

Separable Group Equivariant Neural Networks on Lie groups



David M. Knigge



David W. Romero



Erik J. Bekkers



Short overview

Broadly, research into Equivariant CNNs can be divided into:

- Regular G-CNNs
 - Use **regular representation** to transform kernel
 - Intuitive, **easy to implement**
 - Applicable to **broad range** of groups
 - **Computational complexity** depends on **group size** and dimensionality ←
- Steerable G-CNNs
 - Constrain kernels to steerable basis
 - Applicable to unimodular groups, e.g. **rotation groups**
 - **Decouple computational complexity** from group size

Summary

- **Scalability** remains a problem in regular G-CNNs
 - We propose **separating** the **group convolution** operation for affine groups $G = \mathbb{R}^2 \rtimes H$ by **subgroups**:
 - Factorise into a **separate convolution** over H and \mathbb{R}^2

Group convolutions

- Feature maps f are defined over G
- The kernel k now also extends over G (considerably increasing computational complexity)

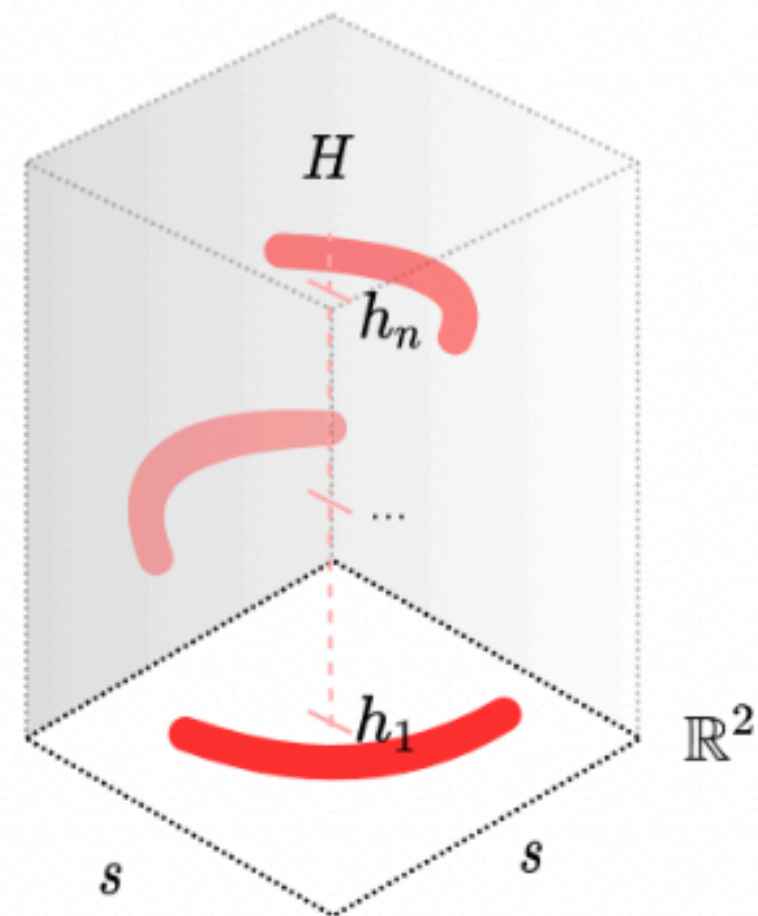
$$\begin{aligned}(f *_{\text{group}} k)(g) &= \int_G f(\tilde{g}) k(g^{-1} \cdot \tilde{g}) d\tilde{g} \\ &= \int_{\mathbb{R}^2} \int_H f(\tilde{x}, \tilde{h}) k(h^{-1}(\tilde{x} - x), h^{-1} \cdot \tilde{h}) \frac{1}{|h|} d\tilde{x} d\tilde{h}\end{aligned}$$

In case of
affine groups

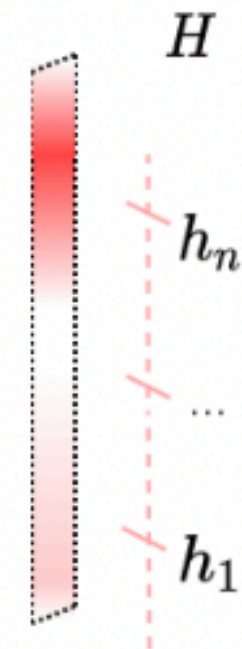
where $g = (x, h)$

Separable group convolutions

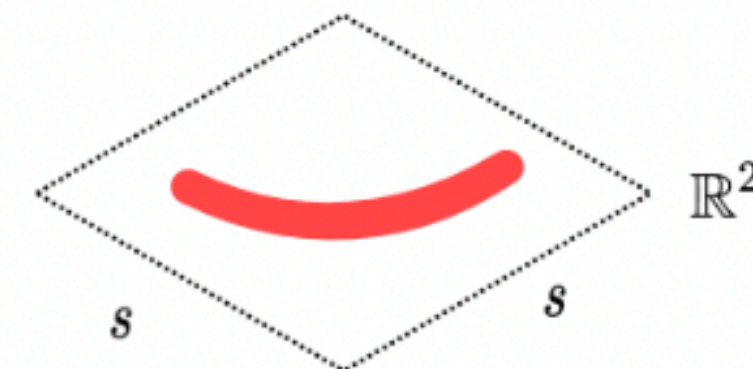
- Idea - treat distinct subgroups separately:
 - i.e. separate convolutions over rotation and spatial dimensions
- Assume: $k(g) = k_{\mathbb{R}^2}(\mathbf{x}) \cdot k_H(h)$



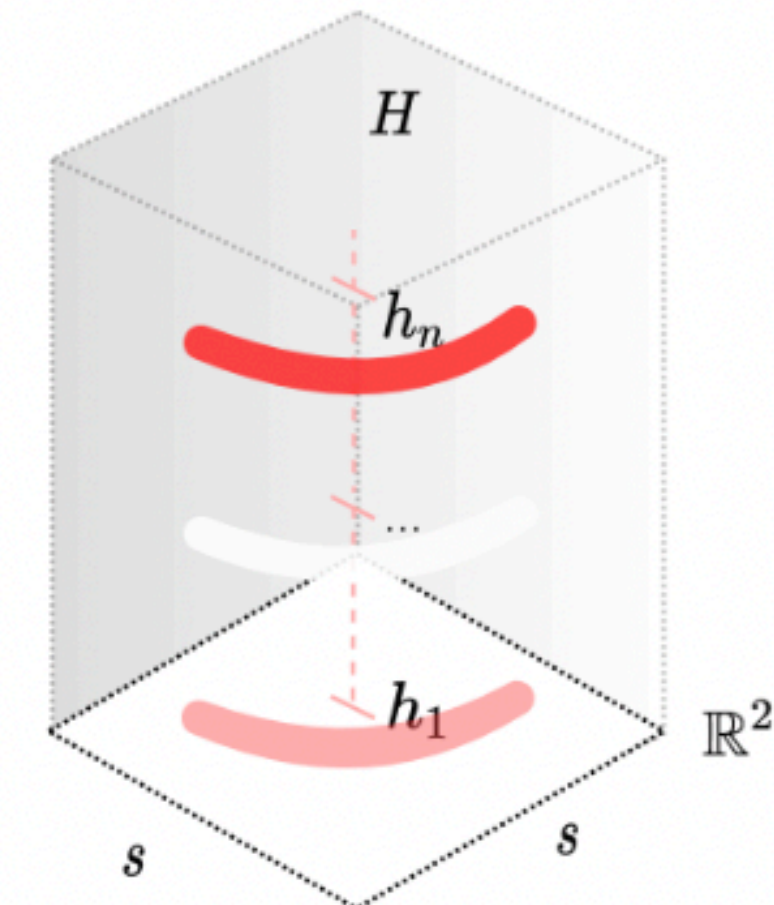
(a) $k : \mathbb{R}^2 \rtimes H \rightarrow \mathbb{R}$



(b) $k_H : H \rightarrow \mathbb{R}$



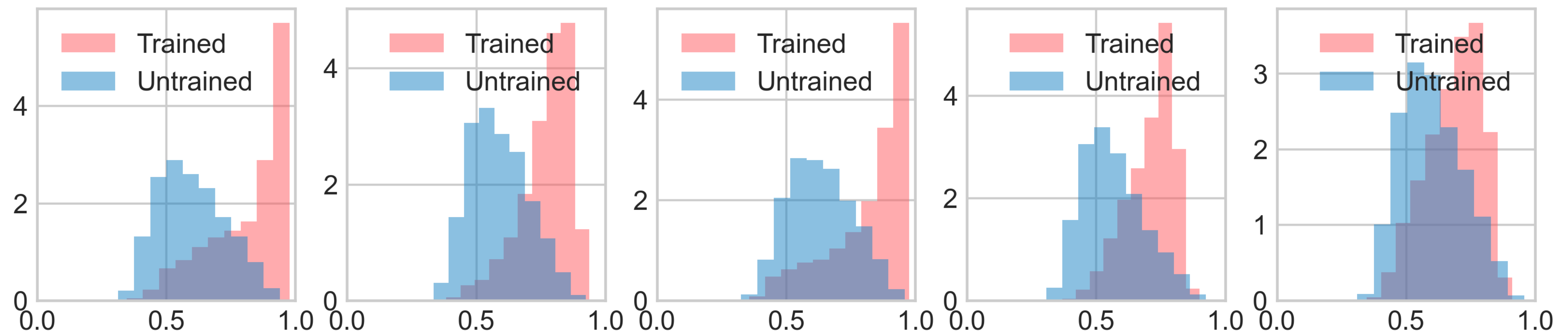
(c) $k_{\mathbb{R}^2} : \mathbb{R}^2 \rightarrow \mathbb{R}$



(d) $k_H \cdot k_{\mathbb{R}^2}$

Separable group convolutions

- It turns out there is empirical motivation for this approach, learned G-conv kernels exhibit redundancy along the H axis!



Visualisation of redundancy in group convolution kernels in subsequent layers

Separable group convolutions

- Idea: treat distinct subgroups separately:
 - i.e. separate convolutions over rotation and spatial dimensions
- Assume: $k(g) = k_{\mathbb{R}^2}(\mathbf{x}) \cdot k_H(h)$

$$\begin{aligned}(f *_{group} k)(g) &\approx \sum_{\tilde{\mathbf{x}} \in \mathbb{Z}^2} \sum_{\tilde{h} \in \mathcal{H}_\epsilon} f(\tilde{\mathbf{x}}, \tilde{h}) k(h^{-1}(\tilde{\mathbf{x}} - \mathbf{x}), h^{-1} \cdot \tilde{h}) \frac{1}{|h|} \\ &= \sum_{\tilde{\mathbf{x}} \in \mathbb{Z}^2} \left[\sum_{\tilde{h} \in \mathcal{H}_\epsilon} f(\tilde{\mathbf{x}}, \tilde{h}) k_H(h^{-1} \cdot \tilde{h}) \right] \frac{1}{|h|} k_{\mathbb{R}^2}(h^{-1}(\tilde{\mathbf{x}} - \mathbf{x}))\end{aligned}$$

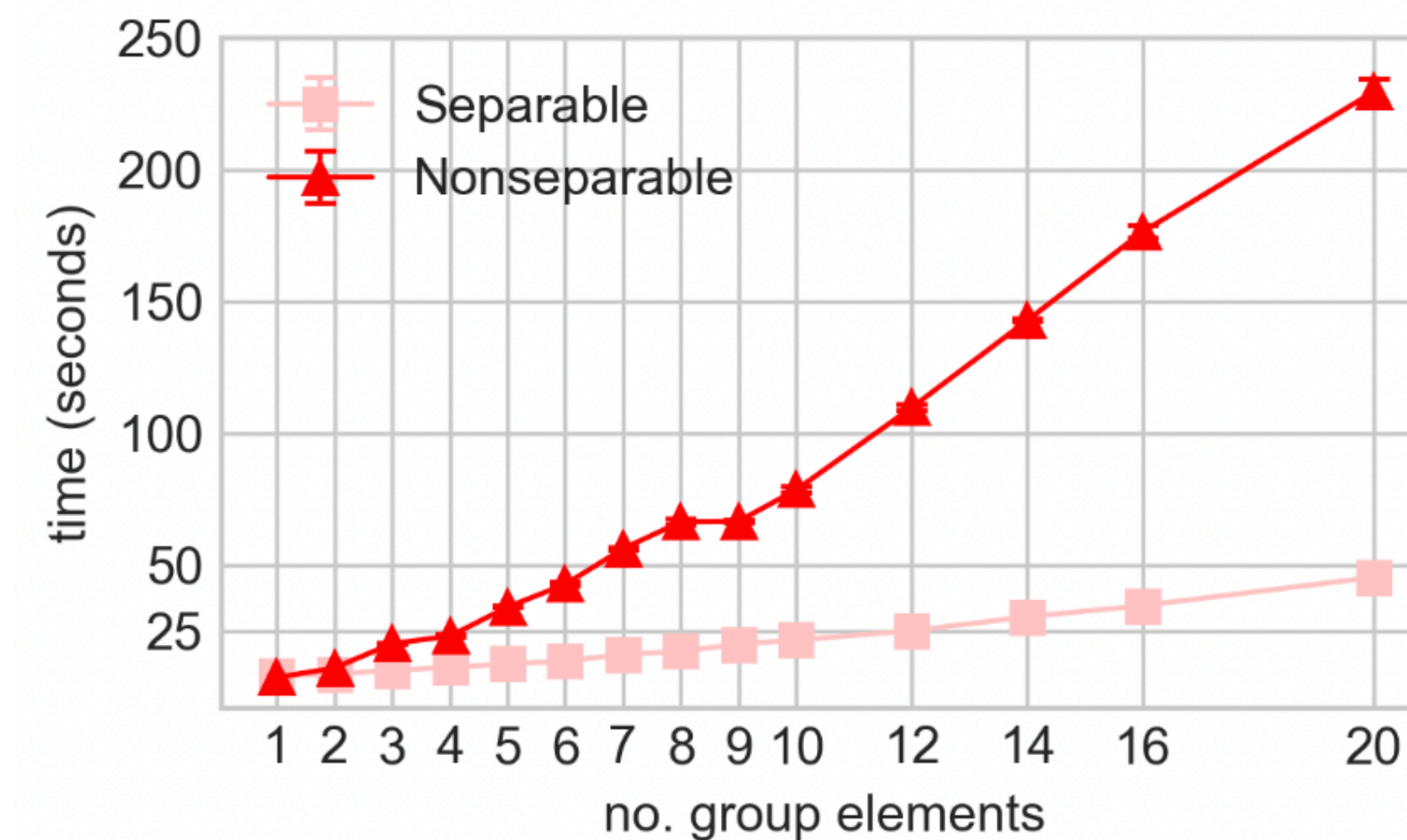
Does not depend on \mathbf{x} ,
precompute this!

Separable group convolutions

Computational efficiency

- Drastically **reduces computational complexity:**

Process time per epoch on MNIST-rot



- In turn allowing for larger groups

Separable group convolutions

Sim(2)-equivariance

Table 2. Test error (%) on rotated MNIST for separable G-CNNs in comparison to other equivariant baselines: G-CNN (Cohen & Welling, 2016a), H-Net (Worrall et al., 2017), RED-NN (Salas et al., 2019), LieConv (Finzi et al., 2020), SFCNN (Weiler et al., 2018b), E(2)-NN (Weiler & Cesa, 2019). † Separable along dilation and rotations dimensions. + Train-time augmentation by continuous rotations.

Baseline Methods							Separable G-CNNs (Ours)			
G-CNN	H-Net	RED-NN	LieConv	SFCNN	SFCNN ₊	E(2)-NN ₊	SE(2)	SE(2) ₊	Sim(2) [†]	Sim(2) ₊ [†]
2.28	1.69	1.39	1.24	0.88	0.714	0.68	0.89 \pm .008	0.66 \pm .023	0.66 \pm .009	0.59 \pm .008

Table 3. Test error (%) on CIFAR10 with All-CNN-C architecture, for our separable group convolutions in comparison to other baselines: All-CNN-C (Springenberg et al., 2014), $p4$ - and $p4m$ -G-CNN (Cohen & Welling, 2016a). † Separable along dilation and rotations dimensions. + Train-time augmentation by random horizontal flips and random cropping. n -Sim(2)-CNNs where n is the SIREN hidden size in units. 6-Sim(2)-CNNs have approximately equal numbers of parameters to the original All-CNN-C.

Baseline Methods					Separable G-CNNs (Ours)					
1.4m param.	1.37m param.		1.27m param.		1.14m param.		1.33m param.		3.22m param.	
All-CNN-C	$p4$ -G-CNN	$p4$ -G-CNN ₊	$p4m$ -G-CNN	$p4m$ -G-CNN ₊	5-Sim(2) [†]	5-Sim(2) ₊ [†]	6-Sim(2) [†]	6-Sim(2) ₊ [†]	16-Sim(2) [†]	16-Sim(2) ₊ [†]
9.08	8.84	7.67	7.59	7.04	8.50	7.41	8.22	6.47	7.27	5.50

Separable group convolutions

Separable vs. nonseparable

