

Robustness and Accuracy Could Be Reconcilable by (Proper) Definition

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Trade-off between robustness and accuracy

Empirically:

Standard training

clean accuracy **95%**

robust accuracy **0%**

Adversarial training

clean accuracy **85%**

robust accuracy **50%**

Theoretically:

Exists in some simple cases

Where the trade-off stems from?



[Zhang et al. ICML 2019; Tsipras et al. ICLR 2019]

What is an **accurate** model?

An **accurate** model refers to the one with **low standard error**:

$$R_{\text{Standard}} = \mathbb{E}_{p_d(x)} [\text{KL} (p_d(y|x) \| p_\theta(y|x))]$$


data distribution model distribution

Optimal solution: $p_{\theta^*}(y|x) = p_d(y|x)$

What is a **robust** model?

A **robust** model refers to the one with **low robust error**:

$$\mathbf{R}_{\text{Madry}} = \mathbb{E}_{p_d(x)} \left[\max_{\mathbf{x}' \in B(x)} \text{KL} \left(p_d(y|x) \middle\| p_\theta(y|\mathbf{x}') \right) \right]$$

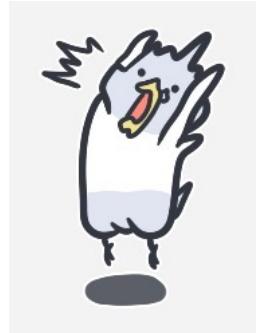
Optimal solution: $p_{\theta^*}(y|x) \neq p_d(y|x)$

Trade-off naturally comes!

An optimally **accurate** model is **NOT** an optimally **robust** model



$p_d(y|x)$ is not an optimally **robust** model w.r.t. itself??!!

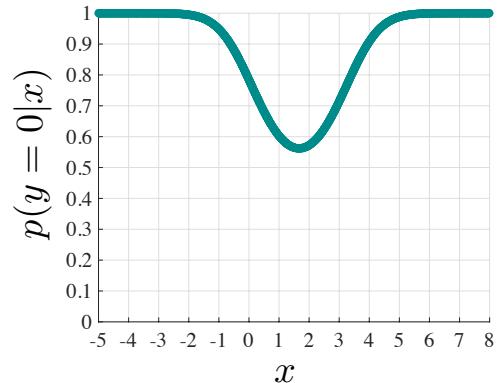


Self-COnsistent Robust Error (SCORE)

$$\mathbf{R}_{\text{SCORE}}(\theta) = \mathbb{E}_{p_d(x)} \left[\max_{\mathbf{x}' \in B(x)} \text{KL} (p_d(y|\mathbf{x}') \| p_\theta(y|\mathbf{x}')) \right]$$

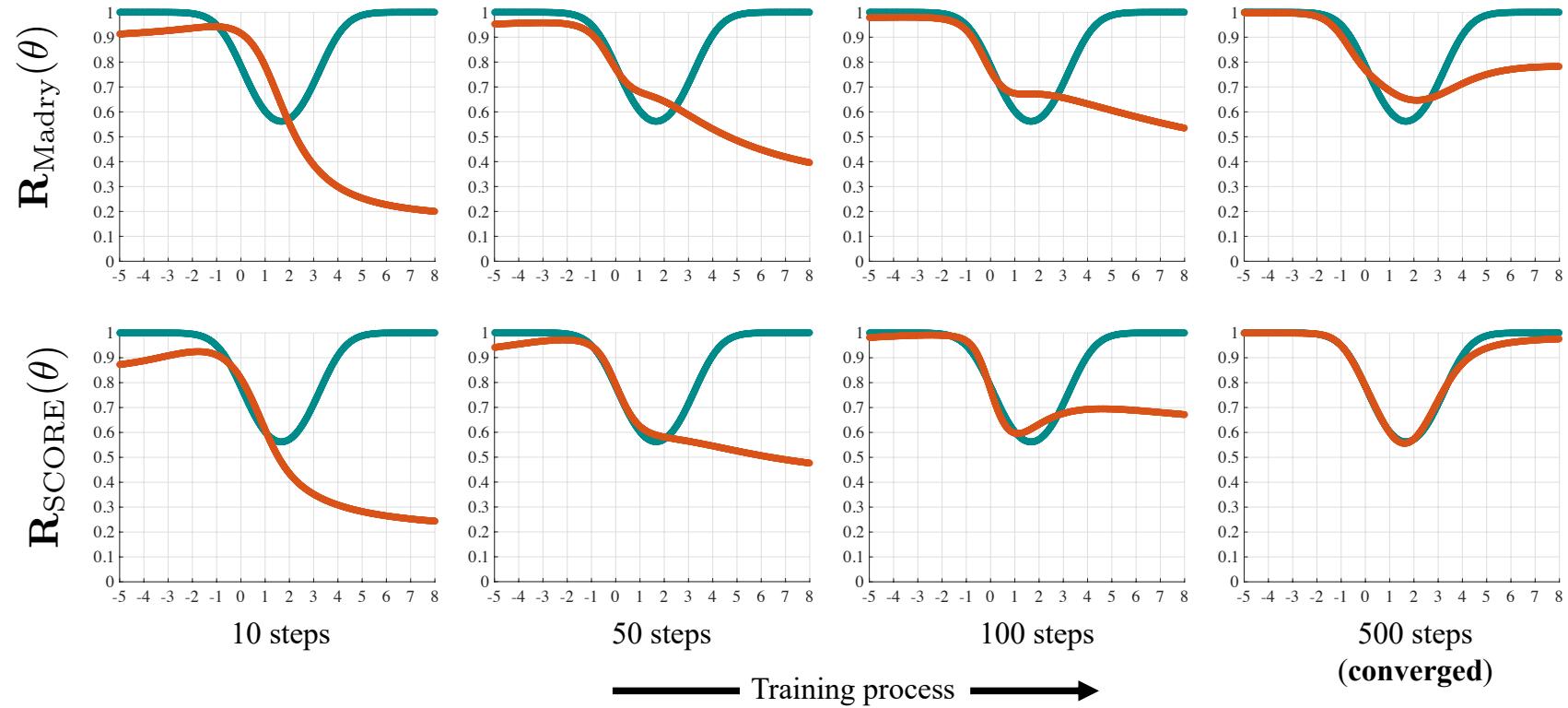
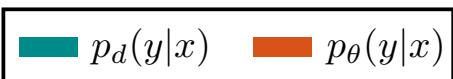
- Optimal solution: $p_{\theta^*}(y|x) = p_d(y|x)$
(self-consistency, i.e., $p_d(y|x)$ is the optimally robust model w.r.t. itself under supervised learning framework)
- Keep the paradigm of robust optimization

Toy demo (self-consistency)



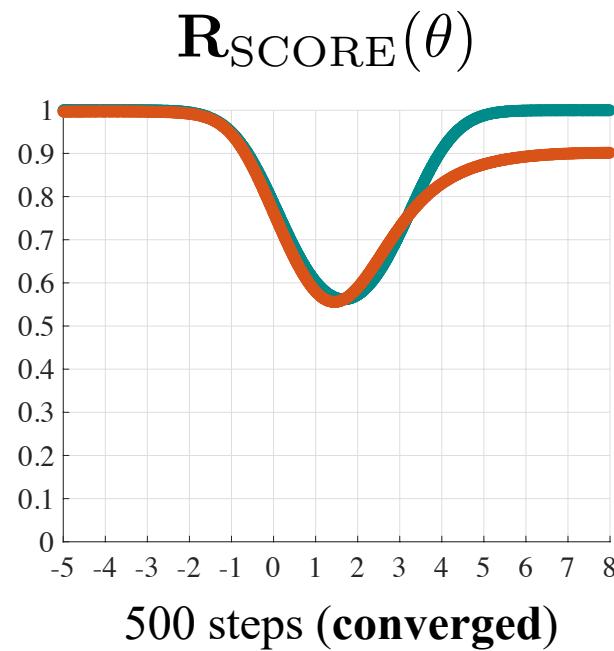
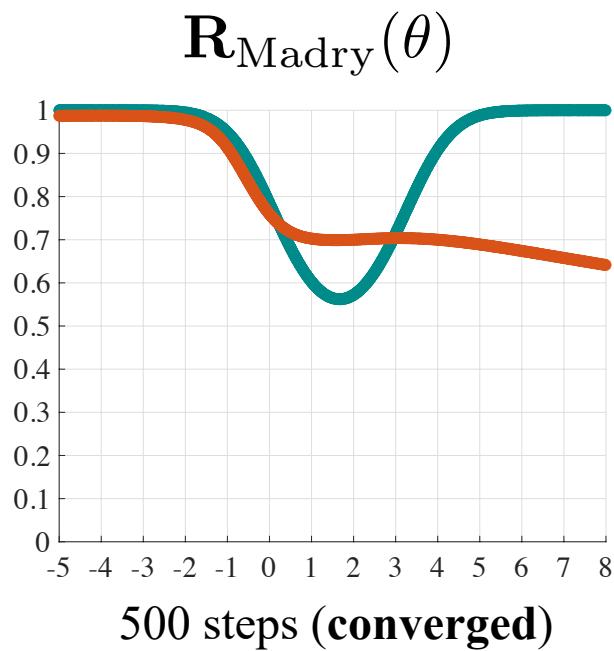
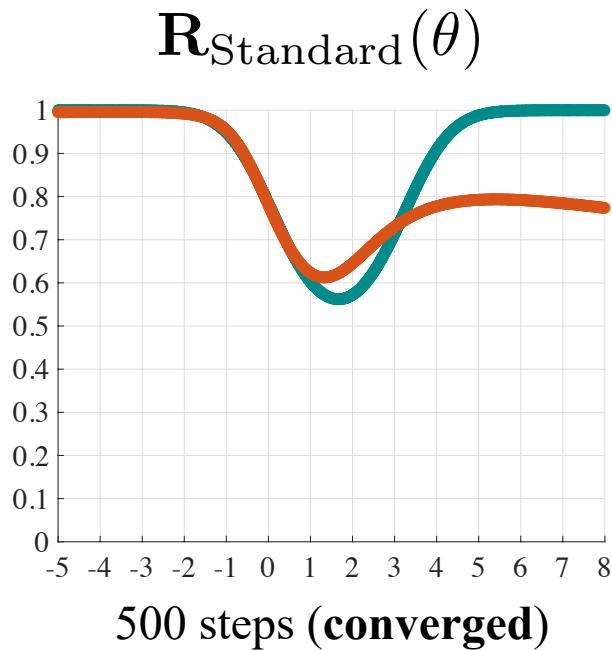
Construction of $p_d(x, y)$:

$$p_d(y=0) = \frac{5}{6}, p_d(y=1) = \frac{1}{6};$$
$$p_d(x|y=0) \sim \mathcal{N}(-1, 4);$$
$$p_d(x|y=1) \sim \mathcal{N}(1, 1).$$



60,000 training pairs, mimics the expectation form

Toy demo (robust optimization)



6 training pairs, mimics the finite-sample form

Standard error has the same optimal solution as SCORE, but does not enjoy robust optimization in finite-sample cases

In practice, how to optimize SCORE?

Directly applying first-order optimizers requires:

$$\nabla_x \text{KL} (p_d(y|x) \| p_\theta(y|x)) \\ = \mathbb{E}_{p_d(y|x)} \left[- \frac{\nabla_x \log p_\theta(y|x)}{\text{model gradient}} + \left(\log \frac{p_d(y|x)}{p_\theta(y|x)} \right) \cdot \frac{\nabla_x \log p_d(y|x)}{\text{data gradient}} \right]$$

- Initial experiments using **score matching** are of high variance
- More advanced score matching like **[Chao et al. ICLR 2022]** could be explored

Goodbye KL divergence!

Substitute KL divergence with any **distance metric** \mathcal{D}

$$\mathbf{R}_{\text{Madry}}^{\mathcal{D}}(\theta) = \mathbb{E}_{p_d(x)} \left[\max_{\mathbf{x}' \in B(x)} \mathcal{D} (p_d(y|x) \| p_\theta(y|\mathbf{x}')) \right];$$

$$\mathbf{R}_{\text{SCORE}}^{\mathcal{D}}(\theta) = \mathbb{E}_{p_d(x)} \left[\max_{\mathbf{x}' \in B(x)} \mathcal{D} (p_d(y|\mathbf{x}') \| p_\theta(y|\mathbf{x}')) \right]$$

Upper and lower bounds for SCORE



Theorem I:

$$|\mathbf{R}_{\text{Madry}}^{\mathcal{D}}(\theta) - C^{\mathcal{D}}| \leq \mathbf{R}_{\text{SCORE}}^{\mathcal{D}}(\theta) \leq \mathbf{R}_{\text{Madry}}^{\mathcal{D}}(\theta) + C^{\mathcal{D}},$$

where $\underline{C^{\mathcal{D}}} = \mathbb{E}_{p_d(x)} \left[\max_{\mathbf{x}' \in B(x)} \mathcal{D} (p_d(y|x) \| p_d(y|\mathbf{x}')) \right]$

**intrinsic property of data distribution, indicates
the (Madry) robust error of $p_d(y|x)$ itself**

Upper and lower bounds for SCORE



Theorem I:

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- **Upper bound:** minimizing SCORE without estimating $\nabla_x \log p_d(y|x)$
- **Lower bound:** indicates the overfitting phenomenon

Upper and lower bounds for SCORE



Theorem I:

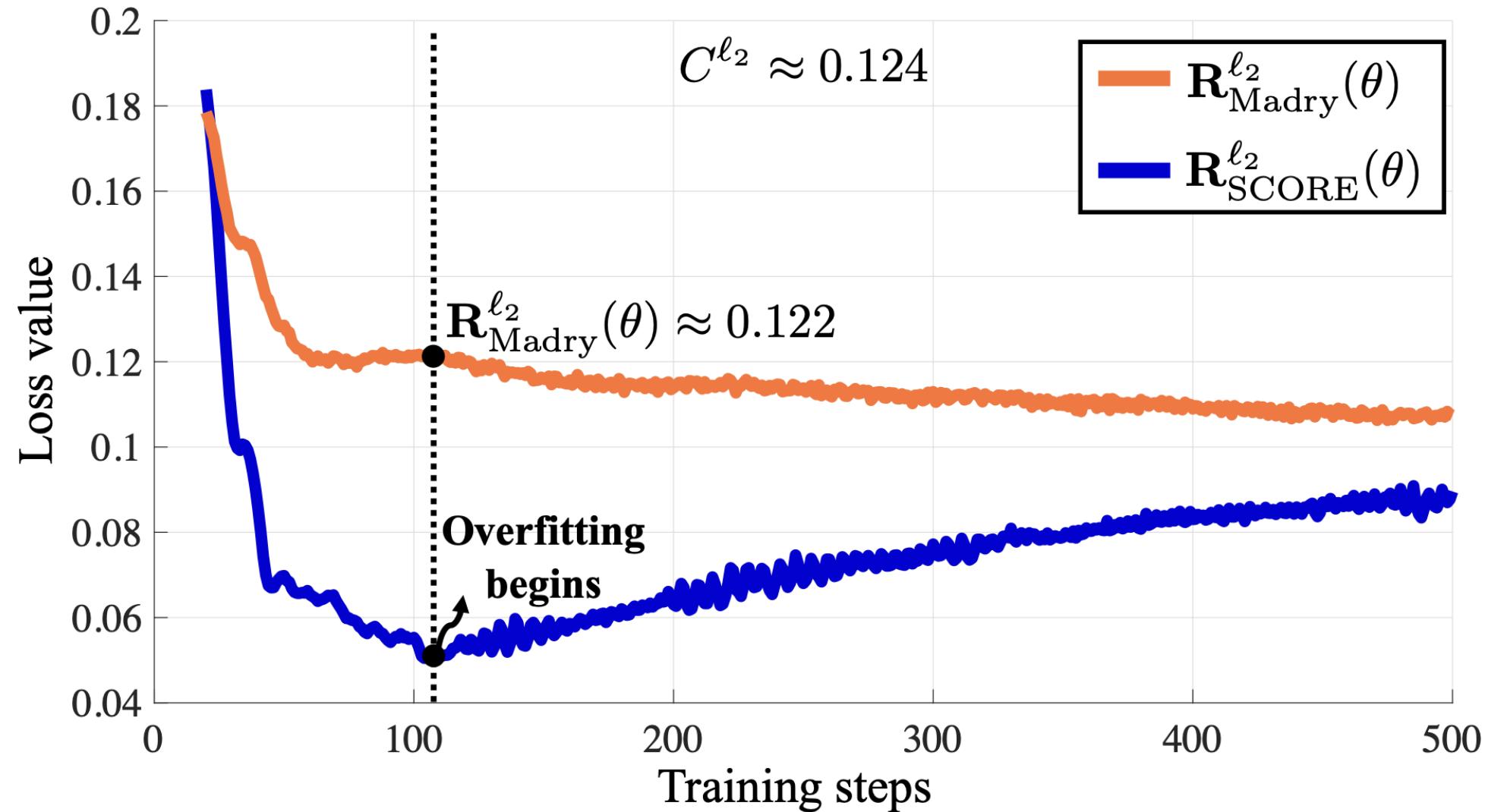
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where $C^{\mathcal{D}} = \mathbb{E}_{p_d(x)} \left[\max_{\mathbf{x}' \in B(x)} \mathcal{D} (p_d(y|x) \| p_d(y|\mathbf{x}')) \right]$

- **Upper bound:** minimizing SCORE without estimating $\nabla_x \log p_d(y|x)$
- **Lower bound:** indicates the overfitting phenomenon

Upper and lower bounds for SCORE

\mathcal{D} is ℓ_2 -distance : $\|A - B\|_2$



Back to KL divergence with new insights

Corollary I:

$$|\mathbf{R}_{\text{SCORE}}^{\ell_1}(\theta) - C^{\ell_1}| \leq \sqrt{2 \cdot \mathbf{R}_{\text{Madry}}(\theta)}$$



original **KL-based** robust error

Explaining overfitting and early-stopping

$$|\mathbf{R}_{\text{SCORE}}^{\ell_1}(\theta) - C^{\ell_1}| \leq \sqrt{2 \cdot \mathbf{R}_{\text{Madry}}(\theta)}$$

↓ $\mathbf{R}_{\text{SCORE}}^{\ell_1}(\theta) = 0$

$$C^{\ell_1} \leq \sqrt{2 \cdot \mathbf{R}_{\text{Madry}}(\theta)} \implies \boxed{\mathbf{R}_{\text{Madry}}(\theta) \geq \frac{(C^{\ell_1})^2}{2}}$$

indicates early-stopping

Explaining semantic gradients (for adversarial training)

Theorem 4: (under mild condition)

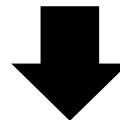
$$\mathbf{R}_{\text{SCORE}}^{\ell_1}(\theta) = \mathbf{R}_{\text{Standard}}^{\ell_1}(\theta) +$$
$$2\epsilon \cdot \mathbb{E}_{p_d(x)} \left[\underbrace{\|\nabla_x p_d(\mathcal{Y}_d(x)|x) - \nabla_x p_\theta(\mathcal{Y}_d(x)|x)\|_q}_\text{alignment between model gradient and data gradient} \right] + o(\epsilon)$$

where $\mathcal{Y}_d(x) = \operatorname{argmax}_y p_d(y|x)$

Explaining semantic gradients (for randomized smoothing)

Theorem 5:

$$\frac{d}{d\sigma} \mathbf{R}_G(\theta; \sigma) = \frac{1}{2} \mathbb{E}_{p_d^\sigma(x, y)} [\nabla_x \log p_\theta(y|x)^\top \nabla_x \log p_d^\sigma(x|y)]$$



$$\mathbf{R}_G(\theta; \sigma) = \boxed{\mathbf{R}_G(\theta; 0)} + \boxed{\sigma \cdot \frac{d}{d\sigma} \mathbf{R}_G(\theta; \sigma) \Big|_{\sigma=0}} + o(\sigma)$$

**cross-entropy
(without augmentation)**

gradient alignment

Table 4. Classification accuracy (%) on clean images and under AutoAttack. The results of our methods are in **bold**, and no clipping loss is executed. Here \dagger means *no CutMix applied*, following [Rade and Moosavi-Dezfooli \(2021\)](#). We use a batch size of 512 and train for 400 epochs due to limited resources, while a larger batch size of 1024 and training for 800 epochs are expected to achieve better performance.

Dataset	Method	Architecture	DDPM	Batch	Epoch	Clean	AutoAttack
CIFAR-10 $(\ell_\infty, \epsilon = 8/255)$	Rice et al. (2020)	WRN-34-20	\times	128	200	85.34	53.42
	Zhang et al. (2020)	WRN-34-10	\times	128	120	84.52	53.51
	Pang et al. (2021)	WRN-34-20	\times	128	110	86.43	54.39
	Wu et al. (2020)	WRN-34-10	\times	128	200	85.36	56.17
	Gowal et al. (2020)	WRN-70-16	\times	512	200	85.29	57.14
	Rebuffi et al. (2021) †	WRN-28-10	1M	1024	800	85.97	60.73
	+ Ours (KL \rightarrow SE, $\beta = 3$)	WRN-28-10	1M	512	400	88.61	61.04
	+ Ours (KL \rightarrow SE, $\beta = 4$)	WRN-28-10	1M	512	400	88.10	61.51
	Rebuffi et al. (2021) †	WRN-70-16	1M	1024	800	86.94	63.58
	+ Ours (KL \rightarrow SE, $\beta = 3$)	WRN-70-16	1M	512	400	89.01	63.35
	+ Ours (KL \rightarrow SE, $\beta = 4$)	WRN-70-16	1M	512	400	88.57	63.74
	Gowal et al. (2021)	WRN-70-16	100M	1024	2000	88.74	66.10
CIFAR-10 $(\ell_2, \epsilon = 128/255)$	Wu et al. (2020)	WRN-34-10	\times	128	200	88.51	73.66
	Gowal et al. (2020)	WRN-70-16	\times	512	200	90.90	74.50
	Rebuffi et al. (2021) †	WRN-28-10	1M	1024	800	90.24	77.37
	+ Ours (KL \rightarrow SE, $\beta = 3$)	WRN-28-10	1M	512	400	91.52	77.89
	+ Ours (KL \rightarrow SE, $\beta = 4$)	WRN-28-10	1M	512	400	90.83	78.10
CIFAR-100 $(\ell_\infty, \epsilon = 8/255)$	Wu et al. (2020)	WRN-34-10	\times	128	200	60.38	28.86
	Gowal et al. (2020)	WRN-70-16	\times	512	200	60.86	30.03
	Rebuffi et al. (2021) †	WRN-28-10	1M	1024	800	59.18	30.81
	+ Ours (KL \rightarrow SE, $\beta = 3$)	WRN-28-10	1M	512	400	63.66	31.08
	+ Ours (KL \rightarrow SE, $\beta = 4$)	WRN-28-10	1M	512	400	62.08	31.40
	Rebuffi et al. (2021) †	WRN-70-16	1M	1024	800	60.46	33.49
	+ Ours (KL \rightarrow SE, $\beta = 3$)	WRN-70-16	1M	512	400	65.56	33.05
	+ Ours (KL \rightarrow SE, $\beta = 4$)	WRN-70-16	1M	512	400	63.99	33.65

Thank you!

Paper: <https://arxiv.org/abs/2202.10103>

Code: <https://p2333.github.io/>



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