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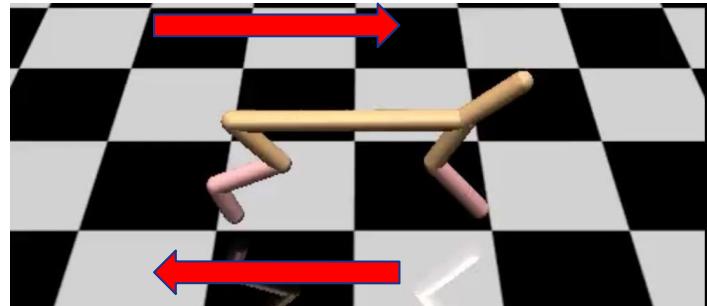
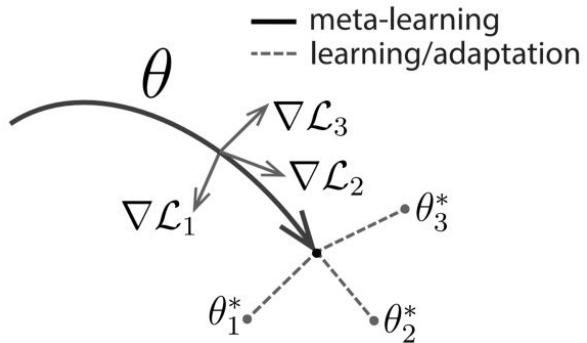
Biased Gradient Estimate With Drastic Variance Reduction For Meta Reinforcement Learning

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Summary of results

- Meta-RL carries out fast adaptation when agent faces a new environment



What we found in a nutshell

- Unbiased meta-gradient estimates have **huge variance** – $O(N)$
 - N – number of inner loop samples
- Biased gradient estimate has better trade-off – **bias** $O(1/N)$ and **variance** $O(1/N)$
 - Sit between score-function estimate and “golden-rule” path-wise estimate



Meta-RL optimization problem with one-step adaptation

- Basic notations

- Policy parameter $\theta \in \Theta$
- Value function $V(\theta)$
- Trajectory $(\tau_i)_{i=1}^N \sim p_\theta$
- Trajectory return $R(\tau_i)$

$$\underbrace{R(\tau_i) \nabla_\theta \log p_\theta(\tau_i)}$$

One-sample estimate to PG

$$\max_{\theta} \mathbb{E}_{(\tau_i)_{i=1}^N \sim p_\theta} \left[V \left(\theta + \eta \frac{1}{N} \sum_{i=1}^N R(\tau_i) \nabla_\theta \log p_\theta(\tau_i) \right) \right]$$

Outer loop evaluation:

Post-adaptation performance

Inner loop update:

One-step N-sample PG estimate



N-sample Monte-Carlo objective

- Classic Monte-Carlo objective

$$L(\theta) = \mathbb{E}_{X \sim p_\theta} [f(X)]$$

- N-sample Monte-Carlo objective

$$L_N(\theta) = \mathbb{E}_{(X_i)_{i=1}^N \sim p_\theta} \left[f \left(\underbrace{\frac{1}{N} \sum_{i=1}^N X_i}_{\neq \frac{1}{N} \sum_{i=1}^N f(X_i)} \right) \right]$$

- One-step meta-RL is a special instance
 - Slight modifications – see paper



Unbiased stochastic gradient estimate

- Unbiased gradient estimate → score-function (SF) estimate has high variance

$$f \left(\frac{1}{N} \sum_{i=1}^N X_i \right) \sum_{i=1}^N \nabla_{\theta} \log p_{\theta}(X_i), \quad (X_i)_{i=1}^N \sim p_{\theta}$$


"Sum" not "average"

- Can construct examples where the variance is $O(N)$
 - In practice (toy example and deep RL), SF exhibits high variance too



Deriving biased gradient estimate

- Limiting behavior of the estimate

$$f \left(\overbrace{\frac{1}{N} \sum_{i=1}^N X_i}^{\rightarrow \mu_\theta} \right) \sum_{i=1}^N \nabla_\theta \log p_\theta(X_i), \quad (X_i)_{i=1}^N \sim p_\theta$$

- Introduce an “unknown” control variate

$$\left(f \left(\frac{1}{N} \sum_{i=1}^N X_i \right) - f(\mu_\theta) \right) \sum_{i=1}^N \nabla_\theta \log p_\theta(X_i)$$

- To bypass the “unknown” control variate
 - First-order Taylor expansion → make use of gradient information → **create bias reduces variance**
 - **Linearized score-function (LSF)**



Biased estimate with drastic variance reduction

- Final LSF estimate

$$\frac{1}{N} \sum_{i=1}^N \left[\nabla f \left(\frac{1}{N} \sum_{i=1}^N X_i \right) \right]^T X_i \cdot \nabla_{\theta} \log p_{\theta}(X_i)$$

Make use of gradient information

“Average” not “sum”

- Theoretical properties: bias $O(1/N)$ and variance $O(1/N)$
 - See paper for formal statements
- An interpolation of “SF estimate” and “path-wise estimate (PW estimate)”
 - “Blackbox” – compatible with RL and meta-RL, similar to SF estimate
 - “Low variance” – make use of gradient information – similar to PW estimate



Back to meta-RL

- N-sample MC objective recovers one-step meta-RL as a special case
 - Derive the corresponding LSF:

$$\left(I + \eta \hat{H}_\theta \right) \cdot \nabla \hat{V} \left(\theta + \eta \frac{1}{N} \sum_{i=1}^N R(\tau_i) \nabla_\theta \log p_\theta(\tau_i) \right)$$

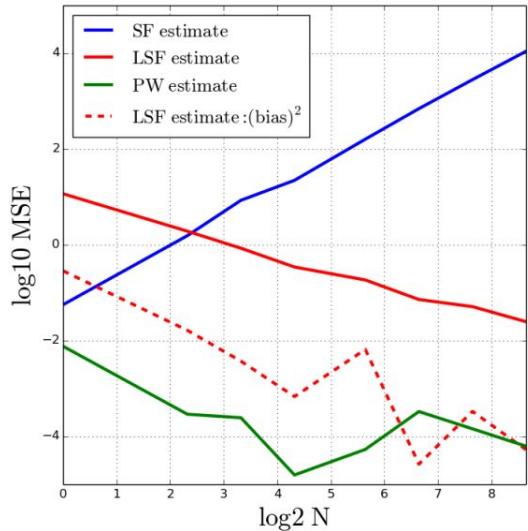
Inner loop Hessian Outer loop gradient

- Convergence guarantees have nicer dependencies on N , compared to SF (Fallah et al, 2020)

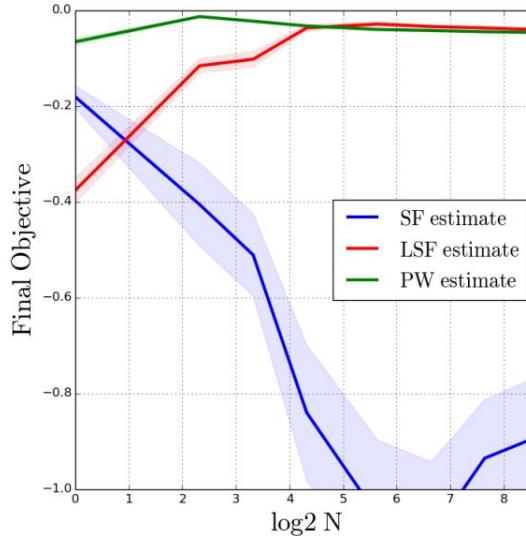


Experiments: 1-D toy example

$$\max_{\theta} L_N(\theta) = \mathbb{E}_{(X_i)_{i=1}^N \sim p_{\theta}} [-(\bar{X}_N - 1)^2]$$



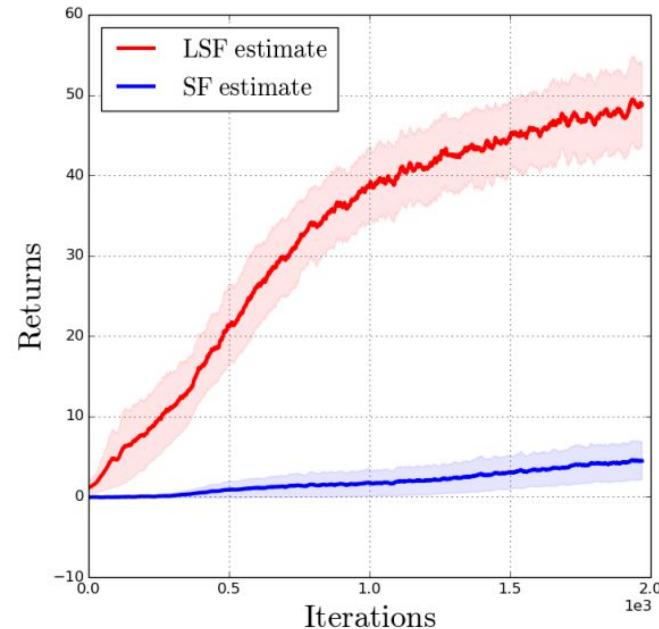
(a) Bias-variance trade-off



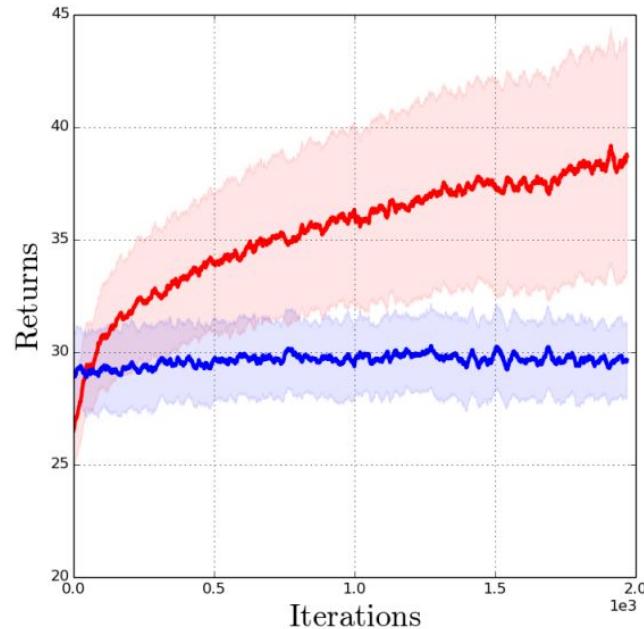
(b) 1-D Optimization



Experiments: deep RL



(c) Meta-RL HalfCheetah



(d) Meta-RL Walker2D



Summary

- Most prior work on “unbiased meta-gradient estimates for RL” are in fact **biased**.
- Some meta-gradient estimates are biased for a very good reason – **drastic variance reduction**.





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Thank you!

