

Meta Learning for Support Recovery in High-dimensional Precision Matrix Estimation

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Introduction

- ▶ Precision (or inverse covariance) matrix estimation
 - ▶ Gaussian graphical models: the set of off-diagonal non-zero entries (support) of the precision matrix \iff the set of edges of the graph.
 - ▶ Sign-consistency: the estimated precision matrix has the same support and sign of entries with respect to the true matrix.
- ▶ Challenges:
 - ▶ High-dimensionality: n (sample size) \ll N (dimension)
 - ▶ assume sparsity; use ℓ_1 -regularized log-determinant Bregman divergence minimization.
 - ▶ Heterogeneity: multiple tasks with different precision matrices
 - ▶ introduce **random precision matrices**;
 - ▶ consider **meta learning** and **improper estimation**.

Model

- ▶ Multivariate sub-Gaussian distributions with **random precision matrices**. For $k \in \{1, \dots, K\}$, $t \in \{1, \dots, n^{(k)}\}$, $i \in \{1, \dots, N\}$:
 - ▶ $X_1^{(k)}, \dots, X_{n^{(k)}}^{(k)} \in \mathbb{R}^N$ i.i.d.;
 - ▶ $\mathbb{E} \left[X_t^{(k)} \mid \bar{\Omega}^{(k)} \right] = 0$, $\text{Cov} \left(X_t^{(k)} \mid \bar{\Omega}^{(k)} \right) = \bar{\Sigma}^{(k)} := (\bar{\Omega}^{(k)})^{-1}$;
 - ▶ $\bar{\Omega}^{(k)} = \bar{\Omega} + \Delta^{(k)}$ with $\bar{\Omega}, \Delta^{(k)} \in \mathbb{R}^{N \times N}$;
 - ▶ $\bar{\Omega} \succ 0$ deterministic, $\Delta^{(k)}$ **i.i.d. from distribution P satisfying some conditions**;
 - ▶ $X_1^{(k)}, \dots, X_{n^{(k)}}^{(k)}$ conditionally independent given $\bar{\Omega}^{(k)}$;
 - ▶ $X_{t,i}^{(k)}$ conditioned on $\bar{\Omega}^{(k)}$ is sub-Gaussian.
- ▶ $\bar{\Omega}$: true common precision matrix.
 $S := \text{supp}(\bar{\Omega})$: support union.

Method

- ▶ Meta learning – a two-step method:
 - ▶ estimate the **support union** from K auxiliary tasks;
 - ▶ estimate the precision matrix of the novel task (the $(K + 1)$ -th task) with the knowledge of the support union.
- ▶ Improper estimation:
 - ▶ pool **all the samples** from auxiliary tasks to estimate a **single** “common precision matrix” to recover the support union.

Method

- ▶ Support union recovery:

$$\hat{\Omega} = \arg \min_{\Omega \succ 0} \left(\sum_{k=1}^K T^{(k)} \left(\langle \hat{\Sigma}^{(k)}, \Omega \rangle - \log \det(\Omega) \right) + \lambda \|\Omega\|_1 \right), \quad (1)$$

$$T^{(k)} \propto n^{(k)}, \quad \hat{\Sigma}^{(k)} := \frac{1}{n^{(k)}} \sum_{t=1}^{n^{(k)}} X_t^{(k)} \left(X_t^{(k)} \right)^\top.$$

- ▶ Support recovery for novel task:

$$\begin{aligned} \hat{\Omega}^{(K+1)} &= \arg \min_{\Omega \succ 0} \left(\langle \hat{\Sigma}^{(K+1)}, \Omega \rangle - \log \det(\Omega) + \lambda \|\Omega\|_1 \right) \\ &\text{s.t. } \text{supp}(\Omega) \subseteq \text{supp}(\hat{\Omega}), \quad \text{diag}(\Omega) = \text{diag}(\hat{\Omega}). \end{aligned} \quad (2)$$

For simplicity, assume $n^{(k)} = n$ for $1 \leq k \leq K$.

Theoretical Results

- ▶ Support union recovery
 - ▶ Under some conditions, with probability at least

$$1 - O(N^2 \exp\{-nK\}), \quad (3)$$

the estimator $\hat{\Omega}$ is sign-consistent.

- ▶ Sufficient sample complexity for support union recovery:
 $n \in O((\log N)/K)$.

Theoretical Results

- ▶ Support union recovery
 - ▶ For some family of N -dimensional random multivariate sub-Gaussian distributions of size K with support union S and any estimate \hat{S} of S , we have

$$\mathbb{P}\{\hat{S} \neq S\} \geq 1 - O\left(\frac{nK}{\log N}\right) \quad (4)$$

- ▶ Necessary sample complexity for support union recovery:
 $n \in \Omega((\log N)/K)$.

Theoretical Results

- ▶ Support recovery for novel task
 - ▶ Suppose the support union S is recovered. For a novel task of multivariate sub-Gaussian distribution with precision matrix $\bar{\Omega}^{(K+1)}$ such that $\text{supp}(\bar{\Omega}^{(K+1)}) \subseteq S$, under some conditions, with probability at least,

$$1 - O\left(|S_{\text{off}}| \exp\left\{-n^{(K+1)}\right\}\right), \quad (5)$$

the estimator $\hat{\Omega}^{(K+1)}$ is sign-consistent.

- ▶ Overall sufficient sample complexity:
 - ▶ $n \in O(\log(N)/K)$ for each auxiliary task;
 - ▶ $n^{(K+1)} \in O(\log(|S_{\text{off}}|))$ for the novel task.

Theoretical Results

- ▶ Support recovery for novel task
 - ▶ Consider n samples generated from some N -dimensional multivariate sub-Gaussian distribution whose precision matrix has support $S^{(K+1)} \subset S$. For any estimate $\hat{S}^{(K+1)}$ of $S^{(K+1)}$, we have

$$\mathbb{P}\{\hat{S}^{(K+1)} \neq S^{(K+1)}\} \geq 1 - O\left(\frac{n}{\log |S_{\text{off}}|}\right) \quad (6)$$

- ▶ Necessary sample complexity for the novel task:
 $n^{(K+1)} \in \Omega(\log(|S_{\text{off}}|))$.
- ▶ Our method is **minimax optimal**.

Related Work

Table 1: Sufficient sample complexity for support union recovery.

Method	Sample Complexity
Our meta learning method	$n \in O(\log(N)/K)$
Multi-task [Honorio et al., 2012]	$n \in O(\log K + \log N)$
Multi-task [Guo et al., 2011]	$n \in O((N \log N)/K)$
Multi-task [Ma and Michailidis, 2016]	$n \in O(K + \log N)$

Table 2: Sufficient sample complexity for support recovery on the novel task.

Method	Sample Complexity
Our meta learning method	$n^{(K+1)} \in O(\log(S_{\text{off}}))$
Single-task [Ravikumar et al., 2011]	$n^{(K+1)} \in O(\log N)$

Thank You!