

# Improving Task-free Continual Learning by Distributionally Robust Memory Evolution



Zhenyi Wang, Li Shen, Le Fang, Qiuling Suo, Tiehang Duan, Mingchen Gao

# Task-free Continual Learning

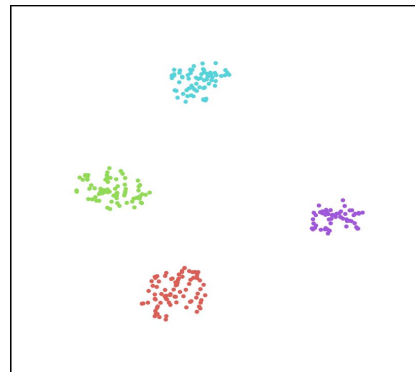
---

- Task-free continual learning aims to learn non-stationary data stream and not forget previous knowledge
- Data distribution shift could happen arbitrarily without clear task splits
- Majority work of existing task-free CL methods are memory-replayed based methods
- Memory-replay methods optimize an objective under a known probability distribution for the memory buffer  $\mu_0$

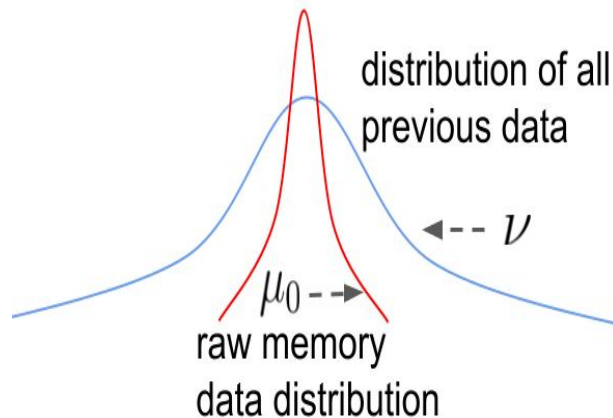
$$\min_{\forall \boldsymbol{\theta} \in \Theta} [\mathcal{L}(\boldsymbol{\theta}, \boldsymbol{x}_k, y_k) + \mathbb{E}_{\boldsymbol{x} \sim \mu_0} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{x}, y)],$$

# Motivation

- **Memory overfitting:** CL model would overfit the memory buffer, and memory buffer gradually less effective for mitigating forgetting as the model repeatedly learns the memory buffer



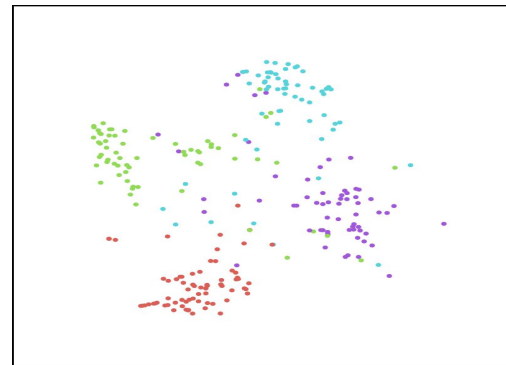
- a big gap between the memory data distribution and the distribution of all the previous data examples
- high uncertainty in the memory data distribution since a limited memory buffer cannot accurately reflect the stationary distribution of all examples seen so far in the data stream



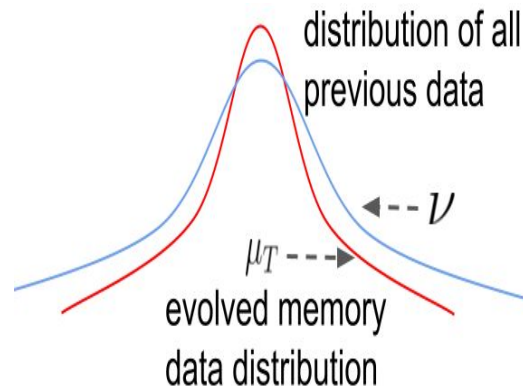
# Task-free DRO

**Solution:** Evolve the memory data distribution by Distributionally Robust Optimization (DRO).

- Make the memory buffer data harder to classify and overfit



- Narrow the gap between the memory data distribution and the distribution of all the previous data examples.



# Task-free DRO

- We optimize the worst-case evolved memory data distribution since we cannot access the actual data distribution of all the previous data examples, named task-free DRO.

$$\begin{aligned} & \min_{\forall \boldsymbol{\theta} \in \Theta} \sup_{\mu \in \mathcal{P}} \mathbb{E}_{\mu} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{x}, y) \\ & \text{s.t. } \mathcal{P} = \{\mu : \mathcal{D}(\mu || \pi) \leq \mathcal{D}(\mu_0 || \pi) \leq \epsilon\}, \\ & \mathbb{E}_{\boldsymbol{x} \sim \mu, \boldsymbol{x}' \sim \mu_0} \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{x}, y) \cdot \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{x}', y) \geq \lambda, \end{aligned}$$

- By Lagrange duality, convert into the following unconstrained optimization problem, still intractable to solve

$$\begin{aligned} & \min_{\forall \boldsymbol{\theta} \in \Theta} \sup_{\mu} [\mathbb{E}_{\mu} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{x}, y) - \gamma \mathcal{D}(\mu || \pi) + \\ & \beta \mathbb{E}_{\boldsymbol{x} \sim \mu, \boldsymbol{x}' \sim \mu_0} \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{x}, y) \cdot \nabla_{\boldsymbol{\theta}} \mathcal{L}(\boldsymbol{\theta}, \boldsymbol{x}', y)], \end{aligned}$$

# Dynamic DRO

---

- Convert task-free DRO into a gradient flow system, named dynamic DRO
- Memory buffer evolves as Wasserstein Gradient Flow (WGF) in probability measure space of memory data.
- Model parameters follows gradient flow in Euclidean space.

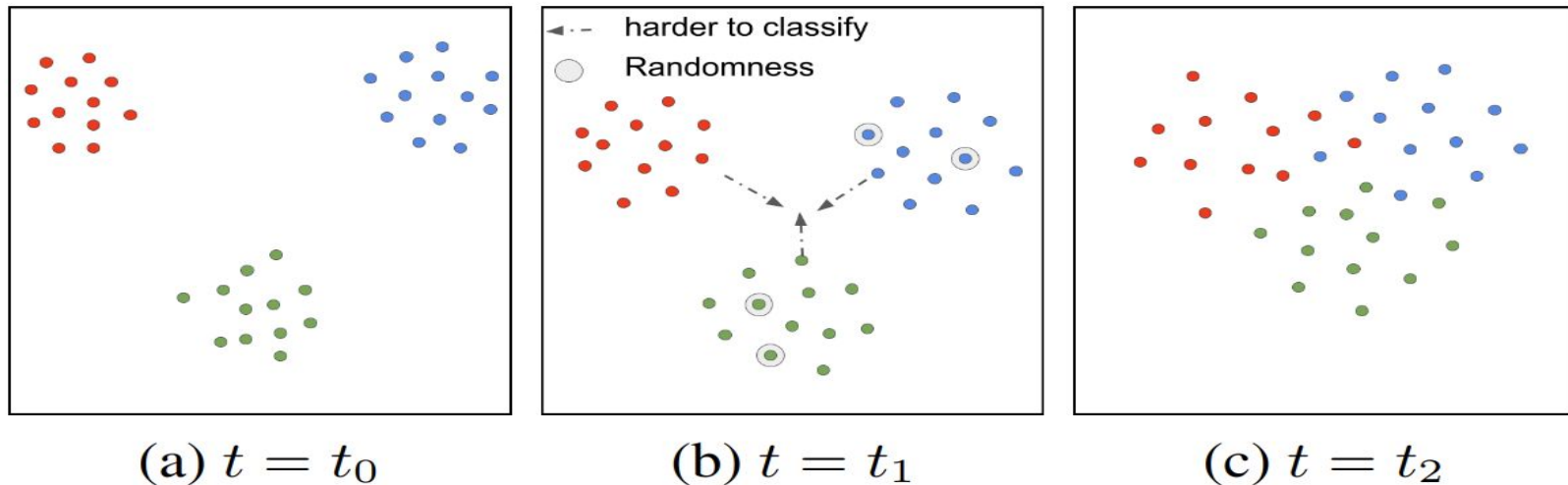
$$\begin{cases} \partial_t \mu_t &= \operatorname{div} \left( \mu_t \nabla \frac{\delta F}{\delta \mu}(\mu_t) \right) ; \\ \frac{d\boldsymbol{\theta}}{dt} &= -\nabla_{\boldsymbol{\theta}} \mathbb{E}_{\mu_t} \mathcal{L}(\boldsymbol{\theta}, \mathbf{x}, y), \end{cases}$$

memory buffer evolves as WGF

model parameters follows gradient flow in Euclidean space

# A family of Memory Evolution Methods for Dynamic DRO

## Langevin Dynamics for Dynamic DRO (WGF-LD)

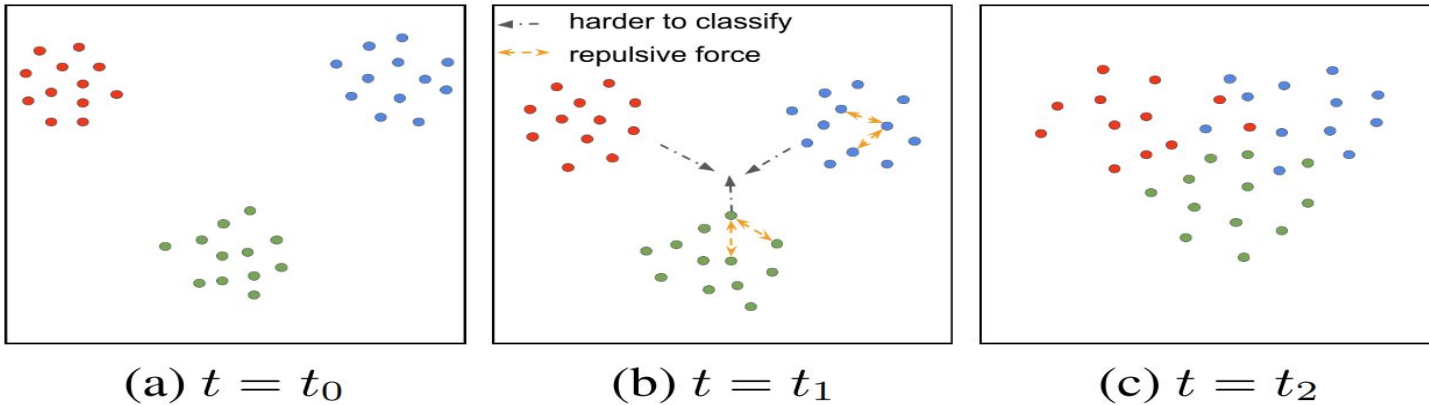


$$dX = -\nabla_X U(X, \boldsymbol{\theta})dt + \sqrt{2}dW_t,$$

$$\mathbf{x}_{t+1}^i - \mathbf{x}_t^i = -\alpha(\nabla_{\mathbf{x}} U(\mathbf{x}_t^i, \boldsymbol{\theta})) + \sqrt{2\alpha}\xi_t$$

# A family of Memory Evolution Methods

## Kernelized Method for Dynamic DRO (WGF-SVGD)



$$\frac{dX}{dt} = -[\mathcal{K}_\mu \nabla \frac{\delta F}{\delta \mu}(\mu_t)](X) \quad \mathcal{K}_\mu f(x) = \int K(x, x') f(x') d\mu(x')$$

$$\mathbf{x}_{t+1}^i - \mathbf{x}_t^i = -\frac{\alpha}{N} \sum_{j=1}^N \underbrace{[k(\mathbf{x}_t^i, \mathbf{x}_t^j) \nabla_{\mathbf{x}_t^j} U(\mathbf{x}_t^j, \boldsymbol{\theta})]}_{\text{smoothed gradient}} + \underbrace{\nabla_{\mathbf{x}_t^j} k(\mathbf{x}_t^i, \mathbf{x}_t^j)}_{\text{repulsive term}}$$



# Experiment

CIFAR10, CIFAR100, MinilImageNet

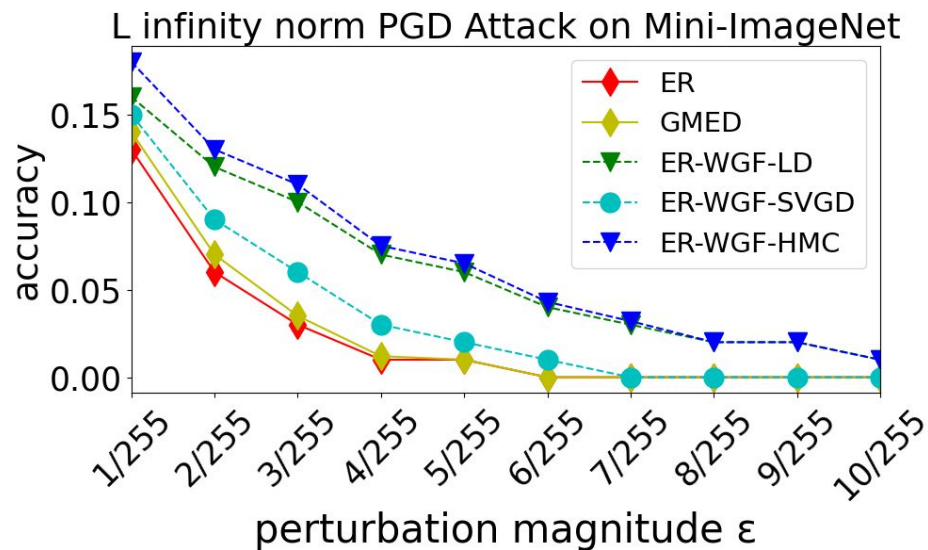
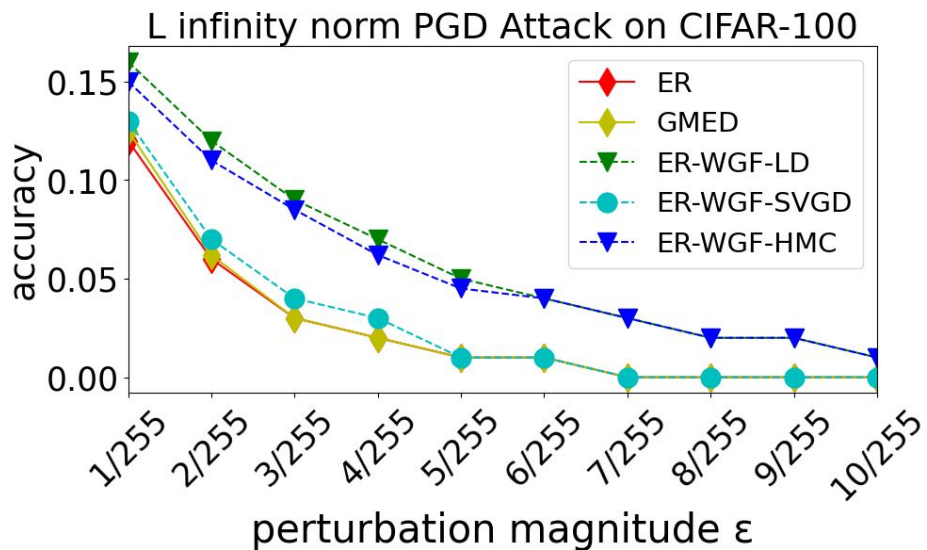
Split CIFAR10 into 5 tasks, each one consists of 2 classes

Split CIFAR100 and MinilImageNet into 20 tasks, each one consists of 5 classes

Algorithm	CIFAR10	CIFAR-100	MiniImagenet
fine-tuning	$18.9 \pm 0.1$	$3.1 \pm 0.2$	$2.9 \pm 0.5$
A-GEM	$19.0 \pm 0.3$	$2.4 \pm 0.2$	$3.0 \pm 0.4$
GSS-Greedy	$29.9 \pm 1.5$	$19.5 \pm 1.3$	$17.4 \pm 0.9$
ER	$33.3 \pm 2.8$	$20.1 \pm 1.2$	$24.8 \pm 1.0$
ER + WGF-LD	$37.6 \pm 1.5$	<b><math>21.5 \pm 1.3</math></b>	$27.3 \pm 1.0$
ER + WGF-SVGD	$36.5 \pm 1.4$	$21.3 \pm 1.5$	<b><math>27.6 \pm 1.3</math></b>
ER + WGF-HMC	<b><math>37.8 \pm 1.3</math></b>	$21.2 \pm 1.4$	$27.2 \pm 1.1$
MIR	$34.4 \pm 2.5$	$20.0 \pm 1.7$	$25.3 \pm 1.7$
MIR + WGF-LD	<b><math>38.2 \pm 1.2</math></b>	<b><math>21.6 \pm 1.2</math></b>	$26.9 \pm 1.0$
MIR + WGF-SVGD	$37.0 \pm 1.4$	$21.2 \pm 1.5$	<b><math>27.4 \pm 1.2</math></b>
MIR + WGF-HMC	$37.9 \pm 1.5$	$21.3 \pm 1.4$	$27.1 \pm 1.3$
GMED (ER)	$34.8 \pm 2.2$	$20.9 \pm 1.6$	$27.3 \pm 1.8$
GMED + WGF-LD	<b><math>38.4 \pm 1.6</math></b>	$21.7 \pm 1.7$	$28.3 \pm 1.9$
GMED + WGF-SVGD	$37.6 \pm 1.7$	<b><math>21.8 \pm 1.5</math></b>	<b><math>28.7 \pm 1.5</math></b>
GMED + WGF-HMC	$37.8 \pm 1.2$	$21.5 \pm 1.9$	$28.4 \pm 1.3$
ER <sub>aug</sub> + ER	$46.3 \pm 2.7$	$18.3 \pm 1.9$	$30.8 \pm 2.2$
ER <sub>aug</sub> + WGF-LD	$47.6 \pm 2.4$	$19.8 \pm 2.2$	$31.9 \pm 1.8$
ER <sub>aug</sub> + WGF-SVGD	<b><math>47.9 \pm 2.5</math></b>	$19.9 \pm 2.3$	<b><math>32.2 \pm 1.5</math></b>
ER <sub>aug</sub> + WGF-HMC	$47.8 \pm 2.6$	<b><math>20.3 \pm 2.1</math></b>	$31.7 \pm 2.0$
iid online	$60.3 \pm 1.4$	$18.7 \pm 1.2$	$17.7 \pm 1.5$
iid offline	$78.7 \pm 1.1$	$44.9 \pm 1.5$	$39.8 \pm 1.4$

# Experiment

As a by-product of the proposed framework, the methods are more robust to adversarial examples.



**Thank you**