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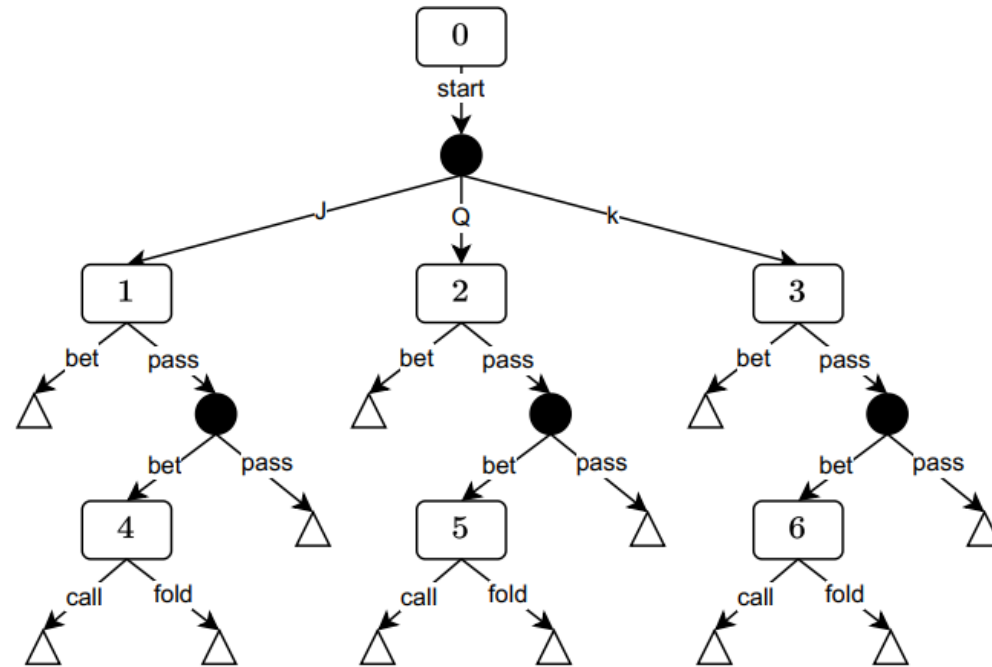
# Equivalence Analysis between Counterfactual Regret Minimization and Online Mirror Descent

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# Introduction

- Extensive-Form Games (**EFGs**)
  - $\Rightarrow$  Sequential Decision Process



Decision process in Kuhn poker

# Introduction

- Extensive-Form Games (**EFGs**)
  - $\Rightarrow$  Sequential Decision Process
- **Algorithms:**
  - Counterfactual Regret Minimization (**CFR**) (Zinkevich et al., 2007)
  - Follow-the-Regularized-Leader (**FTRL**) (Abernethy et al., 2008)
  - Online Mirror Descent (**OMD**) (Beck & Teboulle, 2003)
  - Excessive Gap Technique (Hoda et al., 2010; Kroer et al., 2020), ...
- Target:
  - Converge to a Nash Equilibrium
  - $\Rightarrow$  Exploitability to zero

# Introduction

- Inconsistency between theory and practice
- Theory:
  - CFR+ (Tammelin et al., 2015):  $O(1/\sqrt{T})$
  - Optimistic OMD (O-OMD) (Farina et al., 2019):  $O(1/T)$

# Introduction

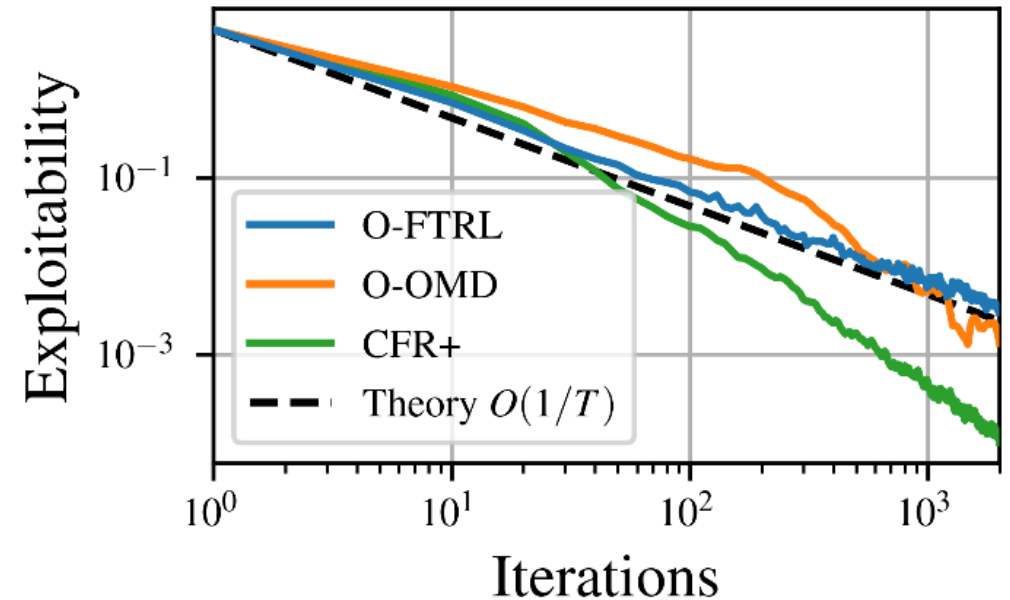
- Inconsistency between theory and practice

- Theory:

- CFR+ (Tammelin et al., 2015):  $O(1/\sqrt{T})$
- Optimistic OMD (O-OMD) (Farina et al., 2019):  $O(1/T)$

- Practice:

- CFR+ (**green line**) is much **faster**.



# Introduction

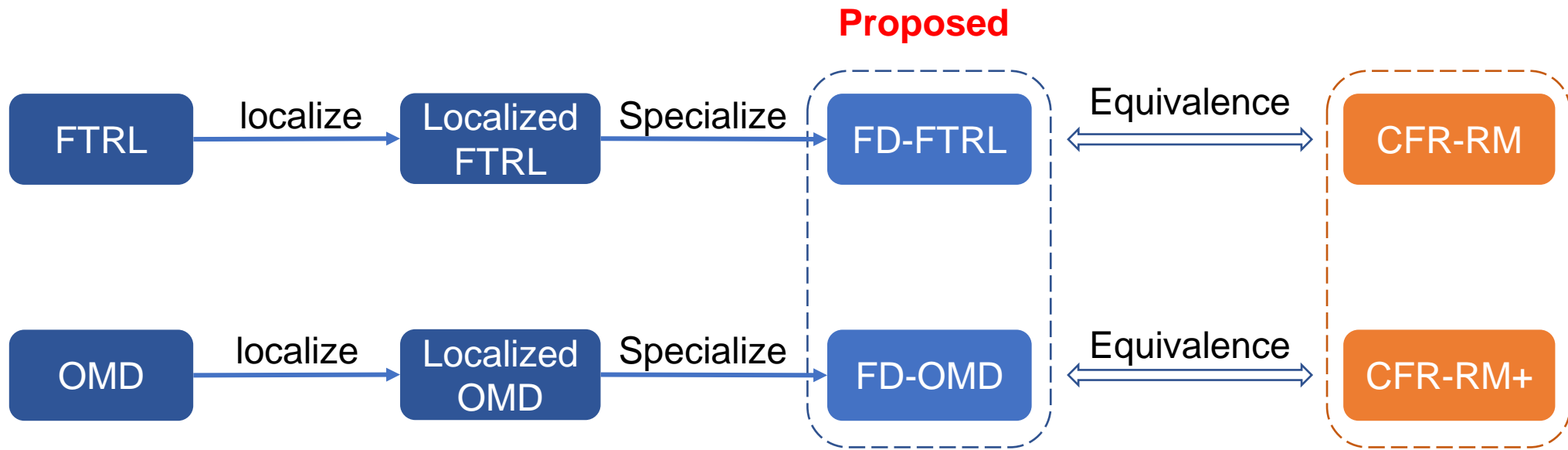
- Questions:

- How to explain the superior performance of CFR?
- How to improve the practical performance of FTRL (OMD)?
- **Are there strong connections between CFR and FTRL (OMD)?**

- Contributions:

- Prove that CFR-RM (CFR-RM+) is equivalent to a special FTRL (OMD)
- Propose a special OMD, which is **faster** than CFR+ in some EFGs.

# Equivalence Analysis: Overview



# Equivalence Analysis: Localization

- Localization (Hoda et al., 2010; Farina et al., 2019b)

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## Algorithm 1 FTRL

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```
1: for iteration  $t = 1$  to  $T$  do  
2:    $l^t \leftarrow \text{ObserveLoss}(\mathbf{x}^t)$ .  
3:    $\mathbf{x}^{t+1} \leftarrow \operatorname{argmin}_{\mathbf{x} \in \mathcal{X}} \{ \langle \mathbf{L}^t, \mathbf{x} \rangle + q^{0:t}(\mathbf{x}) \}$ .  
4: end for
```

Compute the strategy as a whole



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## Algorithm 3 Localized (FD-)FTRL

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```
1: for iteration  $t = 1$  to  $T$  do  
2:    $l^t \leftarrow \text{ObserveLoss}(\mathbf{x}^t)$ .  
3:   for node  $j \in \mathcal{J}$  in bottom-up order do  
4:      $\hat{\mathbf{L}}_j^{t,t}[a] \leftarrow \mathbf{L}^t[j, a] + \sum_{j' \in C_{j,a}} -\psi_{j'}^{*t}(-\hat{\mathbf{L}}_{j'}^{t,t})$ .  
5:      $\hat{\mathbf{x}}_j^{t+1} \leftarrow \nabla \psi_j^{*t}(-\hat{\mathbf{L}}_j^{t,t})$ .  
6:   end for  
7:   Construct  $\mathbf{x}^{t+1}$ .  
8: end for
```

Recursively compute local decisions



# Equivalence Analysis: Localization

- Localization (Hoda et al., 2010; Farina et al., 2019b)
  - $\psi$  is the regularizer, e.g.,  $l_2$  norm function

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## Algorithm 3 Localized (FD-)FTRL

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- 1: **for** iteration  $t = 1$  to  $T$  **do**
- 2:    $l^t \leftarrow \text{ObserveLoss}(\mathbf{x}^t)$ .
- 3:   **for** node  $j \in \mathcal{J}$  in bottom-up order **do**
- 4:      $\hat{\mathbf{L}}_j^{t'}[a] \leftarrow \mathbf{L}^t[j, a] + \sum_{j' \in C_{j,a}} -\psi_{j'}^{*t}(-\hat{\mathbf{L}}_{j'}^{t'})$ .
- 5:      $\hat{\mathbf{x}}_j^{t+1} \leftarrow \nabla \psi_j^{*t}(-\hat{\mathbf{L}}_j^{t'})$ .
- 6:   **end for**
- 7:   Construct  $\mathbf{x}^{t+1}$
- 8: **end for**

**Convex conjugate:**

$$\psi_j^{*t}(\hat{\mathbf{g}}) = \max_{\hat{\mathbf{x}}_j \in \Delta^{n_j}} \{ \langle \hat{\mathbf{g}}, \hat{\mathbf{x}}_j \rangle - \psi_j^t(\hat{\mathbf{x}}_j) \}$$

$$\psi_j^t(\hat{\mathbf{x}}_j) = \frac{1}{2} \beta_j^t \|\hat{\mathbf{x}}_j\|_2^2$$

# Equivalence Analysis: Localization

- Localization (Hoda et al., 2010; Farina et al., 2019b)
  - $\psi$  is the regularizer, e.g.,  $l_2$  norm function
  - **Is there a regularizer such that FTRL can recover CFR-RM?**

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## Algorithm 3 Localized (FD-)FTRL

---

```

1: for iteration  $t = 1$  to  $T$  do
2:    $l^t \leftarrow \text{ObserveLoss}(\mathbf{x}^t)$ .
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6:   end for
7:   Construct  $\mathbf{x}^{t+1}$ 
8: end for
    
```

**Convex conjugate:**

$$\psi_j^{*t}(\hat{\mathbf{g}}) = \max_{\hat{\mathbf{x}}_j \in \Delta^{n_j}} \{ \langle \hat{\mathbf{g}}, \hat{\mathbf{x}}_j \rangle - \psi_j^t(\hat{\mathbf{x}}_j) \}$$

$$\psi_j^t(\hat{\mathbf{x}}_j) = \frac{1}{2} \beta_j^t \|\hat{\mathbf{x}}_j\|_2^2$$

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## Algorithm 2 CFR-RM

---

```

1: for iteration  $t = 1$  to  $T$  do
2:    $l^t \leftarrow \text{ObserveLoss}(\mathbf{x}^t)$ .
3:   for node  $j \in \mathcal{J}$  in bottom-up order do
4:      $\hat{\mathbf{l}}_j^t[a] \leftarrow l^t[j, a] + \sum_{j' \in C_{j,a}} \langle \hat{\mathbf{l}}_{j'}^t, \hat{\mathbf{x}}_{j'}^t \rangle$ .
5:      $\hat{\mathbf{R}}_j^t \leftarrow \hat{\mathbf{R}}_j^{t-1} + \langle \hat{\mathbf{l}}_j^t, \hat{\mathbf{x}}_j^t \rangle \mathbf{1} - \hat{\mathbf{l}}_j^t$ ,
6:      $\hat{\mathbf{x}}_j^{t+1} \leftarrow [\hat{\mathbf{R}}_j^t]^+ / \|[\hat{\mathbf{R}}_j^t]^+\|_1$ .
7:   end for
8:   Construct  $\mathbf{x}^{t+1}$ .
9: end for
    
```

} RM

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# Equivalence Analysis: Specialization

- Future-Dependent FTRL (FD-FTRL)
  - The regularizer is dependent on the next decision  $\hat{\mathbf{x}}_j^{t+1}$ .
  - **Note:** the next decision does not depend on itself.

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**Algorithm 3** Localized (FD-)FTRL

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```
1: for iteration  $t = 1$  to  $T$  do
2:    $l^t \leftarrow \text{ObserveLoss}(\mathbf{x}^t)$ .
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4:      $\hat{\mathbf{L}}_j^{t'}[a] \leftarrow \mathbf{L}^t[j, a] + \sum_{j' \in C_{j,a}} -\psi_{j'}^{*t}(-\hat{\mathbf{L}}_{j'}^{t'})$ .
5:      $\hat{\mathbf{x}}_j^{t+1} \leftarrow \nabla \psi_j^{*t}(-\hat{\mathbf{L}}_j^{t'})$ .
6:   end for
7:   Construct  $\mathbf{x}^{t+1}$ .
8: end for
```

$$\psi_j^t(\hat{\mathbf{x}}_j) = \frac{1}{2}\beta_j^t \|\hat{\mathbf{x}}_j\|_2^2 + \frac{1}{2}\beta_j^t \|\hat{\mathbf{x}}_j^{t+1}\|_2^2$$

# Equivalence Analysis: Theorem

- CFR-RM (CFR-RM+)  $\Leftrightarrow$  a special FD-FTRL (FD-OMD)
  - CFR-RM (CFR-RM+) is an **adaptive** FTRL (OMD).
  - FTRL(OMD) with adaptation could be faster.

**Theorem 3.7.** *CFR-RM (CFR-RM+) is equivalent to a special case of FD-FTRL (FD-OMD) with  $\beta_j^t = \|[\hat{\mathbf{R}}_j^t]^+\|_1$  ( $\|\hat{\mathbf{Q}}_j^t\|_1$ ),  $\forall j \in \mathcal{J}, t \geq 0$ .*

# Application: Adaptive FD-FTRL (FD-OMD)

- Reparametrized FD-FTRL (FD-OMD) with **adaptation**

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## Algorithm 3 Localized (FD-)FTRL

---

```
1: for iteration  $t = 1$  to  $T$  do
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```

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## Algorithm 4 Reparameterized FD-FTRL

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```
1: for iteration  $t = 1$  to  $T$  do
2:    $l^t \leftarrow \text{ObserveLoss}(\mathbf{x}^t)$ .
3:   for node  $j \in \mathcal{J}$  in bottom-up order do
4:      $\hat{\mathbf{L}}_j^{t}[a] \leftarrow \mathbf{L}^t[j, a] + \sum_{j' \in C_{j,a}} \alpha_{j'}^t$ .
5:      $\hat{\mathbf{R}}_j^{t} \leftarrow \alpha_j^t \mathbf{1} - \hat{\mathbf{L}}_j^{t}$ .
6:      $\hat{\mathbf{x}}_j^{t+1} \leftarrow [\hat{\mathbf{R}}_j^{t}]^+ / \|\mathbf{[\hat{R}}_j^{t}]^+\|_1$ .
7:   end for
8:   Construct  $\mathbf{x}^{t+1}$ .
9: end for
```

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# Application: Adaptive FD-FTRL (FD-OMD)

- Reparametrized FD-FTRL (FD-OMD) with **adaptation**
- Adapt the parameters like in CFR-RM (CFR-RM+)

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## Algorithm 3 Localized (FD-)FTRL

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```
1: for iteration  $t = 1$  to  $T$  do
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5:      $\hat{\mathbf{R}}_j^{t} \leftarrow \alpha_j^t \mathbf{1} - \hat{\mathbf{L}}_j^{t}$ .
6:      $\hat{\mathbf{x}}_j^{t+1} \leftarrow [\hat{\mathbf{R}}_j^{t}]^+ / \|\hat{\mathbf{R}}_j^{t}\|_1$ .
7:   end for
8:   Construct  $\mathbf{x}^{t+1}$ .
9: end for
```

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$$\|[\alpha_j^t \mathbf{1} - \hat{\mathbf{L}}_j^{t}]^+\|_2^2 = \lambda_j^t.$$

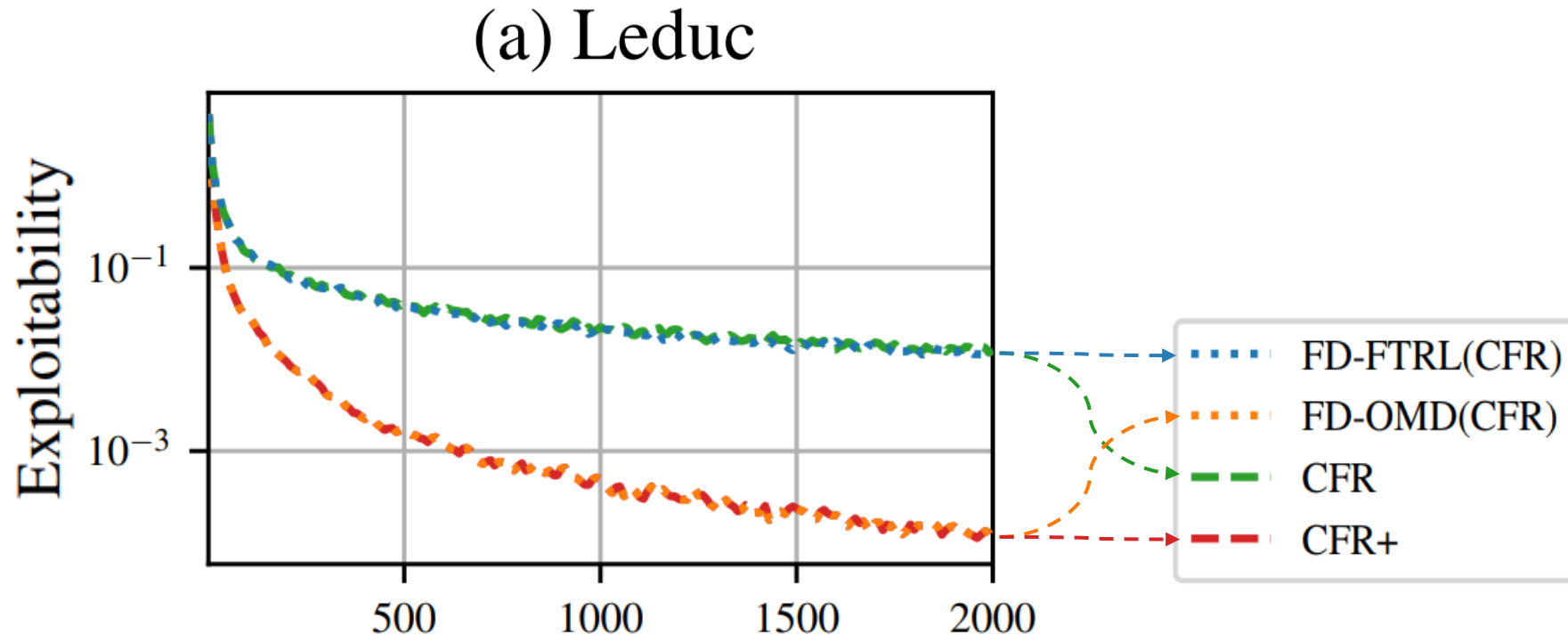
# Application: Convergence

- Let  $\lambda_j^t$  be lower bounded by the cumulative counterfactual regret
- FD-FTRL (FD-OMD) can converge at a rate of  $O(1/\sqrt{T})$

**Corollary 3.9.** *If  $\eta \sum_{k=1}^t \|\hat{\mathbf{r}}_j^k\|_2^2 \leq \lambda_j^t$  and  $\lambda_j^{t-1} \leq \lambda_j^t$ ,  $\forall j \in \mathcal{J}$ ,  $t > 0$ , then, the total regret of FD-FTRL( $R$ ) (FD-OMD( $R$ )) after  $T$  iterations is  $R^T \leq \sum_{j \in \mathcal{J}} \left( \sqrt{n_j} + \frac{1}{\eta} \right) \sqrt{\lambda_j^T}$ .*

# Results: Empirical equivalences

- FD-FTRL (FD-OMD) can recover CFR (CFR+)

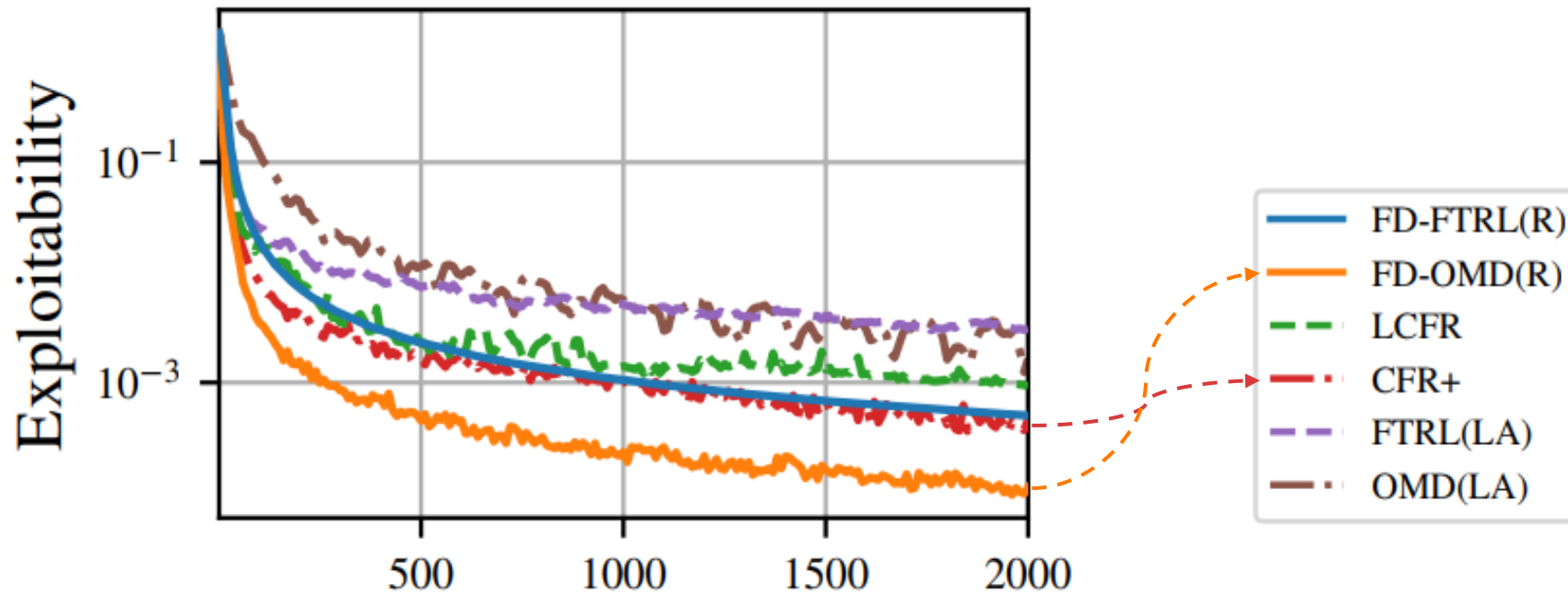




# Results: Adaptive FD-OMD

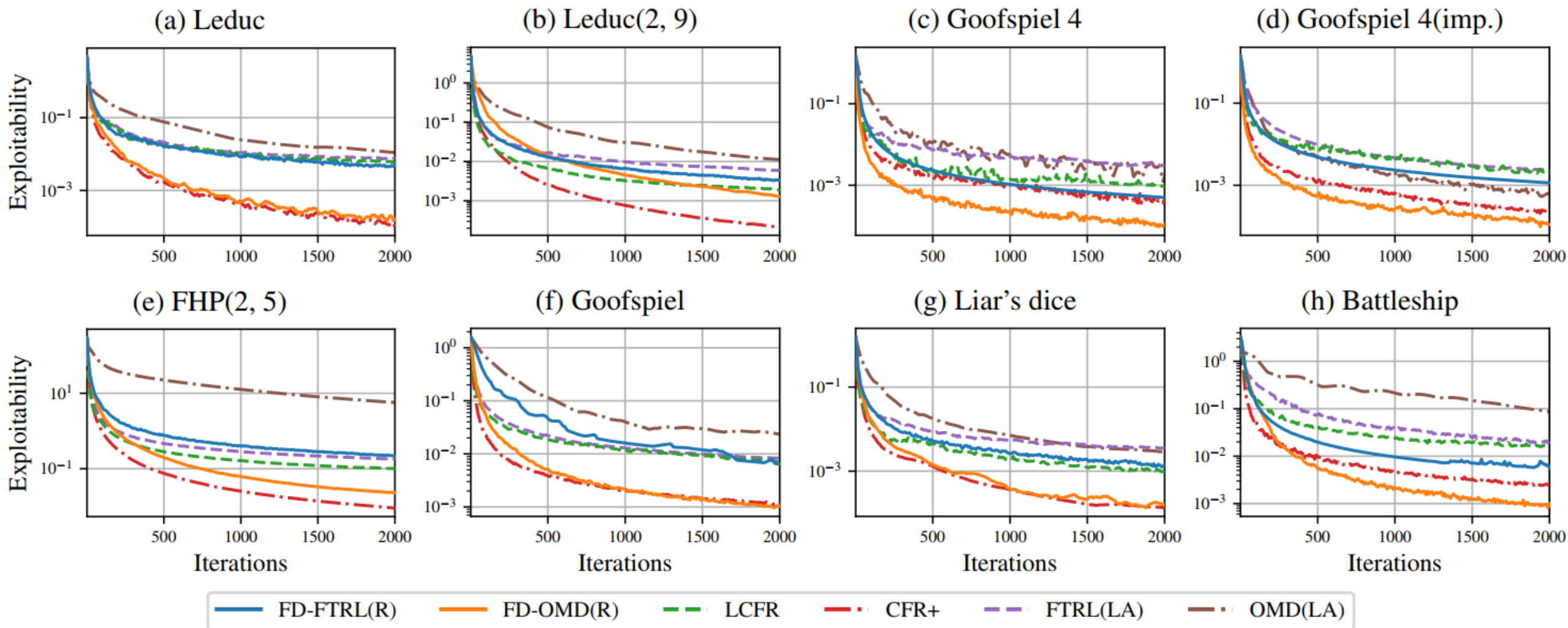
- FD-OMD (Orange) is faster than CFR+ (Red)

(c) Goofspiel 4



# Results: Adaptive FD-OMD

- FD-OMD (Orange) is no worse than CFR+ (Red) in 6/8 games.



# Conclusions

- CFR-RM (CFR-RM+) is equivalent to a special FTRL (OMD)
  - Partially explain the superior performance of CFRs
- Propose FD-FTRL and FD-OMD
  - Faster than the non-adaptive FTRL and OMD in EFGs
  - Contrary to previous findings, OMD can be faster than CFR+

# Thank you!

**Find more details in the paper:**

Liu, W., Jiang, H., Li, B., and Li, H. Equivalence Analysis between Counterfactual Regret Minimization and Online Mirror Descent. In *International Conference on Machine Learning*, 2022.