

Fast Provably Robust Decision Trees and Boosting

Jun-Qi Guo, Ming-Zhuo Teng, Wei Gao and Zhi-Hua Zhou

Nanjing University



About this work

Much attention has been paid to Robust decision trees and ensembles

Previous methods: high comp. or no guarantee of provable robustness

In this work, we propose:

✓ Fast Provably Robust Decision Tree (FPRDT)

- A tradeoff between local and global optimization
- the smallest computational complexity

✓ Provably Robust AdaBoost (PRAdaBoost)

- the smallest computational complexity

Methods	Comp. complexity	Prov. robustness
Our FPRDT	$O(n \log n)$	✓
Our PRAdaBoost	$O(n \log n)$	✓
ROCT (Vos & Verwer, 2021b)	$O(\exp(n))$	✓
TREANT (Calzavara et al., 2020)	$O(n^2)$	✓
PRB (Andriushchenko & Hein, 2019)	$O(n^2)$	✓
GROOT (Vos & Verwer, 2021a)	$O(n \log n)$	✗
RIGDT-heuristic (Chen et al., 2019a)	$O(n \log n)$	✗
RGBDT (Chen et al., 2019a)	$O(n \log n)$	✗
AdvBoost (Kantchelian et al., 2016)	$O(n \log n)$	✗

Outline

- **Introduction**

- Our work

 - Robust decision trees

 - Robust AdaBoost

- Experiments

- Conclusion

Decision tree and ensembles

Decision trees and ensembles are important learning algorithms

- Decision trees [Quinlan et al., 1986; Safavian et al., 1991; Maimon et al., 2014]
- AdaBoost [Freund et al., 1996; Ratsch et al., 2001; Bartlett et al., 2006]
- Random forests [Breiman, 2001; Biau, 2012; Athey et al., 2019]
-

Those models are **vulnerable** to adversarial perturbations:

$$\begin{array}{ccc}
 \begin{array}{c} \text{Image of digit 1} \\ \text{Prediction: "1"} \\ \text{Loss: 0} \end{array} & + 0.1 \times & \begin{array}{c} \text{Adversarial perturbation} \\ \text{Image of noise} \end{array} = \begin{array}{c} \text{Image of digit 7} \\ \text{Prediction: "7"} \\ \text{Loss: 1} \end{array}
 \end{array}$$

Previous robust decision trees and ensembles

- Global robust decision tree [Vos et al., 2021b]
 - Boosting method [Andriushchenko et al., 2019; Chen et al., 2019]
 - Local robust decision tree [Chen et al., 2019; Vos et al., 2021a]
 - Random forests based method [Vos et al., 2021a]
 -
- } **high comp. complexity**
- } **no guarantee of provable robust.**

Can we learn robust decision trees and Boosting with

- **low computational complexity**
- **guarantees of provable robustness**

Outline

- Introduction
- **Our work**
 - **Robust decision trees**
 - Robust AdaBoost
- Experiments
- Conclusion

Adversarial robust learning

Adversarial robust learning aims to optimize

$$\min_{h \in \mathcal{H}} \sum_{i=1}^n \max_{\|z_i - x_i\|_{\infty} < \epsilon} l(h(z_i), y_i)$$

- training data $\{(x_1, y_1), \dots, (x_n, y_n)\}$
- learning model $h \in \mathcal{H}$
- loss function $l(\cdot, \cdot) \rightarrow R$

Our work: decision tree model h

the 0/1 loss $l(h(z_i), y_i) = \mathbb{I}[h(z_i) \neq y_i]$

Objective loss for robust decision tree

- A decision tree has m leaf nodes
- Outputs $v_j = h(\mathbf{z})$ for instance $\mathbf{z}$, which is belong to the j -th leaf

Our objective loss for decision tree is given by

$$\sum_{i=1}^n \max_{\|\mathbf{z}_i - \mathbf{x}_i\|_\infty < \epsilon} l(h(\mathbf{z}_i), y_i) = \sum_{i=1}^n \max_{j \in [m]} \{ \mathbb{I}[v_j \neq y_i] \cdot \text{Fall}(i, j) \}$$

Traversing
all nodes

Is the i -th instance
belong to the j -th leaf

Main idea: potential predictions of $\mathbf{x}_i$ can be solved by traversing all nodes for decision tree

Decomposition of objective loss at a split

- Split the p -th leaf to leaves l and r
- Let v_l and v_r denote the output for two leaves, respectively

We can decompose the objective loss at the split on the p -th leaf as

$$\begin{aligned}
 & \max_{j \in \{l, r\} \cup [m] \setminus p} \{\mathbb{I}[v_j \neq y_i] \text{Fall}(i, j)\} \\
 &= \underbrace{\max\{\mathbb{I}[v_l \neq y_i] \text{Fall}(i, l), \mathbb{I}[v_r \neq y_i] \text{Fall}(i, r)\}}_{\substack{\text{loss for left child} \\ \text{(easy)}}} \underbrace{\max_{j \in [m] \setminus \{p\}} \{\mathbb{I}[v_j \neq y_i] \text{Fall}(i, j)\}}_{\substack{\text{loss for right child} \\ \text{(easy)}}} \underbrace{\max_{j \in [m] \setminus \{p\}} \{\mathbb{I}[v_j \neq y_i] \text{Fall}(i, j)\}}_{\substack{\text{maximal loss for other leaves} \\ \text{(hard)}}}
 \end{aligned}$$

For simplicity, denote by $K_{ip} = \max_{j \in [m] \setminus \{p\}} \{\mathbb{I}[v_j \neq y_i] \text{Fall}(i, j)\}$

Calculate the maximal loss K_{ip}

- Split the p -th leaf to leaves l and r
- K_{ip} : the maximal loss for other leaves
- E_i : the sum of loss for all leaves

We determine K_{ip} by the E_i minus the loss for p -th leaf:

$$\underbrace{K_{ip}}_{\text{maximal loss for other leaves}} = 1 \quad \Leftrightarrow \quad \underbrace{E_i}_{\text{sum of loss for all leaves}} - \underbrace{\mathbb{I}[v_p \neq y_i] \text{Fall}(i, p)}_{\text{loss for } p\text{-th leaf}} \geq 1$$

E_i can be updated efficiently after each split.

Solution

Split the p -th leaf to leaves l and r

Let v_l and v_r denote the output for two leaves, respectively

Let t and η denote the split feature and threshold, respectively

The solution steps:

- Traverse all feature t
- Traverse threshold η from sorted potential splits
- Fixed t' and η' , by traverse $v_l, v_r \in \{0,1\}$, we solve

$$(v'_l, v'_r) = \operatorname{argmin}_{v_l, v_r \in \{0,1\}} L(t', \eta', v_l, v_r)$$

- Update the optimal solution

Fast Provably Robust Decision Trees

Algorithm 2 FPRDT-recursive

Input: Dataset S_n , split leaf p , perturbation size ϵ , previous optimal loss $\hat{\mathcal{L}}^{\text{pre}}$

Output: None

Initialize $\hat{\mathcal{L}}^* \leftarrow +\infty$

Compute loss K_{ip} ($i \in [n]$) according to Eqn. (3) calculate the maximum loss among other leaves

for $t' = 1$ **to** d **do**

 Compute $W_{t'}$ according to Eqn. (4) traverse potential split features and sorted thresholds

for η' **in** sorted($W_{t'}$) **do**

 Compute $\mathbb{I}[\mathcal{E}_{il} \neq \emptyset]$ and $\mathbb{I}[\mathcal{E}_{ir} \neq \emptyset]$ by Eqns. (5)-(6)

 Solve v'_l and v'_r from Eqn. (7) with optimal loss $\hat{\mathcal{L}}'$

if $\hat{\mathcal{L}}' < \hat{\mathcal{L}}^*$ **then**

$t^* = t', \eta^* = \eta', v_l^* = v'_l, v_r^* = v'_r, \hat{\mathcal{L}}^* = \hat{\mathcal{L}}'$ update the minimum loss and the optimal solution

end if

end for

end for

if $\hat{\mathcal{L}}^* < \hat{\mathcal{L}}^{\text{pre}}$ **then**

 Split leaf p via $\{t^*, \eta^*, v_l^*, v_r^*\}$, and obtain children l, r

 Update E_i ($i \in [n]$) according to Eqn. (8)

 FPRDT-recursive($S_n, l, \epsilon, \hat{\mathcal{L}}^*$)

 FPRDT-recursive($S_n, r, \epsilon, \hat{\mathcal{L}}^*$)

end if

Computation complexity $\mathcal{O}(n \log n)$

- sort the potential thresholds $\mathcal{O}(n \log n)$
- solve minimum $\mathcal{O}(n)$

Outline

- Introduction
- **Our Work**
 - Robust Decision Trees
 - **Robust AdaBoost**
- Experiments
- Conclusion

Upper bound on robust AdaBoost

AdaBoost essentially optimizes the exponential loss

For robust AdaBoost, it is an NP-hard problem to optimize the adversarial exponential loss [Kantchelian et al., 2013]

We consider **the upper bound** on adversarial exponential loss as

$$\max_{\|z_i - x_i\|_\infty < \epsilon} \exp\left(\sum_{j=1}^m -y_j \alpha_j h_j(z_i)\right) \leq \prod_{j=1}^m \max_{\|z_i - x_i\|_\infty < \epsilon} \{\exp(-y_i \alpha_j h_j(z_i))\}$$

Main idea: relax the robust problem to several robust sub-problems
for each base learner

Main idea of our fast provably robust AdaBoost

- We use **our fast provably robust decision trees** (FPRDT) as **base learner** by minimizing the weighted adversarial 0/1 loss
- Robust AdaBoost updates the instance weights by

$$w_{t+1,i} = w_{t,i} \max_{\|z_i - x_i\|_\infty < \epsilon} \{\exp(-y_i \alpha_t h_t(z_i))\}$$

Complexity $\mathcal{O}(n \log n)$: update the weights $\mathcal{O}(n)$
train the base learner $\mathcal{O}(n \log n)$

Convergence analysis for PRAdaBoost

Theorem Let $H(x)$ be the final classifier of PRAdaBoost with error ϵ_t for each iteration $t \in [T]$. We have

$$\frac{1}{n} \sum_{i=1}^n \min_{\|z_i - x_i\|_{\infty} < \varepsilon} \mathbb{I}[H(z_i) \neq y_i] \leq \exp \left(-2 \sum_{t=1}^T (0.5 - \epsilon_t)^2 \right)$$

As AdaBoost, empirical adversarial 0/1 error of PRAdaBoost has the exponential decrease with the iteration number T

Outline

- Introduction
- Our Work
 - Robust Decision Trees
 - Robust AdaBoost
- Experiments
- Conclusion

Benchmark datasets

Dataset (Perb.)	# Inst.	# Feat.	Dataset (Perb.)	# Inst.	# Feat.
ionos (.2)	351	34	cifar10:0v5 (.1)	12,000	3,072
breast (.3)	683	9	cifar10:0v6 (.1)	12,000	3,072
diabet (.05)	768	8	cifar10:4v8 (.1)	12,000	3,072
bank (.1)	1,372	4	mnist2v6 (.4)	13,866	784
Japan3v4 (.1)	3,087	14	mnist3v8 (.4)	13,966	784
har1v2 (.1)	3,266	561	F-mnist2v5 (.2)	14,000	784
spam (.05)	4,601	57	F-mnist3v4 (.2)	14,000	784
GesDvP (.01)	4,838	32	F-mnist7v9 (.2)	14,000	784
wine (.05)	6,497	11	mnist1v7 (.4)	15,170	784

- Number of instances: 351 ~ 15170
- Number of features: 4 ~ 3072
- Perturbation rate follows previous work

Compared methods

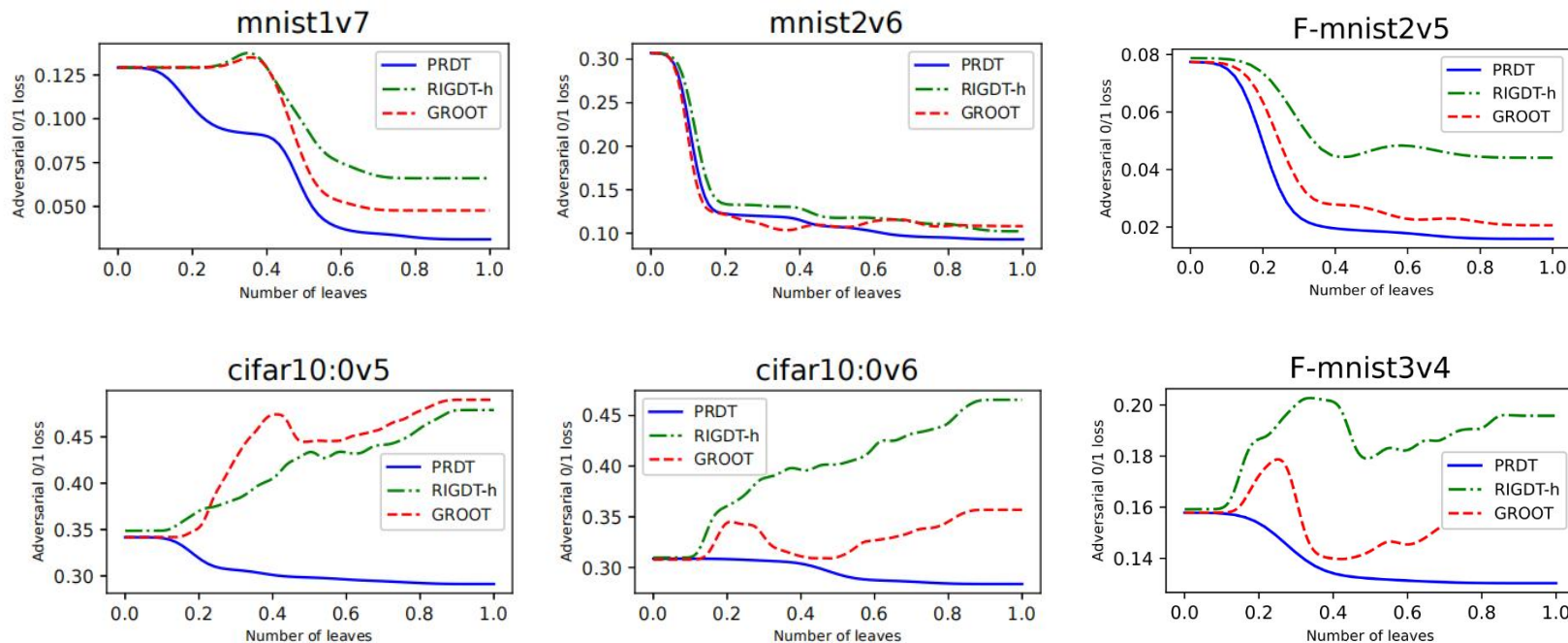
Robust decision trees

- **RIGBT-h**: Robust tree via adversarial information gain [Chen et al., 2019]
- **TREANT**: Robust tree with additional constraints [Calzavara et al., 2020]
- **GROOT**: Robust tree via adversarial Gini impurity [Vos et al., 2021a]
- **ROCT**: Robust tree with global optimization [Vos et al., 2021b]
- **PRB tree**: Robust tree based on adv. exp-loss [Andriushchenko et al., 2021]

Robust tree ensembles:

- **RGBDT**: Robust boosting via approximating adversarial loss [Chen et al., 2019]
- **RIGDT forest**: Random forest with base learner RIGBT-h [Vos et al., 2021b]
- **GROOT forest**: Random forest with base learner GROOT [Vos et al., 2021b]
- **PRBoosting**: Robust GBDT by upper bound of exp-loss [Andriushchenko et al., 2021]

Comparisons on training adversarial error



Our approach: **continuously decreases** the training adversarial errors

Unprovable methods: **may increase** the training adversarial errors

Accuracy comparisons for our FPRDT

Dataset	FPRDT	Decision tree	RIGDT-h	GROOT	TREANT	ROCT	PRB tree
ionos	.7954 ± .0302	.3100 ± .0549●	.7015 ± .0874●	.7829 ± .0325●	.7232 ± .0434●	.7897 ± .0330●	.7601 ± .0346●
breast	.8765 ± .0290	.2501 ± .0457●	.8381 ± .0317●	.8744 ± .0273	.8334 ± .0318●	.8735 ± .0256	.8706 ± .0258●
diabet	.6674 ± .0258	.6333 ± .0346●	.5695 ± .0640●	.6481 ± .0352●	.6695 ± .0228	.6552 ± .0244●	.6633 ± .0333
bank	.6577 ± .0311	.6333 ± .0346●	.4685 ± .0713●	.5410 ± .0440●	.6092 ± .0259●	.6539 ± .0167	.6299 ± .0328●
Japan3v4	.6673 ± .0129	.5751 ± .0377●	.5638 ± .0337●	.5829 ± .0468●	N/A	.6671 ± .0170	.5954 ± .0112●
har1v2	.8044 ± .0249	.2316 ± .0434●	.7074 ± .0257●	.8058 ± .0198	N/A	.7786 ± .0165●	.7383 ± .0148●
spam	.7404 ± .0124	.0006 ± .0012●	.4669 ± .1019●	.7231 ± .0188●	N/A	.4813 ± .0469●	.6968 ± .0110●
GesDvP	.7301 ± .0174	.4783 ± .1390●	.5483 ± .1035●	.7164 ± .0180●	N/A	.7071 ± .0126●	.7014 ± .0190●
wine	.6364 ± .0062	.3515 ± .1430●	.4032 ± .0375●	.6373 ± .0073	.6388 ± .0079○	.6117 ± .0343●	.6299 ± .0080●
cifar10:0v5	.6878 ± .0177	.2960 ± .0598●	.3469 ± .0457●	.4847 ± .0608●	N/A	.6639 ± .0113●	.6501 ± .0106●
cifar10:0v6	.6883 ± .0102	.5878 ± .0568●	.4771 ± .0168●	.5555 ± .0495●	N/A	.6684 ± .0077●	.6833 ± .0051●
cifar10:4v8	.6613 ± .0117	.2561 ± .0784●	.4882 ± .0468●	.4727 ± .0195●	N/A	.6319 ± .0114●	.6698 ± .0093○
mnist2v6	.8954 ± .0025	.0178 ± .0320●	.8850 ± .0079●	.8725 ± .0110●	N/A	.7842 ± .0222●	.8385 ± .0673●
mnist3v8	.8527 ± .0058	.0028 ± .0071●	.8102 ± .0102●	.7575 ± .0185●	N/A	.7565 ± .0280●	.8030 ± .0235●
F-mnist2v5	.9780 ± .0027	.3214 ± .2143●	.9446 ± .0080●	.9714 ± .0054●	N/A	.9394 ± .0128●	.9761 ± .0025●
F-mnist3v4	.8652 ± .0056	.0166 ± .0521●	.7928 ± .0129●	.8193 ± .0104●	N/A	.8271 ± .0168●	.8407 ± .0052●
F-mnist7v9	.8760 ± .0058	.2930 ± .1554●	.8100 ± .0108●	.8291 ± .0115●	N/A	.8376 ± .0188●	.8399 ± .0106●
mnist1v7	.9633 ± .0034	.0036 ± .0081●	.9325 ± .0076●	.9457 ± .0052●	N/A	.8937 ± .0095●	.9196 ± .0264●
Average	.7802 ± .1090	.2922 ± .2172	.6530 ± .1877	.7233 ± .1494	—	.7342 ± .1134	.7503 ± .1075
Win/Tie/Loss		18/0/0	18/0/0	15/3/0	16/1/1	15/3/0	16/1/1

Our FPRDT: significantly better than other decision trees

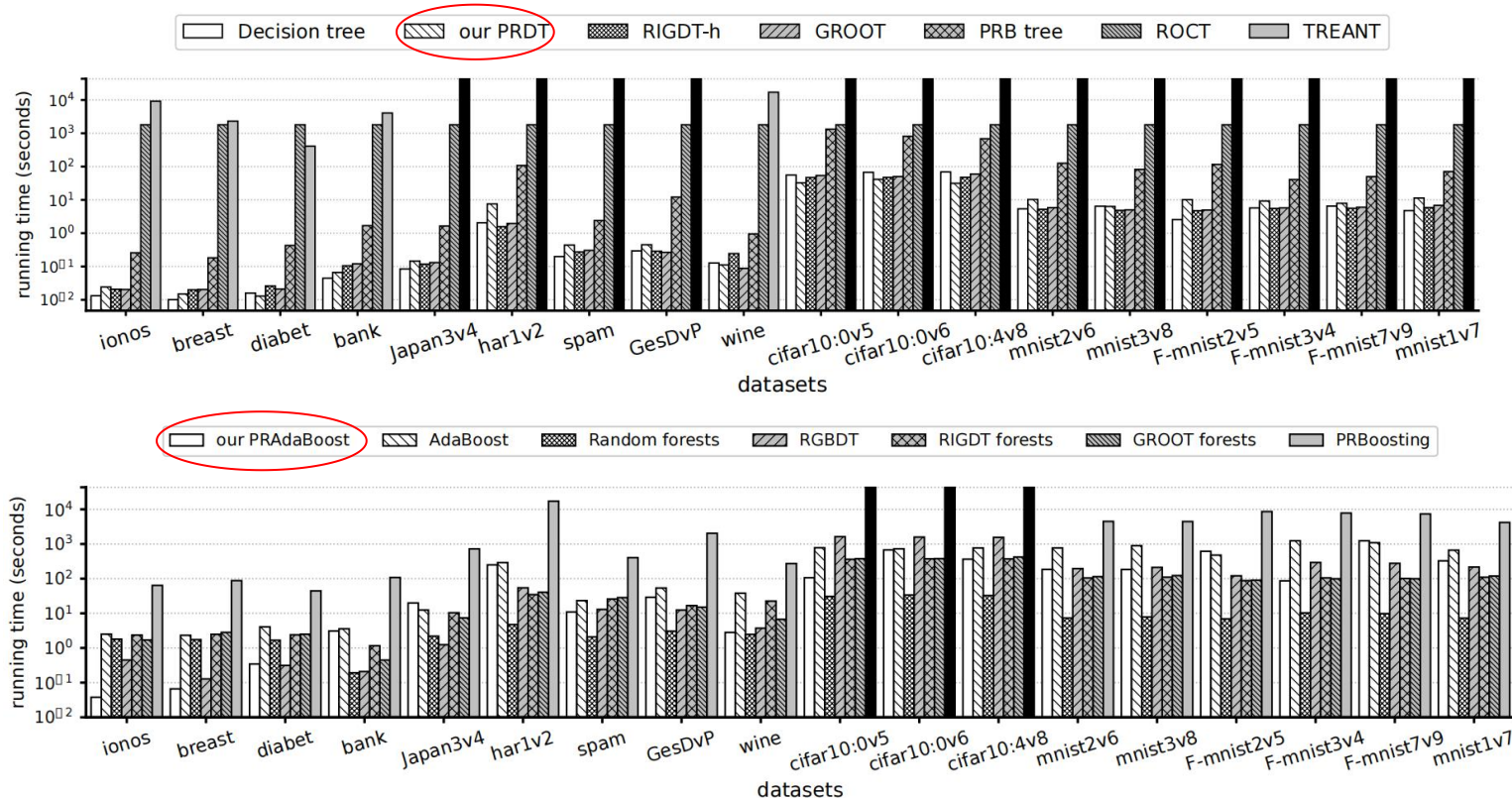
- unprovable methods make local optimizations
- provable methods do not obtain good result due to high complexity

Accuracy comparisons for our PRAdaBoost

Dataset	PRAdaBoost	AdaBoost	Random forests	RGBDT	RIGDT forests	GROOT forests	PRBoosting
ionos	.7960 ± .0329	.0321 ± .0137●	.1122 ± .0353●	.5276 ± .0472●	.6565 ± .0414●	.7869 ± .0346	.7755 ± .0370
breast	.8793 ± .0263	.0732 ± .0156●	.2167 ± .0193●	.7034 ± .0648●	.8437 ± .0280●	.8838 ± .0251	.8694 ± .0282●
diabet	.6635 ± .0281	.1352 ± .0156●	.4523 ± .0411●	.4560 ± .0371●	.5999 ± .0371●	.6578 ± .0210●	.6276 ± .0325●
bank	.6680 ± .0361	.4019 ± .0619●	.5087 ± .0292●	.4427 ± .0333●	.5087 ± .0292●	.6407 ± .0308●	.6195 ± .0403●
Japan3v4	.6816 ± .0165	.4913 ± .0231●	.5187 ± .0184●	.5885 ± .0099●	.6039 ± .0171●	.6580 ± .0160●	.6874 ± .0167
har1v2	.8601 ± .0162	.0092 ± .0065●	.8326 ± .0137●	.6417 ± .0165●	.4998 ± .0212●	.7917 ± .0169●	.8653 ± .0130
spam	.7540 ± .0129	.0000 ± .0000●	.0000 ± .0000●	.4888 ± .0349●	.6212 ± .0202●	.7495 ± .0130●	.7312 ± .0101●
GestDvP	.7315 ± .0165	.1031 ± .0079●	.1887 ± .0086●	.2420 ± .0090●	.6459 ± .0118●	.7314 ± .0127	.7318 ± .0179
wine	.6397 ± .0069	.0002 ± .0004●	.0910 ± .0112●	.1068 ± .0118●	.4161 ± .0129●	.6329 ± .0008●	.6356 ± .0066
cifar10:0v5	.6906 ± .0159	.0083 ± .0035●	.3015 ± .0058●	.3137 ± .0095●	.4413 ± .0094●	.5262 ± .0123●	N/A
cifar10:0v6	.6958 ± .0092	.0556 ± .0041●	.3678 ± .0103●	.3446 ± .0091●	.5199 ± .0082●	.5604 ± .0098●	N/A
cifar10:4v8	.6710 ± .0096	.0019 ± .0014●	.2956 ± .0074●	.2707 ± .0103●	.4614 ± .0074●	.4983 ± .0068●	N/A
mnist2v6	.9437 ± .0046	.0000 ± .0000●	.0000 ± .0000●	.8442 ± .0266●	.8999 ± .0062●	.9249 ± .0045●	.9365 ± .0044●
mnist3v8	.8829 ± .0106	.0000 ± .0000●	.0000 ± .0000●	.7155 ± .0147●	.7756 ± .0081●	.8228 ± .0057●	.8680 ± .0082●
F-mnist2v5	.9823 ± .0028	.3852 ± .0552●	.4561 ± .0041●	.9645 ± .0050●	.9654 ± .0040●	.9791 ± .0029●	.9843 ± .0018○
F-mnist3v4	.8674 ± .0055	.0000 ± .0000●	.0441 ± .0311●	.7172 ± .0131●	.8063 ± .0064●	.8392 ± .0063●	.8640 ± .0054
F-mnist7v9	.8691 ± .0066	.0000 ± .0000●	.1357 ± .0358●	.7401 ± .0164●	.8282 ± .0067●	.8359 ± .0068●	.8779 ± .0069○
mnist1v7	.9752 ± .0031	.0000 ± .0000●	.0000 ± .0000●	.7897 ± .1170●	.9600 ± .0032●	.9668 ± .0031●	.9781 ± .0028
Average	.7918 ± .1134	.0943 ± .1545	.2512 ± .2279	.5499 ± .2276	.6697 ± .1763	.7492 ± .1422	—
Win/Tie/Loss		18/0/0	18/0/0	18/0/0	18/0/0	15/3/0	9/7/2

Our PRAdaBoost: significantly better than other unprovable methods
comparable with PRBoosting yet with smaller time

Running time



Our approaches: faster than other provable robust methods
comparable with unprovable robust methods

Conclusion

In this work, we propose

- **Fast Provably Robust Decision Tree (FPRDT)**
adversarial 0/1 loss, smallest computational complexity
- **Provably Robust AdaBoost (PRAdaBoost)**
upper bound on adversarial exp. loss, smallest comp. complexity

Future work: other adversarial losses for robust decision trees

Thanks!