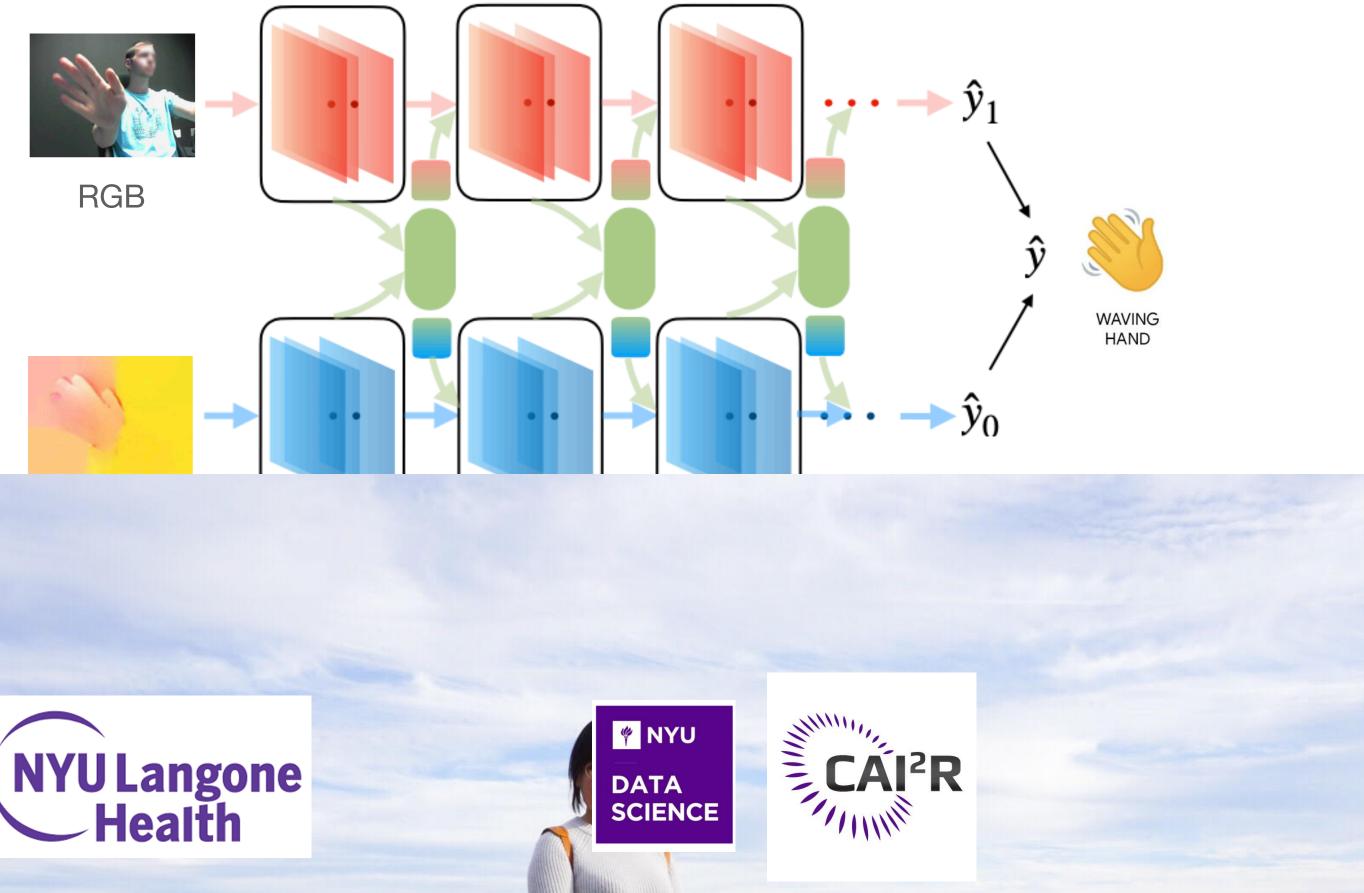
# **Characterizing and Overcoming the Greedy Nature of** Learning in Multi-Modal Deep Neural Networks

#### **Dynamic Hand Gestures Recognition**







ztof J. Geras.

# **Characterizing and Overcoming the Greedy Nature of** Learning in Multi-Modal Deep Neural Networks

Dyna RG

**NYU Langone** 

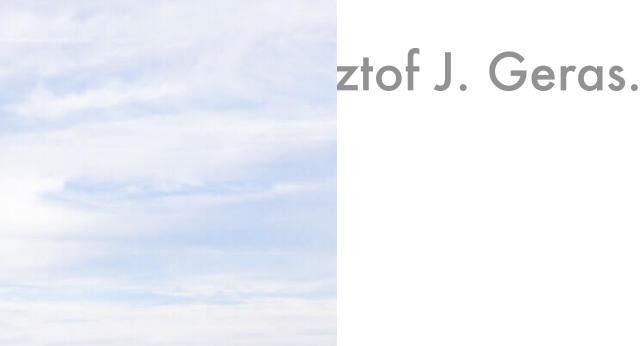
**— Health** 



WYU

DATA

- Do multi-modal DNNs attend to all modalities? Can we make multi-modal DNNs utilize all modalities?
  - **Does better utilization of all modalities imply better generalization?**



$$\hat{y}_0 = f_0({m x}_{m_0}, {m x}_{m_1})$$

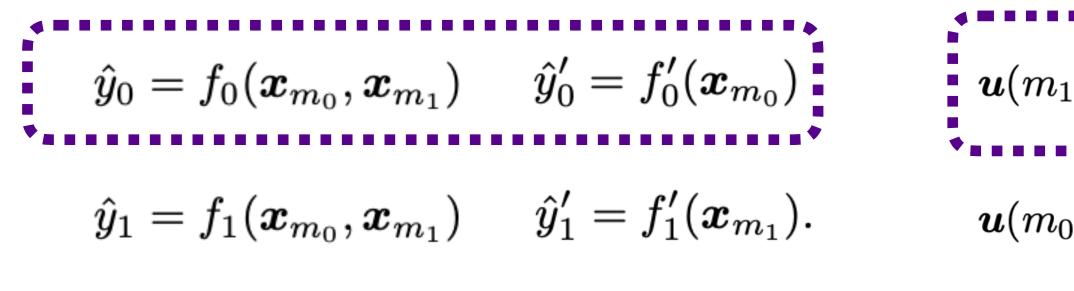
$$\hat{y}_1 = f_1(x_{m_0}, x_{m_1})$$



$$\hat{y}_0 = f_0(m{x}_{m_0}, m{x}_{m_1}) ~~ \hat{y}_0' = f_0'(m{x}_{m_0})$$

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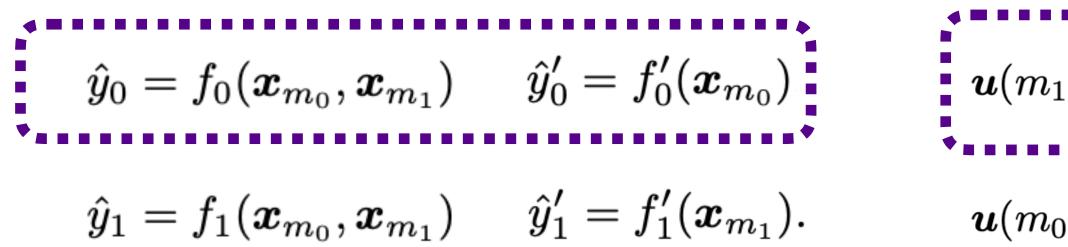


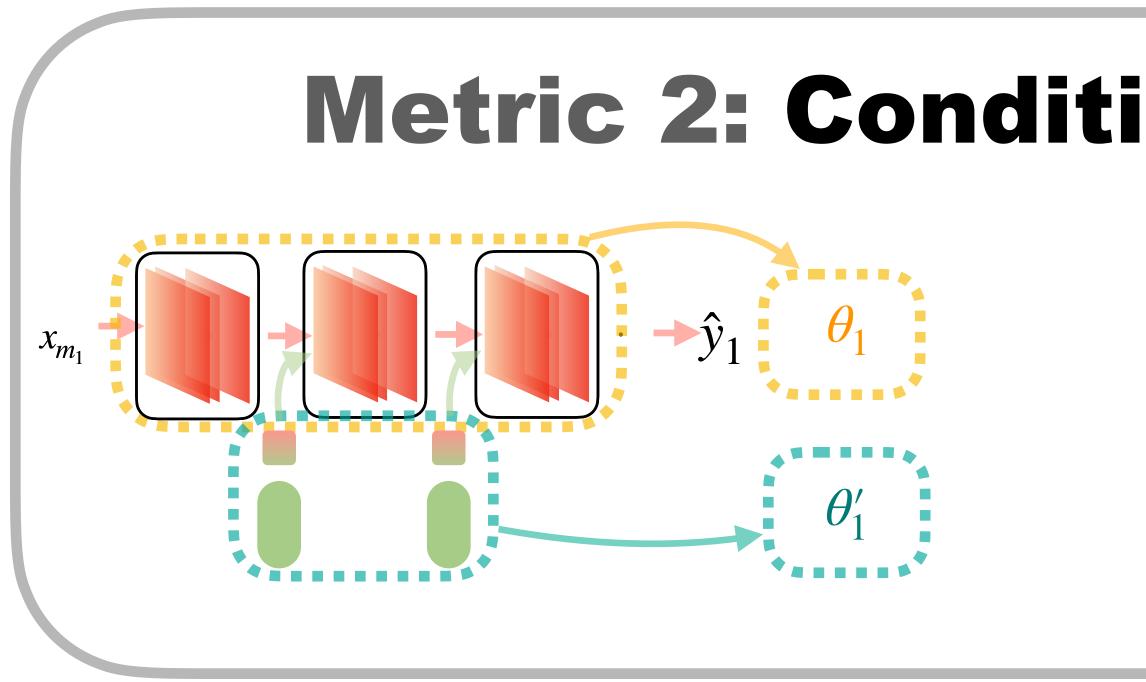
$$A_1|m_0) = rac{A(f_0) - A(f_0')}{A(f_0)},$$
  
 $A(f_0) = rac{A(f_1) - A(f_1')}{A(f_1)},$ 

The relative change in accuracy between the two models:

- one using all modalities,
- the other using only one.







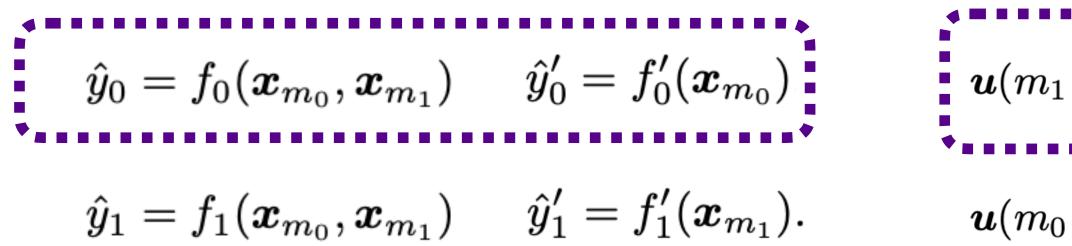
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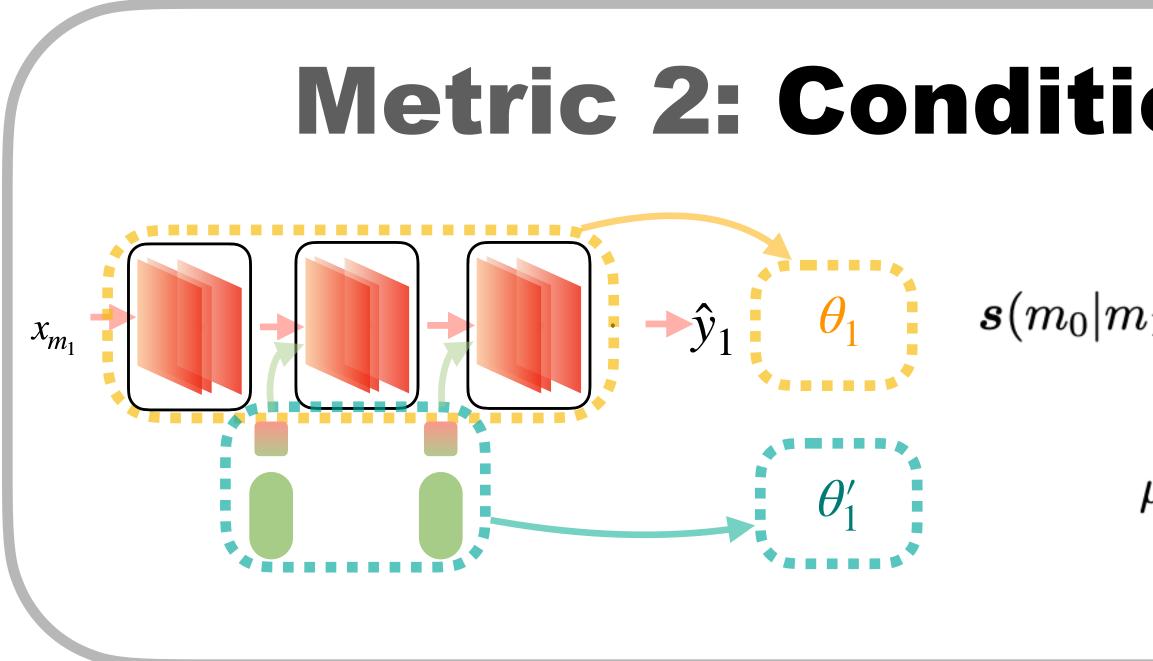
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# Metric 2: Conditional learning speed







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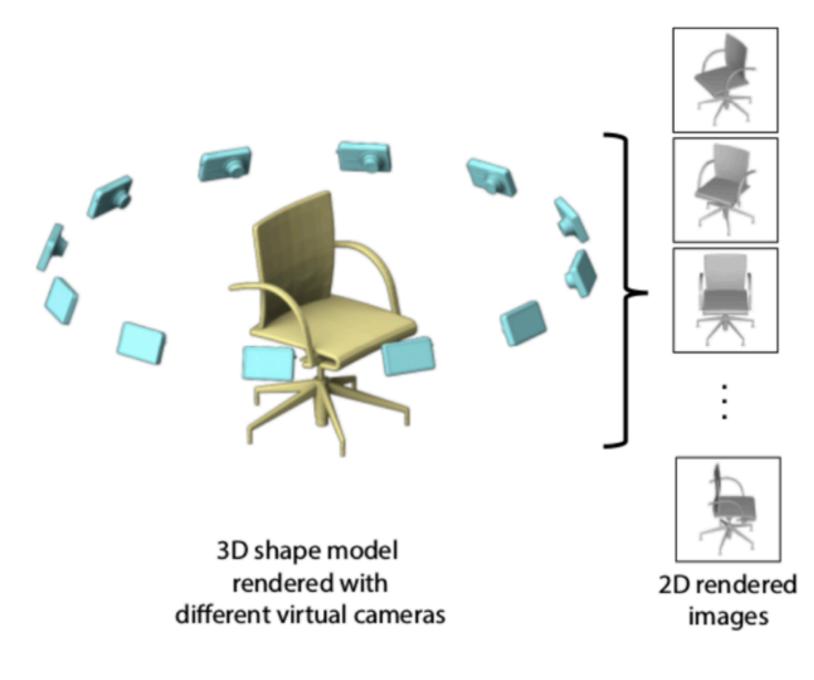
$$\mu_1;t) = \log rac{\sum_{i=1}^t \mu(oldsymbol{ heta}_1';i)}{\sum_{i=1}^t \mu(oldsymbol{ heta}_1;i)},$$

 $\mu({m heta};i) = ||{m G}||_2^2 / ||{m heta}_{(i)}||_2^2$ 

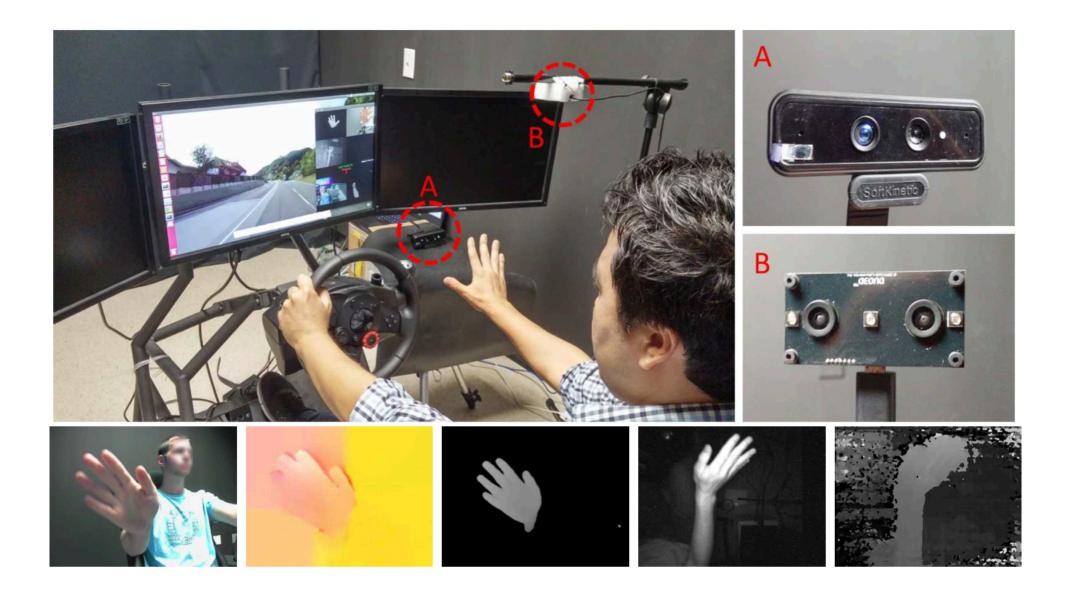
the log-ratio between the learning speed of

- the uni-modal branch and
- the corresponding fusion components.





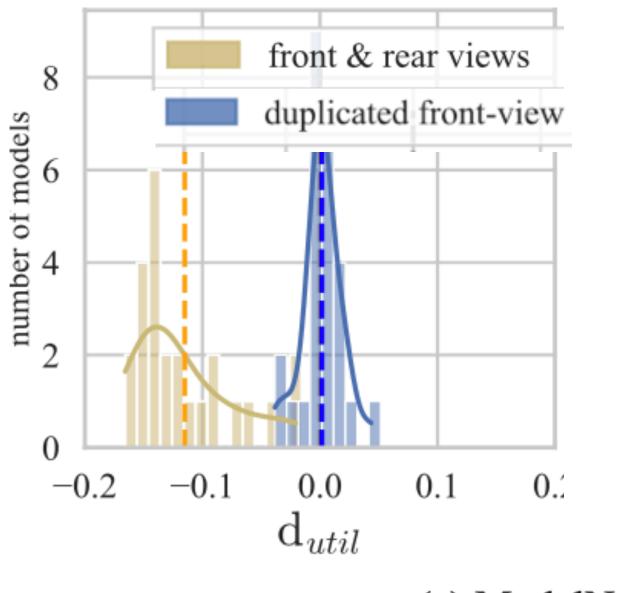
(a) ModelNet40



(b) NVGesture

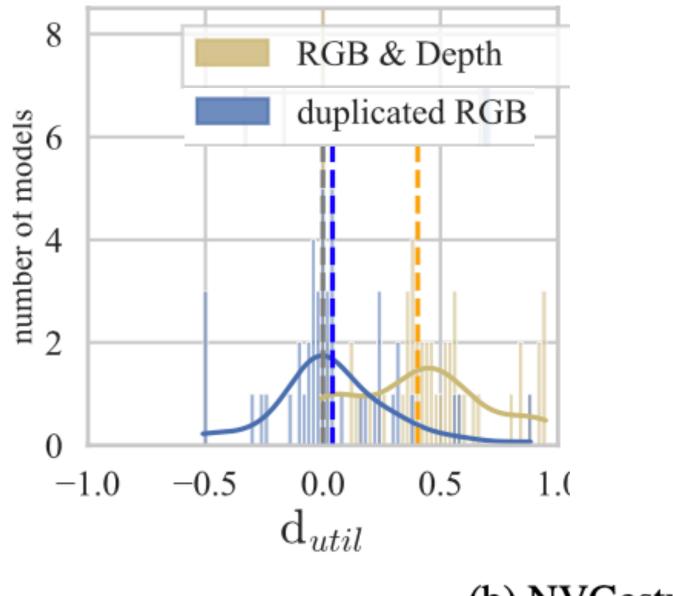
 $d_{util}(f) = u(m_1|m_0) - u(m_0|m_1)$  $d_{speed}(f; t) = s(m_1|m_0; t) - s(m_0|m_1; t)$ 





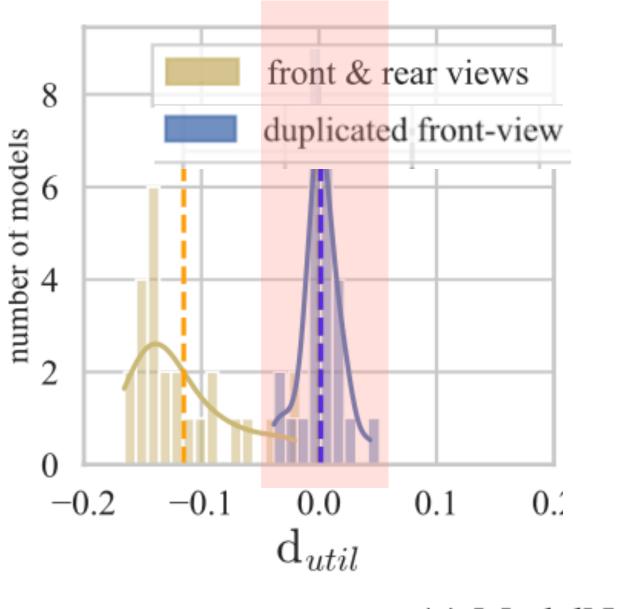


$$egin{aligned} \mathsf{d}_{\mathsf{util}}(f) &= m{u}(m_1 | m_0) - m{u}(m_0 | m_1) \ \mathsf{d}_{\mathsf{speed}}(f;t) &= m{s}(m_1 | m_0;t) - m{s}(m_0 | m_1;t) \end{aligned}$$



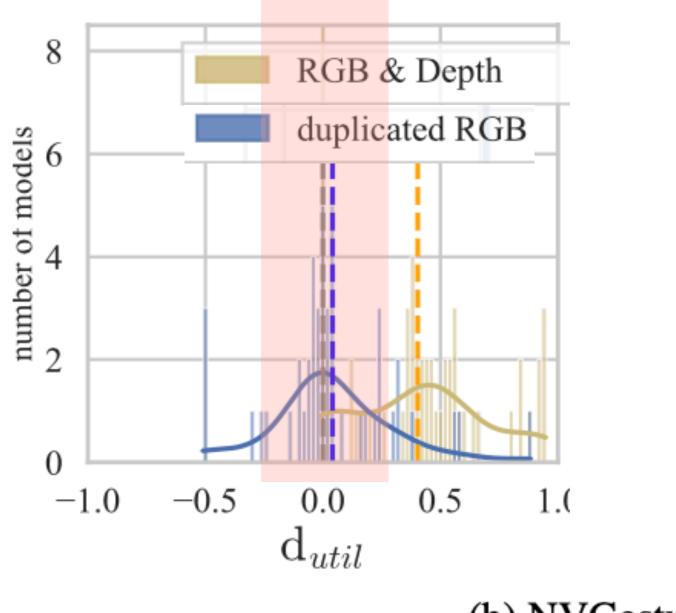






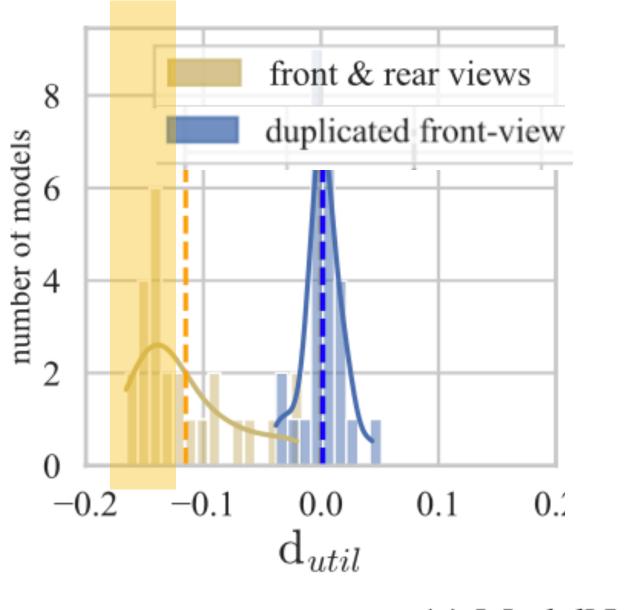


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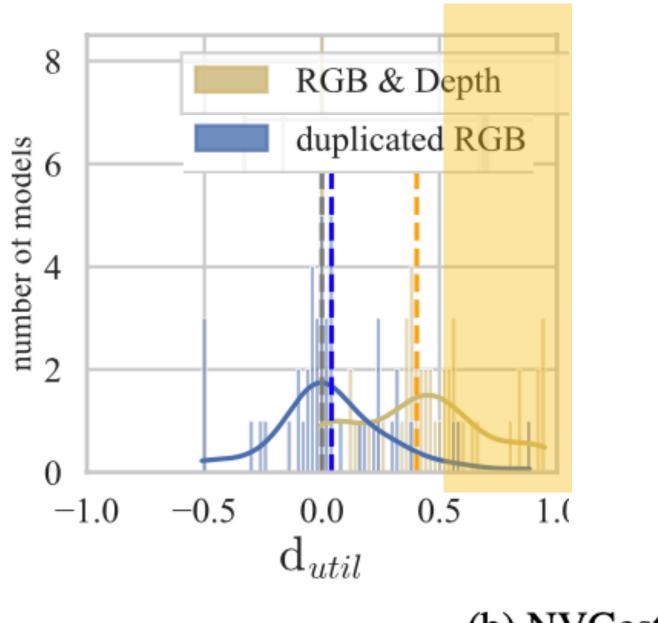






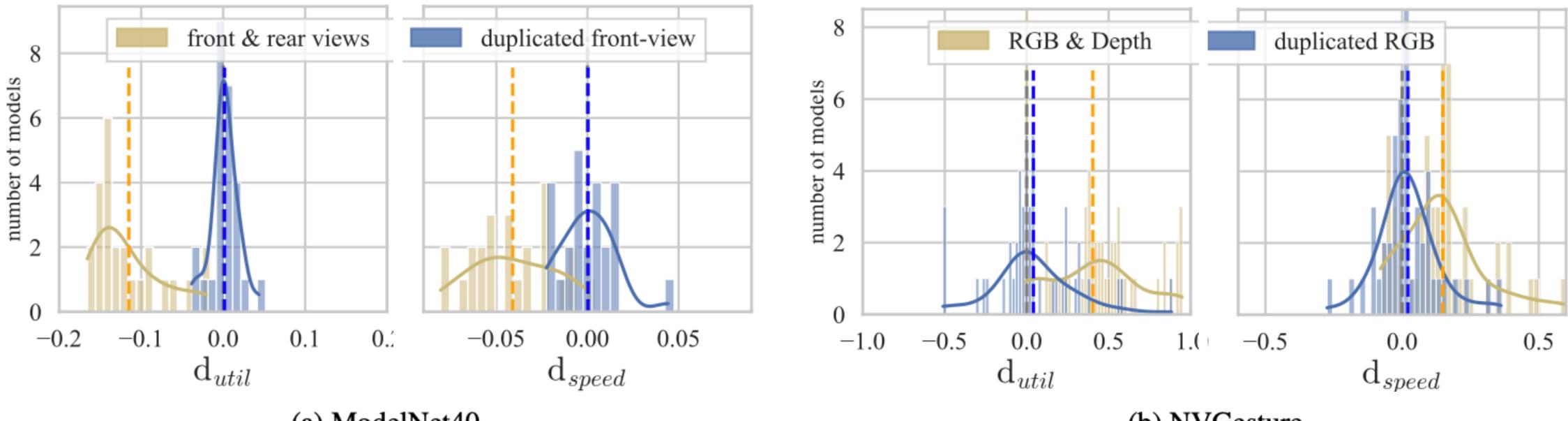


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(a) ModelNet40

(b) NVGesture

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# **Greedy learner hypothesis**

### A multi-modal learning process is greedy when it produces models that rely on only one of the available modalities.



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# The modality that the multi-modal DNN primarily relies on is the modality that is the fastest to learn from.



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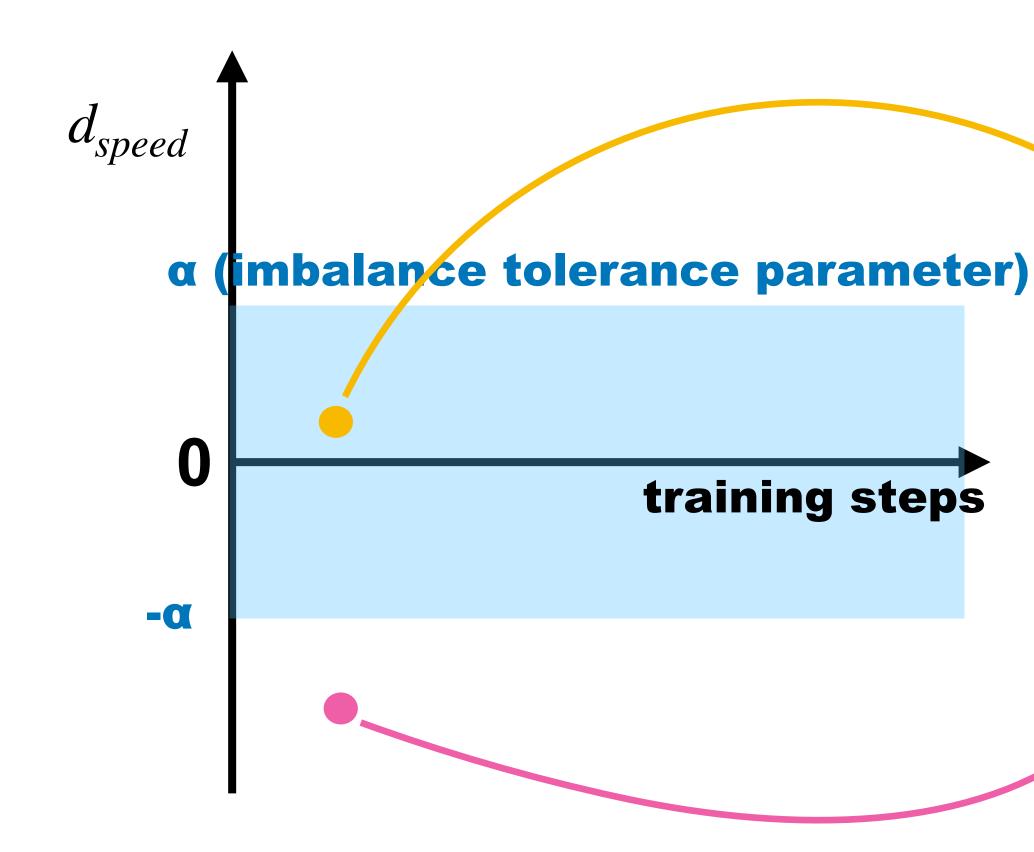
### A multi-modal learning process is greedy when it produces models that rely on only one of the available modalities.

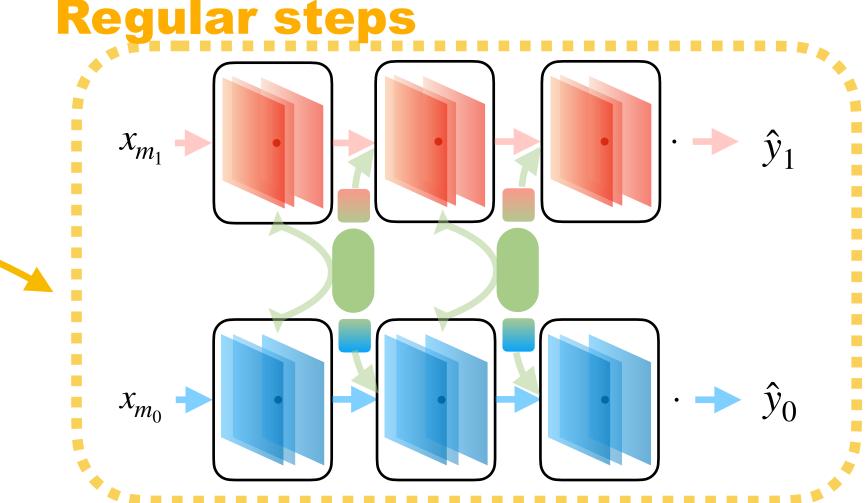
The modality that the multi-modal DNN primarily relies on is the modality that is the fastest to learn from.

We hypothesize that a multi-modal learning process, in which a multi-modal DNN is trained to minimize the sum of the modality-specific losses, is greedy.

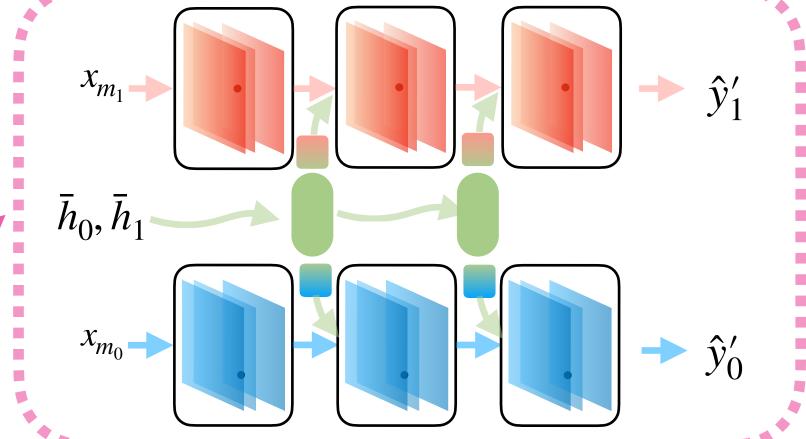


# Balanced multimodal learning [Guided]





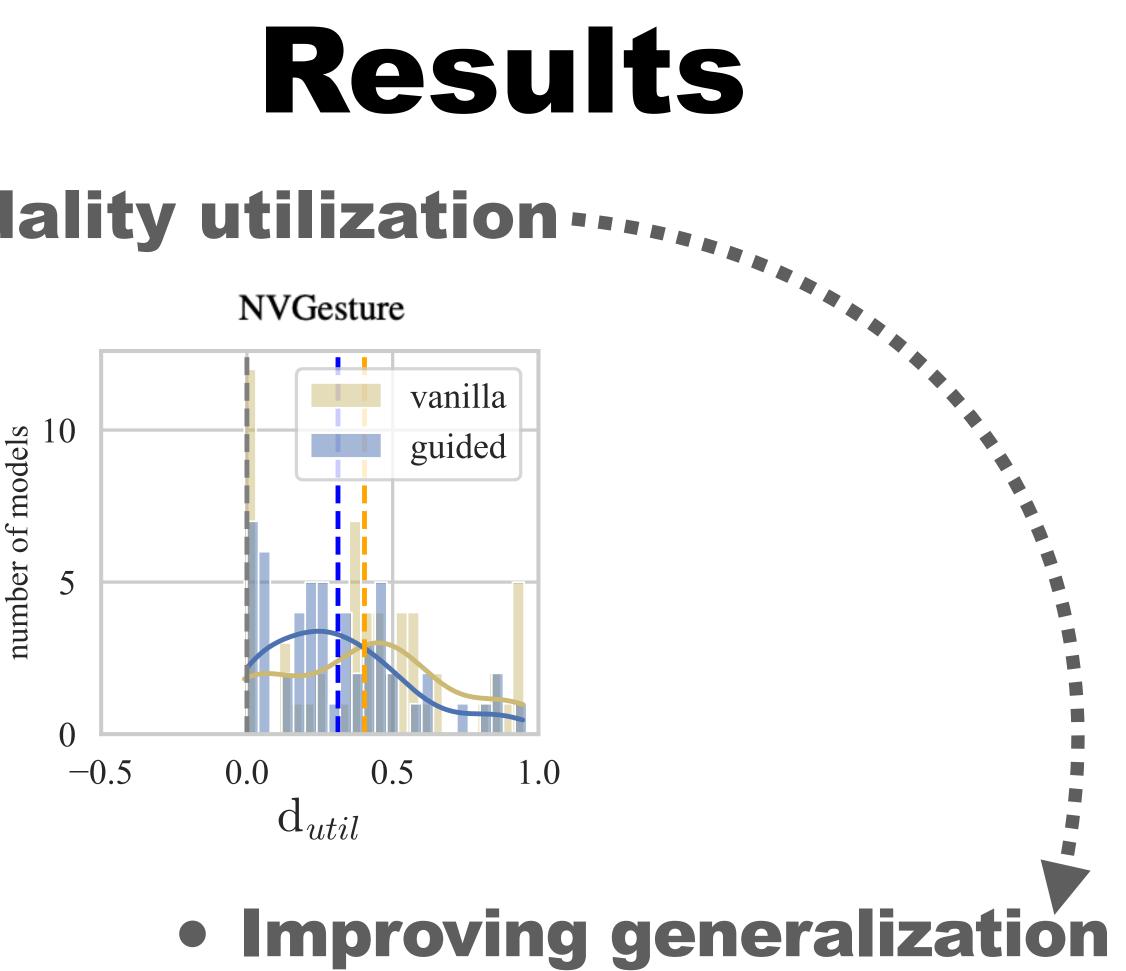




### Calibrating modality utilization

#### vanilla 8 number of models guided 0 0.0 0.2 -0.2 $d_{util}$

ModelNet40



uni-modal (best

- multi-modal (va
- + RUBi (Cade
- + random (pro
- + guided (prop

	ModelNet40	NVGesture-scratch	NVGesture-pretrained
st)	89.34±0.39	$77.59{\pm}0.55$	$78.98{\pm}2.02$
vanilla)	90.09±0.58	79.81±1.14	83.20±0.21
ene et al., 2019)	$90.45 {\pm} 0.58$	$79.95 {\pm} 0.12$	$81.60 \pm 1.28$
oposed)	91.36±0.10	$79.88 \pm 0.90$	$82.64 \pm 0.84$
posed)	91.37±0.28	80.22±0.73	83.82±1.45

### Nan Wu [email: <u>nan.wu@nyu.edu;</u> twitter: Nan Wu @NanWu\_ ]. Stanisław Jastrzębski, Kyunghyun Cho and Krzysztof J. Geras. Characterizing and overcoming the greedy nature of learning in multi-modal deep neural networks. ICML, 2022.

https://github.com/nyukat/greec

e

