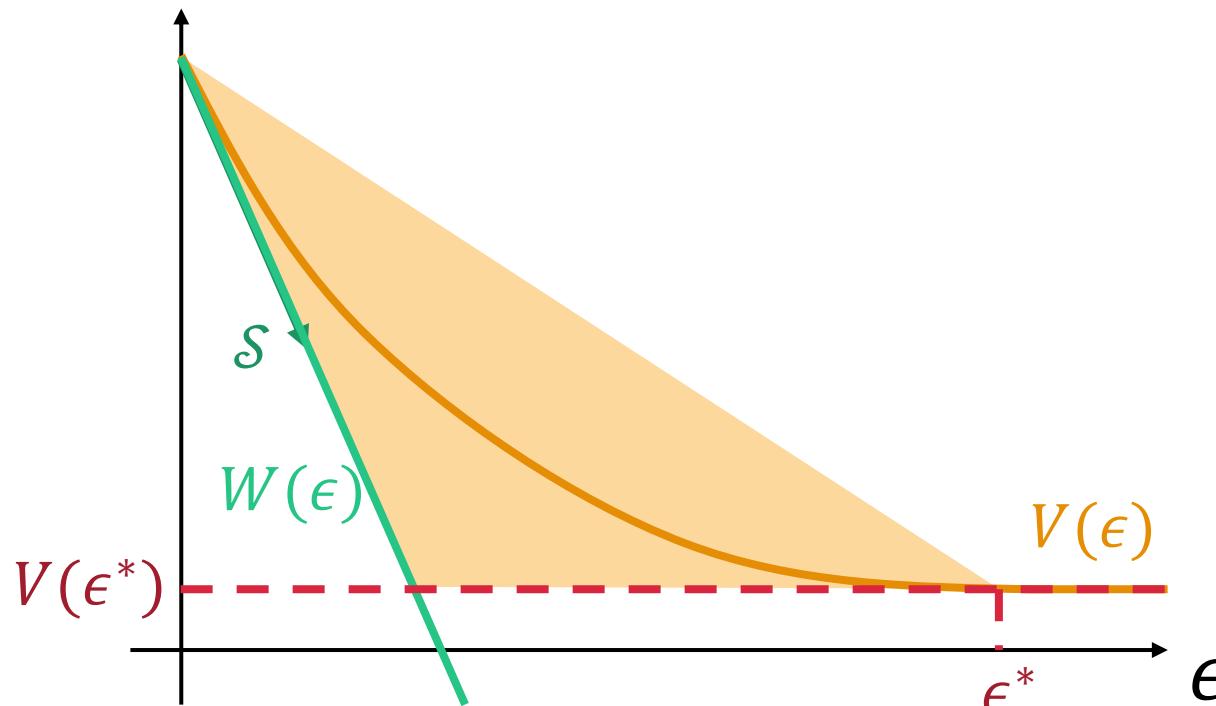
- Define the **worst-case expected value**  $V(\epsilon) := \min_{\mathbf{q} \in \mathcal{U}} \mathbb{E}_{\mathbf{c} \sim \mathbf{q}}[\text{ucb}(\mathbf{x}, \mathbf{c})]$ .
- $V(\epsilon)$  is convex with respect to the margin  $\epsilon$  (size of the uncertainty set  $\mathcal{U}$ ) when  $d$  is convex

# Approximating the convex opt. solution



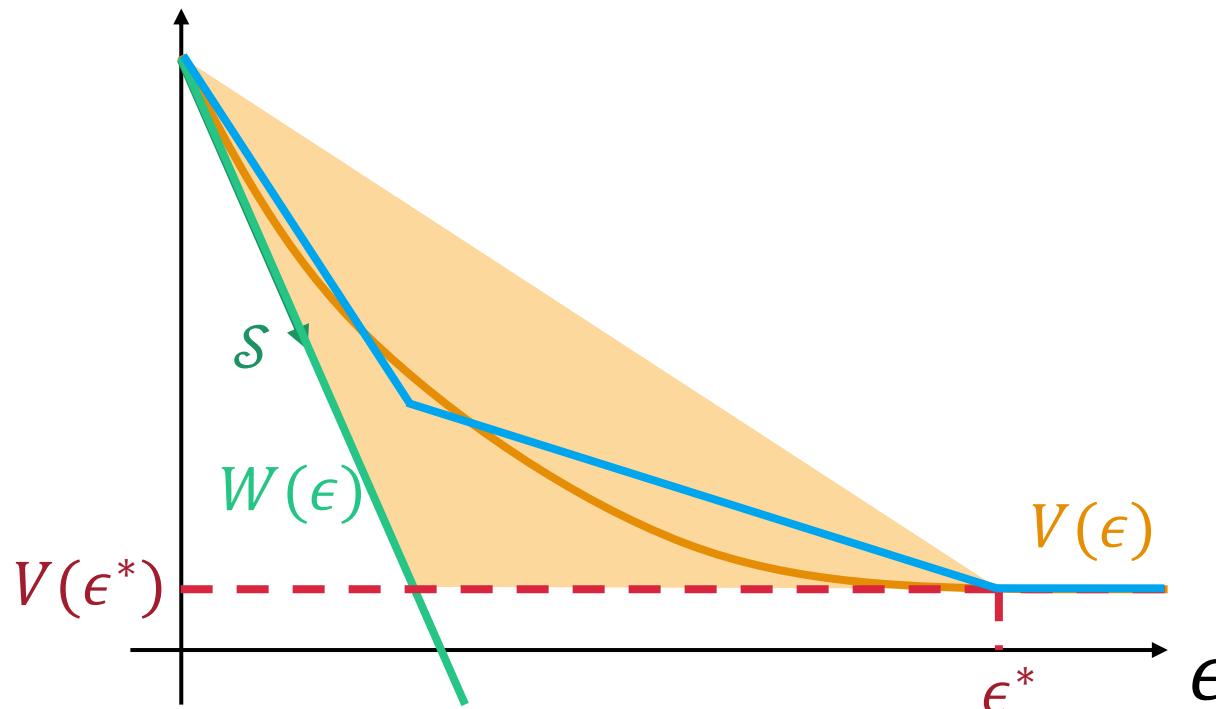
- Gotoh et al. (2020)<sup>1</sup> defined the **worst-case sensitivity**  $\mathcal{S}$  as the gradient of  $V(\epsilon)$  as  $\epsilon \rightarrow 0$ , and derived closed forms of  $\mathcal{S}$  for many distribution distances.
- Since  $V(\epsilon)$  is convex, we can lower bound  $V(\epsilon)$  with its linear approximation around  $\epsilon = 0$  with the function  $W(\epsilon)$  constructed using  $\mathcal{S}$ .

# Approximating the convex opt. solution



- However, the approximation  $W(\epsilon)$  gets arbitrarily worse as  $\epsilon$  increases. We can refine it further by computing (cheaply)  $\epsilon^*$  and  $V(\epsilon^*)$  (worst possible value of  $V(\epsilon)$ ). By the convexity of  $V(\epsilon)$ , we can then upper and lower bound  $V(\epsilon)$  into a region termed the **valid region**.

# Approximating the convex opt. solution



- Our approximation titled **MinimaxApprox** is then a piece-wise linear bisection of the valid region. This minimizes the maximum possible approximation error incurred.

# Computational efficiency

Table 1. Comparing time complexity of DRBO algorithms utilizing the **EXACT** worst-case expected value (Kirschner et al., 2020) vs. our fast approximation called **MINIMAXAPPROX** with various distribution distances  $d$ . The **EXACT** worst-case expected value is obtained by solving a general convex optimization problem with  $|\mathcal{C}|$  variables using interior point methods which, we assume, incur  $\mathcal{O}(|\mathcal{C}|^3)$  time.

Distribution distance $d$	<b>EXACT</b>	<b>MINIMAXAPPROX</b>
Maximum mean discrepancy (MMD)	$\mathcal{O}( \mathcal{C} ^3)$	$\mathcal{O}( \mathcal{C} ^2)$
Total variation (TV)	$\mathcal{O}( \mathcal{C} ^3)$	$\mathcal{O}( \mathcal{C} )$
Modified $\chi^2$ -divergence ( $\chi^2$ )	$\mathcal{O}( \mathcal{C} ^3)$	$\mathcal{O}( \mathcal{C} )$
Wasserstein metric ( $\mathcal{W}$ )	$\mathcal{O}( \mathcal{C} ^6)$	$\mathcal{O}( \mathcal{C} ^2)$

# Approximation quality

- Robust regret is bounded by

$$R_T \leq 4\beta_T \sqrt{T \left( \gamma_T + 4 \log \frac{12}{\delta} \right)} + \sum_{t=1}^T (2B'_{d,t} \epsilon_{d,t} + 2A_{d,t}^{\max})$$

- Scales linearly in  $T$ , however so does the robust regret of the previous work in the same setting. Our approximation does no worse than the exact solution in terms of dependence on  $T$ .
- Confirms intuition that better approximation ( $A_{d,t}^{\max}$ ) ultimately leads to better robust regret.

# Choice of distribution distance

- Worst-case sensitivity has interpretable meanings: for e.g., worst-case sensitivity when  $d$  is  $\chi^2$ -divergence is the **variance** of outcome values  $g$ , while that when using total variation (TV) is the **range**.

# Choice of distribution distance

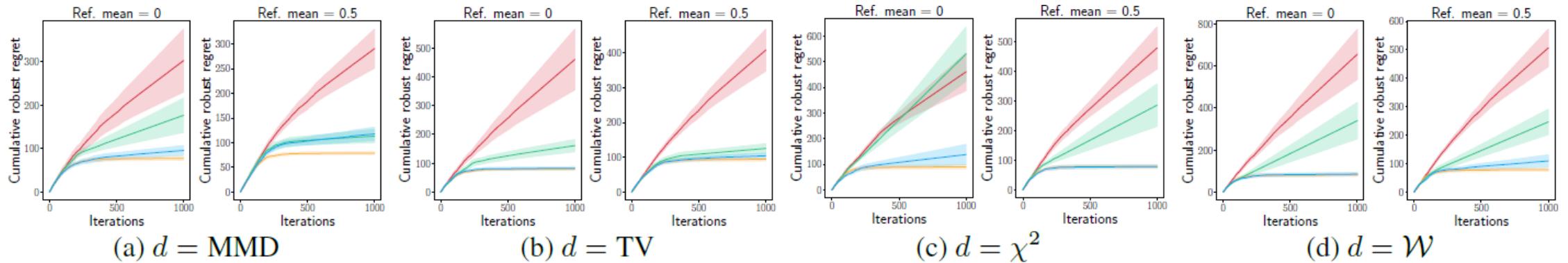
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- Denoting MinimaxApprox as  $\hat{V}$ , in some regimes of  $\epsilon$ ,  $\hat{V}$  can be re-written as a linear combination of the **expected value**, **worst-case sensitivity**, and the **worst value**. Presence of worst-case sensitivity term provides interpretability and guides choice of  $d$ .

$$\hat{V}_d(\epsilon_d, g) = \left(1 - \frac{\epsilon_d}{2\epsilon_d^*}\right) \underbrace{\mathbb{E}_p[g]}_{\text{Expected value}} + \frac{\epsilon_d}{2} \underbrace{\mathcal{S}_d(g)}_{\text{Worst-case sensitivity}} + \frac{\epsilon_d}{2\epsilon_d^*} \underbrace{\min_i[g]_i}_{\text{Worst value}}$$

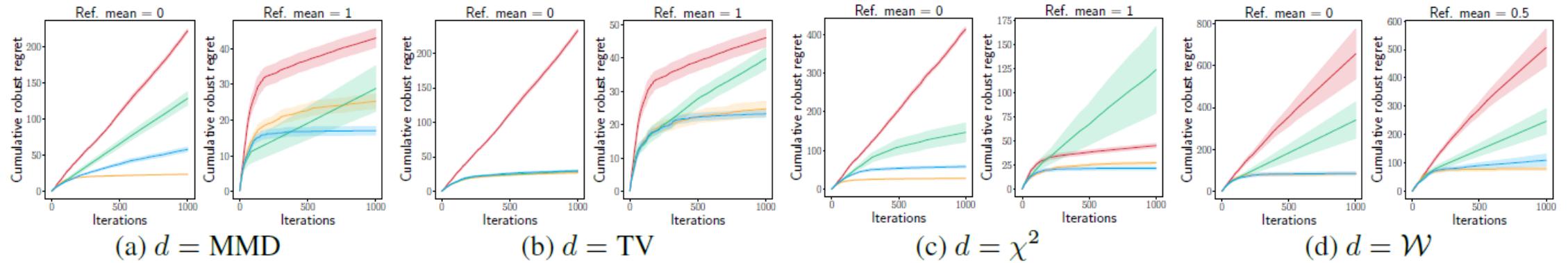
# Experiments: Robust regret

Comparing the robust regret of **stochastic GP-UCB**,  **$W$** , **Exact** (previous work) and **MinimaxApprox** (ours)

Synthetic random functions:



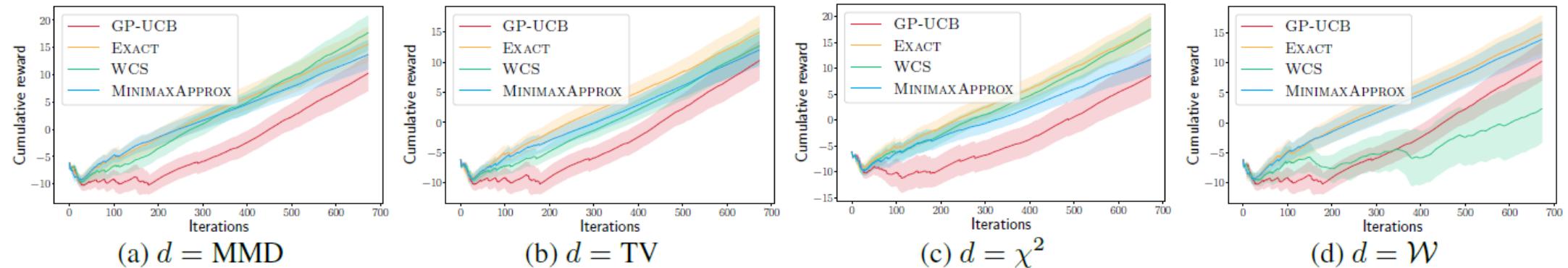
Plant maximum leaf area:



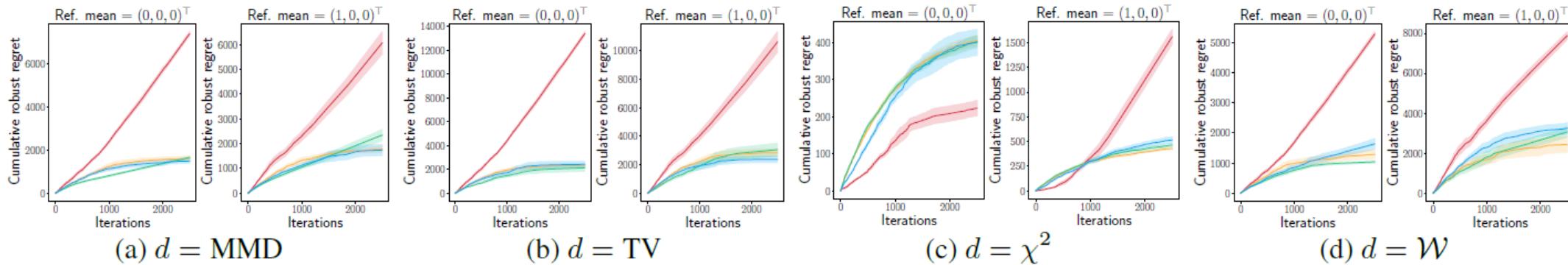
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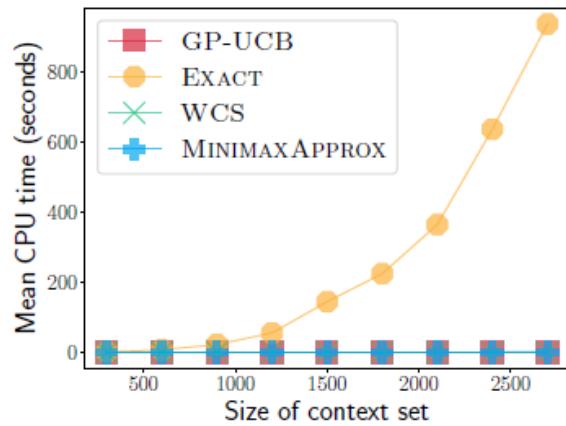
Wind power dataset:



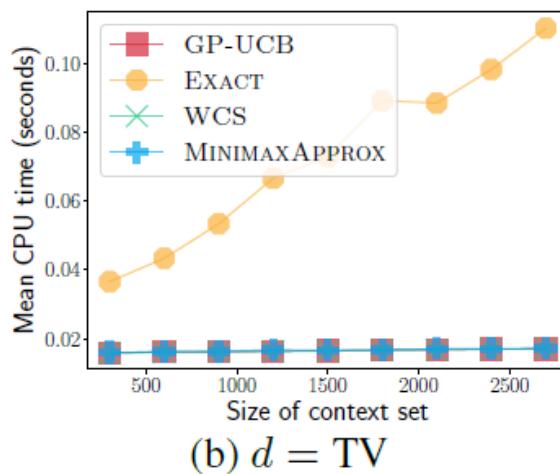
COVID-19 test allocation:



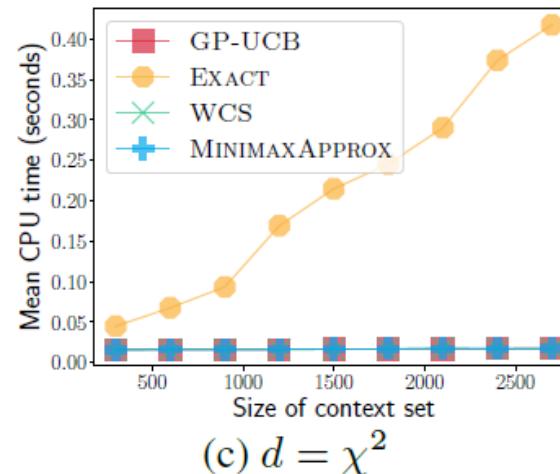
# Experiments: Computation time



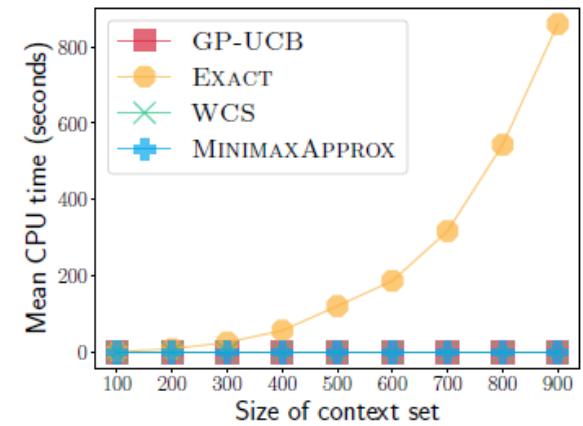
(a)  $d = \text{MMD}$



(b)  $d = \text{TV}$

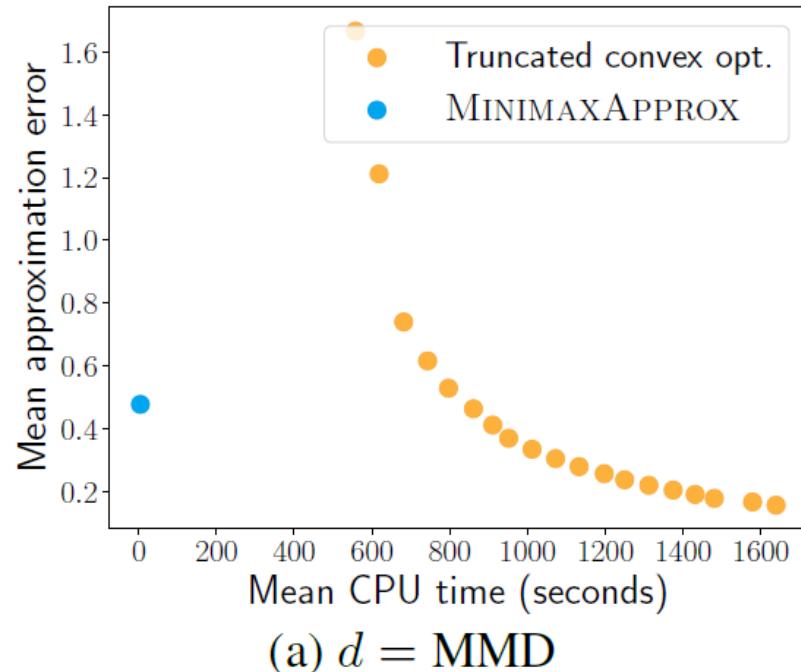


(c)  $d = \chi^2$

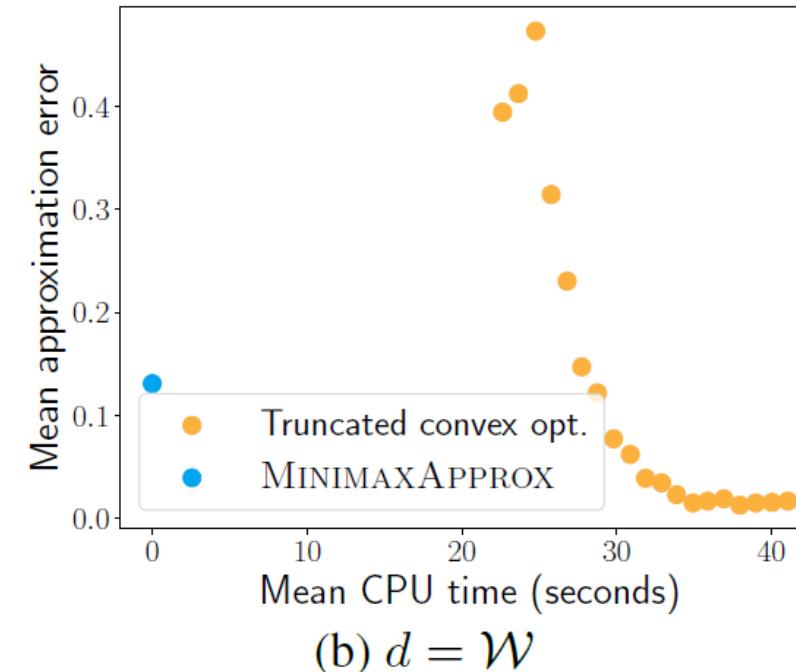


(d)  $d = \mathcal{W}$

# Experiments: Error-time trade-off



(a)  $d = \text{MMD}$



(b)  $d = \mathcal{W}$

# || Summary

- Distributionally robust Bayesian optimization (DRBO) is a novel setting for Bayesian optimization (BO) with stochastic context variables.

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- We borrow a concept from the distributionally robust optimization (DRO) literature known as **worst-case sensitivity** to formulate a fast algorithm.
  - Theoretical bounds
  - Empirically competitive with the previous method<sup>1</sup> while incurring **significantly less computation time**

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  - Theoretical bounds
  - Empirically competitive with the previous method<sup>1</sup> while incurring **significantly less computation time**
- To guide the choice of distribution distance in DRBO (model selection problem), we show that our approximation implicitly optimizes an objective close to an **interpretable risk-sensitive value**.

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# Thank You