

# Detection of Signal in the Spiked Rectangular Models

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2021 ICML

# Spiked rectangular models

- Rectangular matrix with *spiked mean* (additive model)

$$\sqrt{\lambda} \mathbf{u} \mathbf{v}^T + X$$

$X$ :  $M \times N$  random i.i.d. matrix, centered with variance  $N^{-1}$

$$\mathbf{u} \in \mathbb{R}^M, \mathbf{v} \in \mathbb{R}^N, \|\mathbf{u}\| = \|\mathbf{v}\| = 1$$

- Rectangular matrix with *spiked covariance* (multiplicative model)

$$(I + \lambda \mathbf{u} \mathbf{u}^T)^{1/2} X$$

$X$ :  $M \times N$  random i.i.d. matrix, centered with variance  $N^{-1}$

$$\mathbf{u} \in \mathbb{R}^M, \|\mathbf{u}\| = 1$$

# Spiked rectangular models

$$\sqrt{\lambda} \mathbf{u} \mathbf{v}^T + \mathcal{X} \quad (I + \lambda \mathbf{u} \mathbf{u}^T)^{1/2} \mathcal{X}$$

- If  $\mathbf{u}$  and  $\mathbf{v}$  are centered, the population covariance  $\Sigma = I + \lambda \mathbf{u} \mathbf{u}^T$ .
- If  $\mathbf{v}$  is i.i.d. Gaussian (scaled standard normal), the two models coincide.
- High-dimensional assumption  $M, N \rightarrow \infty$  with  $M/N \rightarrow d_0 \in (0, \infty)$ .
- If  $\lambda > \sqrt{d_0}$ , signal can be reliably detected and recovered by PCA. (BBP transition)
- If  $0 < \lambda < \sqrt{d_0}$  and the noise is Gaussian,
  - signal cannot be detected by PCA,
  - no tests can reliably detect the signal.
 (Onatski, Moreira, Hallin '13, '14, El Alaoui, Jordan '18)

## Improved PCA - additive model

$Y = \sqrt{\lambda} \mathbf{u} \mathbf{v}^T + X$ ,  $\sqrt{N} X_{ij}$  is drawn from a distribution with a density  $g$ .

- Fisher information

$$F_g = \int_{-\infty}^{\infty} \frac{g'(x)^2}{g(x)} dx.$$

( $F_g \geq 1$  with equality if and only if  $g$  is Gaussian.)

- Entrywise transformation

$$h(x) := -\frac{g'(x)}{g(x)}, \quad \tilde{Y}_{ij} = \frac{1}{\sqrt{F_g N}} h(\sqrt{N} Y_{ij}).$$

### Theorem (J.-C.-L.)

For the largest eigenvalue  $\tilde{\mu}_1$  of  $\tilde{Y} \tilde{Y}^T$ , almost surely

$$\tilde{\mu}_1 \rightarrow \begin{cases} (1 + \lambda_g)(1 + \frac{d_0}{\lambda_g}) & \text{if } \lambda_g > \sqrt{d_0}, \\ (1 + \sqrt{d_0})^2 & \text{if } \lambda_g < \sqrt{d_0}. \end{cases} \quad (\lambda_g = \lambda F_g)$$

## Improved PCA - multiplicative model

$$Y = (I + \lambda \mathbf{u}\mathbf{u}^T)^{1/2} X, \quad \lambda = 2\gamma + \gamma^2.$$

- Entrywise transformation

$$h_\alpha(x) := -\frac{g'(x)}{g(x)} + \alpha x, \quad \alpha = \frac{-\gamma F_g + \sqrt{4F_g + 4\gamma F_g + \gamma^2 F_g^2}}{2(1 + \gamma)}.$$

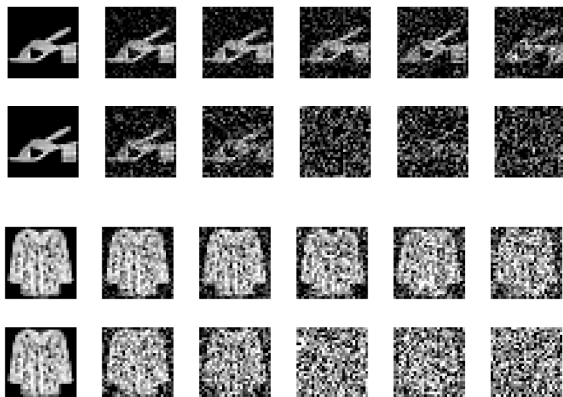
$$\tilde{Y}_{ij} \equiv \tilde{Y}_{ij}^{(\alpha)} = \frac{1}{\sqrt{(\alpha^2 + 2\alpha + F_g)N}} h_\alpha(\sqrt{N} Y_{ij})$$

## Theorem (J.-C.-L.)

For the largest eigenvalue  $\tilde{\mu}_1$  of  $\tilde{Y}\tilde{Y}^T$ , almost surely

$$\tilde{\mu}_1 \rightarrow \begin{cases} (1 + \lambda_g)(1 + \frac{d_0}{\lambda_g}) & \text{if } \lambda_g > \sqrt{d_0}, \\ (1 + \sqrt{d_0})^2 & \text{if } \lambda_g < \sqrt{d_0}. \end{cases} \quad (\lambda_g = \gamma + \gamma^2 F_g + \gamma(1 + \gamma)\alpha \geq \lambda)$$

# Reconstruction by the proposed PCA



**Figure:** Reconstruction performance of the proposed PCA (top lines) and the standard PCA (bottom lines) for two FashionMNIST images, with  $N = [3136, 1568, 784, 588, 392]$  and  $M = 784$ .

## Weak detection of signal

Recall  $\mathbb{E}[X_{ij}] = 0$ ,  $\mathbb{E}[X_{ij}^2] = 1/N$ . Set  $\mathbb{E}[X_{ij}^4] = w_4/N^2$ .

- Hypothesis testing  $\mathbf{H}_0 : \lambda = 0$ ,  $\mathbf{H}_1 : \lambda = \omega > 0$
- Compute the test statistic

$$\begin{aligned}
 L_\omega = & -\log \det \left( \left(1 + \frac{d_0}{\omega}\right) (1 + \omega)I - YY^T \right) \\
 & + \frac{\omega}{d_0} \left( \frac{2}{w_4 - 1} - 1 \right) (\text{Tr } YY^T - M) \\
 & + M \left[ \frac{\omega}{d_0} - \log \left( \frac{\omega}{d_0} \right) - \frac{1 - d_0}{d_0} \log(1 + \omega) \right].
 \end{aligned}$$

Theorem (J.-C.-L.)

*For both the additive model and the multiplicative model,*

$$L_\omega \Rightarrow \mathcal{N}(m(\lambda), V_0)$$

# Hypothesis testing - Algorithm

- Set  $m_\omega = \frac{1}{2}(m(0) + m(\omega))$ .
- Accept  $\mathbf{H}_0$  if  $L_\omega \leq m_\omega$ . Accept  $\mathbf{H}_1$  if  $L_\omega > m_\omega$ .
- The error of the test

$$\text{err}(\omega) = \mathbb{P}(L_\omega > m_\omega | \mathbf{H}_0) + \mathbb{P}(L_\omega \leq m_\omega | \mathbf{H}_1) \rightarrow \text{erfc} \left( \frac{\sqrt{V_0}}{4\sqrt{2}} \right)$$

- Universality: For any deterministic or random  $\mathbf{u}$  (and  $\mathbf{v}$ ), the proposed test and its error do not change,
- Optimality: For Gaussian noise, the error of the proposed test with low computational complexity converges to the optimal limit.



# Error of the proposed test

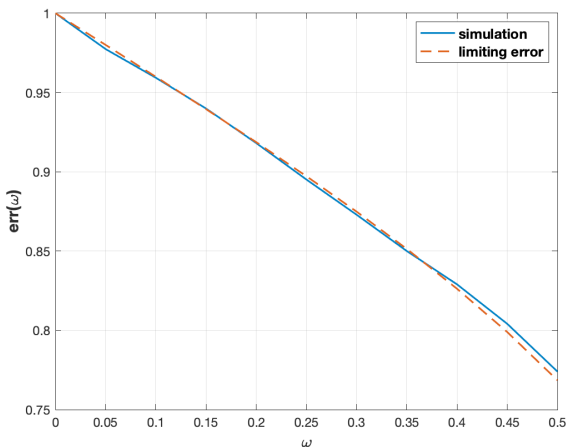


Figure: The error from the simulation (solid) and the theoretical error (dashed).

# Conclusion / Future Works

- We showed that PCA can be improved for non-Gaussian noise by transforming the data entrywise.
- We proved the effective SNR and the optimal entrywise transforms for both the additive model and the multiplicative model.
- We proposed a universal hypothesis test for the weak detection, which is optimal if the noise is Gaussian.
- Future work: improving the hypothesis test by applying the entrywise transformation