Partially Linear Additive Gaussian Graphical Models

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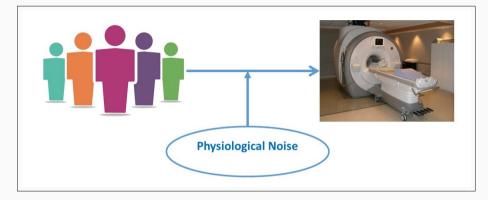
Minhao Yan Cornell University

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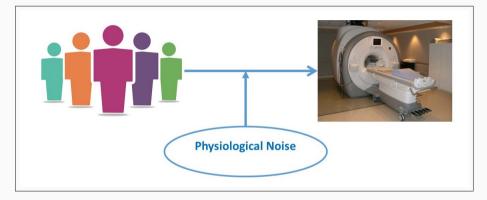
Sanmi Koyejo University of Illinois

Poster: Partially Linear Additive Gaussian Graphical Models Thu Jun 13th 06:15 – 09:00 PM @ Pacific Ballroom

Brain Functional Connectivity Analysis

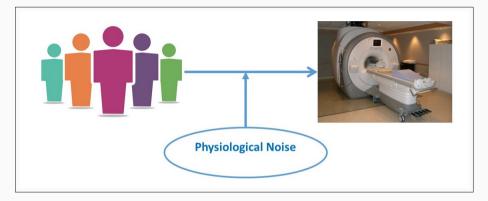


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Estimation is distorted by physiological noise [Van Dijk et al., 2012, Goto et al., 2016]. The noise sources are observable e.g. motion, breathing

Model Formulation: Goals

 \rightarrow A general formulation of the effects caused by the noise.

→ Stronger theoretical guarantees compared tp methods with hidden variables.

Model Formulation

- \rightarrow **Z** denotes the observed fMRI data, and random variable *G*, the physiological noise.
- → $\mathbf{Z} \mid G = g$ follows a Gaussian graphical model [Yang et al., 2015] with a parameter matrix, denoted by $\Omega(g)$:

$$\mathsf{P}(\mathbf{Z}=\mathbf{z}; \mathbf{\Omega}(\mathbf{g}) \mid \mathbf{G}=\mathbf{g}) \propto \exp\left\{\sum_{j=1}^{p} \Omega_{jj}(\mathbf{g}) z_{j} \sum_{j=1}^{p} \sum_{j'>j}^{p} \Omega_{jj'}(\mathbf{g}) z_{j} z_{j'} - \frac{1}{2} \sum_{j}^{p} z_{j}^{2}\right\}.$$

 \rightarrow Parameter matrices are additive:

$$\mathbf{\Omega}(oldsymbol{g}) := \mathbf{\Omega}_0 + \mathbf{R}(oldsymbol{g}).$$

Model Formulation: $\Omega(g)$

Goals:

- Identifiable parameters
- A general formulation

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• ${f R}(g)=0$ for any g satisfying $|g|\leq g^*.$

• $\mathbf{R}(g)$, and $\Omega(g)$ are smooth enough to be recovered by kernel methods.

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Existing assumptions:

- $\mathbf{R}(g) = \mathbf{0}$ [Van Dijk et al., 2012, Power et al., 2014].
- $\mathbb{E}(\mathbf{R}(g)) = \mathbf{0}$ [Lee and Liu, 2015, Geng et al., 2018].

Parameter Estimation

Log Pseudo Likelihood:

• We summarize the varying effects as $M_{ij} := \mathbf{x}_{ij}^\top \Omega_{i\cdot j}$, where \mathbf{x}_{ij}^\top denotes the *i*th row vector of \mathbf{x}_j .

$$\ell_{PL}\left(\{\mathbf{z}_{i}, g_{i}\}_{i \in [n]}; \mathbf{R}(\cdot), \Omega_{0}\right)$$

= $\sum_{i=1}^{n} \sum_{j=1}^{p} \left\{ Z_{ij}\left(\mathbf{x}_{ij}^{\top} \Omega_{0:j} + M_{ij}\right) - \frac{1}{2} Z_{ij}^{2} - \frac{1}{2}\left(\mathbf{x}_{ij}^{\top} \Omega_{0:j} + M_{ij}\right)^{2} \right\}.$

Parameter Estimation

- Pseudo-Profile Likelihood [Fan et al., 2005]
- Suppose that Assumptions are satisfied. Then, for any $\epsilon > 0$, with probability of at least 1ϵ , there exists $C_4 > 0$, so that $\hat{\Omega}_0$ shares the same structure with the underlying true parameter Ω_0^* , if for some constant $C_5 > 0$,

$$C_5 \sqrt{\frac{\log p}{n}} \ge \lambda \ge \frac{4}{\alpha} C_4 \sqrt{\frac{\log p}{n}},$$

$$r := 4C_2 \lambda \le \|\Omega_{0S}^*\|_{\infty},$$

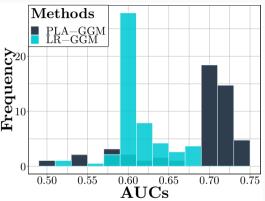
and $n \ge \left(64C_5C_2^2C_3/\alpha\right)^2 \log p$.

Sparsistency: The underlying structure can be recovered with a high probability.

 \sqrt{n} Convergence: The smallest scale of the non-zero component that the PPL method can distinguish from zero converges to zero at a rate of \sqrt{n} .

Overall Performance

- \rightarrow LR-GGM
- \rightarrow fMRI dataset with control
- → Diagnosis using the re-covered structure by the different method



Thank you!

References I

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