



State Transition of Dendritic Spines Improves Learning of Sparse Spiking Neural Networks

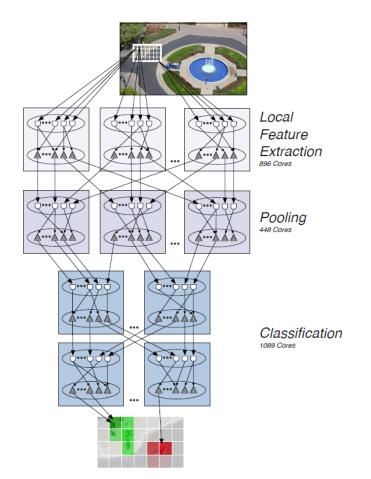
Yanqi Chen ¹² Zhaofei Yu ^{† 12 3} Wei Fang ¹² Zhengyu Ma ^{† 2} Tiejun Huang ^{12 3} Yonghong Tian ^{† 12}

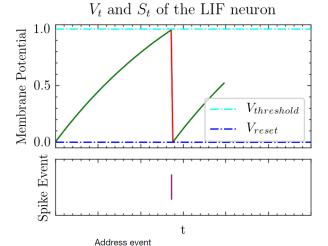
Speaker: Yanqi Chen

Introduction

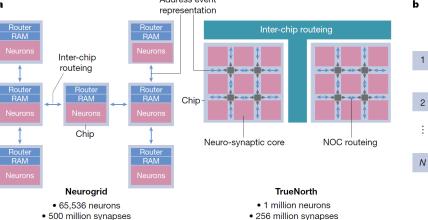
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Spiking Neural Networks (SNNs)

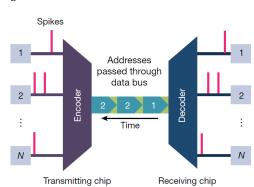




Dynamic of the Leaky Integrate-and-Fire Neurons (Constant input)



• Analog mixed-signal design



Borrowed from Roy, Kaushik, et al. "Towards spike-based machine intelligence with neuromorphic computing." *Nature* 575.7784 (2019): 607-617.

· Custom digital design

Borrowed from Merolla, Paul A., et al. "A million spiking-neuron integrated circuit with a scalable communication network and interface." *Science* 345.6197 (2014): 668-673.



Motivation



Directly trained SNNs are going deeper

Restricted number of synapses in a single neuromorphic chip



Motivation



Directly trained SNNs are going deeper



· Restricted number of synapses in a single neuromorphic chip



Motivation



Directly trained SNNs are going deeper



Restricted number of synapses in a single neuromorphic chip

	Max # Neuron	Max # Synapse
SpiNNaker	1.6×10 ⁴	1.6×10 ⁷
DYNAPs	10 ³	6.4×10 ⁴
TrueNorth	10 ⁶	2.56×10 ⁸
Loihi	1.3×10 ⁵	1.3×10 ⁸
BrainScaleS	512	14080
Tianjic	4×10 ⁴	10 ⁷
Darwin 2	1.5×10 ⁴	>107



Contributions



- Bio-inspired pruning algorithm for deep SNNs
 - I. Inspired by filopodial model of spinogenesis
 - II. Theoretical proof of convergence
 - III. SOTA low performance loss on ImageNet and deep SNN
 - IV. In-depth discussion of pruning settings



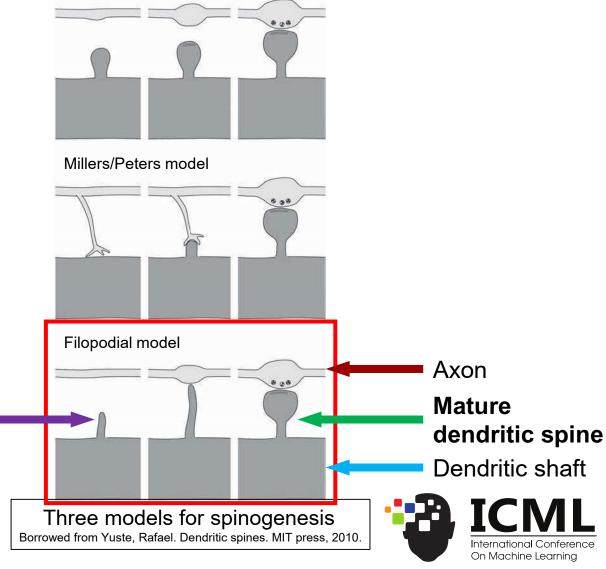
Filopodial Model

- Spinogenesis—The emergence of dendritic spines
 - Connect dendrite to axon terminal
 - Form synapse between neurons
 - Changes of spine size and shape
- Synaptic weight & Spine size
 - Positive correlation

Dendritic Filopodia

- 1. Precursors of dendritic spines
- 2. Lack clear heads (w.r.t. mature spines)
- 3. No synaptic contact





Sotelo model

Filopodium

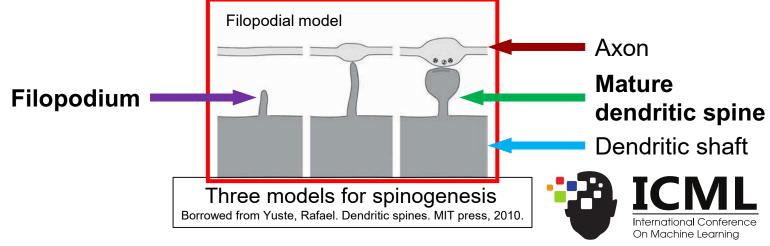
Filopodial Model

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Dendritic Filopodia

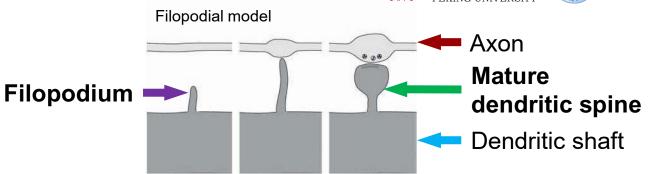
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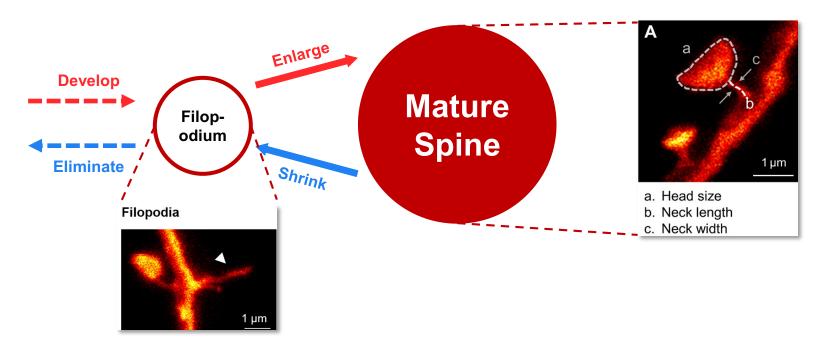


Filopodial Model

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- Pruning model
 - Transition from mature spine → filopodium
- Weight learning & Structure learning



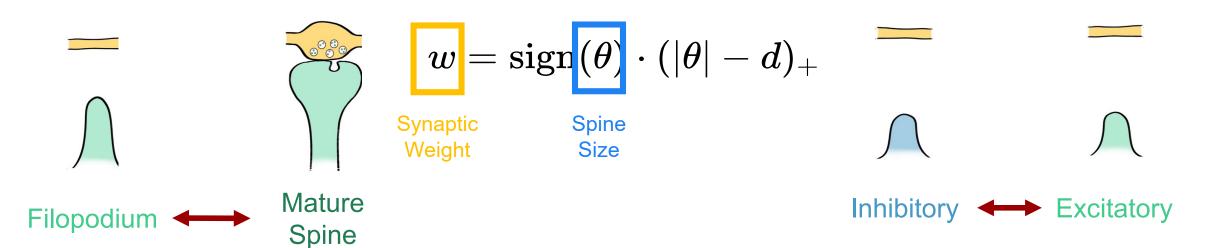




Reparameterization of Weights



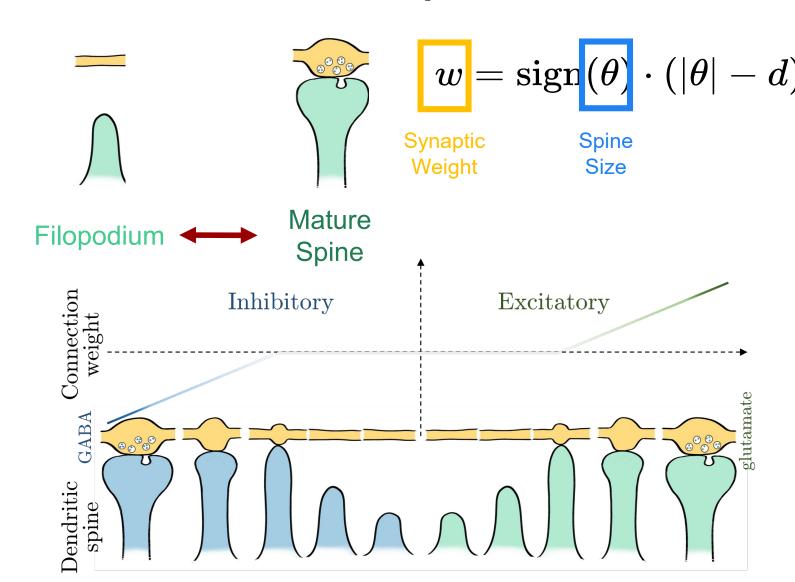
Model transitions of spines in two folds

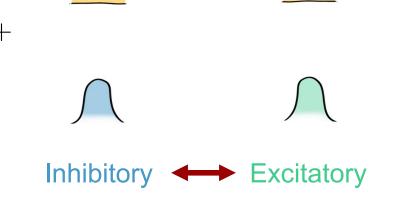


Reparameterization of Weights



Model transitions of spines in two folds

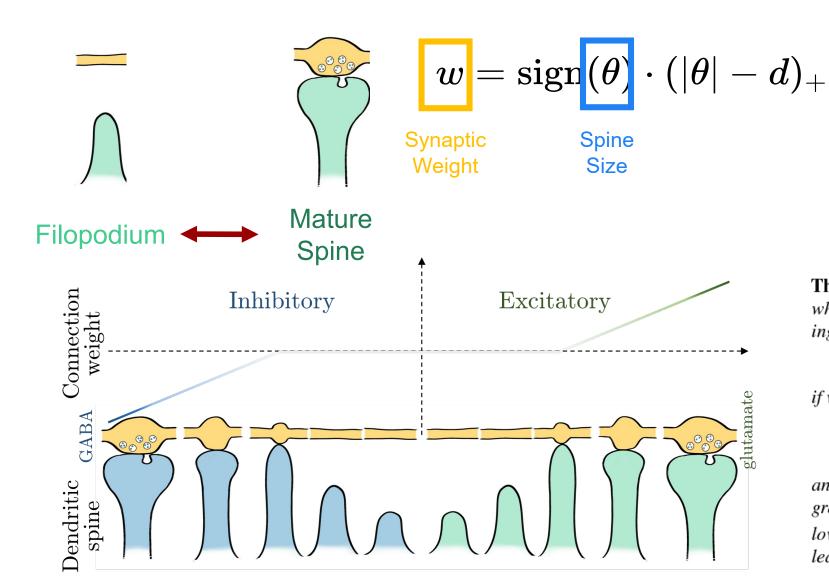


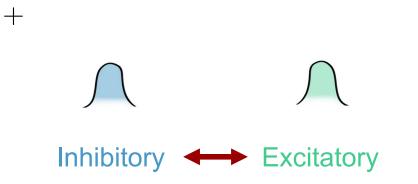


Reparameterization of Weights



Model transitions of spines in two folds





Theorem 4.1 (Convergence). For a spiking neural network, where each synaptic weight w is dominated by corresponding spine size θ through a soft threshold mapping

$$w = \operatorname{sign}(\theta) \cdot (|\theta| - d)_+, d \ge 0, \tag{18}$$

if we apply a smooth approximation

$$w = f(\theta) := \frac{1}{\alpha} \log \left(\frac{1 + e^{\alpha(\theta - d)}}{1 + e^{-\alpha(\theta + d)}} \right), \alpha \gg 1, \quad (19)$$

and define the pseudo partial derivative during computing gradients as $\frac{\partial w}{\partial \theta}_p \equiv 1$, the loss function \mathcal{L} is L-smooth and lower bounded, the sequence $\{\mathcal{L}(\theta^t)\}_{t\in\mathbb{N}}$ must converge if learning rate $\eta < \frac{4}{L(1+e^{\alpha d})}$.

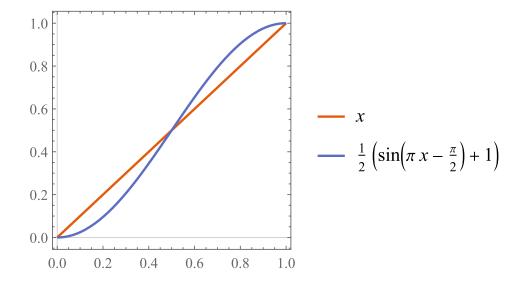
Threshold Scheduler



Increasing threshold of soft threshold function over training process

$$d^t = D \cdot f(t/T)$$

• Choice of scheduler function *f*



Act as proximal gradient descent under L1 regularized loss

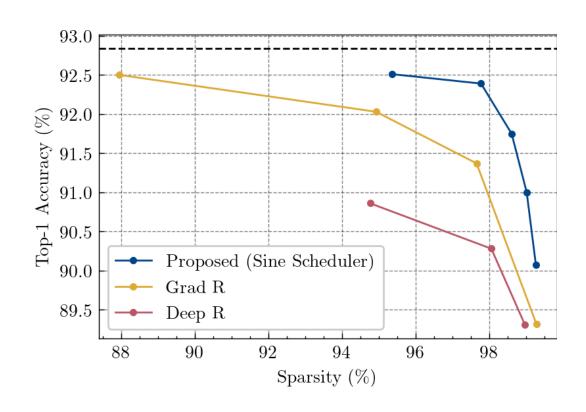
$$oldsymbol{w}^t = \operatorname*{argmin}_{oldsymbol{w}} \left\{ rac{1}{2\eta} \|oldsymbol{w} - (oldsymbol{w}^{t-1} \eta
abla_{oldsymbol{w}} \mathcal{L}(oldsymbol{w}^{t-1})) \|_2^2 + \Delta d^t \|oldsymbol{w}\|_1
ight\}$$



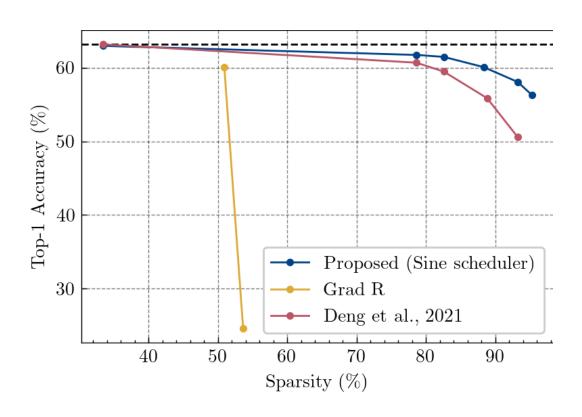
Results



Acc. vs Sparsity



CIFAR-10



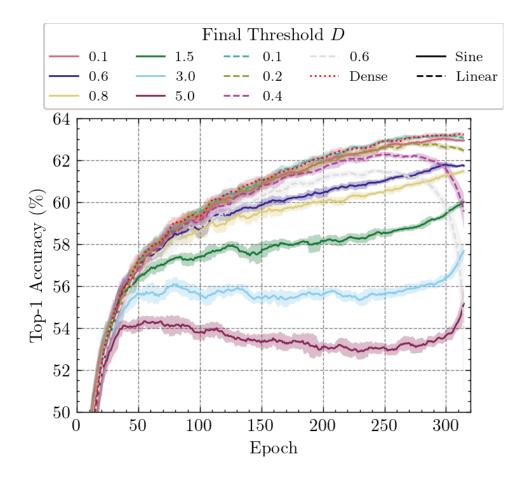
ImageNet



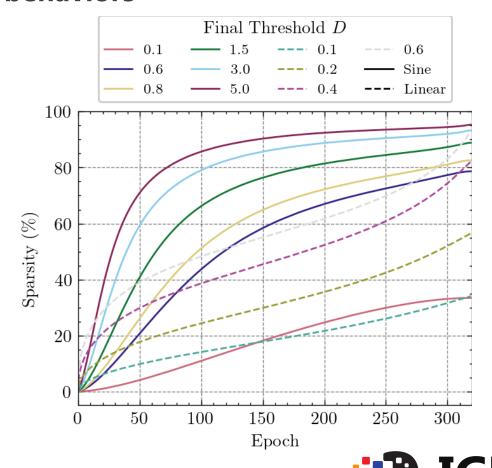
Results



• Final threshold *D* control the sparsity



Different schedulers has different behaviors

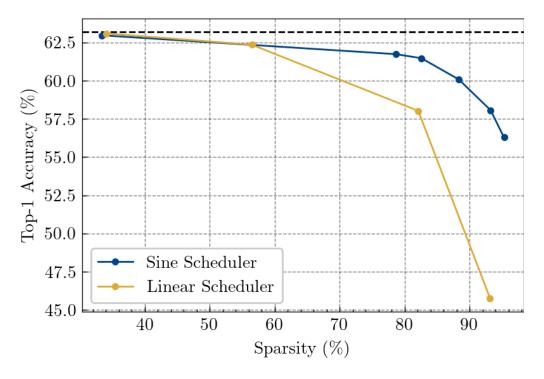


On Machine Learning

Results



- Choice of schedulers matters
 - Sine > Linear



• Sine has milder penalty at the end of training stage



Summary & Discussion



A pruning method for really deep SNNs

- Gradient-based method coupled with any directly trained SNNs
- Effcient Low accuracy loss under high sparsity

Based on elaborate model of synapses

- Bio-plausibility
- May shed light on more meticulously designed models

Future work

- Pursuing the optimal threshold schedulers
- Adding more biological ingredients (More Yummy!)

