

Asymptotically-Optimal Gaussian Bandits with Side Observations

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Gaussian Bandits with Side Observations

Model (introduced in Wu, Györfgy, and Szepesvári 2015):

- ▶ K Gaussian arms with (unknown) mean rewards (μ_1, \dots, μ_K)
- ▶ Known feedback matrix $\Sigma = (\sigma_{i,j})_{i,j \in [K]}$
- ▶ At each round t , by playing an action $i \in [K]$ the player:
 - ▶ collects $X_{i,t} \sim \mathcal{N}(\mu_i, \sigma_{i,i}^2)$
 - ▶ observes $X_{j,t} \sim \mathcal{N}(\mu_j, \sigma_{i,j}^2)$ for each arm $j \in [K]$
 - ▶ (rewards are realized independently)

Goal: Maximize the total expected reward collected

Gaussian Bandits with Side Observations

Previous related work:

- ▶ Wu, György, and Szepesvári 2015: asymptotically optimal regret for the special case where $\sigma_{i,j} \in \{\sigma, \infty\}$
- ▶ Graph-structured feedback: Given (directed) graph of arms (nodes), playing arm i reveals the (not necessarily Gaussian) reward of every adjacent arm

Our contribution:

- ▶ Asymptotic LP lower bound for the case of general feedback $\Sigma = (\sigma_{i,j})_{i,j \in [\kappa]}$
- ▶ An asymptotically optimal LP-based bandit algorithm for the general setting

Linear Programming-based Lower Bound

Formulation: For any reward vector $\mu \in [0, \infty)^K$, we define:

$$C(\mu) = \left\{ c \in [0, \infty)^K : \begin{array}{l} \sum_{j \in [K]} \frac{c_j}{\sigma_{j,i}^2} \geq \frac{2}{\Delta_i^2(\mu)}, \forall i \neq i^*(\mu) \\ \sum_{j \in [K]} \frac{c_j}{\sigma_{j,i}^2} \geq \frac{2}{\Delta_{\min}^2(\mu)}, i = i^*(\mu) \end{array} \right\},$$

where $i^*(\mu) = \operatorname{argmax}_{i \in [K]} \mu_i$, $\Delta_i(\mu) = \max_{j \in [K]} \mu_j - \mu_i$, and $\Delta_{\min}(\mu) = \min_{i \in [K], \Delta_i(\mu) > 0} \Delta_i(\mu)$.

Theorem

For environment (μ, Σ) , the regret of any consistent policy satisfies

$$\liminf_{T \rightarrow \infty} \frac{R_T(\mu)}{\log T} \geq \min_{c \in C(\mu)} \sum_{i \in [K]} c_i \Delta_i(\mu).$$

LP-based Algorithm with Asymptotically Optimal Regret

Notation:

- ▶ Let $N_i(t)$ the number of samples arm i has been played so far
- ▶ Maximum-Likelihood reward estimator at round t :

$$\hat{\mu}_i(t) = \sum_{\tau=1}^{t-1} \frac{X_{i,\tau}}{\sigma_{i_\tau,i}^2} \bigg/ \sum_{\tau=1}^{t-1} \frac{1}{\sigma_{i_\tau,i}^2} \quad \forall i \in [K],$$

where i_τ the arm played at round τ

Algorithm: At each round t , the algorithm performs one of the following:

- ▶ **Greedy exploitation:** Play the arm of best estimated reward
- ▶ **Uniform exploration:** Ensure $C(\hat{\mu})$ is “close” to $C(\mu)$
- ▶ **LP-dictated exploration:** Follow the actions indicated by (estimated) LP based on $C(\hat{\mu})$

LP-based Algorithm with Asymptotically Optimal Regret

At each round t :

Greedy exploitation: If $(\frac{N_1(t)}{\log t}, \frac{N_2(t)}{\log t}, \dots, \frac{N_K(t)}{\log t}) \in C(\hat{\mu})$, then play

$$i_t \leftarrow \arg \max_{i \in [K]} \hat{\mu}_i(t)$$

LP-based Algorithm with Asymptotically Optimal Regret

At each round t :

n_e : # exploration rounds (initialized at 0)

Uniform exploration: If $(\frac{N_1(t)}{\log t}, \frac{N_2(t)}{\log t}, \dots, \frac{N_K(t)}{\log t}) \notin C(\hat{\mu})$ and

$$\min_{i \in [K]} \sum_{\tau=1}^{t-1} \frac{1}{\sigma_{i\tau}^2} < o(n_e(t)) \text{ (not uniformly explored)}$$

then play

$$i_t \leftarrow \arg \min_{k \in [K]} \sigma_{k,i}^2, \text{ where } i = \arg \min_{k \in [K]} \sum_{\tau=1}^{t-1} \frac{1}{\sigma_{i\tau,k}^2},$$

and increase n_e by 1

LP-based Algorithm with Asymptotically Optimal Regret

At each round t :

LP-dictated exploration:

If $(\frac{N_1(t)}{\log t}, \frac{N_2(t)}{\log t}, \dots, \frac{N_K(t)}{\log t}) \notin C(\hat{\mu})$ and arms uniformly explored, then

- ▶ Compute $c^*(\hat{\mu}(t)) \leftarrow \arg \min_{c \in C(\hat{\mu}(t))} \sum_{i \in [K]} c_i \Delta_i(\hat{\mu}(t))$
- ▶ Play arm

$$i_t = i \text{ with } N_i(t) < c_i^*(\hat{\mu}(t)) \log t,$$

and increase n_e by 1

LP-based Algorithm with Asymptotically Optimal Regret

Algorithm: At each round t , the algorithm performs either:

- ▶ **Greedy exploitation:** Play the arm of best estimated reward
- ▶ **Uniform exploration:** Ensure $C(\hat{\mu})$ is “close” to $C(\mu)$
- ▶ **LP-dictated exploration:** Follow the actions indicated by (estimated) LP based on $C(\hat{\mu})$

Theorem

The regret of our algorithm satisfies

$$\limsup_{T \rightarrow \infty} \frac{R_T(\mu)}{\log T} \leq \sum_{j \in [K]} \Delta_j(\mu) c_j^*(\mu) \quad (\text{up to constant factors})$$



Wu, Yifan, András György, and Csaba Szepesvári (2015).
“Online Learning with Gaussian Payoffs and Side
Observations”. In: *Proceedings of the 28th International
Conference on Neural Information Processing Systems - Volume
1*. NIPS’15. Montreal, Canada: MIT Press, pp. 1360–1368.