

Learning Bounds for Open-Set Learning

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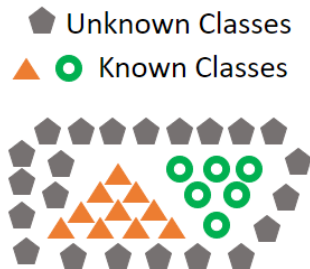
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Open-Set Learning

Definition (Domain)

Given a feature space $\mathcal{X} \subset \mathbb{R}^d$ and a label space \mathcal{Y} , a domain is a joint distribution $P_{\mathcal{X}, \mathcal{Y}}$, where random variables $X \in \mathcal{X}, Y \in \mathcal{Y}$.

Known classes are a subset of \mathcal{Y} . We define the label space of known classes as \mathcal{Y}_k . Then, the *unknown classes* are from the space $\mathcal{Y} / \mathcal{Y}_k$.

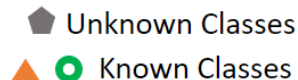


Open-Set Learning

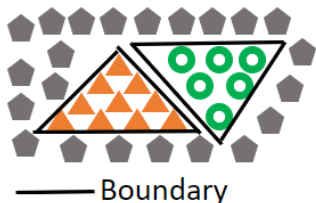
Definition (Open-Set Learning)

Given i.i.d. samples $S = \{(x^i, y^i)\}_{i=1}^n$ drawn from $P_{X, Y|Y \in \mathcal{Y}_k}$. The aim of open-set learning is to train a classifier f using S such that f can classify

- 1) the sample from known classes into correct known classes;
- 2) the sample from unknown classes into unknown classes.



Only using samples from known classes



Main Idea

Aim to construct an auxiliary domain, which has larger support set than that of the known distribution $P_{X,Y|Y \in \mathcal{Y}_k}$. By transferring unknown information from unknown classes of the auxiliary domain, we can recognize the unknown classes.

Step 1. Given an auxiliary distribution U such that $P_{X,Y|Y \in \mathcal{Y}_k} \ll U$;

Step 2. Construct a weight function w such that $P_{X,Y|Y \in \mathcal{Y}_k} \approx wU$;

Step 3. Construct a weight transformation $L_{\tau,\beta}$ such that the density $L_{\tau,\beta}(w)U$ of unknown classes is β ;

Step 4. Transfer knowledge from $L_{\tau,\beta}(w)U$ to $P_{X,Y}$.

Main Theoretical Results

Generalization Error for Open-Set Learning

Given mild assumptions, any $\epsilon_0 > 0$ and samples S with size n , there exists an algorithm A_{ϵ_0} whose output belongs to a hypothesis space \mathcal{H} , the estimation error of A_{ϵ_0} is close to $O(\sqrt{1/n})$, i.e.,

$$|R_P^\alpha(A_{\epsilon_0}(S)) - \min_{\mathbf{h} \in \mathcal{H}} R_P^\alpha(\mathbf{h})| \leq O_p(\sqrt{1/n}) + \epsilon_0,$$

where R_P^α is the risk for open-set learning and O_p is related to ϵ_0 .

The generalization error bound proved in our work provides the first almost-PAC-style guarantee on open-set learning.

Proposed Algorithm

Based on our theory, we minimize a proxy risk:

$$\tilde{R}_{S,T}^{\tau,\beta}(\mathbf{h}) := \hat{R}_S(\mathbf{h}) + \frac{\alpha\gamma'}{1-\alpha} \hat{R}_{S,T,u}^{\tau,\beta}(\mathbf{h}),$$

where $\hat{R}_S(\mathbf{h})$ is the risk for known classes and $\hat{R}_{S,T,u}^{\tau,\beta}(\mathbf{h})$ is the risk for unknown classes, i.e., given m auxiliary data T from U ,

$$\hat{R}_{S,T,u}^{\tau,\beta}(\mathbf{h}) := \frac{1}{m} \sum_{x \in T} L_{\tau,\beta}^-(\hat{w}(x)) \ell(\mathbf{h}(x), y_{C+1}),$$

here

$$L_{\tau,\beta}^-(x) = \begin{cases} x + \beta, & x \leq \tau; \\ 0, & 2\tau \leq x; \\ -\frac{\tau + \beta}{\tau}x + 2\tau + 2\beta, & \tau < x < 2\tau. \end{cases} \quad (1)$$

Experiments

- The performance on dataset MNIST, CIFAR-10 using F1 scores. Dark colour means best performance.

Algorithm	Omniglot	MNIST-Noise	Noise
Openmax	0.780	0.816	0.826
CROSR	0.793	0.827	0.826
CGDL	0.850	0.887	0.859
Ours (AOSR)	0.825	0.953	0.953

Algorithm	ImageNet-crop	ImageNet-resize	LSUN-crop	LSUN-resize
Openmax	0.660	0.684	0.657	0.668
CROSR	0.721	0.735	0.720	0.749
CGDL	0.840	0.832	0.806	0.812
Ours (AOSR)	0.798	0.795	0.839	0.838

Acknowledgements

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Thank You !