

# Gibbs Sampling from $k$ -Determinantal Point Processes

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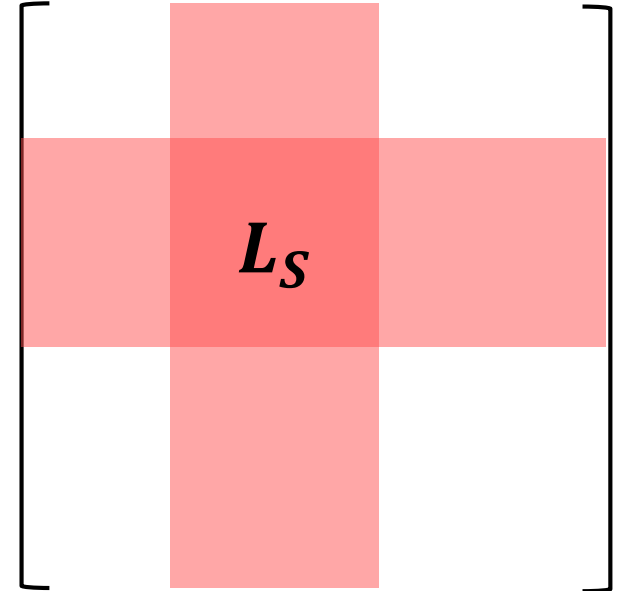
Based on joint work with

Shayan Oveis Gharan

**Point Process:** A distribution on subsets of  $[N] = \{1, 2, \dots, N\}$ .

**Determinantal Point Process:** There is a PSD kernel  $L \in \mathbb{R}^{N \times N}$  such that

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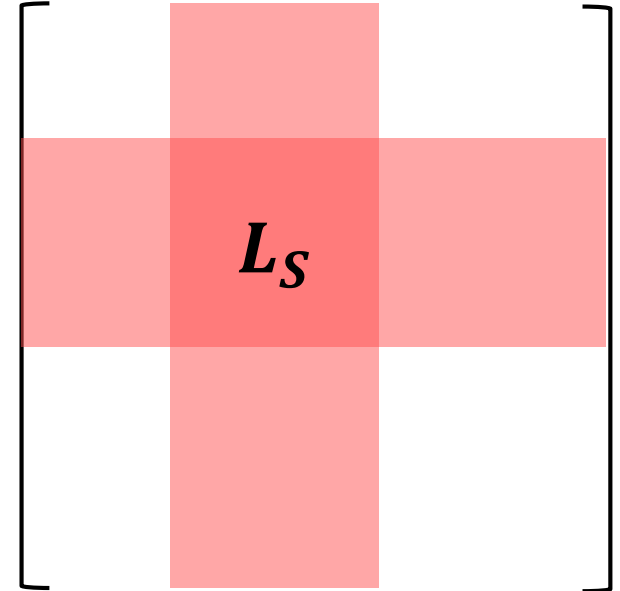
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**$k$ -DPP:** Conditioning of a DPP on picking subsets of size  $k$

Focus of the talk:  
Sampling from  $k$ -  
DPPs

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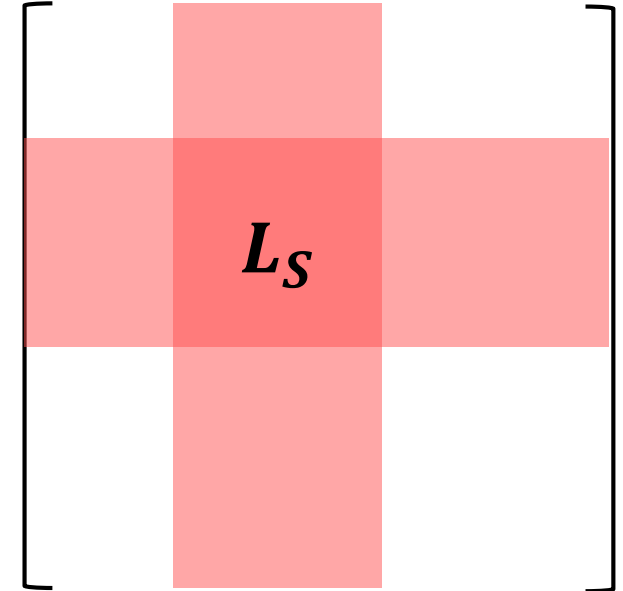
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DPPs are Very popular probabilistic models in machine learning to capture **diversity**.

**Applications** [Kulesza-Taskar'11, Dang'05, Nenkova-Vanderwende-McKeown'06, Mirzasoleiman-Jegelka-Krause'17]

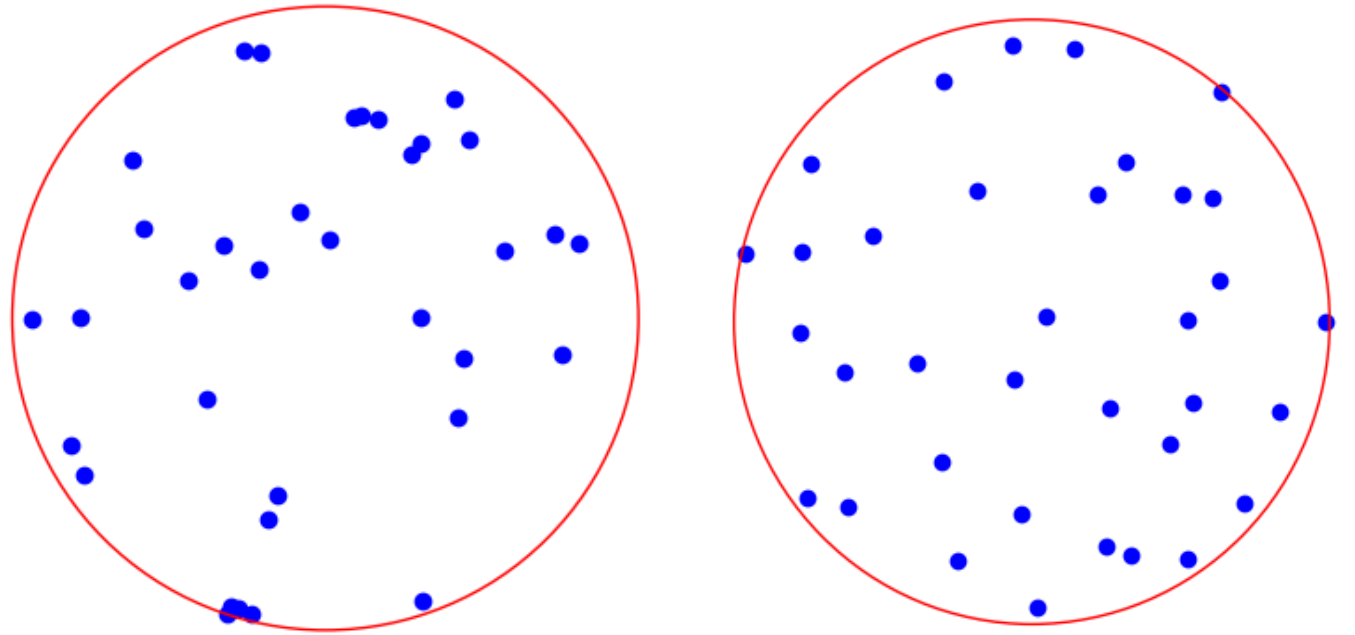
- Image search, document and video summarization, tweet timeline generation, pose estimation, feature selection

# Continuous Domain

**Input:** PSD operator  $L: \mathcal{C} \times \mathcal{C} \rightarrow \mathbb{R}$   
and  $k$

select a subset  $S \subset \mathcal{C}$  with  $k$  points  
from a distribution with PDF function

$$p(S) \propto \det(\{L(x, y)\}_{x, y \in S})$$

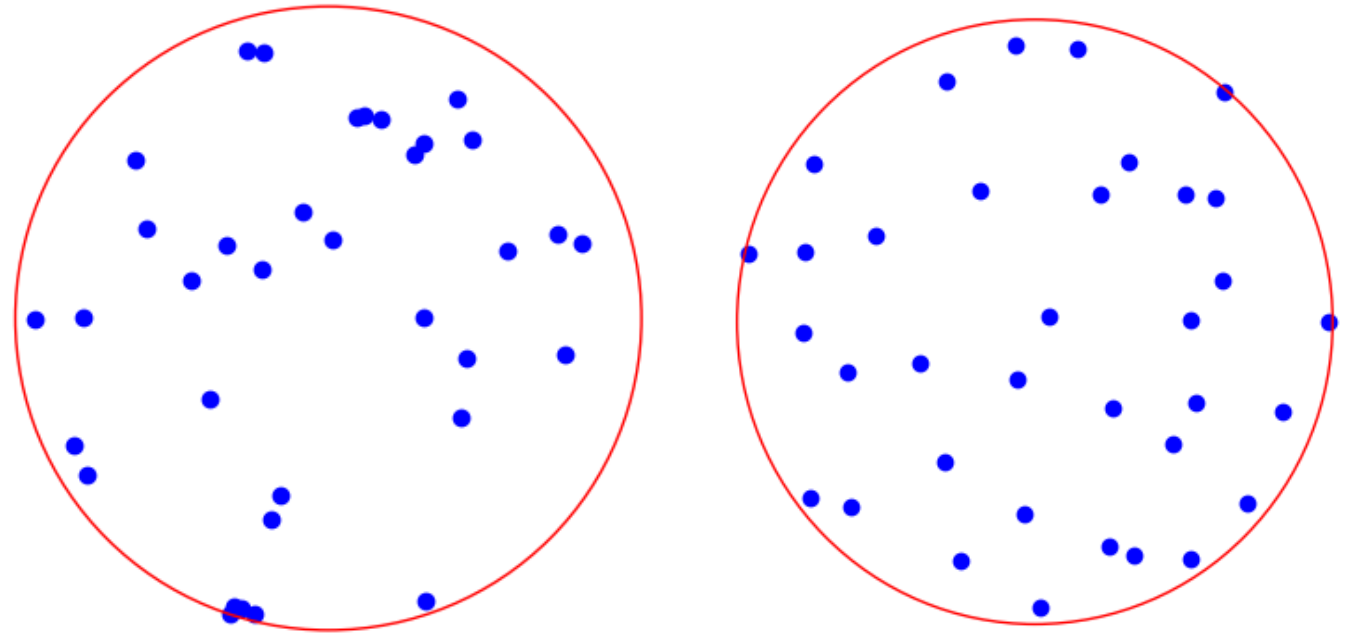


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**Ex.** Gaussian :  $L(x, y) = \exp\left(-\frac{(x-y)\Sigma^{-1}(x-y)}{2}\right)$

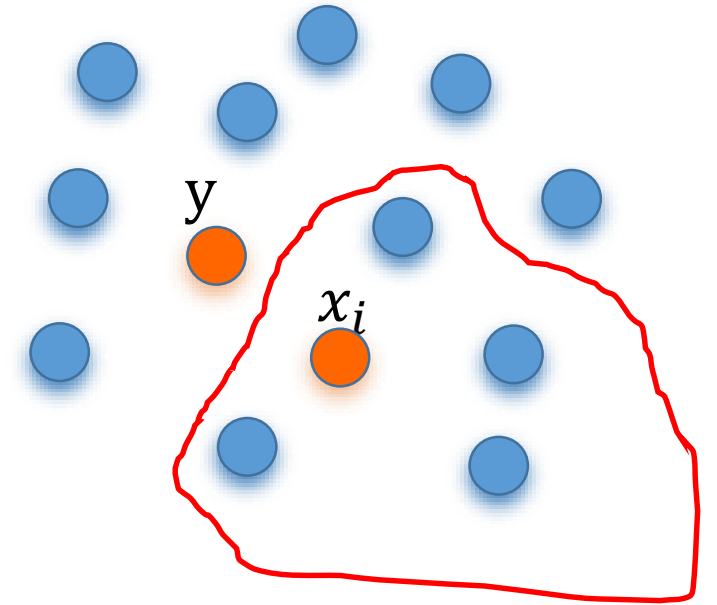
## Applications.

- Hyper-parameter tuning [Dodge-Jamieson-Smith'17]
- Learning mixture of Gaussians [Affandi-Fox-Taskar'13]

# Random Scan Gibbs Sampler for $K$ -DPP

1. Stay at the current state  $S = \{x_1, \dots, x_k\}$  with prob  $\frac{1}{2}$ .
2. Choose  $x_i \in S$  u.a.r
3. Choose  $y \notin S$  from the conditional dist  $\pi(\cdot | S - x_i$  is chosen)

**Continuous:** PDF( $y$ )  $\propto \pi(x_1, \dots, x_{i-1}, y, x_{i+1}, \dots, x_k)$



$$S \in \binom{[N]}{k}$$

## Main Result

Given a  $k$ -DPP  $\pi$ , an “approximate” sample from  $\pi$  can be generated by running the Gibbs sampler for  $\tau = \tilde{O}(k^4) \cdot \log\left(\frac{p_\mu}{p_\pi}\right)$  steps where  $\mu$  is the starting dist.



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**Discrete:** A simple greedy initialization gives  $\tau = O(k^5 \log k)$ . Total running time is  $O(N) \cdot \text{poly}(k)$ .

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- Using a rejection sampler as the conditional oracles for Gaussian kernels  $L(x, y) = \exp\left(-\frac{\|x-y\|^2}{\sigma^2}\right)$  defined a **unit sphere in  $\mathbb{R}^d$** , the total running time is
  - If  $k = \text{poly}(d)$ :  $\text{poly}(d, \sigma)$
  - If  $k \leq e^{d^{1-\delta}}$  and  $\sigma = O(1)$ :  $\text{poly}(d) \cdot k^{O(\frac{1}{\delta})}$

**Thank you!**  
**Poster: Pacific Ballroom #204**