# Tackling covariate shift with node-based Bayesian neural networks

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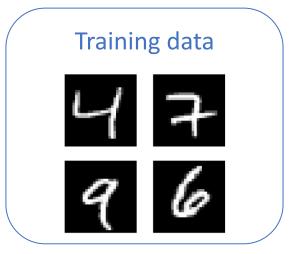


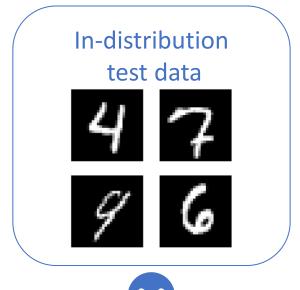




## Background

#### Covariate shift









#### Shift due to corruptions



Shifts due to corruptions



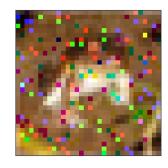
#### Neural networks under input corruptions

#### Corruption severity

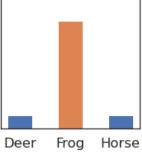


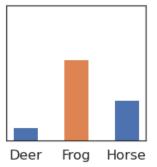


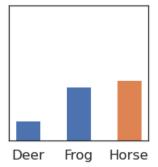


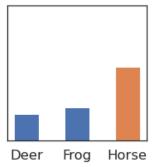


Typical behavior

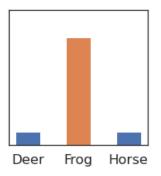


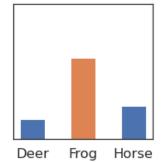


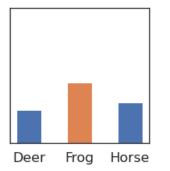


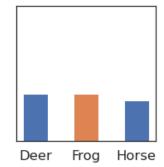


Desirable behavior



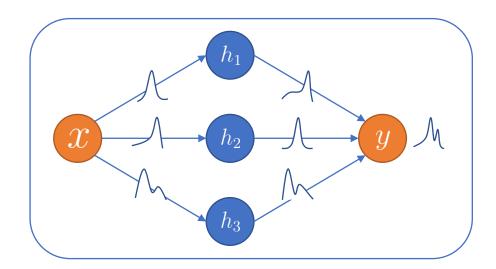






#### Bayesian neural networks (BNNs)

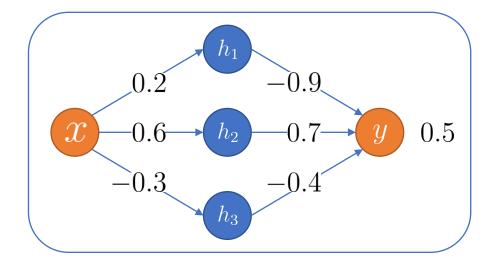
Bayesian neural network



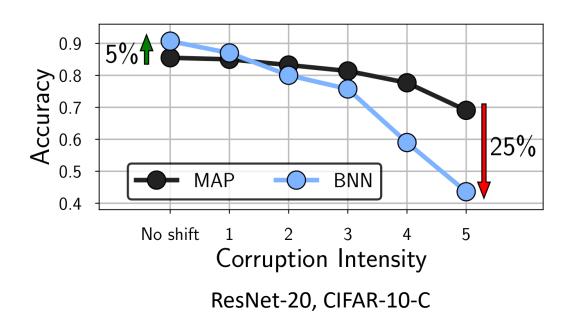


Thomas Bayes

Standard neural network



#### BNNs perform worse than MAP models under corruptions<sup>1</sup>



Why? Because the standard Gaussian prior does not provide good inductive biases to handle input corruptions.<sup>2</sup>

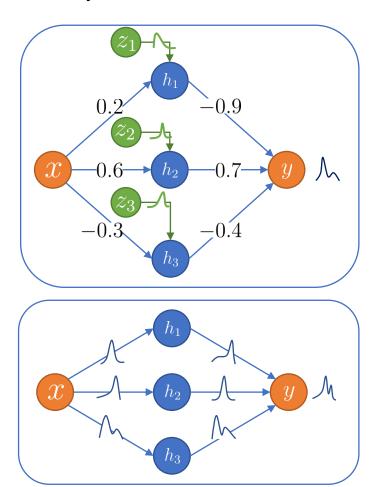
<sup>&</sup>lt;sup>1</sup>Izmailov et al. (2021). What are Bayesian neural network posteriors really like?

<sup>7</sup> 

#### Node-based Bayesian neural networks

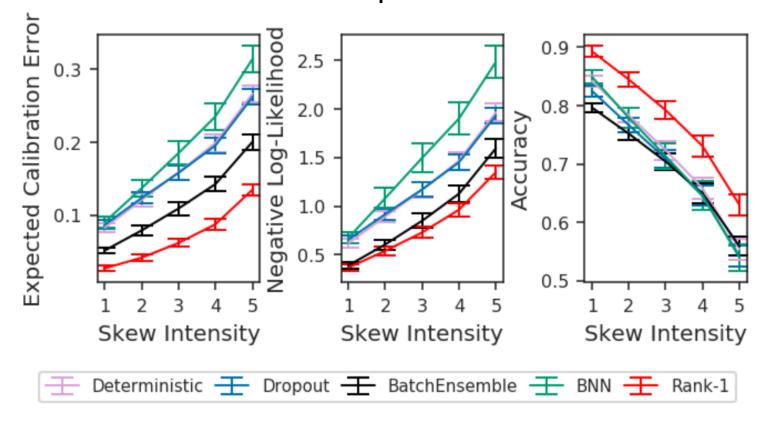
Node-BNNs

Weight-BNNs



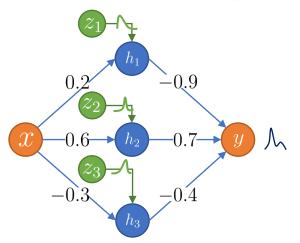
E.g.: MC-Dropout (Gal et al, 2015), Rank-1 BNNs (Dusenberry et al, 2020)

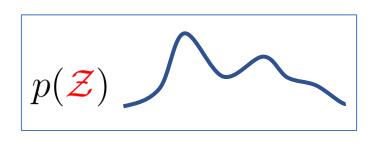
## Node-BNNs perform better than MAP models under corruptions



WideResNet-28-10 / CIFAR-10-C

#### Node-based Bayesian neural networks





An L-layer node-BNN with latent variables  $\mathcal{Z} = \{z^{(\ell)}\}_{\ell=1}^L$ :

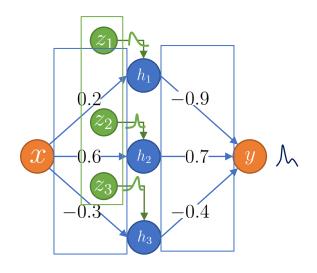
$$\mathcal{Z} = \{z^{(\ell)}\}_{\ell=1}^L$$
 :

Previous layer's output Latent node variables  $f_{in}^{(\ell)} = f^{(\ell-1)}(x; \mathbf{Z}) \circ z^{(\ell)}$  $f^{(\ell)}(x; \mathbf{Z}) = \sigma \left( W^{(\ell)} f_{in}^{(\ell)} + b^{(\ell)} \right)$ 

For 
$$\mathcal{Z} \sim p(\mathcal{Z})$$
:

For 
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: 
$$f(x; \mathbf{Z}) = f^{(L)}(x; \mathbf{Z})$$

#### Node-based Bayesian neural networks



		Parameters		
Network	Layers	weights	nodes	w/n ratio
LeNet	5	42K	23	/1800x
AlexNet	8	61M	18,307	3300x
VGG16-small	16	15M	5,251	2900x
VGG16-large	16	138M	36,995	3700x
ResNet50	50	26M	24,579	1000x
WideResNet-28x10	28	36M/	9,475	\3800x

#### Two types of parameters:

- 1. Weights and biases  $\theta = \{(W^{(\ell)}, b^{(\ell)})\}_{\ell=1}^L$ 
  - → Find a MAP estimate.
- 2. Latent node variables  $\mathcal{Z} = \{z^{(\ell)}\}_{\ell=1}^L$ 
  - → Infer the posterior distribution.
- → Node BNNs are efficient alternatives to standard weight-based BNNs.

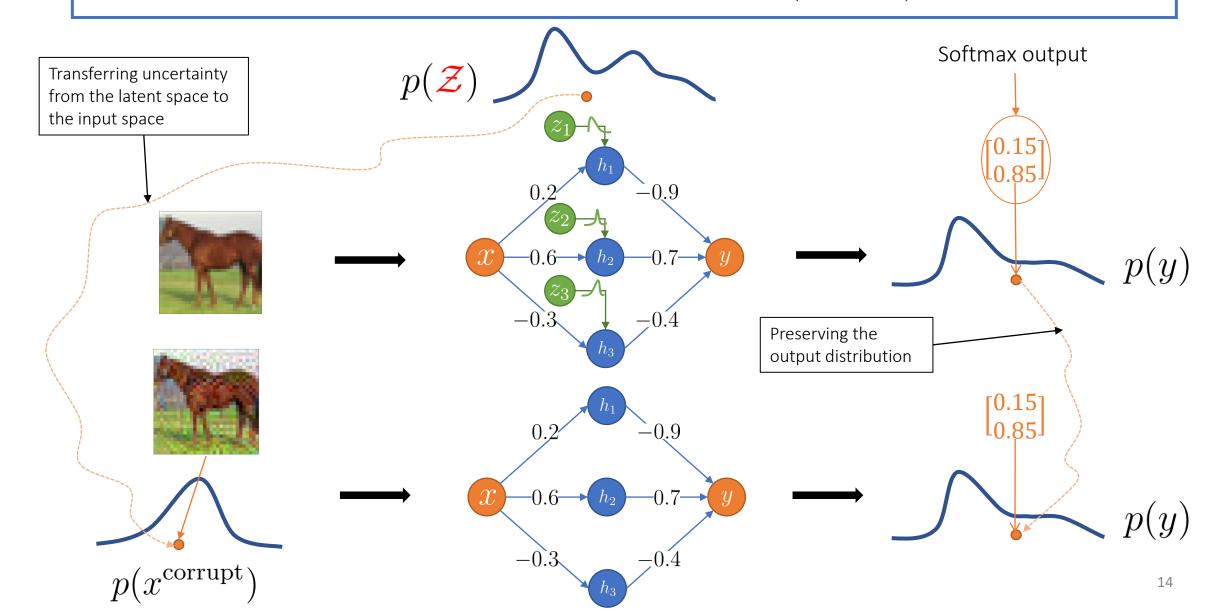
#### Our paper's goals

Providing insights into the robustness of node-based BNNs under input corruptions.

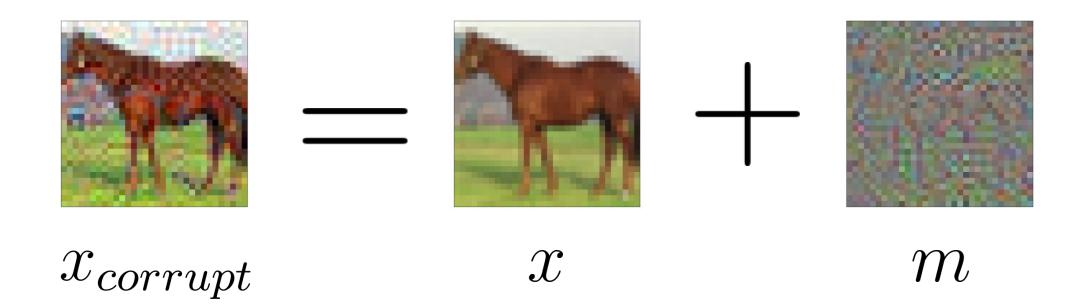
Proposing a method to further improve the robustness of node-based BNNs in this setting.

Why do node-based BNNs generalize well under input corruptions?

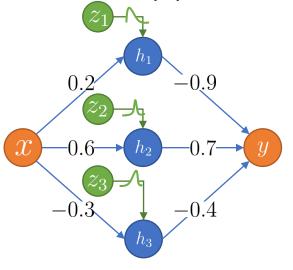
We hypothesize that the distribution of the latent variables p(Z) induce a distribution of implicit corruptions in the input space  $p(x^{\text{corrupt}})$ .



#### Approximating the implicit corruption



#### Approximating the implicit corruption



$$\begin{array}{c|c}
 & h_1 \\
\hline
0.2 & -0.9 \\
\hline
0.6 & h_2 & -0.7 \\
\hline
-0.3 & -0.4 \\
\hline
h_3 & -0.4
\end{array}$$

$$f(x; \mathbf{Z})$$

$$\hat{f}(x) = f(x; \mathbf{Z} = \mathbf{1})$$

Given  $\mathcal{Z} \sim p(\mathcal{Z})$  , approximating  $\, \mathcal{M} \,$  minimizing the following loss function using GD:

$$\frac{1}{2} \left| \left| f(x; \mathbf{Z}) - \hat{f}(x+m) \right| \right|_{2}^{2} + \frac{\lambda}{2} ||m||_{2}^{2}$$
Output matching

Output matching

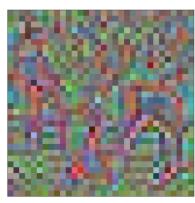
L2-regularization

#### Example of implicit corruptions

#### Severity

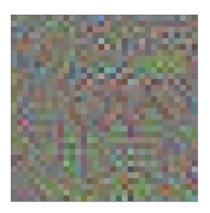






$$\lambda = 0.03$$





$$\lambda = 0.1$$

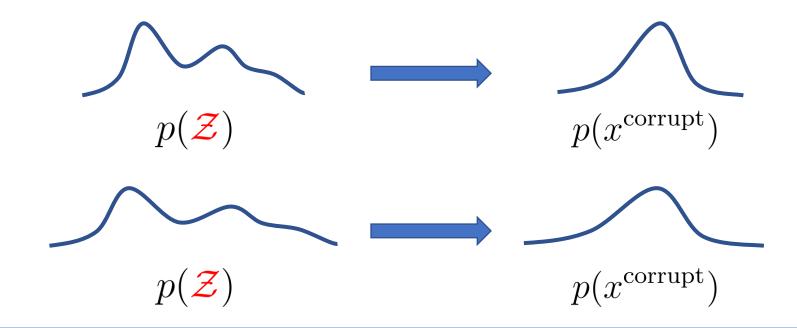




$$\lambda = 0.3$$



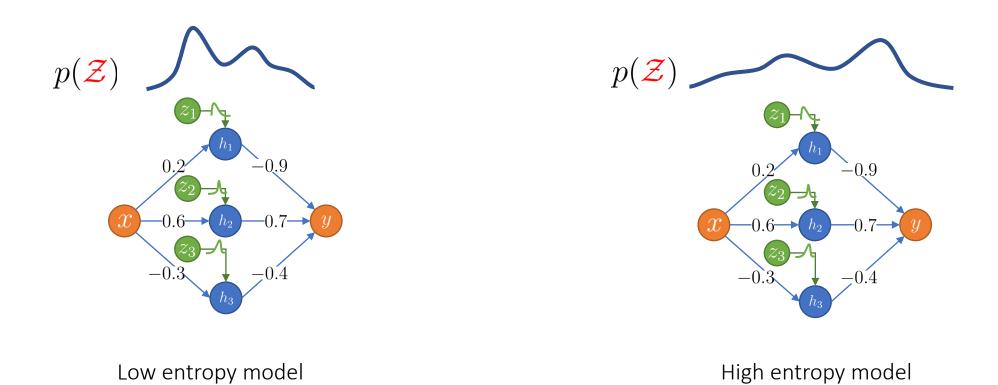
#### Entropy of latent variables and implicit corruptions



#### We hypothesize that:

- 1. Increasing the entropy of the latent variables  $\overline{\mathcal{Z}}$  increase the diversity of the implicit corruptions.
- 2. By training under more diverse implicit corruptions, node-based BNNs become more robust against natural corruptions.

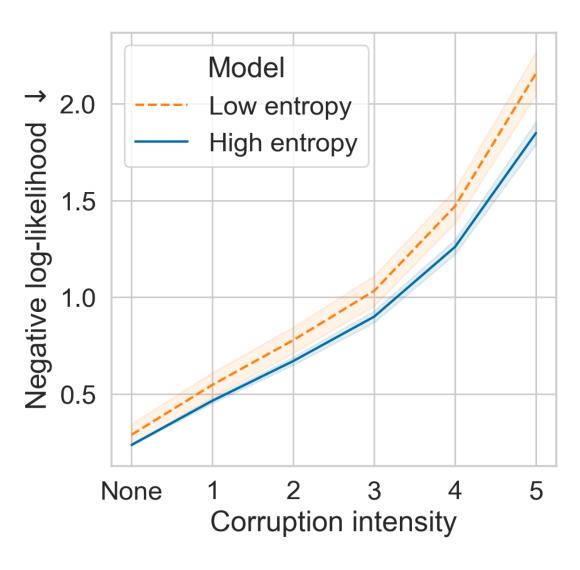
Is it true that "higher entropy = more robust node-based BNNs"?



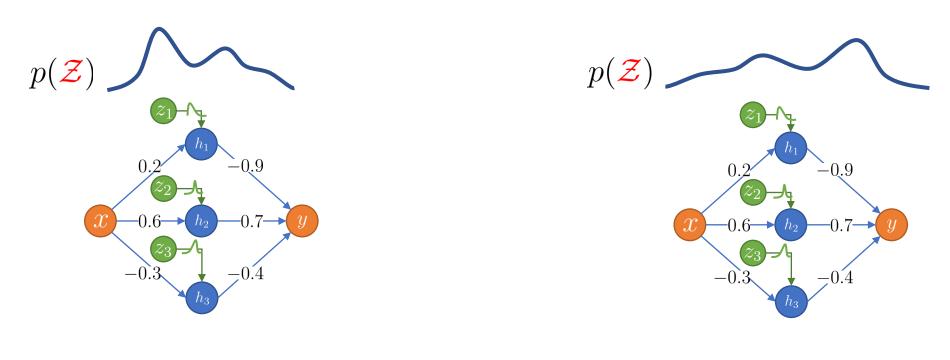
Same ConvNet architecture
Train on CIFAR-10
Test on CIFAR-10-C

Is it true that "higher entropy = more robust node-based BNNs"?

YES!!!



#### Is a model robust against its own corruptions?



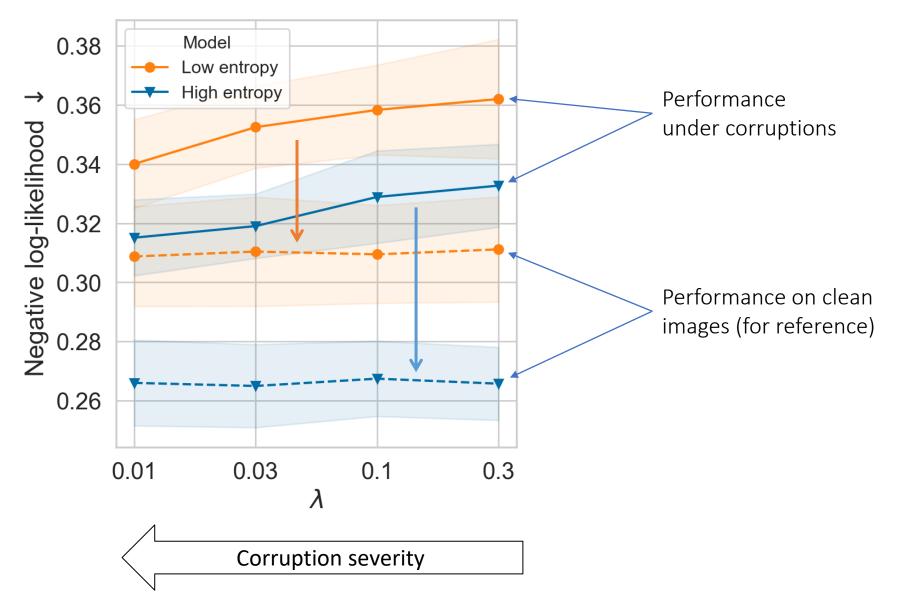
We use each model to generate a set of corrupted test images, then evaluate each model on its own generated corruptions.

Low entropy model

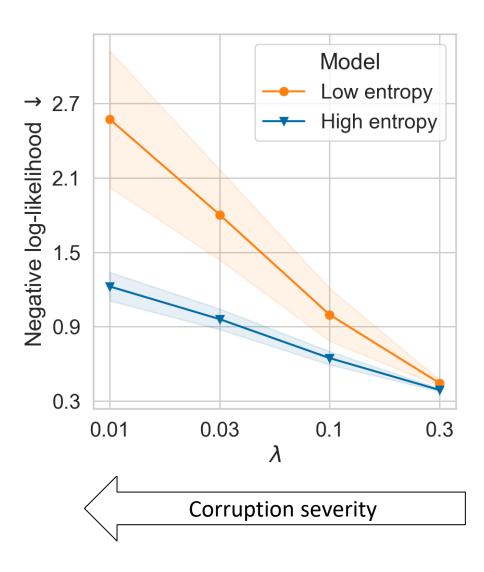
High entropy model

#### Is a model robust against its own corruptions?

#### YES (in this small experiment)

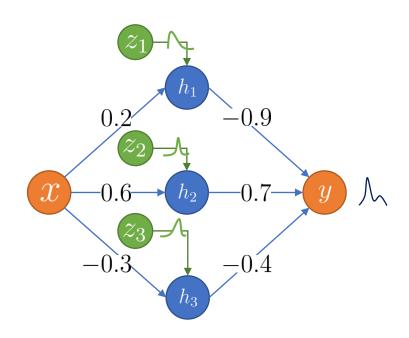


#### How robust is a model against the other model's corruptions?



## How to increase the latent entropy?

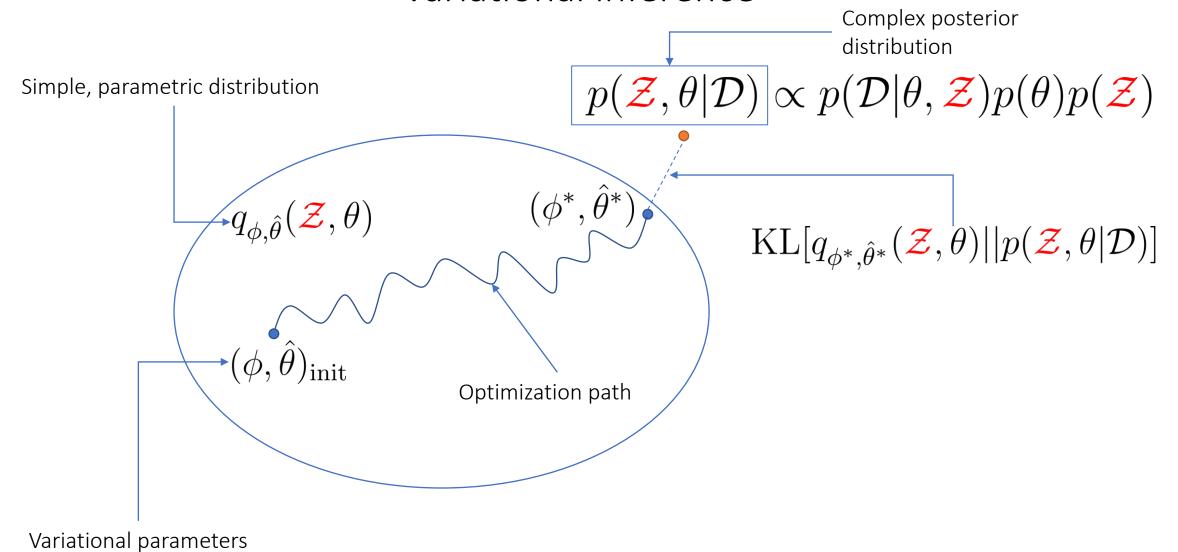
#### Training a node-based BNN



Two types of parameters:

- 1. Weights and biases  $\theta = \{(W^{(\ell)}, b^{(\ell)})\}_{\ell=1}^L$  with a prior  $p(\theta)$ .
  - → Find a MAP estimate.
- 2. Latent node variables  $\mathbf{Z} = \{z^{(\ell)}\}_{\ell=1}^L$  with a prior  $p(\mathbf{Z})$ .
  - → Infer the posterior distribution.

#### Variational inference



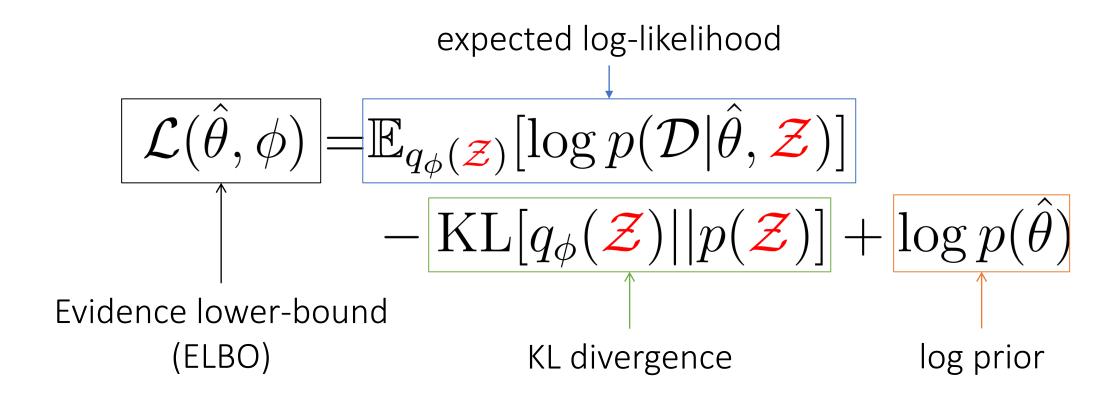
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#### Variational posterior

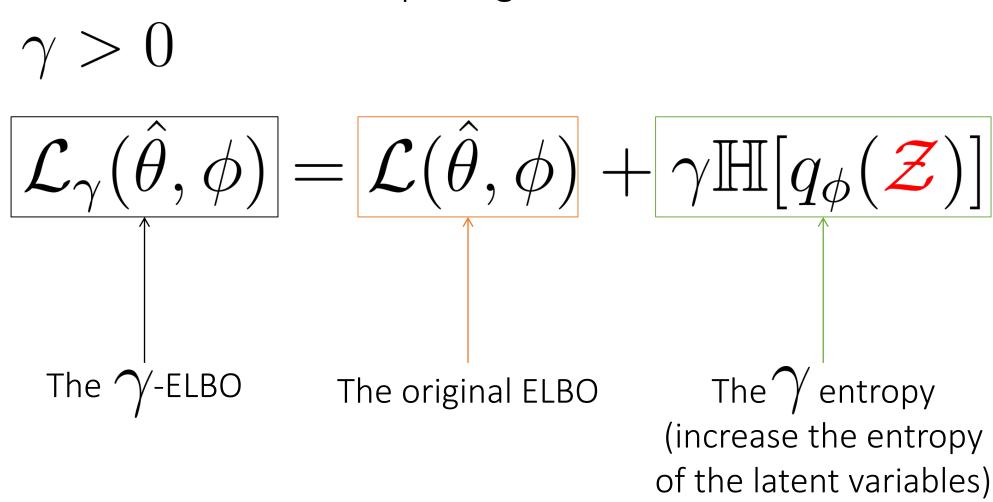
$$q_{\phi,\hat{\theta}}(\mathcal{Z},\theta) = q_{\hat{\theta}}(\theta)q_{\phi}(\mathcal{Z})$$
 
$$= \delta(\theta - \hat{\theta})q_{\phi}(\mathcal{Z})$$
 Dirac delta measure (for MAP estimation) Mixture of Gaussians MAP estimation of  $\theta$ 

#### Training objective

We find  $(\hat{\theta}, \phi)$  maximizing the following objective using SGD:



#### Entropic regularization

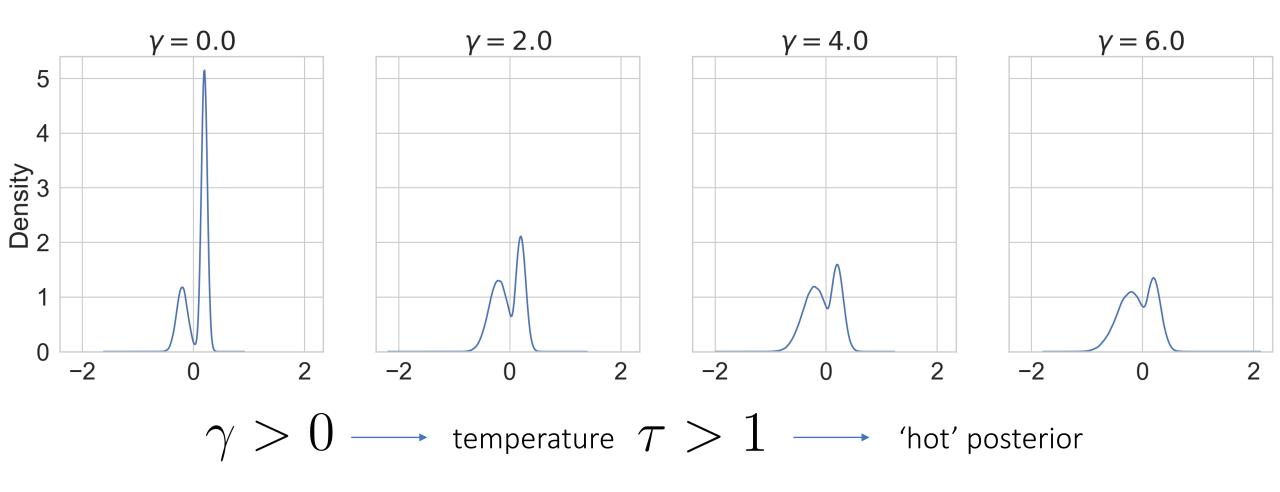


The 
$$\gamma$$
 – ELBO = tempered posterior

Maximizing the  $\gamma$  – ELBO is equivalent to minimizing:

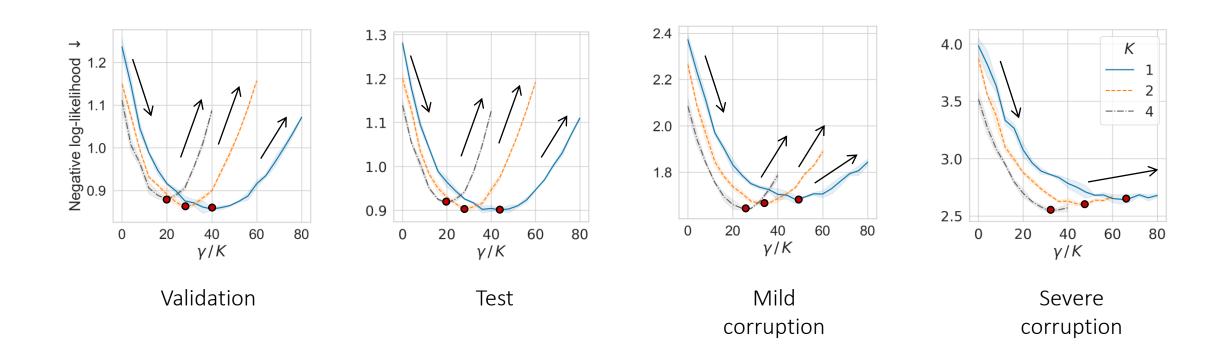
$$\begin{split} \mathrm{KL}[q_{\phi,\hat{\theta}}(\boldsymbol{\mathcal{Z}},\boldsymbol{\theta})||p_{\gamma}(\boldsymbol{\mathcal{Z}},\boldsymbol{\theta}|\boldsymbol{\mathcal{D}})] \\ p_{\gamma}(\boldsymbol{\mathcal{Z}},\boldsymbol{\theta}|\boldsymbol{\mathcal{D}}) &\propto p(\boldsymbol{\mathcal{D}}|\boldsymbol{\mathcal{Z}},\boldsymbol{\theta})^{\frac{1}{\gamma+1}}p(\boldsymbol{\mathcal{Z}},\boldsymbol{\theta})^{\frac{1}{\gamma+1}} \end{split}$$
 Temperature  $\tau = \gamma + 1$ 

#### Effects of $\gamma > 0$ on the target posterior.



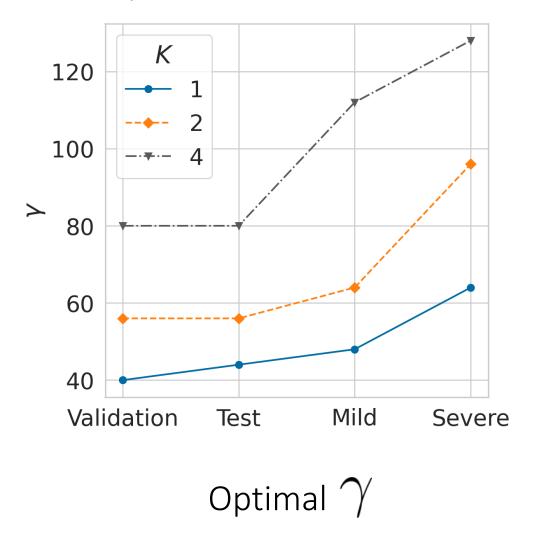
### Ablation study

#### Effects of $\gamma$ on corruption robustness



VGG16 / CIFAR-100. Test on CIFAR-100-C K: number of Gaussian components in  $q_{\phi}(\mathcal{Z})$ .

#### Effects of $\gamma$ on corruption robustness



More severe corruptions require higher optimal  $\gamma$ 

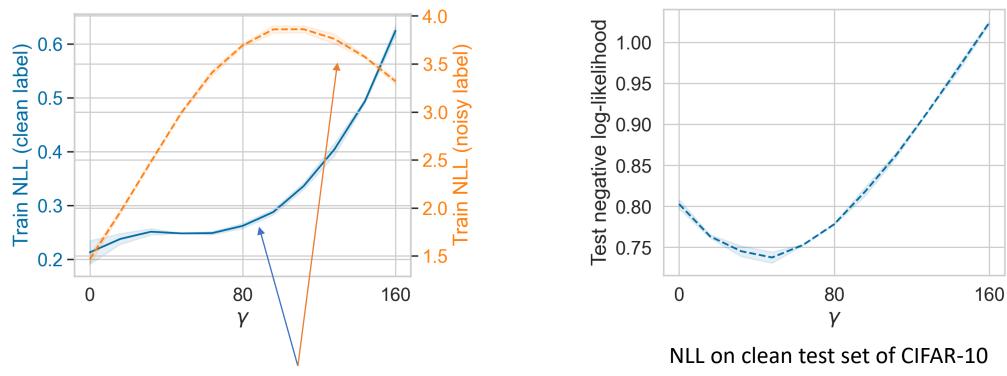
#### Robust learning under label noise

Memorizing random labels is harder than learning generalizable patterns<sup>1</sup>



If a sample with a wrong label is corrupted with sufficiently diverse corruptions, the model fails to memorize this wrong label.

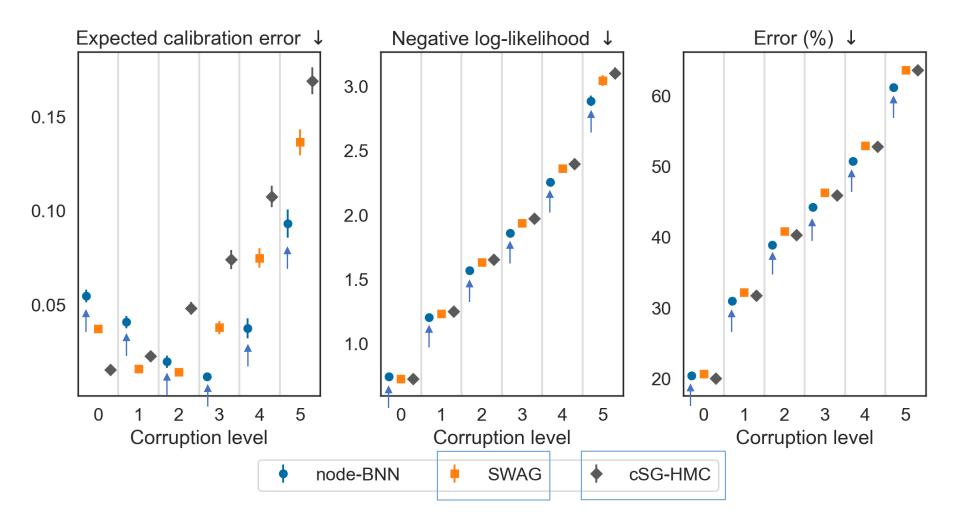
#### Robust learning under label noise



Train NLL of wrongly labelled samples (in orange) increase much faster than the train NLL of correctly labelled samples (in blue)

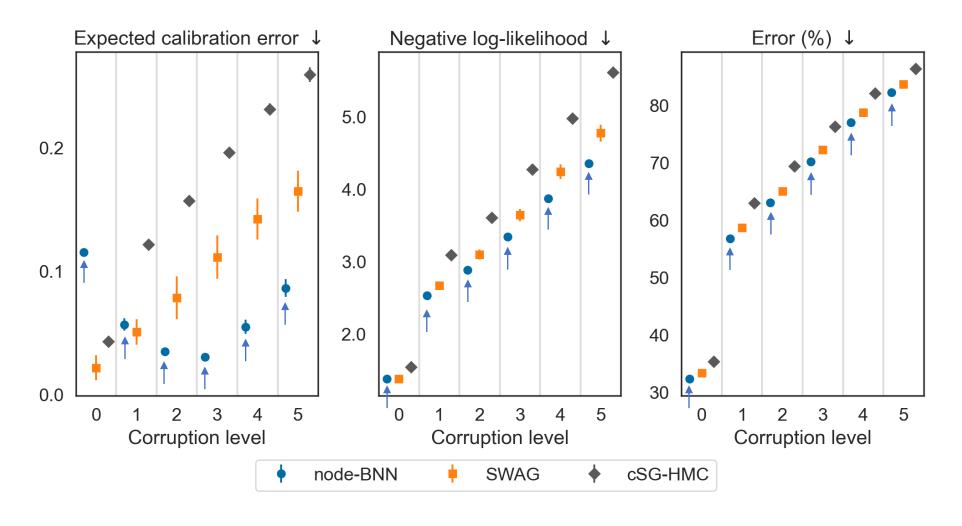
ResNet18 / CIFAR-10 40% of training labels are corrupted

#### Benchmark comparison



ResNet18 / CIFAR-100

#### Benchmark comparison



PreActResNet18 / TinyImageNet

#### Conclusion

We showed that the latent variables simulated a set of implicit corruptions, and by training under these corruptions, node-based BNNs become robust against natural corruptions.

By maximizing the entropy of the latent variables, we increase the diversity of the implicit corruptions and thus improve the robustness of node-based BNNs.

We demonstrated that the latent entropy controls the trade-off between in-distribution performance and performance under corruptions, with more severe corruptions require higher optimal latent entropy which decreases the in-distribution performance.

As a side effect, our method also provides robustness against noisy training labels.

For more information visit:

