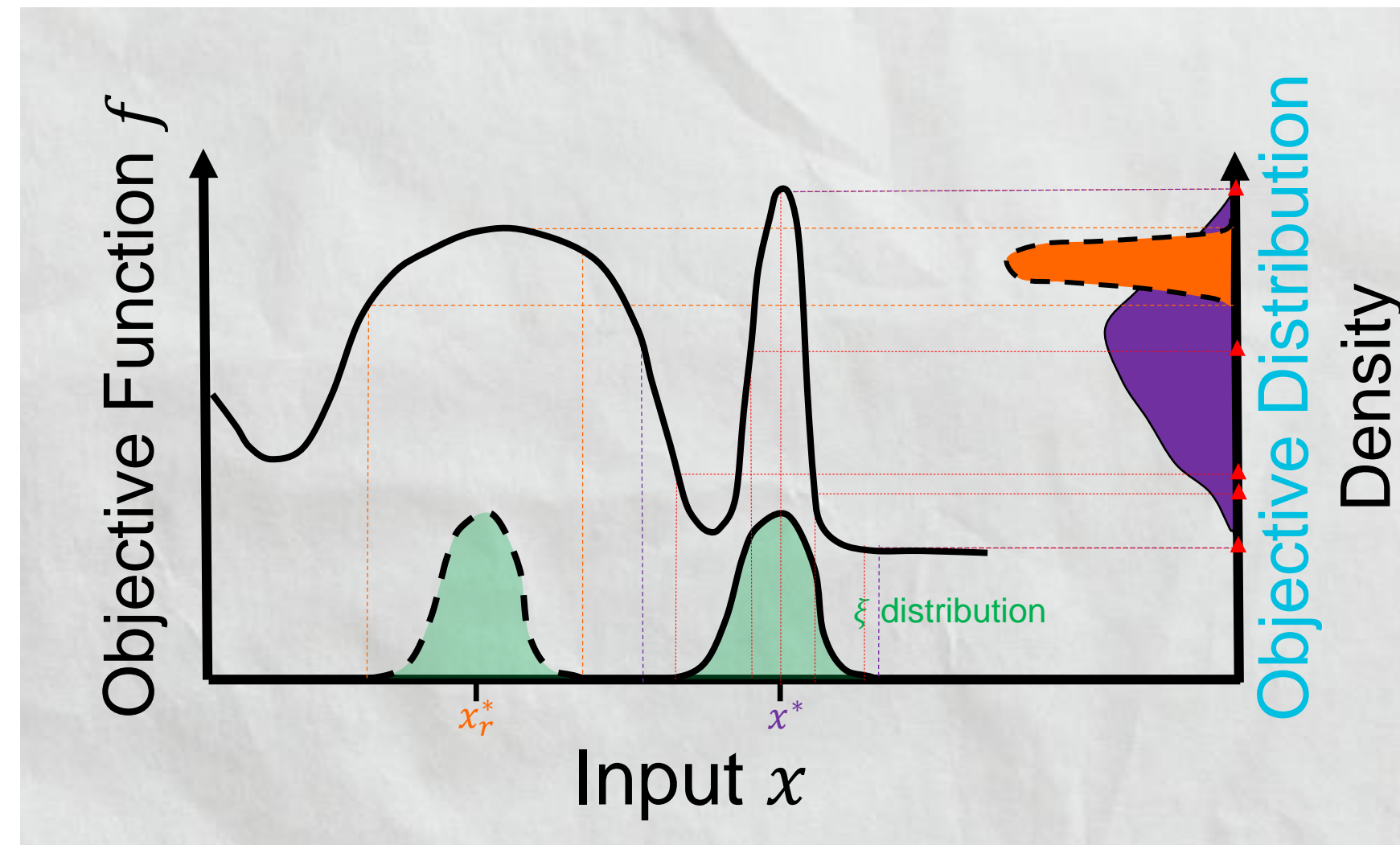


SPECTRAL REPRESENTATION OF ROBUSTNESS MEASURES FOR OPTIMIZATION UNDER INPUT UNCERTAINTY

Jixiang Qing, Tom Dhaene, Ivo Couckuyt

PROBLEM FORMULATION

- Robust optimization
 - Optimize black box function f
 - Consider **Input Uncertainty**
- What is a robust solution?
 - First moment: $\mathbb{J}_{\xi}(f) = \mathbb{E}_{\xi}[f(x + \xi)]$
 - Second moment: $\mathbb{V}_{\xi}(f) = \mathbb{V}_{\xi}[f(x + \xi)]$



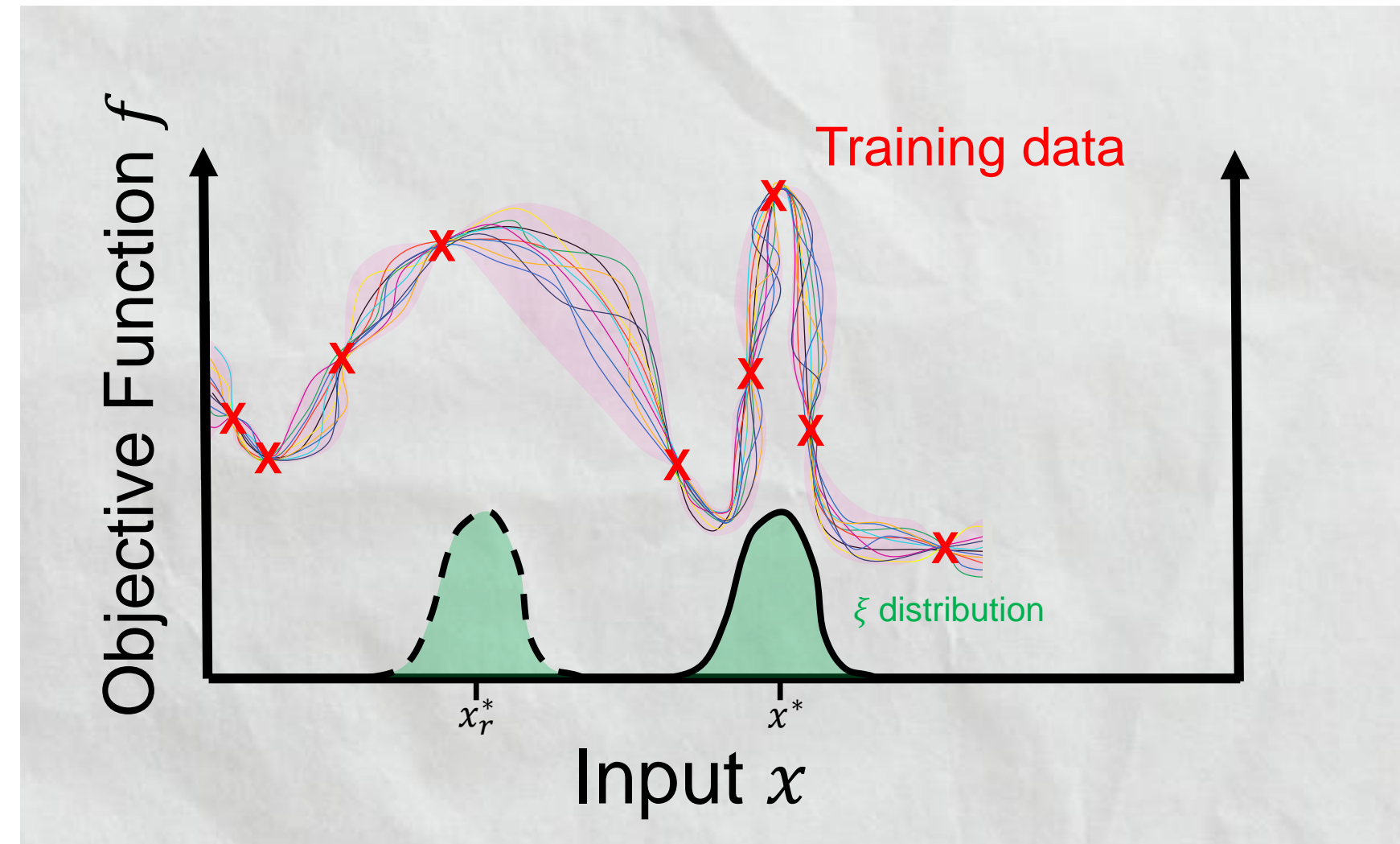
“Solution x_r^* is more robust than x^* ”

Mean: $\mathbb{E}_{\xi}[f(x_r^* + \xi)] \geq \mathbb{E}_{\xi}[f(x^* + \xi)]$

Variance: $\mathbb{V}_{\xi}[f(x_r^* + \xi)] \leq \mathbb{V}_{\xi}[f(x^* + \xi)]$

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- **Bayesian** approach:
 - Gaussian Process $f \sim \mathcal{GP}$
 - Bayesian Treatment of the above moments
 - $\mathbb{J}_{\xi}[\mathcal{GP}(f)] = \mathbb{E}_{\xi}[\mathcal{GP}(x + \xi)]$
 - $\mathbb{V}_{\xi}[\mathcal{GP}(f)] = \mathbb{V}_{\xi}[\mathcal{GP}(x + \xi)]$



APPROACH

$k(x, x')$ Bochner's Theorem

$$= \sigma^2 \int p(\omega) \cos(\omega^T L(x - x')) d\omega \approx$$

Inner Product Form

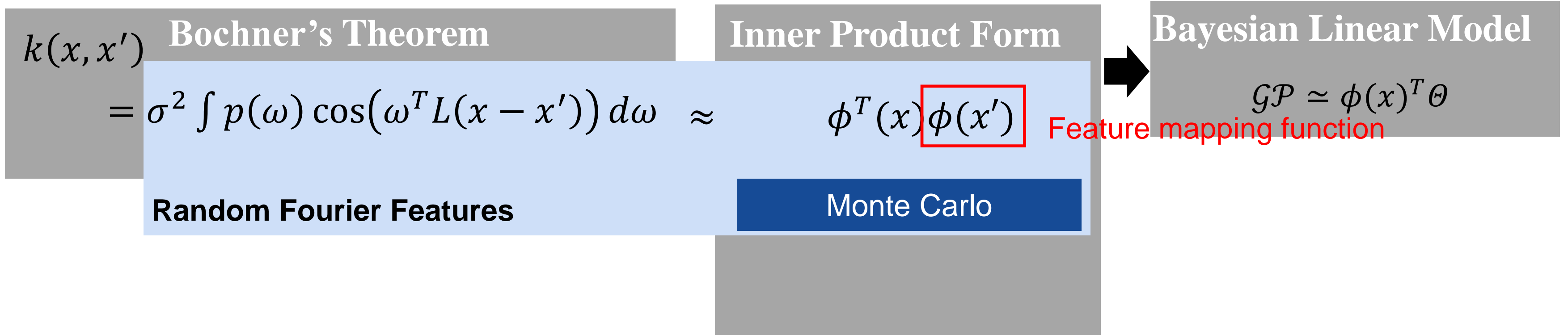
$$\phi^T(x) \phi(x')$$

Feature mapping function

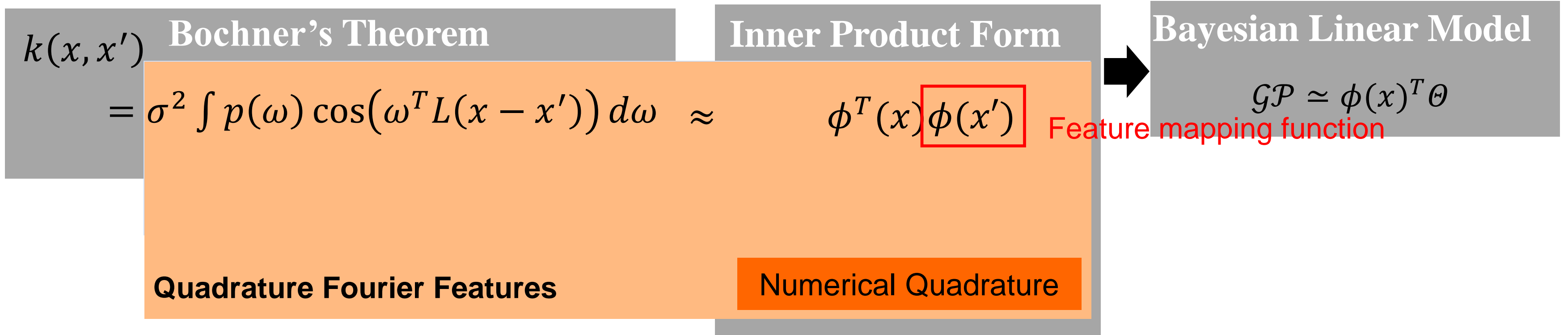
Bayesian Linear Model

$$\mathcal{GP} \simeq \phi(x)^T \theta$$

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 $[\mathbb{E}_{\xi}[\phi(x + \xi)^T] \theta]^2$

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Fourier feature base robustness measures

A spectral representation (i.e., a parametric representation) of robustness measures that supports **sampling** continuous posterior trajectories

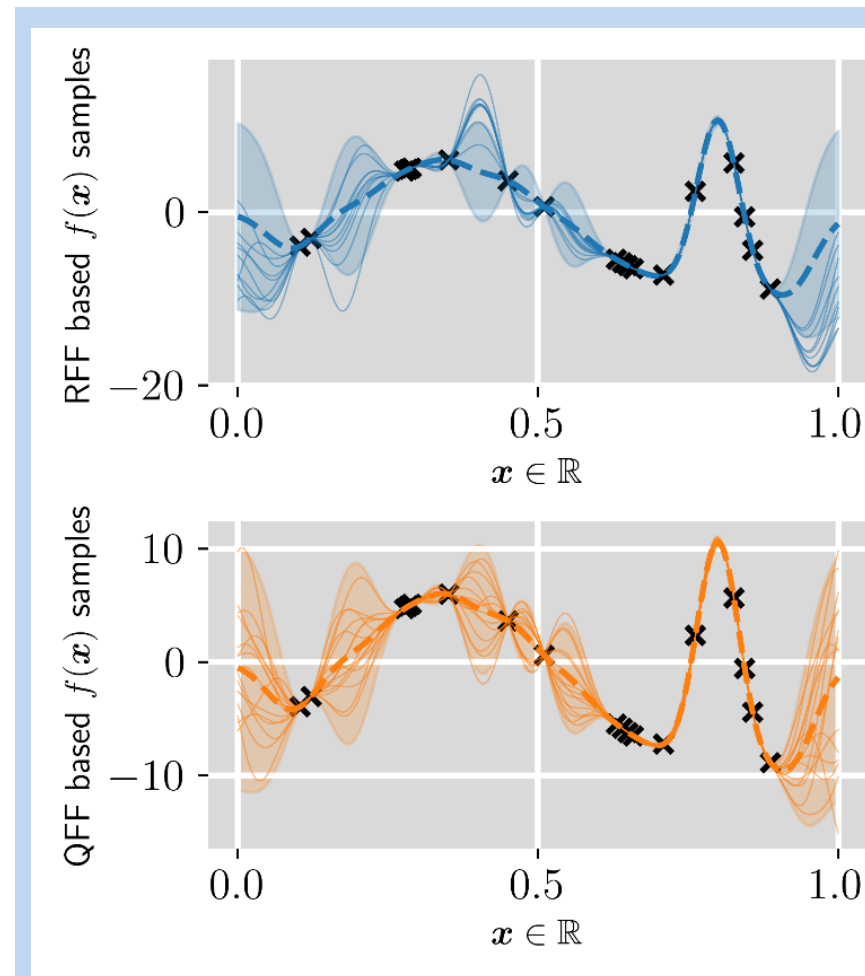
MAIN CONTRIBUTION

Fourier feature-based robustness measures

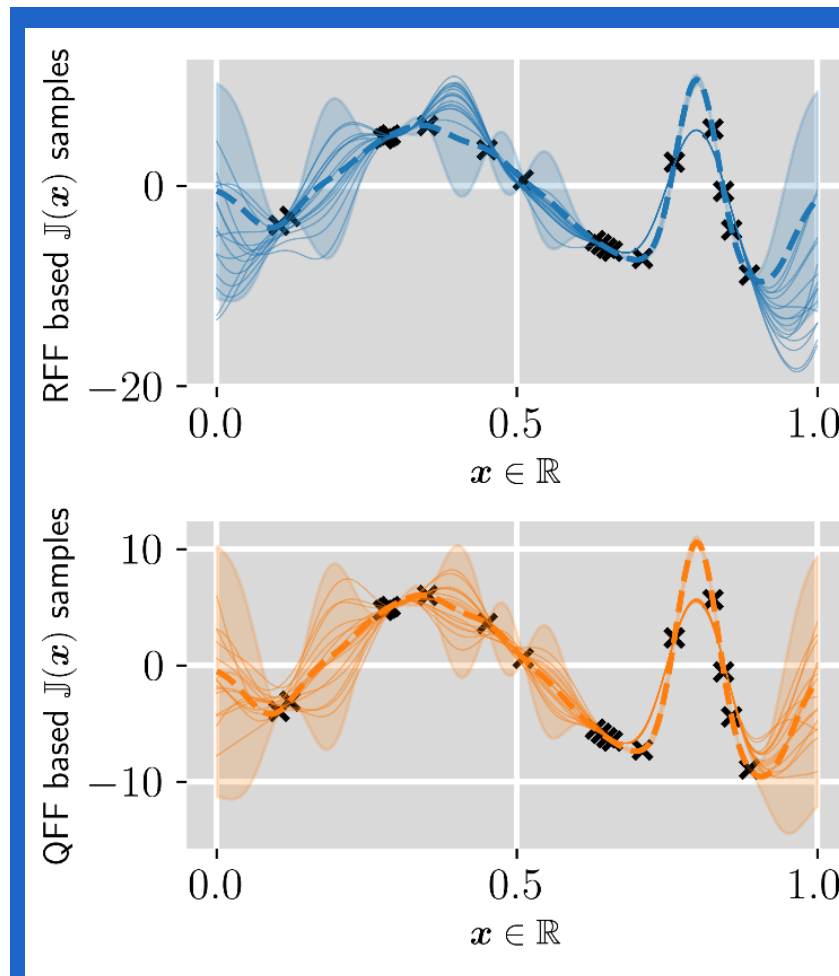
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Application in **Robust Bayesian Optimization**

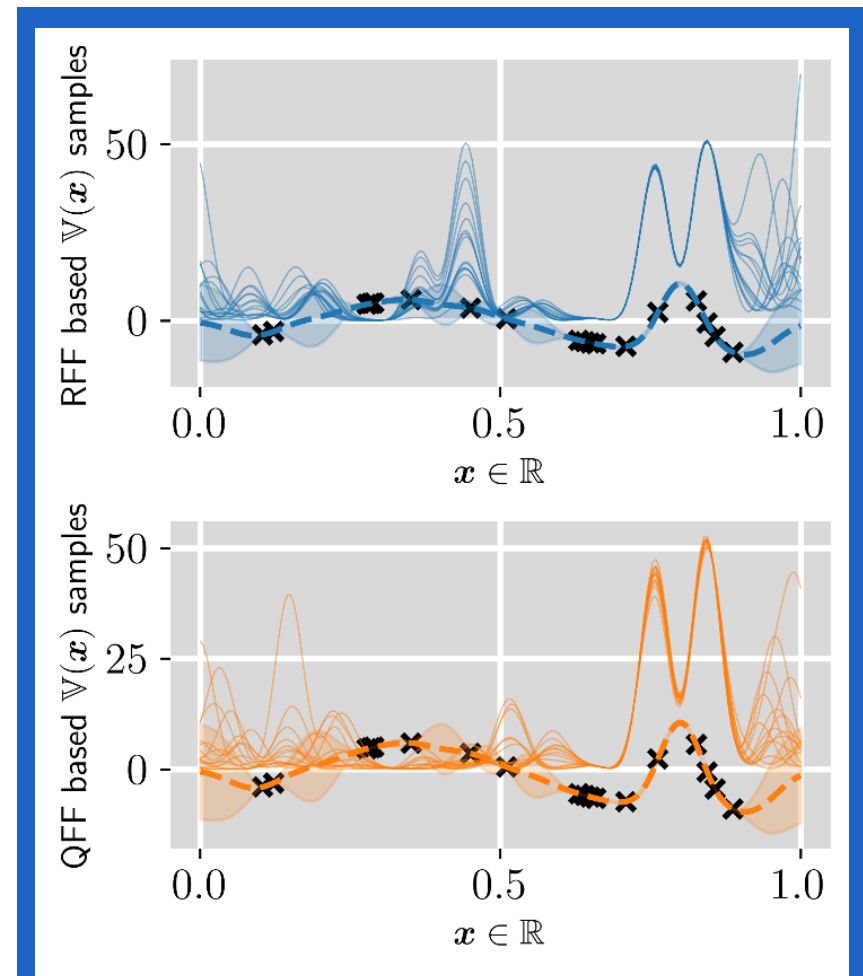
- Supports **various problem formulations**
- Supports **various acquisition functions**



Sample f posterior



Sample J posterior



Sample V posterior

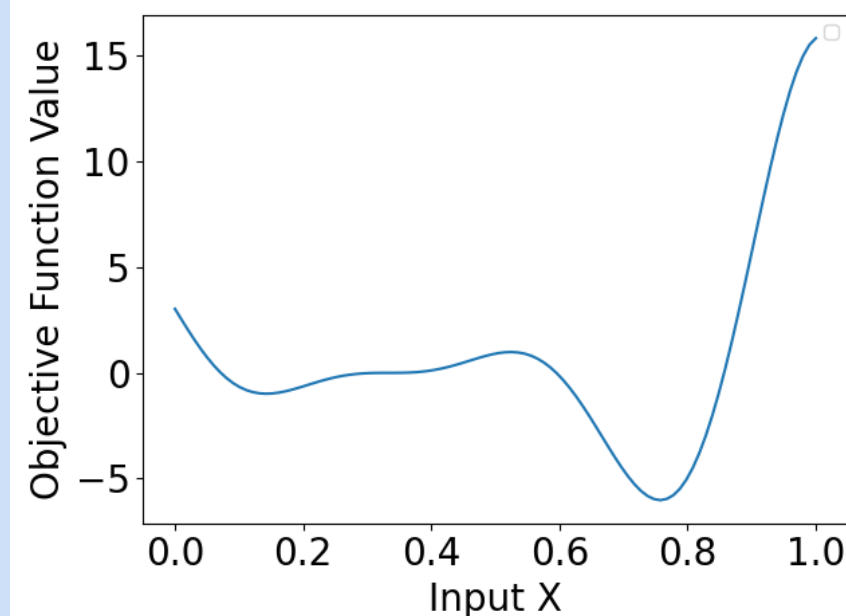
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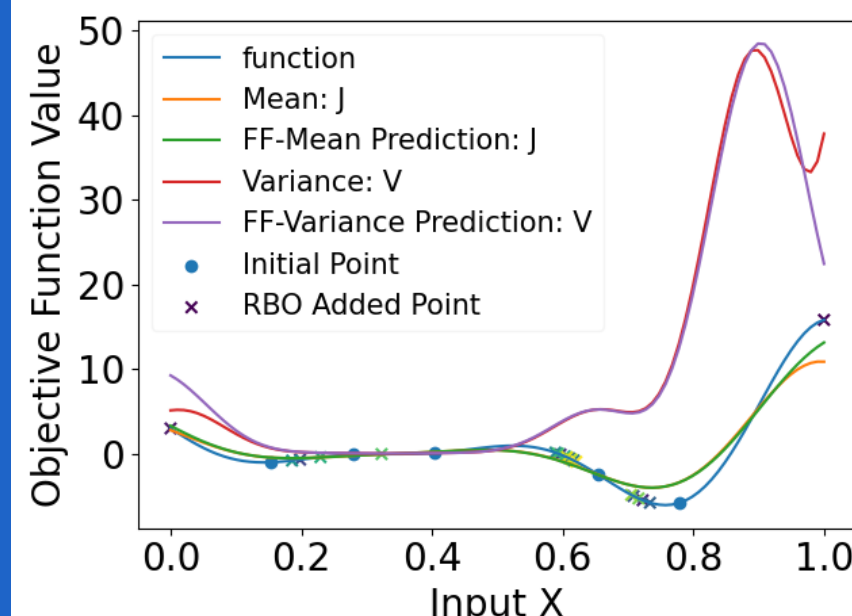
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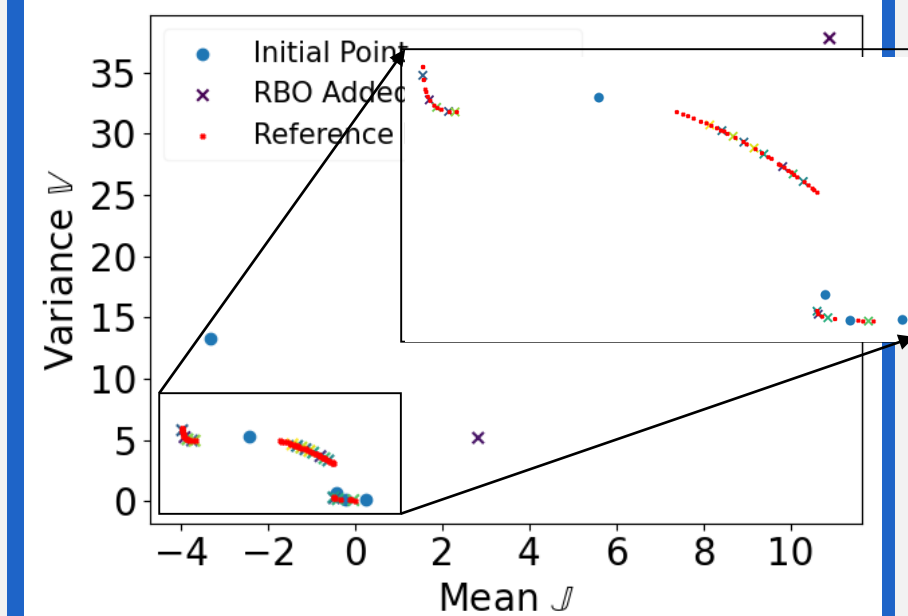


Benchmark Function

Proof of Concept



RBO Added Points



Pareto frontier

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Code is available at:

https://github.com/TsingQAQ/gp_mean_var_rbo