

Generalization Bounds using Lower Tail Exponents in Stochastic Optimizers

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**What are generalization
bounds?**

Empirical Risk Minimization

To train parameterized models, solve

$$w^* = \arg \min_w \mathcal{R}_n(w), \quad \mathcal{R}_n(w) := \frac{1}{n} \sum_{i=1}^n \ell(w, X_i),$$

for a loss ℓ depending on weights w and data

$$X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \mathcal{D}.$$

Generalization bounds

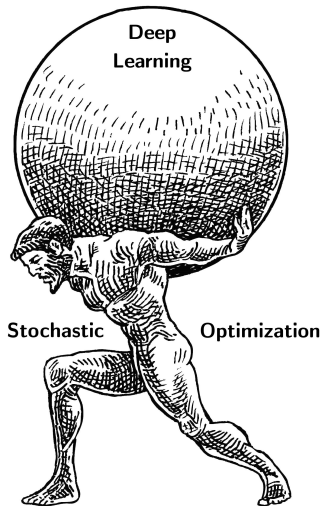
Bounds on the *generalization error*

$$\mathcal{E}_n(w^*) = \mathcal{R}_n(w^*) - \underbrace{\mathbb{E}_{\mathcal{D}} \mathcal{R}_n(w^*)}_{\text{population risk}}$$

Stochastic optimization

is the process of minimizing an objective function via the simulation of random elements.

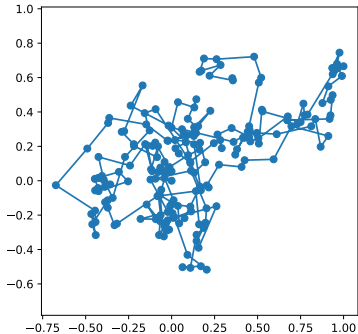
“the backbone of modern machine learning”



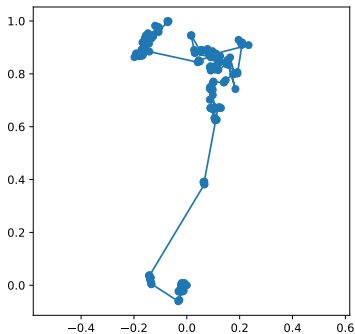
**How do the dynamics of
the optimizer influence
generalization?**

Types of Dynamics

Brownian motion
light-tailed

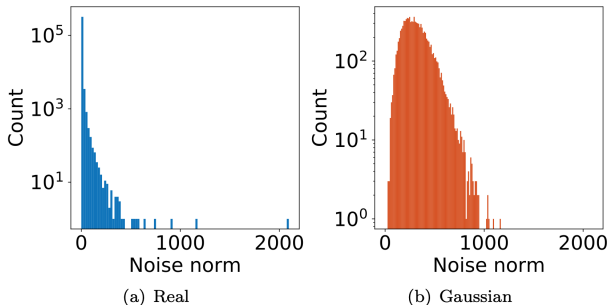


Lévy flight
heavy-tailed



Heavy Tails in Machine Learning

Norms of optimizer steps in a deep learning task



Şimşekli, U., Sagun, L., & Gurbuzbalaban, M. (2019, May). A tail-index analysis of stochastic gradient noise in deep neural networks. In International Conference on Machine Learning (pp. 5827-5837). PMLR.

Previous Work

Under a **(continuous-time) Feller process model** of SGD,

heavier tails \implies smaller \mathcal{E}_n .



Şimşekli, U., Sener, O., Deligiannidis, G., & Erdogdu, M. A. (2020). Hausdorff dimension, heavy tails, and generalization in neural networks. *Advances in Neural Information Processing Systems*, 33, 5138-5151.

- ▶ Complicated assumptions
- ▶ What about **discrete time**, i.e. SGD itself?

Markov Assumption

Assume that the iterates of the
optimizer

$$W_1, W_2, \dots, W_k, \dots$$

are a **Markov chain**.

Upper Tail Exponent

Previous works have considered the
upper tail exponent:

$$\mathbb{P}(\|W_{k+1} - W_k\| > r) \approx \mathcal{O}(r^{-\beta}).$$

as $r \rightarrow \infty$.

Lower Tail Exponent

What about the **lower tail exponent**?

$$\mathbb{P}(\|W_{k+1} - W_k\| \leq r) \approx \mathcal{O}(r^\alpha).$$

as $r \rightarrow 0^+$.

Lower Tail Exponent

Theorem (Informal)

Assume that iterates W_k of an optimizer satisfy

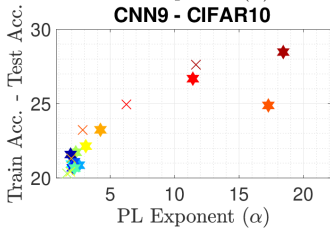
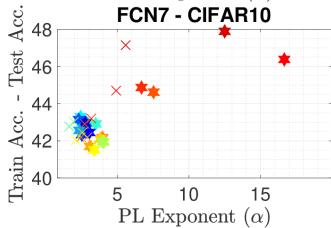
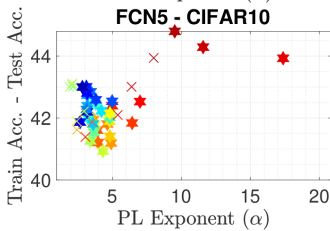
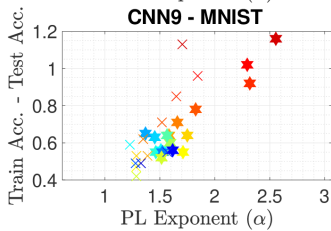
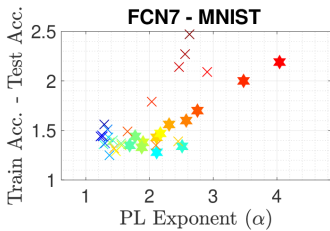
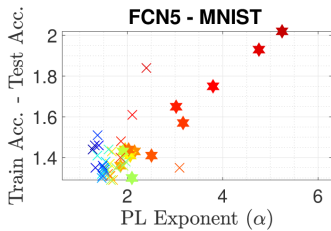
$$\mathbb{P}(\|W_{k+1} - W_k\| \leq r) \approx \mathcal{O}(r^\alpha)$$

in the neighbourhood of a local optimum w^* . Then an upper bound on

$$\mathbb{E} \sup_{k=1, \dots, m} |\mathcal{E}_n(W_k)| \text{ is positively correlated with } \alpha.$$

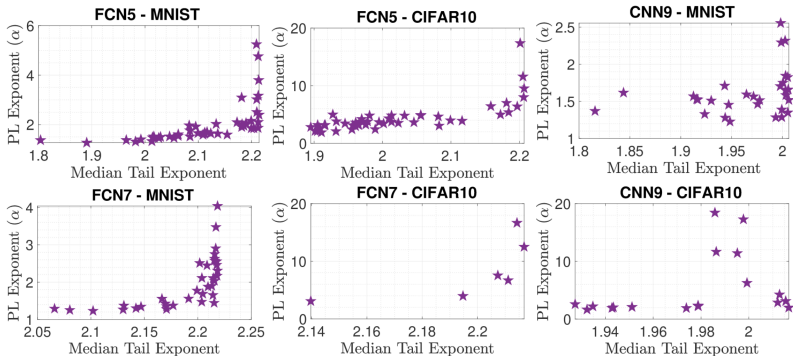
Is this true in practice?

*Train NNs with **varying hyperparameters** &
regularization*



Lower Tail Exponent

Lower tail often correlates with upper tail



Contributions and Conclusions

- ▶ Developed a **general proof technique** for linking optimizer dynamics to generalization
- ▶ Extended results of Şimşekli et al., 2020.
- ▶ Lower tail exponent correlates with \mathcal{E}_n
 - ▶ Supported in practice
 - ▶ Lower tail correlates with upper tail