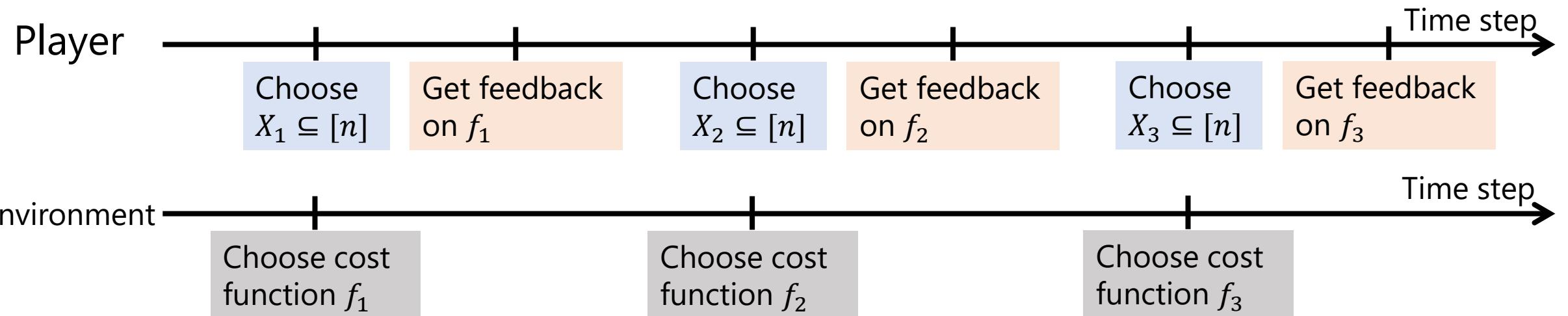


# Revisiting Online Submodular Minimization: Gap-Dependent Regret Bounds, Best of Both Worlds and Adversarial Robustness

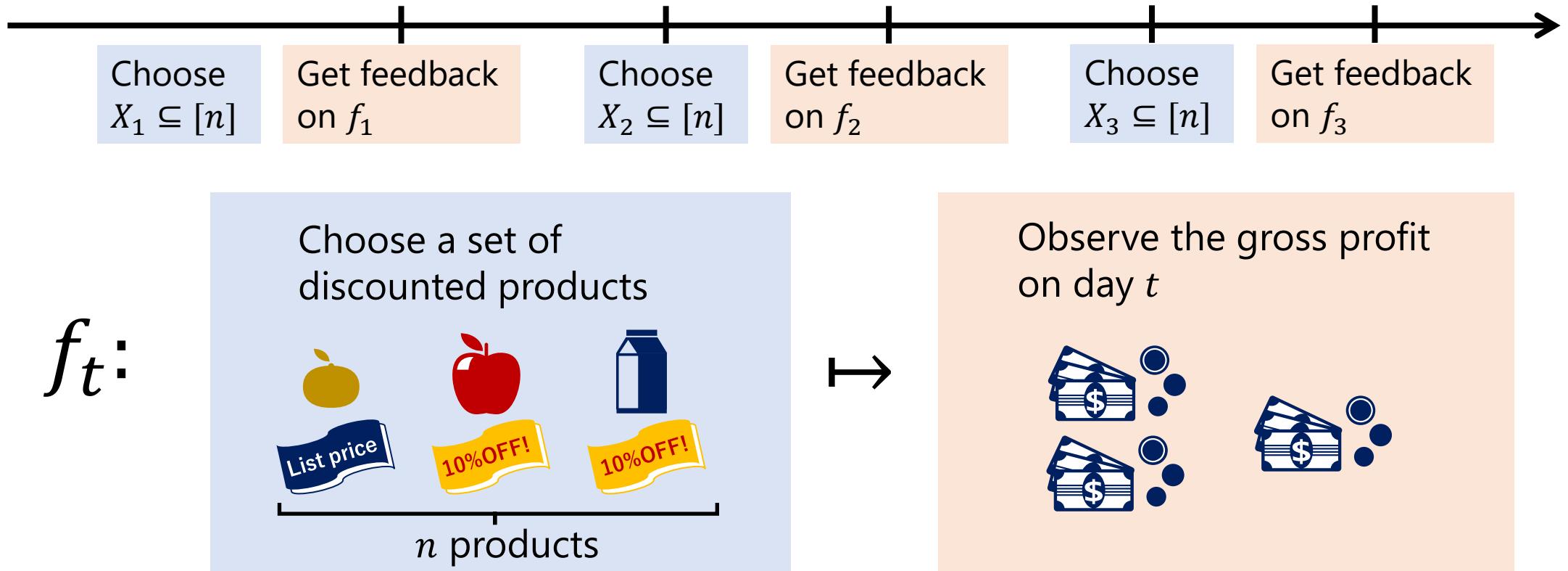
Shinji Ito (NEC Corporation)  
ICML2022

# Online submodular minimization [Hazan & Kale, 2012]

- Given ground set  $[n] = \{1, 2, \dots, n\}$  is given
- For  $t = 1, 2, \dots, T$ :
  - The environment chooses *submodular cost function*  $f_t: 2^{[n]} \rightarrow [0, 1]$
  - The player chooses *action*  $X_t \subseteq [n]$  without knowing  $f_t$
  - The player gets *feedback* on  $f_t$  *Full-info setting*:  $f_t(X)$  for any  $X \subseteq [n]$  is observable  
*Bandit setting*: only  $f_t(X_t)$  is observable



# Application example: multi-product price optimization



Under some assumptions on the demand model (substitute-goods property), the objective function  $f_t$  is submodular (cf. [Ito & Fujimaki, 2016])

# Performance metric: Regret

Algorithm performance is evaluated by means of *regret*  $R_T$  defined as

$$R_T = \mathbb{E} \left[ \sum_{t=1}^T f_t(X_t) \right] - \min_{X^* \subseteq [n]} \mathbb{E} \left[ \sum_{t=1}^T f_t(X^*) \right]$$

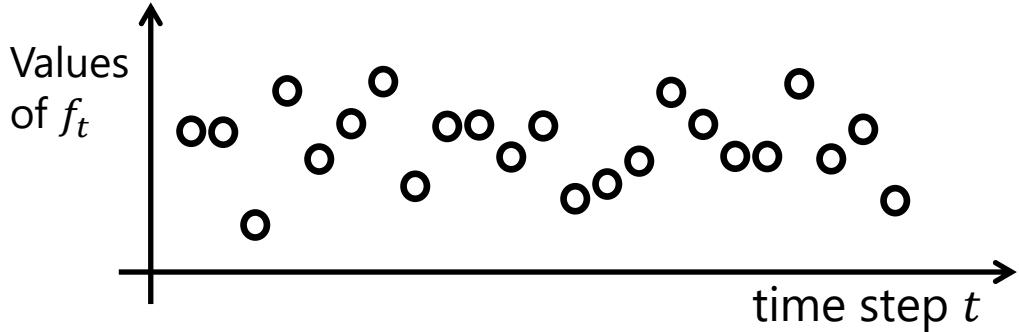


Cumulative costs incurred by **the player**

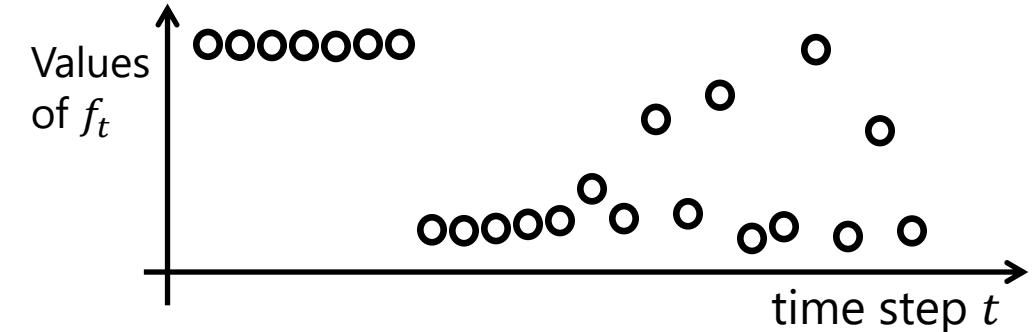
Cumulative costs for **the optimal fixed action  $X^*$**

# Two models for environments

1. **Stochastic (stationary) model:**  
cost functions  $f_t$  follow **i.i.d. distributions**

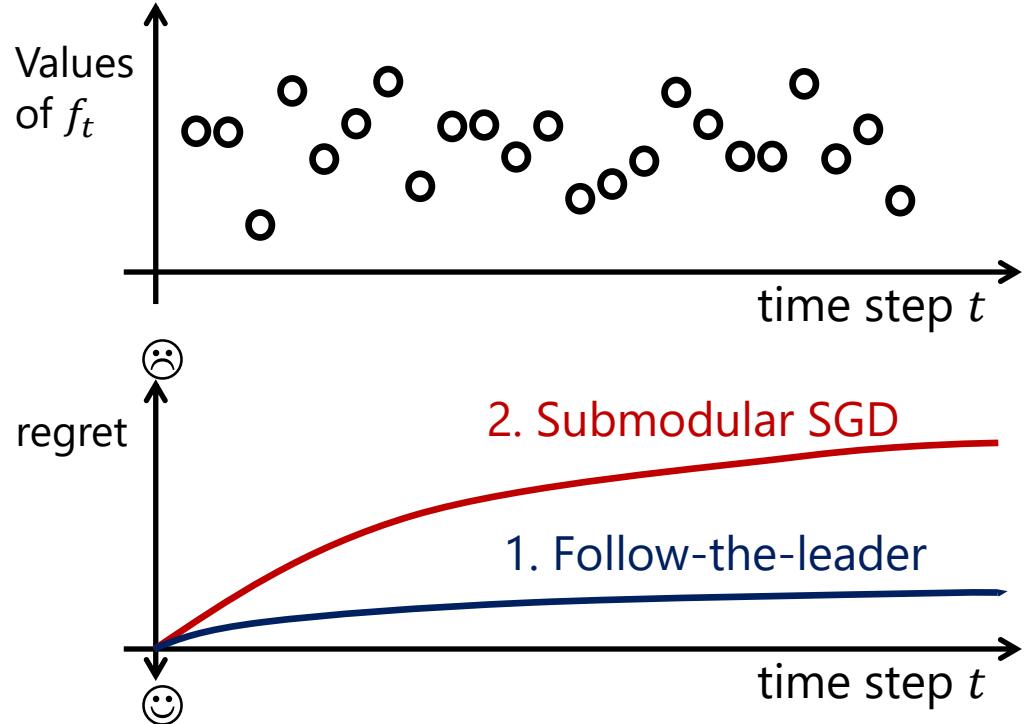


2. **Adversarial (non-stationary) model:**  
 $\{f_t\}_{t=1}^T$  is an **arbitrary sequence**

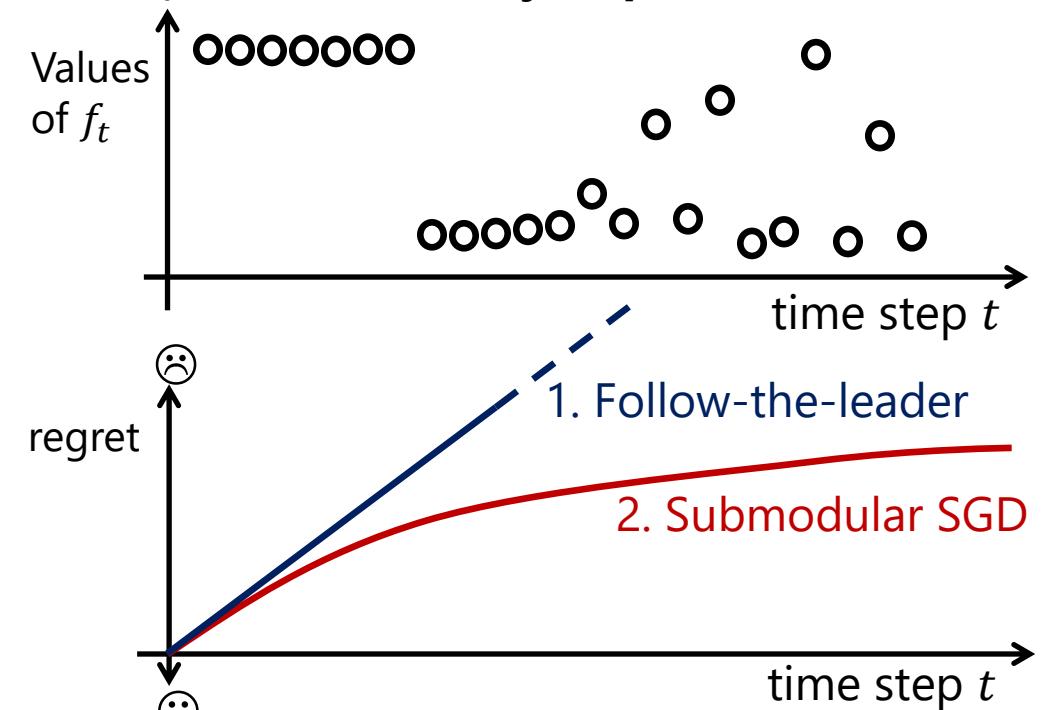


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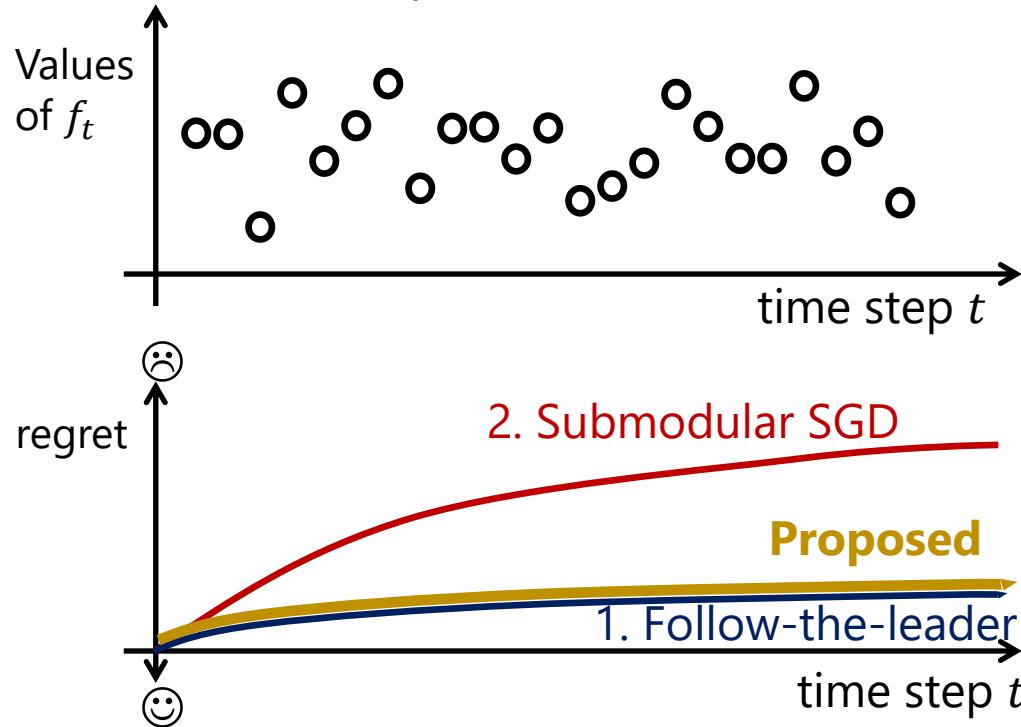


- It is important to choose **the right algorithm for the environment**.
- However, it is difficult to know in advance which algorithm better matches the environment.

# Two models for environments

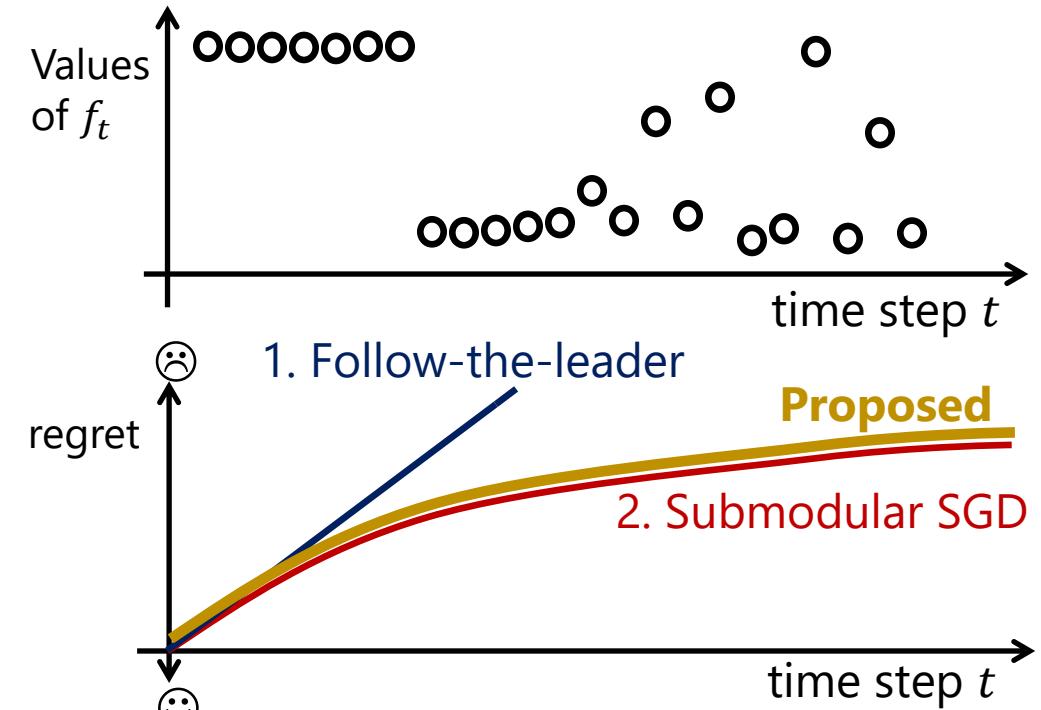
## 1. Stochastic (stationary) model:

cost functions  $f_t$  follow **i.i.d. distributions**



## 2. Adversarial (non-stationary) model:

$\{f_t\}_{t=1}^T$  is an **arbitrary sequence**



- It is important to choose **the right algorithm for the environment**.
- However, it is difficult to know in advance which algorithm better matches the environment.
- **This study: best-of-both-worlds** algorithms that work well for both models

# Summary of contributions

Regret bounds for full-information settings.  $\Delta$ : suboptimality gap,  $C$ : corruption level

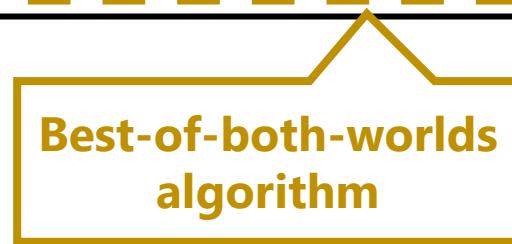
Algorithm	Stochastic	Adversarial	Stochastic + adversarial
Submodular SGD [Hazan&Kale, 2012]	$O(\sqrt{nT})$	$O(\sqrt{nT})$	$O(\sqrt{nT})$
Follow-the-leader	$O\left(\min\left\{\sqrt{nT}, \frac{n}{\Delta}\right\}\right)$	-	-
<b>Proposed algo. 1</b> <b>[This work]</b>	$O\left(\min\left\{\sqrt{nT}, \frac{n}{\Delta}\right\}\right)$	$O(\sqrt{nT})$	$O\left(\min\left\{\sqrt{nT}, \frac{n}{\Delta} + \sqrt{\frac{cn}{\Delta}}\right\}\right)$

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**Best-of-both-worlds algorithm**



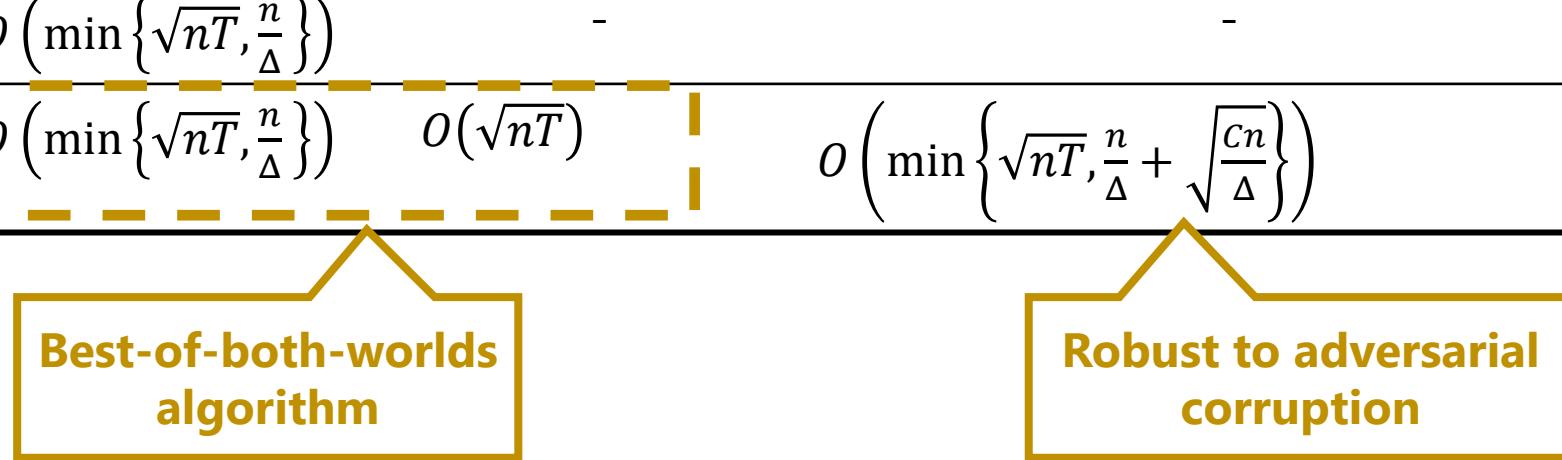
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**Best-of-both-worlds algorithm**

**Robust to adversarial corruption**



# Summary of contributions

Regret bounds for full-information settings.  $\Delta$ : suboptimality gap,  $C$ : corruption level

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<b>Proposed algo. 1</b> <b>[This work]</b>	$O\left(\min\left\{\sqrt{nT}, \frac{n}{\Delta}\right\}\right)$	$O(\sqrt{nT})$	$O\left(\min\left\{\sqrt{nT}, \frac{n}{\Delta} + \sqrt{\frac{cn}{\Delta}}\right\}\right)$

Regret bounds for bandit-feedback settings.

Model	Stochastic	Adversarial	Stochastic + adversarial
Bandit submodular SGD [Hazan&Kale, 2012]	$O(nT^{2/3})$	$O(nT^{2/3})$	$O(nT^{2/3})$
<b>Proposed algo. 1</b> <b>[This work]</b>	$\tilde{O}\left(\min\left\{nT^{2/3}, \frac{n^3}{\Delta^2}\right\}\right)$	$\tilde{O}(nT^{2/3})$	$\tilde{O}\left(\min\left\{nT^{2/3}, \frac{n^3}{\Delta^2} + \left(\frac{C^2 n^3}{\Delta^2}\right)^{1/3}\right\}\right)$