

Comprehensive Analysis of Negative Sampling in Knowledge Graph Representation Learning

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Negative Sampling (NS) Loss in Knowledge Graph Embedding (KGE)

Two types of loss functions

In KGE, we commonly use the following loss functions:

- The original NS loss by Mikolov+ 2013

$$-\frac{1}{|D|} \sum_{(x,y) \in D} \left[\log(\sigma(s_{\theta}(x, y))) + \sum_{y_i \sim p_n(y|x)}^{\nu} \log(\sigma(-s_{\theta}(x, y_i))) \right]$$

- The one used for KGE [Sun+ 2019, Ahrabian+ 2020]

$$-\frac{1}{|D|} \sum_{(x,y) \in D} \left[\log(\sigma(s_{\theta}(x, y) + \gamma)) + \frac{1}{\nu} \sum_{y_i \sim p_n(y|x)}^{\nu} \log(\sigma(-s_{\theta}(x, y_i) - \gamma)) \right]$$

Observed data following $p_d(x, y)$: $D = \{(x_1, y_1), \dots, (x_n, y_n)\}$ Noise distribution: $p_n(y|x)$
Score function: $s_{\theta}(x, y)$ Number of negative samples: ν Margin term: γ

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The two loss functions have the different terms

Differences of the Two Loss Functions

Different terms

The two NS loss functions have the following differences:

- The original NS loss does not have the margin term γ different from the NS loss in KGE.
- The NS loss in KGE has the normalization term $1/v$ for the number of negative samples.

We investigated the differences to understand the characteristics of the two loss functions

Our Theoretical Findings

Theoretical analysis

Our theoretical findings:

- 1. Equivalence between the two loss functions**
- 2. Effects of the Margin Term γ**
- 3. Effects of the Number of Negative Samples ν**
- 4. Relationship between the Margin Term γ and the Number of Negative Samples ν .**
- 5. Relationship between the NS loss in KGE and Self-adversarial Negative Sampling (SANS) loss.**
- 6. Subsampling for KGE**

Our Theoretical Findings

Theoretical analysis

Our theoretical findings:

1. Equivalence between the two loss functions

2. We show that the existence of ν and γ has no effect on the distribution that the model
3. will fit when the NS loss reaches the optimal solution.

4. See Prop. 3.1 in our paper for the details.

5. Relationship between the NS loss in KGE and Self-adversarial Negative Sampling (SANS) loss.

6. Subsampling for KGE

Our Theoretical Findings

Theoretical analysis

Our theoretical findings:

1. **Equivalence between the two loss functions**
2. **Effects of the Margin Term γ**
3. **Effects of the Number of Negative Samples v**
4. **Relationship between the Margin Term γ and the Number of Negative Samples v .**
5. We show that to make a **distance-based scoring method** capable to reach the optimal solution, we should tune γ in the NS loss used for KGE and v in the original NS loss.
6. Distance-based scoring: $-||f_{\theta}(x, y)||_p$
 - Used in TransE and RotatE

However, scoring methods with **unlimited value ranges**, such as RESCAL, ComplEx, and DistMult are **not related** to the discussion.

See Props. 3.2, 3.3, 3.4, and 3.5 in our paper for the details.

Our Theoretical Findings

Theoretical analysis

Our theoretical findings:

1. **Equivalence between the two loss functions**
 2. **Effects of the Margin Term γ**
 3. **Effects of the Number of Negative Samples v**
 4. **Relationship between the Margin Term γ and the Number of Negative Samples v .**
 5. **Relationship between the NS loss for KGE and Self-adversarial Negative Sampling (SANS) loss.**
 6. **Subsampling**
- We show that we can consider the SANS loss as the NS loss for KGE when v is enough large and $p_n(y|x) = p_\theta(y|x)$.

$$p_\theta(y|x) = \frac{\exp(s_\theta(x, y))}{\sum_{y' \in Y} \exp(s_\theta(x, y'))}$$

See Prop. 3.6 in our paper for the details.

Our Theoretical Findings

Theoretical analysis

Our theoretical findings:

1. **Equivalence between**
2. **Effects of the Margin**
3. **Effects of the Number**
4. **Relationship between**
5. **Relationship between loss.**
6. **Subsampling for KGE**

To fill in the gap between the distribution of the observed data and a true distribution behind the data, we reformulate the NS loss by introducing functions $A(x, y)$ and $B(x)$ as follows:

The NS loss with subsampling

$$-\frac{1}{|D|} \sum_{(x, y) \in D} A(x, y) \log(\sigma(s_{\theta}(x, y) + \gamma)) + \frac{1}{\nu} \sum_{y_i \sim p_n(y_i | x)} B(x) \log(\sigma(-s_{\theta}(x, y_i) - \gamma))$$

Frequency-based subsampling (Freq)

Unique-based subsampling (Uniq)

$$A(x, y) = \frac{\frac{1}{\sqrt{\#(x, y)}}}{\sum_{(x', y') \in D} \frac{1}{\sqrt{\#(x', y')}}}, B(x) = \frac{\frac{1}{\sqrt{\#x}}}{\sum_{x' \in D} \frac{1}{\sqrt{\#x'}}} \quad A(x, y) = B(x) = \frac{\frac{1}{\sqrt{\#x}}}{\sum_{x' \in D} \frac{1}{\sqrt{\#x'}}}$$

$$\#(x, y) \approx \#(e_i, r_k) + \#(r_k, e_j)$$

See subsection 3.5 in our paper for the details.

Empirical Analysis

Experiments

- We examined whether our theoretical is valid for actual datasets and models shown below.

Datasets

Dataset	Entities	Relations	Tuples		
			Train	Valid	Test
FB15k-237	14,541	237	272,115	17,535	20,466
WN18RR	40,943	11	86,835	3,034	3,134
YAGO3-10	123,182	37	1,079,040	4,978	4,982

Models

Model	Score Function	Parameters
RESCAL	$\mathbf{h}^\top \mathbf{M}_r \mathbf{t}$	$\mathbf{h}, \mathbf{t} \in \mathbb{R}^d$, $\mathbf{M} \in \mathbb{R}^{d \times d}$
DistMult	$\mathbf{h}^\top \text{diag}(\mathbf{r}) \mathbf{t}$	$\mathbf{h}, \mathbf{r}, \mathbf{t} \in \mathbb{R}^d$
ComplEx	$\text{Re}(\mathbf{h}^\top \text{diag}(\mathbf{r}) \bar{\mathbf{t}})$	$\mathbf{h}, \mathbf{r}, \mathbf{t} \in \mathbb{C}^d$
TransE	$- \mathbf{h} + \mathbf{r} - \mathbf{t} _p$	$\mathbf{h}, \mathbf{r}, \mathbf{t} \in \mathbb{R}^d$
RotatE	$- \mathbf{h} \circ \mathbf{r} - \mathbf{t} _p$	$\mathbf{h}, \mathbf{r}, \mathbf{t} \in \mathbb{C}^d, r_i = 1$, $\mathbf{h}, \mathbf{t} \in \mathbb{R}^d, \mathbf{r} \in \mathbb{R}_+^d$
HAKE	$- \mathbf{h} \circ \mathbf{r} - \mathbf{t} _p$ $-\lambda \sin((\mathbf{h}' + \mathbf{r}' - \mathbf{t}')/2) _1$	$\mathbf{h}', \mathbf{r}', \mathbf{t}' \in [0, 2\pi)^d$, $\lambda \in \mathbb{R}$

- We confirmed that the observed Mean Reciprocal Ranks (MRRs) are along with our theoretical analysis.
 - See section 4 in our paper for the details.

Conclusion

Our analysis

- We conducted a theoretical analysis for the NS loss used in KGE learning and derived theoretical facts.
- The experimental results indicate that the theoretical facts we derived are also observed in the real-world datasets.