

Robust SDE-Based Variational Formulations for Solving Linear PDEs via Deep Learning

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(equal contribution)

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Scope: Linear Kolmogorov PDEs

- We want to solve PDEs (*partial differential equations*) of the form

$$\left(\partial_t + \frac{1}{2}(\sigma\sigma^\top) : \nabla^2 + b \cdot \nabla \right) V(x, t) = 0, \quad V(x, T) = g(x), \quad (x, t) \in \mathbb{R}^d \times [0, T].$$

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- **Applications:** modelling of diffusion processes in physics, pricing of financial derivatives, reinforcement learning, diffusion-based generative modeling, ...
- **Idea:** minimize *variational formulations* using neural networks $u_\theta \in \mathcal{U}$ with parameters θ , i.e. consider losses

$$\mathcal{L} : \mathcal{U} \rightarrow \mathbb{R}_{\geq 0},$$

which shall be minimal iff $u \in \mathcal{U}$ fulfills the PDE.

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- **Stochastic representation:** *Itô calculus* (cf. Feynman-Kac formula) shows

$$\underbrace{g(X_T) - V(\xi, \tau)}_{:=\Delta_V} - \underbrace{\int_{\tau}^T \sigma(X_s)^\top \nabla V(X_s, s) \cdot dW_s}_{:=S_V} = 0,$$

where X is the solution to the SDE (*stochastic differential equation*)

$$dX_s = b(X_s) ds + \sigma(X_s) dW_s, \quad X_\tau = \xi.$$

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- As the stochastic integral S_u has vanishing expectation, this motivates the two losses

$$\mathcal{L}_{\text{FK}}(u) := \mathbb{E} [\Delta_u^2] \quad \text{and} \quad \mathcal{L}_{\text{BSDE}}(u) := \mathbb{E} [(\Delta_u - S_u)^2],$$

where $(\xi, \tau) \sim \text{Unif}(\mathbb{R}^d \times [0, T])$.

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Proposition (Variance of Losses)

$$\mathbb{V} \left[\mathcal{L}_{\text{FK}}^{(K)}(u_\theta) \right] = \frac{1}{K} \mathbb{V} [S_V^2] \quad \text{and} \quad \mathbb{V} \left[\mathcal{L}_{\text{BSDE}}^{(K)}(u_\theta) \right] = 0.$$

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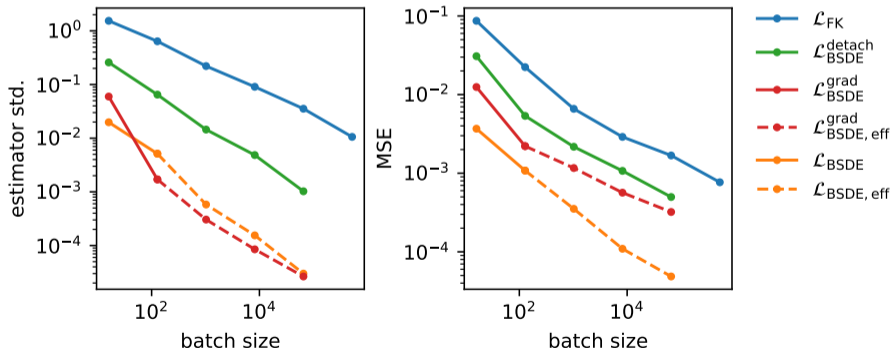
Proposition (Variance of Gradients)

$$\mathbb{V} \left[\nabla_\theta \mathcal{L}_{\text{FK}}^{(K)}(u_\theta) \right] = \frac{4}{K} \mathbb{V} [S_V \nabla_\theta u_\theta(\xi, \tau)] \quad \text{and} \quad \mathbb{V} \left[\nabla_\theta \mathcal{L}_{\text{BSDE}}^{(K)}(u_\theta) \right] = 0.$$

- We propose various versions to include the control variate: $\mathcal{L}_{\text{BSDE}}^{\text{grad}}$, $\mathcal{L}_{\text{BSDE}}^{\text{detach}}$ and $\mathcal{L}_{\text{BSDE}, \text{eff}}$.

Numerical Experiments

- We propose various versions to include the control variate: $\mathcal{L}_{\text{BSDE}}^{\text{grad}}$, $\mathcal{L}_{\text{BSDE}}^{\text{detach}}$ and $\mathcal{L}_{\text{BSDE}, \text{eff}}$.
- We improve state-of-the-art performance and analyze trade-offs between accuracy and complexity.



Thank you for your attention!

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Source code: https://github.com/juliusberner/robust_kolmogorov