

Understanding the “Unstable Convergence” of Gradient Descent

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Motivation

- Gradient descent (GD) runs the iteration

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- When cost is quadratic&convex, condition (Stable Regime) is in fact necessary for convergence: if $\eta > \frac{2}{L}$, then GD diverges.

Is this true for nonconvex deep learning optimization?

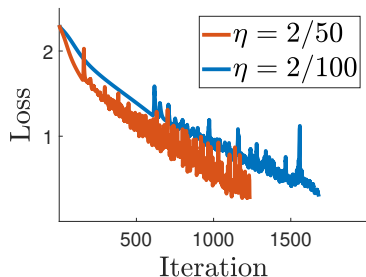
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- Throughout the talk, **sharpness** means the maximum eigenvalue of the loss Hessian, i.e., $\lambda_{\max}(\nabla^2 f(\boldsymbol{\theta}^t))$.

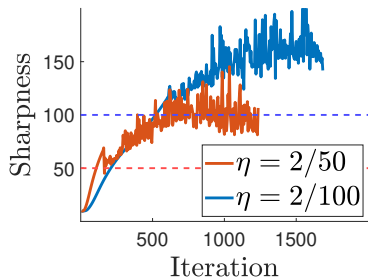
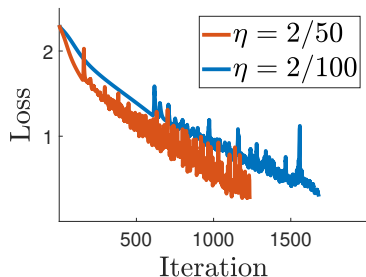
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Unstable convergence

- Recently, it has been observed that GD on neural networks often violates condition (**Stable Regime**). (Cohen et al. 2021) observe that when we run GD to train a neural network, the condition (**Stable Regime**) fails, ¹

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- but contrary to the common wisdom from convex optimization, the training loss still (non-monotonically) decreases in the long run.
- We call this phenomenon **unstable convergence**.

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- Investigate and clarify the **relations between them**.
- Our characterizations demonstrate that the features of unstable convergence are in stark contrast with those of traditional stable convergence.
- In particular, our main features provide **alternative ways to identify unstable convergence** in practice.

Illustration of our main results (ReLU network)

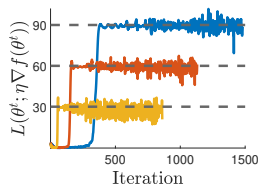
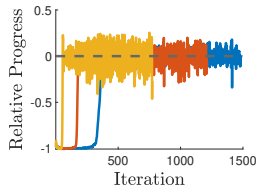
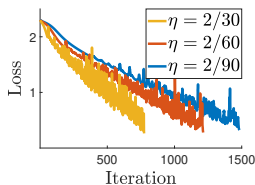
Object	Quantity	Behavior
Loss	$RP(\theta^t)$	oscillates <small>near</small> 0
Iterates	$L(\theta^t; \eta \nabla f(\theta^t))$	oscillates <small>near</small> $2/\eta$
Sharpness	$\lambda_{\max}(\nabla^2 f(\theta^t))$	oscillates <small>near</small> $2/\eta$ <small>above</small>

- **Relative Progress:** $RP(\theta) := \frac{f(\theta - \eta \nabla f(\theta)) - f(\theta)}{\eta \|\nabla f(\theta)\|^2}$
- **Directional smoothness:** $L(\theta; \mathbf{v}) := \frac{\langle \mathbf{v}, \nabla f(\theta) - \nabla f(\theta - \mathbf{v}) \rangle}{\|\mathbf{v}\|^2}$

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It's actively studied in the literature!!

- ▶ Cohen, Kaur, Li, Kolter, Talwalkar. “*Gradient descent on neural networks typically occurs at the edge of stability.*” ICLR, 2021
- ▶ Arora, Li, Panigrahi, “*Understanding gradient descent on edge of stability in deep learning.*” ICML 2022.
- ▶ Ma, Kunin, Wu, Ying. “*The multiscale structure of neural network loss functions: The effect on optimization and origin.*” 2022.
- ▶ and more!!

Thank you for listening

If you have any questions, shoot me an email! kjahn@mit.edu