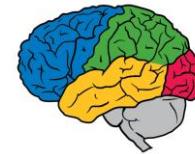


Why Should I Trust You, Bellman? The Bellman Error is a Poor Replacement for Value Error

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Overview of Paper

We show the Bellman error is a poor proxy for value error.

Reasons:

- (1) The magnitude of the Bellman error hides bias.
- (2) The Bellman equation has infinite solutions over an incomplete dataset.

Bellman Error & Value Error

Given an approximate value function Q .

Bellman Error

$$\epsilon(s, a) := Q(s, a) - E[r + \gamma Q(s', a')]$$

= The difference of each side of the Bellman equation.

Value Error

$$\Delta(s, a) := Q(s, a) - Q^\pi(s, a)$$

= The difference between Q and the true value function.

Bellman Error & Value Error

Value error is our actual objective, but is typically unavailable.

Known result:

If the Bellman error = 0 for all state-action pairs, then value error = 0.

This suggests that the Bellman error can be used as a proxy.

Problem 1: The Magnitude of the Bellman Error Hides Bias

From the Bellman equation:

$$\epsilon(s, a) = \Delta(s, a) - \gamma E_{s', a' \sim \pi} [\Delta(s', a')]$$

This means that $\Delta(s, a)$ can cancel with $\Delta(s', a')$.

⇒ Biased value functions will have lower Bellman error.

Example

Given the true value function Q^π for any MDP.

Define, for all (s, a) :

$$Q_1(s, a) := Q^\pi(s, a) + 1$$

$$Q_2(s, a) := Q^\pi(s, a) \pm 1$$

Where \pm is random with equal probability of being 1 or -1 .

The absolute value error of Q_1 and Q_2 at any (s, a) is 1 .

Example

Recall

$$\epsilon(s, a) = \Delta(s, a) - \gamma E_{s', a' \sim \pi}[\Delta(s', a')]$$

For all (s, a) ...

$$\begin{aligned} \text{Bellman error of } Q_1 &:= Q^\pi + 1 \\ &= 1 - \gamma 1 = 1 - \gamma \end{aligned}$$

$$\begin{aligned} \text{Expected Bellman error of } Q_2 &:= Q^\pi \pm 1 \\ &= E[|\pm 1 - \gamma E[\pm 1]|] = E|\pm 1 - 0| = 1 \end{aligned}$$

Example

Recall

$$\epsilon(s, a) = \Delta(s, a) - \gamma E_{s', a' \sim \pi}[\Delta(s', a')]$$

For all (s, a) ...

Bellman error of $Q_1 := Q^\pi + 1$
 $= 1 - \gamma 1 = \boxed{1 - \gamma}$

Expected Bellman error of $Q_2 := Q^\pi \pm 1$
 $= E[|\pm 1 - \gamma E[\pm 1]|] = E|\pm 1 - 0| = 1$

Example

Recall

$$\epsilon(s, a) = \Delta(s, a) - \gamma E_{s', a' \sim \pi}[\Delta(s', a')]$$

For all (s, a) ...

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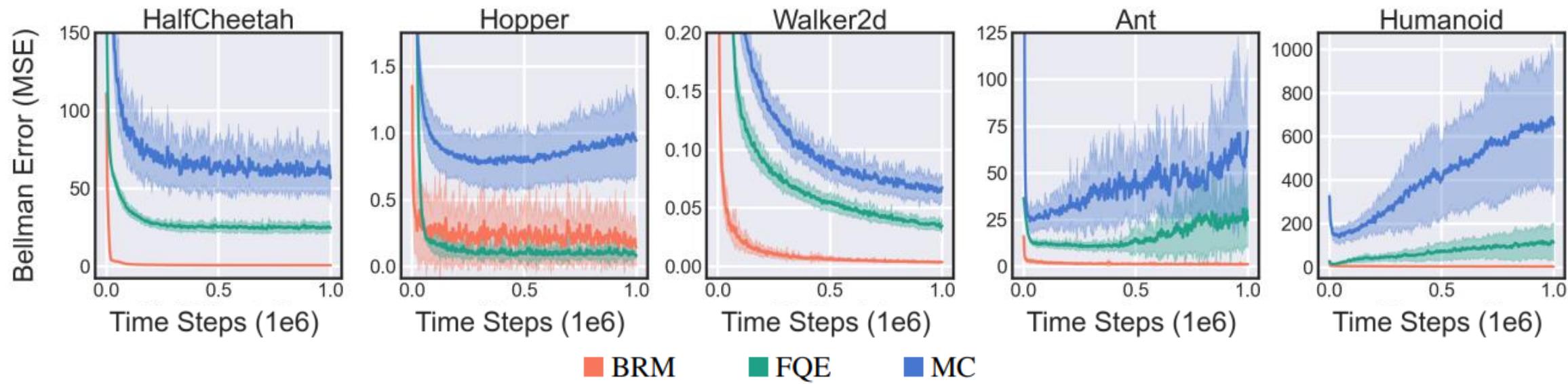
Expected Bellman error of $Q_2 := Q^\pi \pm 1$
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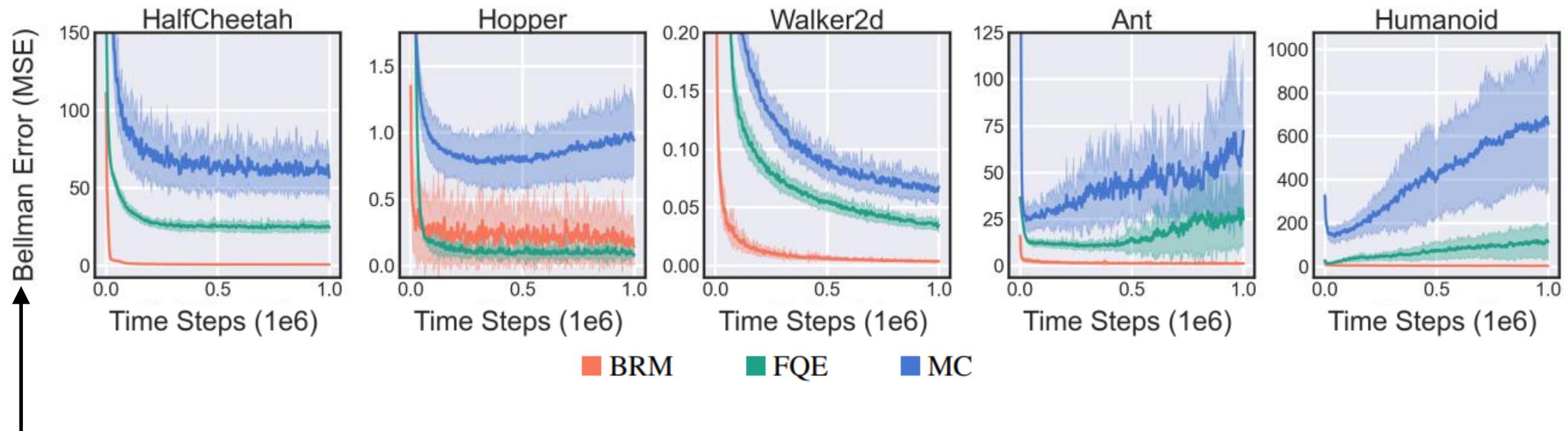
Experiment

Setup:

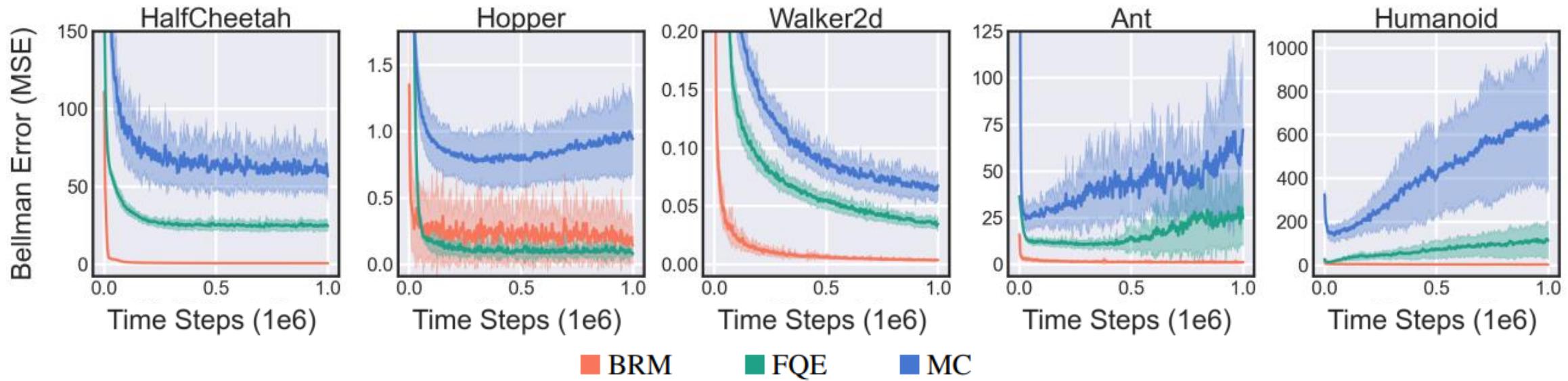
On-policy evaluation from large dataset (1m samples).

Deterministic environment = no double-sampling issue.

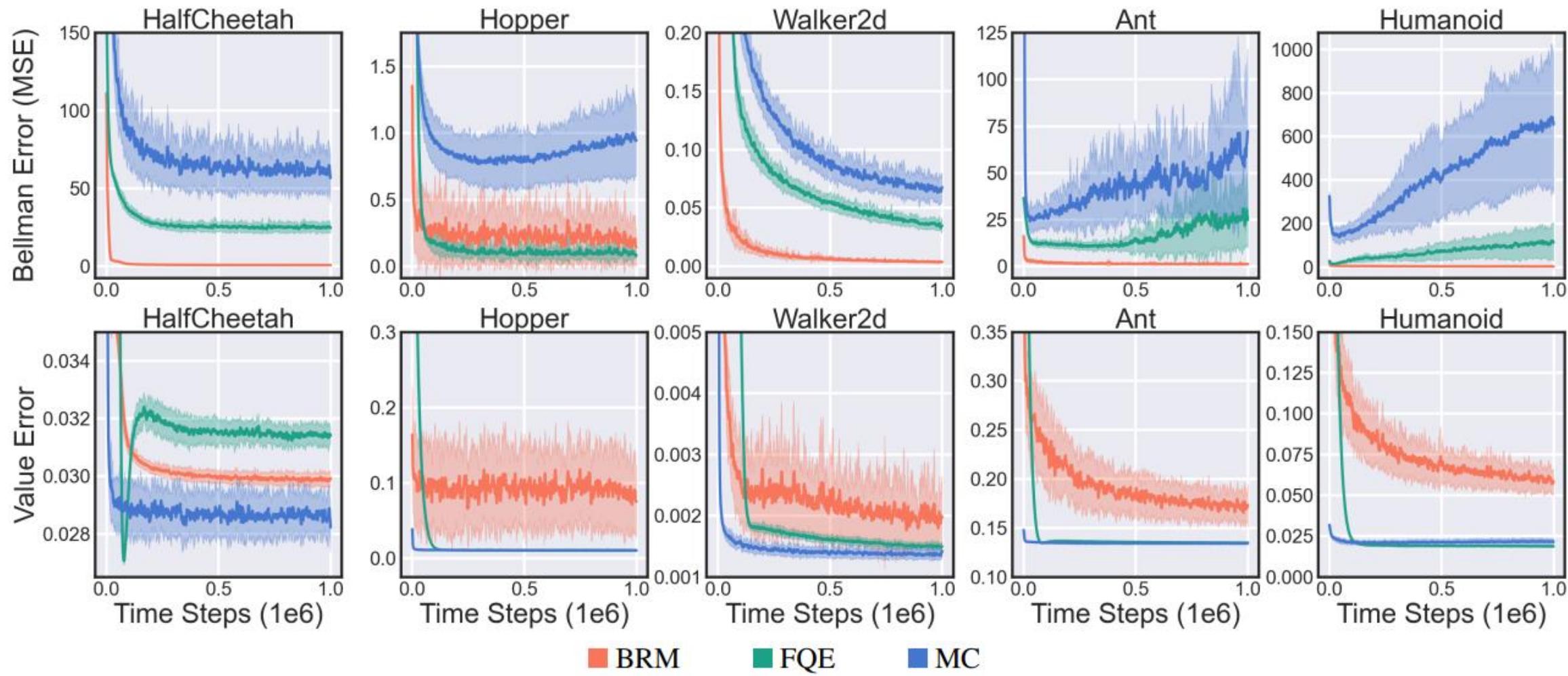


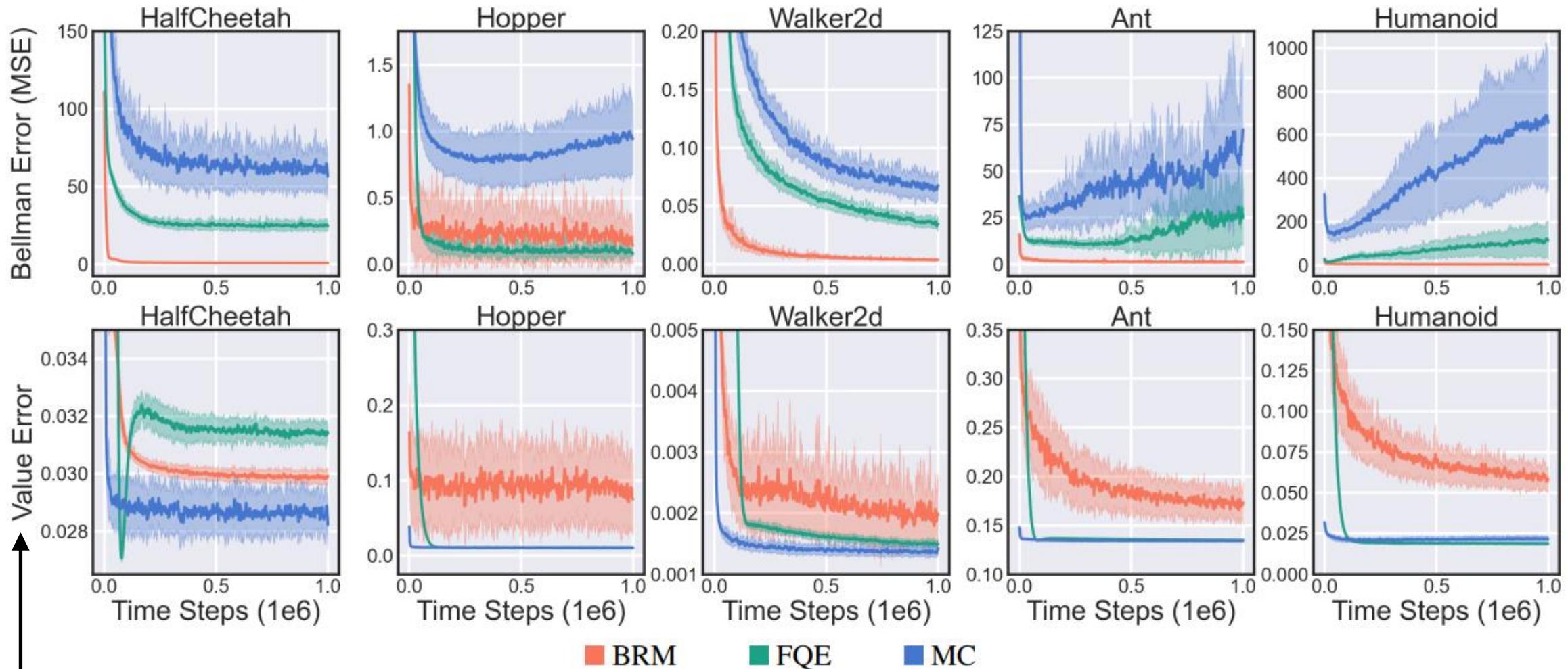


Bellman Error



Monte-Carlo Policy Evaluation (MC) does not consider the Bellman error.
Fitted Q-Evaluation (FQE) indirectly minimize the Bellman error.
Bellman Residual Minimization (BRM) directly minimizes the Bellman error.





Normalized Value Error

Problem 2: Missing Transitions Breaks the Bellman Equation

Can we make Bellman error work as an off-policy objective?

Recall:

If the Bellman error = 0 for all state-action pairs, then value error = 0.

What if we are missing data?

Bellman Equations over an Incomplete Dataset

Consider a set of Bellman equations:

$$\begin{bmatrix} Q(s_0, a_0) = r_1 + \gamma Q(s_1, a'_1) \\ Q(s_1, a_1) = r_2 + \gamma Q(s_2, a'_2) \\ \vdots \\ Q(s_{N-1}, a_{N-1}) = r_N + \gamma Q(s_N, a'_N) \end{bmatrix}$$

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N Variables

Bellman Equations over an Incomplete Dataset

Consider a set of Bellman equations:

$$\left[\begin{array}{l} Q(s_0, a_0) \\ Q(s_1, a_1) \\ \vdots \\ Q(s_{N-1}, a_{N-1}) \end{array} \right] = r_1 + \gamma \left[\begin{array}{l} Q(s_1, a'_1) \\ Q(s_2, a'_2) \\ \vdots \\ Q(s_N, a'_N) \end{array} \right]$$

N Variables

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An underdetermined system = infinite solutions

Bellman Equations over an Incomplete Dataset

Consider a set of Bellman equations:

$$\left. \begin{aligned}
 Q(s_0, a_0) &= r_1 + \gamma Q(s_1, a'_1) \\
 Q(s_1, a_1) &= r_2 + \gamma Q(s_2, a'_2) \\
 &\vdots \\
 Q(s_{N-1}, a_{N-1}) &= r_N + \gamma Q(s_N, a'_N)
 \end{aligned} \right\} \text{N Equations}$$

N Variables

N Variables = 2N Variables

An underdetermined system = infinite solutions

Problem: Not every solution has low value error.

Bellman Equations over an Incomplete Dataset

Consider a single transition (where $r = 0$):

$$Q(s, a) = 0 + \gamma Q(s', a')$$

If we set $Q(s', a') = 100$ then $Q(s, a) = 100\gamma$

If we set $Q(s', a') = 0$ then $Q(s, a) = 0$

In both cases the Bellman error is 0, but the value prediction is very different.

In our experiments we show...

When working with off-policy datasets...

Minimizing the Bellman error finds value functions with low Bellman error but high value error.

⇒ The Bellman error is not a meaningful off-policy objective.

Summary

- (1) The magnitude of the Bellman error is influenced heavily by bias.
- (2) Low Bellman error has little significance if there is missing data.

⇒ The Bellman error is not a good proxy for value error.

Additional insights, analysis, and experiments in the paper.

Thanks for listening!