

Convergence and Recovery Guarantees of the K-Subspaces Method for Subspace Clustering

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(Joint Work with Huikang Liu, Anthony Man-Cho So, and Laura Balzano)

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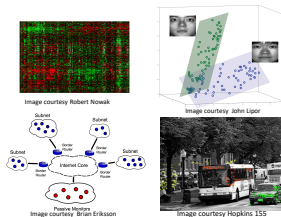
Outline

Introduction

Main Results

K-Subspaces Method (KSS)

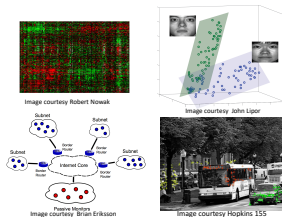
- Applications in computer vision, image segmentation, and network analysis...¹



¹Source papers for images: (Top right) Lipor, J. and Balzano, L. "Clustering quality metrics for subspace clustering." Pattern Recognition 104 (2020): 107328; (Bottom left) Eriksson, B., Balzano, L., and Nowak, R. "High-rank matrix completion." In Artificial Intelligence and Statistics, pp. 373-381. PMLR, 2012.

K-Subspaces Method (KSS)

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- KSS Formulation

$$\min_{\mathcal{C}, \mathbf{U}} \sum_{k=1}^K \sum_{i \in \mathcal{C}_k} \|\mathbf{z}_i - \mathbf{U}_k \mathbf{U}_k^T \mathbf{z}_i\|^2, \quad (1)$$

where $\mathbf{z}_i \in \mathbb{R}^n$ for all $i \in [N]$ denote data points, \mathcal{C}_k for all $k \in [K]$ denote estimated clusters, and \mathbf{U}_k denotes an orthonormal basis of the corresponding cluster.

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KSS Method with TIPS Initialization

- ▶ Given the t -th iterate $(\mathcal{C}_1^t, \dots, \mathcal{C}_K^t, \mathbf{U}_1^t, \dots, \mathbf{U}_K^t)$, KSS alternates between

- ▶ **Subspace update step**

$$\mathbf{U}_k^{t+1} = \text{PCA} \left(\sum_{i \in \mathcal{C}_k^t} \mathbf{z}_i \mathbf{z}_i^T, \hat{d}_k \right),$$

where \hat{d}_k for all $k \in [K]$ are candidate subspace dimensions.

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- ▶ **Cluster assignment step**

$i \in \mathcal{C}_k^{t+1}$, if $k \in [K]$ satisfies $\|\mathbf{U}_k^{t+1^T} \mathbf{z}_i\| \geq \|\mathbf{U}_\ell^{t+1^T} \mathbf{z}_i\|, \forall \ell \neq k$.

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- ▶ KSS: a generalization of the **k-means method**, handle clusters in subspaces.
- ▶ **Initialization method:** Thresholding inner-product based spectral (TIPS) method

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Master Theorems (Informal)

► **Theorem 1.** Suppose that the following hold:

- (i) (**Data input**) Let $\{z_i\}_{i=1}^N$ be generated by the UoS model, i.e., $z_i = U_k^* a_i$ for $i \in \mathcal{C}_k^*$, where $a_i \stackrel{i.i.d.}{\sim} \text{Unif}(\mathbb{S}^{d_k-1})$ for all $k \in [K]$.
- (ii) (**Affinity requirement**) $\text{aff}(S_k^*, S_\ell^*) / \min\{\sqrt{d_k}, \sqrt{d_\ell}\} \leq 1/2$ for all $1 \leq k \neq \ell \leq K$, where $\text{aff}(S_k^*, S_\ell^*) := \|U_k^{*T} U_\ell^*\|_F$.
- (iii) (**Sampling requirement**) $N_{\min} \gtrsim d_k \gtrsim \log N$ for all $k \in [K]$.
- (iv) (**Initial requirement**) The initial assignment $\mathbf{H}^0 \in \mathcal{M}^{N \times K}$ satisfies

$$d_F(\mathbf{H}^0, \mathbf{H}^*) \lesssim \frac{N_{\min}}{\sqrt{N}}. \quad (2)$$

The following statement holds with probability at least $1 - N^{-\Omega(1)}$: The KSS method converges superlinearly and finds the true partition within $\Theta(\log \log N)$ iterations.

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► **Theorem 2.** It holds with probability at least $1 - N^{-\Omega(1)}$ that the TIPS method can return a qualified initial point that satisfies (2).

Comments on the Master Theorems

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- ▶ A neighborhood of size $O\left(\frac{N_{\min}}{\sqrt{N}}\right)$ around each true cluster forms a *basin of attraction* in the UoS model, in which the KSS method converges superlinearly.
- ▶ Any method that can return a point satisfying (2) is qualified as an initialization scheme for the KSS method. In this work, we design a TIPS method that can provably generate a qualified point.

Thank You!