

# On the Random Conjugate Kernel and Neural Tangent Kernel

Zhengmian Hu <sup>1</sup>, Heng Huang <sup>1,2</sup>

<sup>1</sup>Department of Electrical and Computer Engineering, University of Pittsburgh, Pittsburgh, PA 15213, USA.

<sup>2</sup>JD Finance America Corporation, Mountain View, CA 94043, USA.

## Definition

A neural network:  $N(x) = W h(x)$ .  $W$  is the last fully connected layer weight,  $h$  is the last hidden layer.

Conjugate Kernel (CK):

$$\Sigma(x, y) = h(x)^\top h(y)$$

## Definition

A neural network:  $N(x) = W h(x)$ .  $W$  is the last fully connected layer weight,  $h$  is the last hidden layer.

Conjugate Kernel (CK):

$$\Sigma(x, y) = h(x)^\top h(y)$$

Only train last layer, fix previous layers.

Use all previous layers as random features.

Gradient descent on input  $x$  for one step with step size  $t$ :

$$\Delta W = -t \frac{\partial L}{\partial N(x)} h(x)^\top$$

$$\Delta N(y) = -t \frac{\partial L}{\partial N(x)} h(x)^\top h(y)$$

## Definition

Neural network has parameters  $W_i$  and  $b_i$  as weights and biases.

Neural Tangent Kernel (NTK):

$$K_{W_i}(x, y) = \sum_{j,l} \frac{\partial N(x)}{\partial [W_i]_{j,l}} \frac{\partial N(y)}{\partial [W_i]_{j,l}}$$

$$K_{b_i}(x, y) = \sum_j \frac{\partial N(x)}{\partial [b_i]_j} \frac{\partial N(y)}{\partial [b_i]_j}$$

$$K(x, y) = \sum_i (K_{W_i}(x, y) + K_{b_i}(x, y))$$

## Definition

Neural network has parameters  $W_i$  and  $b_i$  as weights and biases.

Neural Tangent Kernel (NTK):

$$K_{W_i}(x, y) = \sum_{j,l} \frac{\partial N(x)}{\partial [W_i]_{j,l}} \frac{\partial N(y)}{\partial [W_i]_{j,l}}$$

$$K_{b_i}(x, y) = \sum_j \frac{\partial N(x)}{\partial [b_i]_j} \frac{\partial N(y)}{\partial [b_i]_j}$$

$$K(x, y) = \sum_i (K_{W_i}(x, y) + K_{b_i}(x, y))$$

Train all layers for a small step  $t$  on input  $x$ :

$$\Delta N(y) \approx -t \frac{\partial L}{\partial N(x)} K(x, y)$$

## Two types of neural network

Feedforward network:



$d$  - Depth

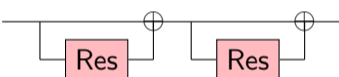
$n$  - Hidden layer width

# Two types of neural network

Feedforward network: 

$d$  - Depth

$n$  - Hidden layer width

Residual network: 

$m$  - Number of branches

$d$  - Sum depth of each branch

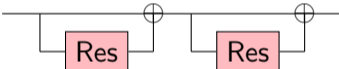
$n$  - Hidden layer width

## Two types of neural network

Feedforward network: 

$d$  - Depth

$n$  - Hidden layer width

Residual network: 

$m$  - Number of branches

$d$  - Sum depth of each branch

$n$  - Hidden layer width

Both has Gaussian initialization for weights and set initial bias to 0.



## Previous Results

Training a neural network is approximately kernel gradient descent. However, the kernel is not generally a constant.

When  $n \rightarrow \infty$ ,  $d$  is fixed. CK and NTK converge to fixed values. (Cho, Y. & Saul, 2009, Jacot et al., 2018)

For finite width and depth case, the second order moments of random CK and NTK is bounded for both feedforward network (Hanin & Nica 2020) and residual network (Littwin et al. 2020).

CK of feedforward network converges to log normal distribution (Hanin & Nica 2019).

## Our results

We study the diagonal elements of CK and NTK for both feedforward network and residual network with Relu activation:

- ▶ Derive every order moments of CK and NTK.
- ▶ Show that random CK and NTK converge to log normal distribution under certain constraints.

# Moments

Feedforward Network CK:

$$\mathbb{E}[\Sigma(x_0, x_0)^r] = \|x_0\|^{2r} c^r \left( \exp \left( \binom{r}{2} \beta \right) + \mathcal{O} \left( \sum_{i=1}^{d-1} \frac{1}{n_i^2} \right) \right)$$

$c$  depends on variance of Gaussian initialization.

Noise parameter:

$$\beta = \sum_{k=1}^{d-1} \frac{5}{n_k}$$

# Moments

Feedforward Network CK:

$$\mathbb{E}[\Sigma(x_0, x_0)^r] = \|x_0\|^{2r} c^r \left( \exp \left( \binom{r}{2} \beta \right) + \mathcal{O} \left( \sum_{i=1}^{d-1} \frac{1}{n_i^2} \right) \right)$$

$c$  depends on variance of Gaussian initialization.

Noise parameter:

$$\beta = \sum_{k=1}^{d-1} \frac{5}{n_k}$$

Feedforward Network NTK:

$$\frac{\mathbb{E}[K(x_0, x_0)^r]}{(\mathbb{E}[K(x_0, x_0)])^r} \leq \exp \left( \binom{r}{2} \beta \right) + \mathcal{O} \left( \sum_{i=1}^{d-1} \frac{1}{n_i^2} \right)$$

# Distribution Convergence

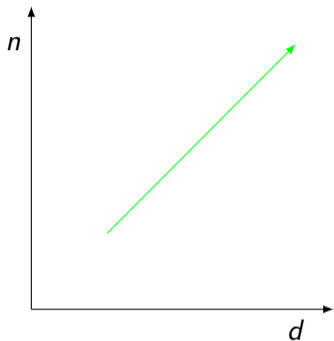


Figure: Different limiting behaviour of CK and NTK.

For feedforward network:

Green line: Diagonal elements of CK and NTK of each parameter converge to log-normal distribution.

# Moments

Residual Network CK:

$$E[\Sigma(x_0, x_0)^r] = \exp\left(\left(r + \frac{4}{n} \binom{r}{2}\right) \sum_{i=0}^{m-1} c_i\right) + \mathcal{O}\left(\sum_{i=0}^{m-1} c_i^2\right)$$

$c_i$  depends on variance of Gaussian initialization.

# Moments

Residual Network CK:

$$\mathbb{E}[\Sigma(x_0, x_0)^r] = \exp\left(\left(r + \frac{4}{n} \binom{r}{2}\right) \sum_{i=0}^{m-1} c_i\right) + \mathcal{O}\left(\sum_{i=0}^{m-1} c_i^2\right)$$

$c_i$  depends on variance of Gaussian initialization.

Residual Network NTK:

$$\frac{\mathbb{E}[K(x_0, x_0)^r]}{(\mathbb{E}[K(x_0, x_0)])^r} \leq \exp\left(\binom{r}{2} \left(\max_i \beta_i + \frac{4}{n} \sum_i c_i\right)\right) + \mathcal{O}\left(\sum_{i=0}^{m-1} \sum_{j=1}^{d_i} \frac{1}{n_{i,j}^2} + \sum_{i=0}^{m-1} c_i^2\right)$$

$\beta_i$  is noise parameter for  $i$ -th branch

# Moments

Residual Network CK:

$$\mathbb{E}[\Sigma(x_0, x_0)^r] = \exp\left(\left(r + \frac{4}{n} \binom{r}{2}\right) \sum_{i=0}^{m-1} c_i\right) + \mathcal{O}\left(\sum_{i=0}^{m-1} c_i^2\right)$$

$c_i$  depends on variance of Gaussian initialization.

Residual Network NTK:

$$\frac{\mathbb{E}[K(x_0, x_0)^r]}{(\mathbb{E}[K(x_0, x_0)])^r} \leq \exp\left(\binom{r}{2} \left(\max_i \beta_i + \frac{4}{n} \sum_i c_i\right)\right) + \mathcal{O}\left(\sum_{i=0}^{m-1} \sum_{j=1}^{d_i} \frac{1}{n_{i,j}^2} + \sum_{i=0}^{m-1} c_i^2\right)$$

$\beta_i$  is noise parameter for  $i$ -th branch



# Moments

Residual Network CK:

$$E[\Sigma(x_0, x_0)^r] = \exp\left(\left(r + \frac{4}{n} \binom{r}{2}\right) \sum_{i=0}^{m-1} c_i\right) + \mathcal{O}\left(\sum_{i=0}^{m-1} c_i^2\right)$$

$c_i$  depends on variance of Gaussian initialization.

Residual Network NTK:

$$\frac{E[K(x_0, x_0)^r]}{(E[K(x_0, x_0)])^r} \leq \exp\left(\binom{r}{2} \left(\max_i \beta_i + \frac{4}{n} \sum_i c_i\right)\right) + \mathcal{O}\left(\sum_{i=0}^{m-1} \sum_{j=1}^{d_i} \frac{1}{n_{i,j}^2} + \sum_{i=0}^{m-1} c_i^2\right)$$

$\beta_i$  is noise parameter for  $i$ -th branch

# Distribution Convergence

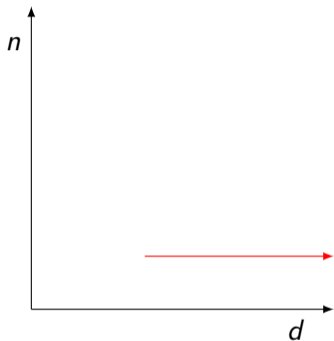
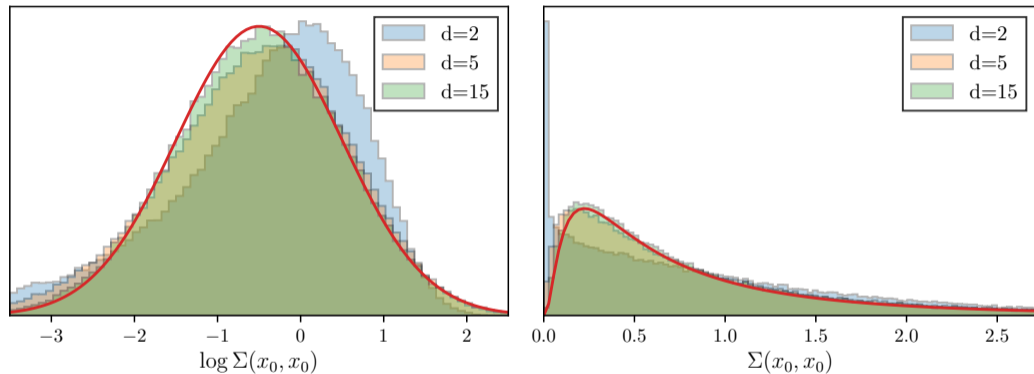


Figure: Different limiting behaviour of CK and NTK.

For residual network:

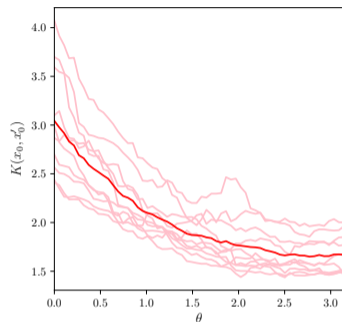
Red line: Diagonal elements of CK converges to log-normal distribution, and diagonal elements of NTK for each parameter converges in law to a log-normal distributed variable times CK of a feedforward network.

## Experimental Verification

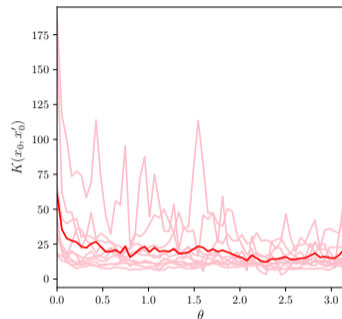


**Figure:** Distribution of CK for feedforward network. The red line is the theoretical limiting distribution given  $c$  and  $\beta$ .

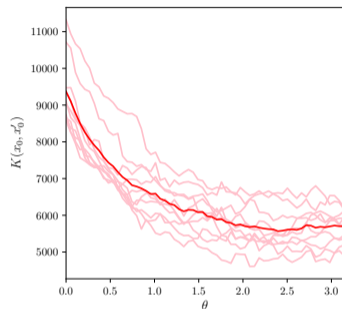
# Feedforward Network vs Residual Network



(a) FFNet ( $d=5$ )



(b) FFNet ( $d=100$ )



(c) ResNet ( $d=5, m=20$ )

Figure: NTK for different network with same hidden layer width  $n$ .

The NTK of deep residual network is less noisy and more informative, therefore deep residual network is easier to train than deep feedforward network.

# Final Picture

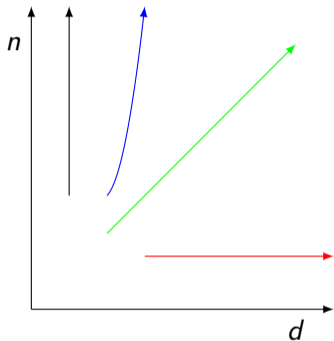


Figure: Different limiting behaviour of CK and NTK.

Black and Blue line: CK and NTK converge to fixed value.

Green line: For feedforward network, CK and NTK converge to log-normal distribution.

Red line: For residual network, CK converges to log-normal distribution and NTK converges to certain distribution.

*Thank you*