

# Improving Mini-batch Optimal Transport via Partial Transportation

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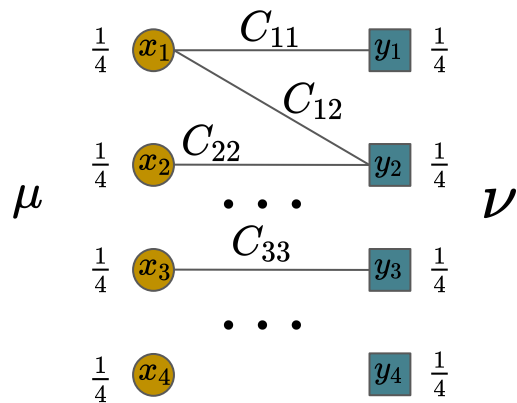
<sup>2</sup>**VinAI Research**

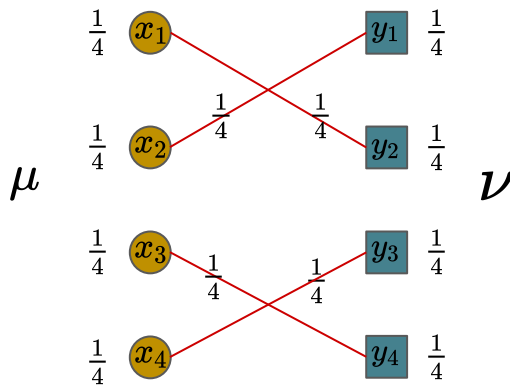


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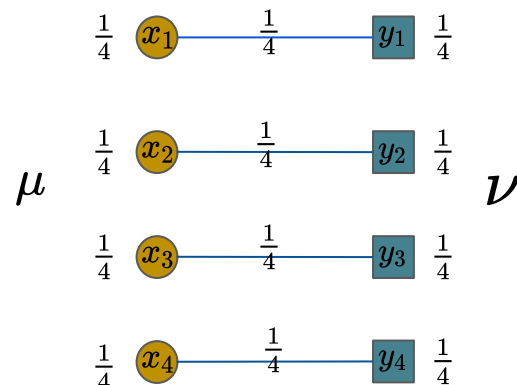
# Optimal Transport



$$C = \begin{matrix} & \begin{matrix} C_{11} & C_{12} & C_{13} & C_{14} \end{matrix} \\ \begin{matrix} C_{21} \\ C_{31} \\ C_{41} \end{matrix} & \begin{matrix} C_{22} \\ C_{32} \\ C_{42} \end{matrix} & \begin{matrix} C_{23} \\ C_{33} \\ C_{43} \end{matrix} & \begin{matrix} C_{24} \\ C_{34} \\ C_{44} \end{matrix} \end{matrix}$$


$$\pi = \begin{matrix} & \begin{matrix} \square & \blacksquare & \square & \square \end{matrix} \\ \begin{matrix} \blacksquare \\ \square \\ \square \end{matrix} & \begin{matrix} \square \\ \square \\ \square \end{matrix} & \begin{matrix} \square \\ \square \\ \square \end{matrix} & \begin{matrix} \square \\ \square \\ \blacksquare \end{matrix} \end{matrix}$$

✗ Not Optimal

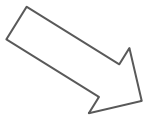


$$\pi^* = \begin{matrix} \begin{matrix} \blacksquare & \square & \square & \square \end{matrix} \\ \begin{matrix} \square \\ \square \\ \square \end{matrix} & \begin{matrix} \blacksquare \\ \square \\ \square \end{matrix} & \begin{matrix} \square \\ \blacksquare \\ \square \end{matrix} & \begin{matrix} \square \\ \square \\ \blacksquare \end{matrix} \end{matrix}$$

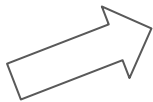
✓ Optimal

# Mini-batch Optimal Transport

The number of supports is large?  
e.g., millions

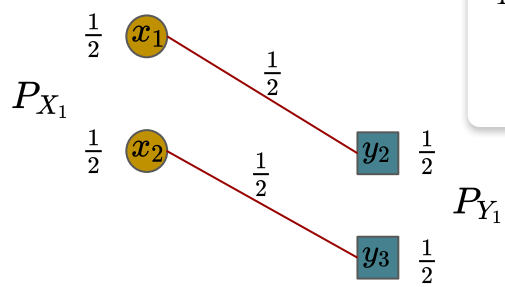
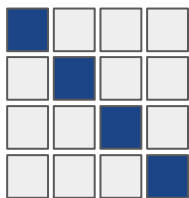
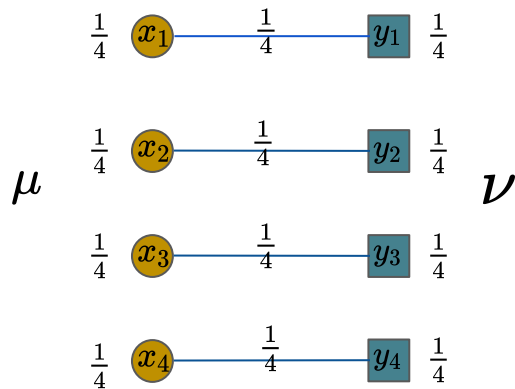


Repeated computation?  
e.g., deep learning

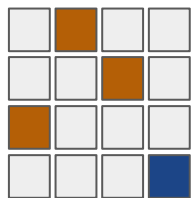


- ❑ Impossible to store the cost matrix  $C$  in the computational graph
- ❑ Slow computation of OT losses which leads to slow training

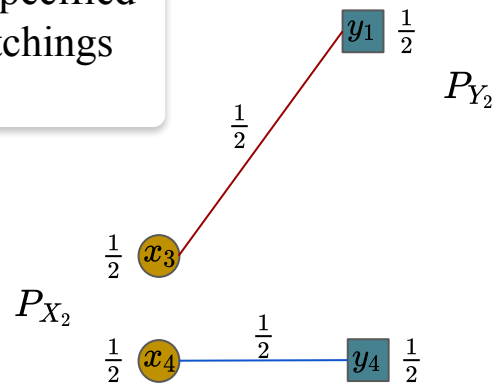
# Mini-batch Optimal Transport



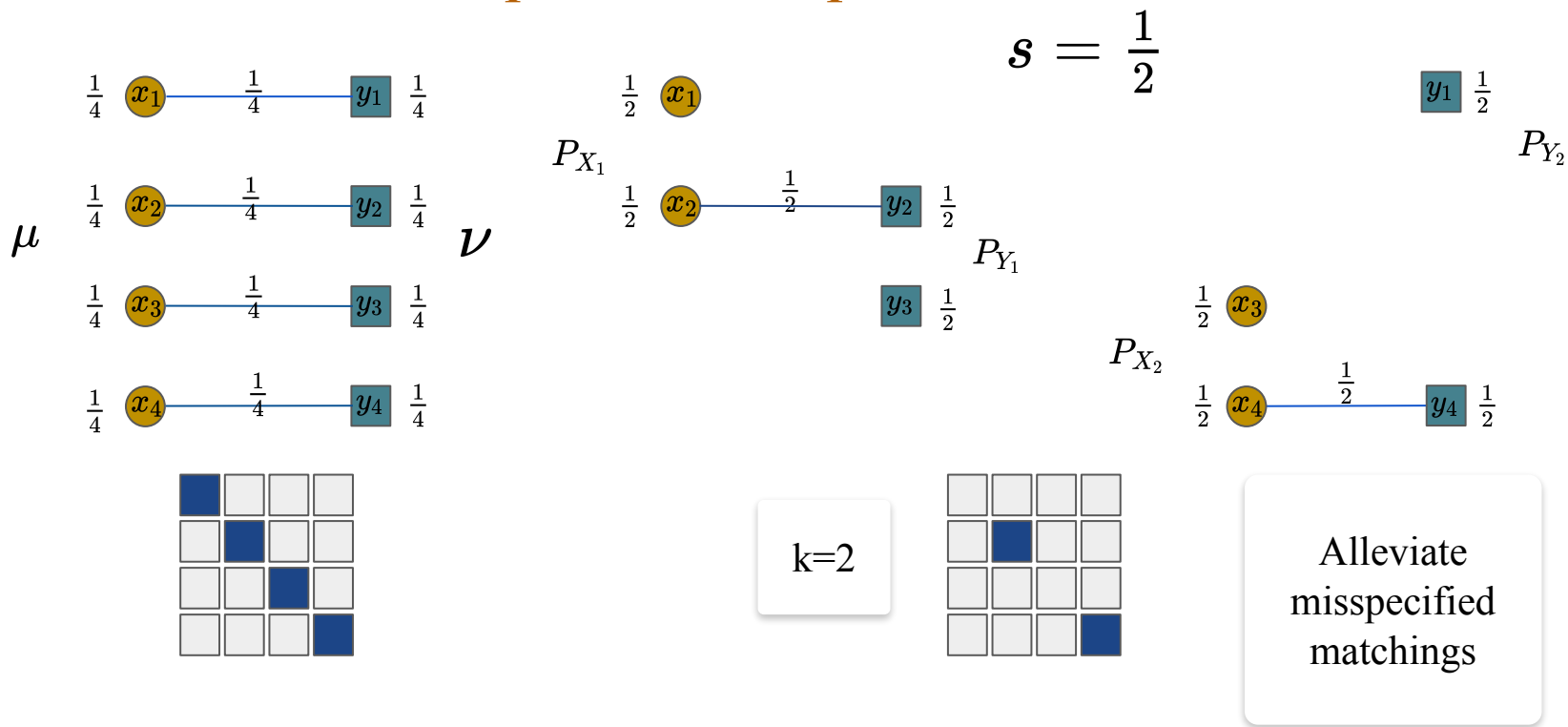
$k=2$



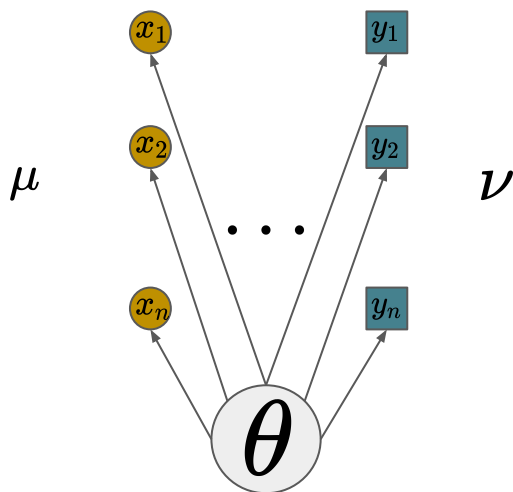
Misspecified matchings



# Mini-batch Partial Optimal Transport



# Training deep networks with m-POT loss



Supports are functions of parameters of neural networks

Set  $\nabla_{\theta}^k = 0$

For  $i = 1$  to  $k$

Compute  $X_i(\theta), Y_i(\theta)$

Compute  $\nabla_{\theta}^k = \nabla_{\theta}^k + \frac{1}{k} \nabla_{\theta} POT^s(P_{X_i(\theta)}, P_{Y_i(\theta)})$

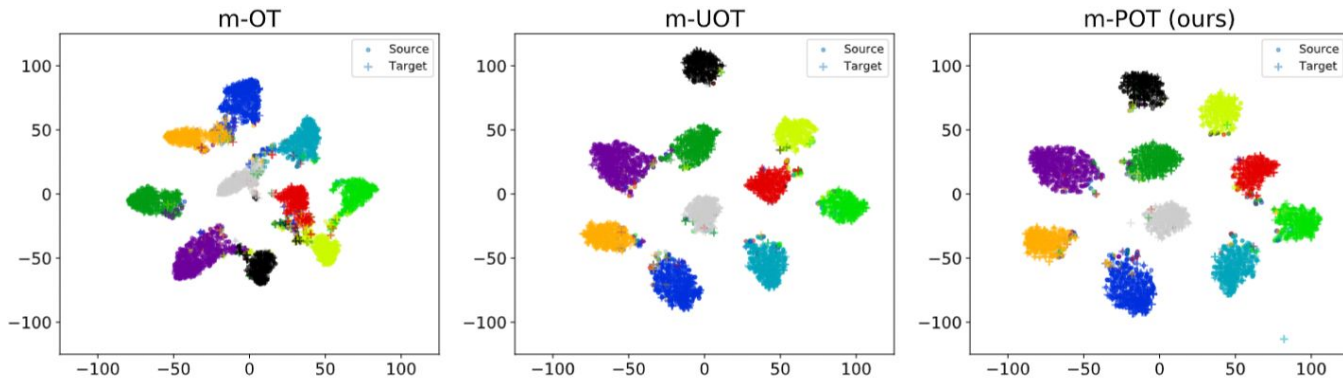
Update  $\theta$  based on the stochastic gradient  $\nabla_{\theta}^k$

- ☐ Only one OT problem in memory at a time
- ☐ Parallel training

# Experiments on Deep Domain Adaptation

## Adapting classification on digits datasets

Method	SVHN to MNIST	USPS to MNIST	MNIST to USPS	Avg
DANN	$95.80 \pm 0.29$	$94.71 \pm 0.12$	$91.63 \pm 0.53$	94.05
ALDA	$98.81 \pm 0.08$	$98.29 \pm 0.07$	$95.29 \pm 0.16$	97.46
m-OT	$94.18 \pm 0.32$	$96.71 \pm 0.24$	$86.93 \pm 1.16$	92.60
m-UOT	$98.89 \pm 0.13$	$98.54 \pm 0.20$	$95.83 \pm 0.05$	97.75
m-POT (Ours)	<b><math>98.98 \pm 0.08</math></b>	<b><math>98.63 \pm 0.13</math></b>	<b><math>96.04 \pm 0.02</math></b>	<b>97.88</b>



# Experiments on Deep Domain Adaptation

## Adapting classification on Office-Home datasets

Method	A2C	A2P	A2R	C2A	C2P	C2R	P2A	P2C	P2R	R2A	R2C	R2P	Avg
RESNET-50 (*)	34.90	50.00	58.00	37.40	41.90	46.20	38.50	31.20	60.40	53.90	41.20	59.90	46.1
DANN	47.92	67.08	74.85	53.80	63.47	66.42	52.99	44.35	74.43	65.53	52.96	79.41	61.93
CDAN-E (*)	52.50	71.40	76.10	59.70	69.90	71.50	58.70	50.30	77.50	70.50	57.90	83.50	66.60
ALDA	54.04	74.89	77.14	61.37	70.62	72.75	60.32	51.03	76.66	67.90	55.94	81.87	67.04
ROT (*)	47.20	71.80	76.40	58.60	68.10	70.20	56.50	45.00	75.80	69.40	52.10	80.60	64.30
m-OT	51.75	70.01	75.79	59.60	66.46	70.07	57.60	47.88	75.29	66.82	55.71	78.11	64.59
m-UOT	54.99	74.45	80.78	65.66	<b>74.93</b>	74.91	64.70	53.42	80.01	74.58	59.88	83.73	70.17
m-POT (Ours)	55.65	73.80	80.76	66.34	74.88	76.16	64.46	53.38	<b>80.60</b>	74.55	59.71	83.81	70.34
TS-OT (Ours)	53.89	71.01	77.13	59.82	69.20	71.95	59.18	51.17	76.54	66.46	56.97	80.19	66.13
TS-UOT (Ours)	56.35	73.56	80.16	65.02	73.12	76.50	63.66	54.49	79.97	71.24	60.11	82.92	69.76
TS-POT (Ours)	<b>57.06</b>	<b>76.13</b>	<b>81.53</b>	<b>68.44</b>	72.82	<b>76.53</b>	<b>66.21</b>	<b>54.87</b>	80.39	<b>75.57</b>	<b>60.50</b>	<b>84.31</b>	<b>71.20</b>

Method	Accuracy
DANN	67.63 $\pm$ 0.34
ALDA	71.22 $\pm$ 0.12
m-OT	62.42 $\pm$ 0.12
m-UOT	72.34 $\pm$ 0.32
m-POT (Ours)	73.59 $\pm$ 0.15
TS-OT (Ours)	69.14 $\pm$ 0.72
TS-UOT (Ours)	70.91 $\pm$ 0.11
TS-POT (Ours)	<b>75.96 <math>\pm</math> 0.44</b>

## Adapting classification on VISDA dataset



# Conclusion

- ❑ Using partial optimal transport (POT) could alleviate misspecified matchings in mini-batch optimal transport:
  - ❑ Replacing OT by POT in mini-batch losses could improve the performance.
- ❑ Two stage training is better than the conventional training when having two computational memories e.g., RAM and GPUs' memory.
- ❑ Future works
  - ❑ Develop algorithms to choose the fraction of masses  $\mathcal{S}$ .

Thank you for listening!

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