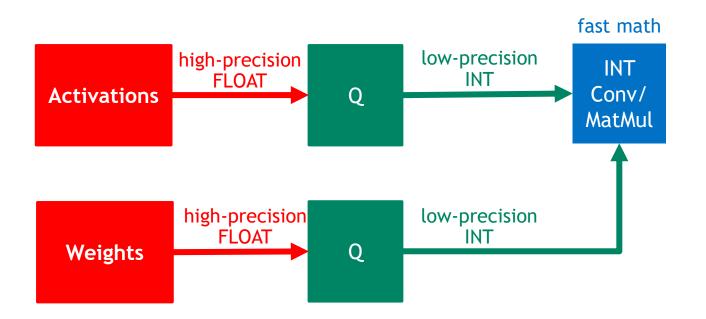
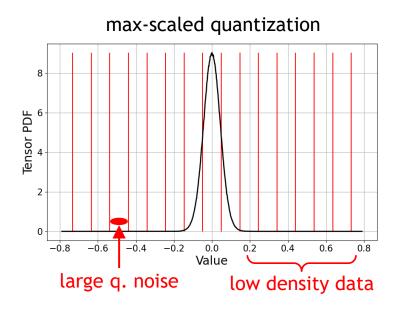
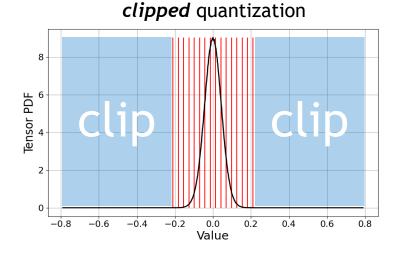


NEURAL NETWORK QUANTIZATION



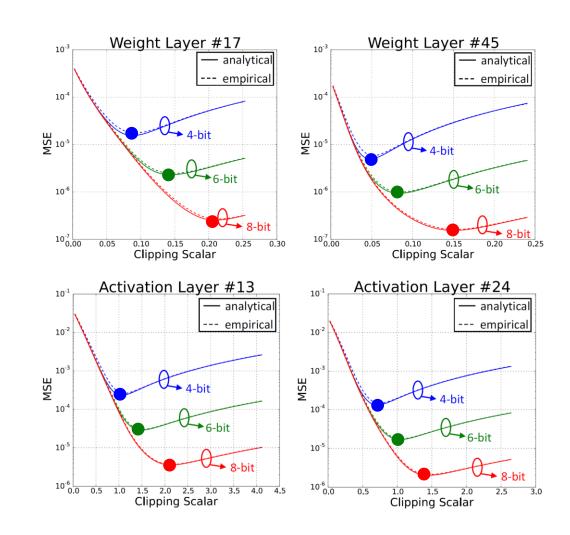
- Convert a floating-point model to low-precision format
 - Reduce hardware cost of implementation
 - Focus on integer quantization
- Problem: Quantization to low bit-width induces large noise
- Solution: Improve quantization using clipping





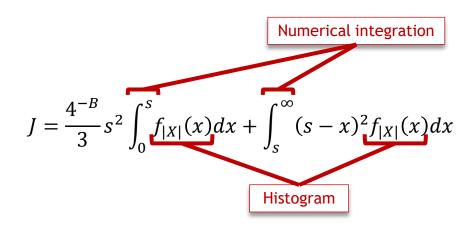
OPTIMALLY CLIPPED QUANTIZATION

- Mean squared error (MSE) $J = E[(Q[X] X)^2]$
 - Analytical: $J = \frac{4^{-B}}{3}s^2 \int_0^s f_{|X|}(x)dx + \int_s^\infty (s-x)^2 f_{|X|}(x)dx$
 - Empirical: averaged over tensor entries
 - Both curves closely track each other
- There exists an optimal choice of clipping scalar s^*
 - Balances clipping and discretization noise
 - $s < s^* \Rightarrow$ excess clipping
 - $s > s^* \Rightarrow$ large quantization step
- Optimum depends on number of bits
 - $s^*@4$ -bit $\neq s^*@6$ -bit $\neq s^*@8$ -bit
- Optimum depends on data distribution
 - s^* @WL-17 $\neq s^*$ @WL-45 $\neq s^*$ @AL-13 $\neq s^*$ @AL-24 $\neq \cdots$
- How can we find this optimum?



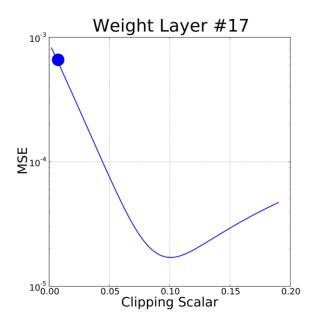
FINDING OPTIMAL CLIPPING SCALAR

- Using analytical formula:
 - Build histogram to approximate data distribution
 - Numerically integrate MSE for every candidate s



- Both approaches are computationally inefficient
 - Can be done offline (for weights) but takes a very long time
 - Unrealistic for dynamic activations
- Our contribution: an algorithm to find this optimum on the fly

- Empirically measure MSE $J = E[(Q[X] X)^2]$
 - Quantize tensor and evaluate square differences
 - Repeat for every candidate s



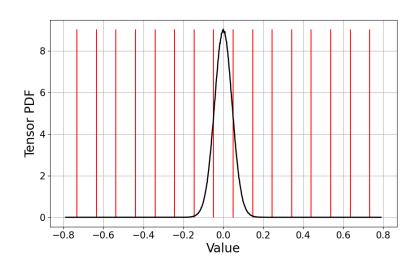
OPTIMIZING CLIPPING SCALARS ON THE FLY

OCTAV: Optimally Clipped Tensors and Vectors

- Fast recursive algorithm based on the Newton-Raphson method to determine MSE-minimizing clipping scalar s^*
- Quickly computes s* for every tensor at every iteration
- QAT is implemented with minimum quantization noise

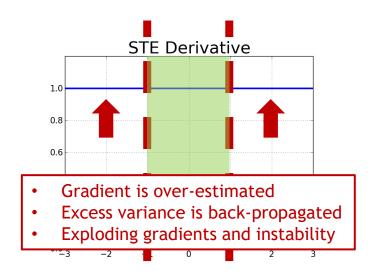
Main idea

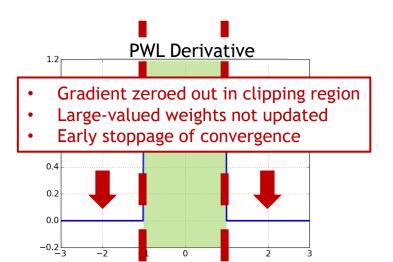
- Optimal clipping scalar: $s_0 = \arg\min J(s) = \frac{4^{-B}}{3} s^2 E[\mathbf{1}_{\{|X| < s\}}] + E[(s |X|)^2 \cdot \mathbf{1}_{\{|X| > s\}}]$
- Newton-Raphson method: $s_{n+1} = s_n \frac{J'(s_n)}{J''(s_n)}$
- Resulting recursion: $s_{n+1} = \frac{E[|X| \cdot \mathbf{1}_{\{|X| > s_n\}}]}{\frac{4^{-B}}{3} E[\mathbf{1}_{\{|X| < s_n\}}] + E[\mathbf{1}_{\{|X| > s_n\}}]}$
- Mathematical details and proofs in paper

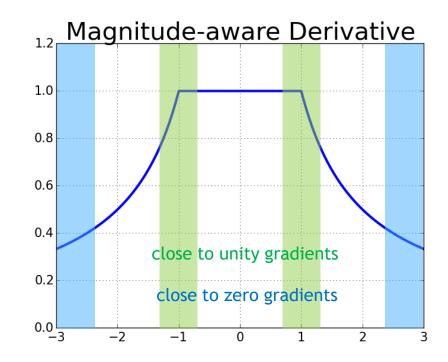




MAGNITUDE-AWARE DIFFERENTIATION







Treat clipping as magnitude attenuation operation

$$dx = \left(\mathbf{1}_{\{x \in [-s,s]\}} + \frac{s}{|x|} \mathbf{1}_{\{x \notin [-s,s]\}}\right) dy$$

- Smaller clipped values have gradients close to but less than unity
- Larger clipped values have gradients close to but greater than zero

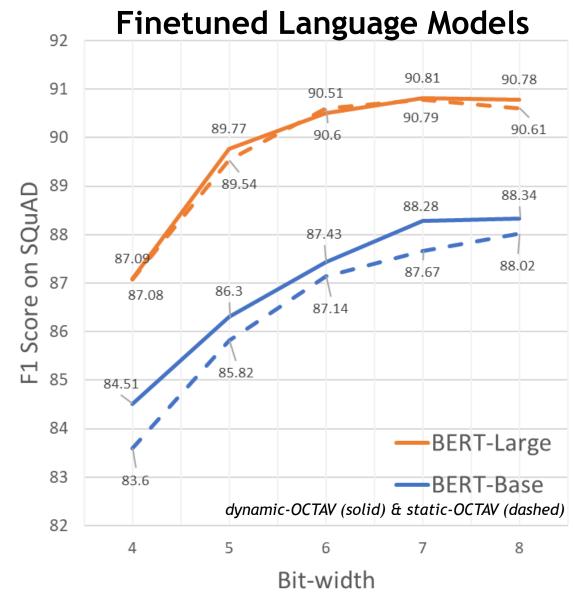


SELECTED EMPIRICAL RESULTS

4-bit ImageNet Networks

| Network | ResNet | ResNet | MobileNet | MobileNet |
|-------------------------------------|---------|---------|-----------|-----------|
| | 50 | 101 | V2 | V3-Large |
| Training-from-scratch Dynamic OCTAV | 75.15 | 76.48 | 70.88 | 65.86 |
| | (-0.92) | (-0.80) | (-0.83) | (-7.11) |
| Retraining | 76.21 | 76.84 | 71.23 | 69.21 |
| Dynamic OCTAV | (+0.14) | (-0.44) | (-0.48) | (-3.76) |
| Retraining | 76.46 | 77.48 | 1.21 | 0.60 |
| Static OCTAV | (+0.39) | (+0.20) | (-70.50) | (-72.37) |

- SOTA accuracy achieved
 - 4-bit training and retraining of ImageNet networks
 - BERT finetuning at very low precision
- Our results require no modification to the training recipe





CONCLUSION

- Optimally Clipped Tensors and Vectors
- Magnitude-Aware Differentiation
- Empirical results show OCTAV-enabled QAT has SOTA accuracy
- Future work: other number formats, fully quantized training, alternate metrics to MSE, beyond quantization

